

Nichols algebras with standard braiding Iván Ezequiel Angiono


# Nichols algebras with standard braiding 

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#### Abstract

The class of standard braided vector spaces, introduced by Andruskiewitsch and the author in 2007 to understand the proof of a theorem of Heckenberger, is slightly more general than the class of braided vector spaces of Cartan type. In the present paper, we classify standard braided vector spaces with finitedimensional Nichols algebra. For any such braided vector space, we give a PBW basis, a closed formula of the dimension and a presentation by generators and relations of the associated Nichols algebra.


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## Introduction

A breakthrough in the development of the theory of Hopf algebras occurred with the discovery of quantized enveloping algebras [Drinfel'd 1987; Jimbo 1985]. This special class of Hopf algebras has been intensively studied by many authors and from many points of view. In particular, finite-dimensional analogues of quantized enveloping algebras were introduced and investigated by Lusztig [1990a; 1990b].

About ten year ago, a classification program of pointed Hopf algebras was launched by Andruskiewitsch and Schneider [1998] (see also [Andruskiewitsch and Schneider 2002b]). The success of this program depends on finding solutions to several questions, among them:

[^0]Question 1 [Andruskiewitsch 2002, Question 5.9]. Given a braided vector space of diagonal type $V$, such that the entries of its matrix are roots of unity, compute the dimension of the associated Nichols algebra $\mathfrak{B}(V)$. If it is finite, give a nice presentation of $\mathfrak{B}(V)$.

Partial answers to this question were given in [Andruskiewitsch and Schneider 2000; Heckenberger 2006b] for the class of braided vector spaces of Cartan type. These answers were already crucial to proving a classification theorem for finitedimensional Hopf algebras whose group is abelian with prime divisors of the order great than 7 [Andruskiewitsch and Schneider 2005]. Later, a complete answer to the first part of Question 1 was given in [Heckenberger 2006a].

The notion of a standard braided vector space, a special kind of diagonal braided vector space, was introduced in [Andruskiewitsch and Angiono 2008], and is reviewed in Definition 3.5 below. This class includes properly the class of braided vector spaces of Cartan type.

The purpose of this paper is to develop from scratch the theory of standard braided vector spaces. Here are our main contributions:

- We give a complete classification of standard braided vector spaces with finitedimensional Nichols algebras. As usual, we may assume the connectedness of the corresponding braiding. It turns out that standard braided vector spaces are of Cartan type when the associated Cartan matrix is of type $C, D, E$ or $F$, see Proposition 3.8. For types $A, B, G$ there are standard braided vector spaces not of Cartan type; these are listed in Propositions 3.9, 3.10 and 3.11. Those of type $A_{2}$ and $B_{2}$ appeared already in [Graña 2000]. Our classification does not rely on [Heckenberger 2006a], but we can identify our examples in the tables of that reference.
- We describe a concrete PBW (Poincaré-Birkhoff-Witt) basis of the Nichols algebra of a standard braided vector space as in the previous point; this follows from the general theory of Kharchenko [1999] together with [Heckenberger 2006b, Theorem 1]. As an application, we give closed formulas for the dimension of these Nichols algebras.
- We present a concrete set of defining relations of the Nichols algebras of standard braided vector spaces as in the previous points. This is an answer to the second part of Question 1 in the standard case. We note that this seems to be new even for Cartan type, for some values of the roots of unity appearing in the picture. Essentially, these relations are either quantum Serre relations or powers of root vectors; but in some cases, there are some substitutes of the quantum Serre relations due to the smallness of the intervening root vectors. Some of these substitutes can be recognized already in the relations in [Andruskiewitsch and Dăscălescu 2005].

Here is the plan of this article. We start by collecting necessary tools. Namely, we recall the definition of Lyndon words and give some properties about them, such as the Shirshov decomposition, in Section 1A. Next, in Section 1B, we discuss the notions of hyperletter and hyperword, following [Kharchenko 1999] (where they are called superletter and superword); these are certain iterations of braided commutators applied to Lyndon words. In Section 1C, a PBW basis is given for any quotient of the tensor algebra of a diagonal braided vector space $V$ by a Hopf ideal using these hyperwords. This applies in particular to Nichols algebras.

In Section 2, after some technical preparations, we present a transformation of a braided graded Hopf algebra into another, with different space of degree one. This generalizes an analogous transformation for Nichols algebras given in [Heckenberger 2006b, Proposition 1]; see Section 2C.

In Section 3 we classify standard braided vector spaces with finite-dimensional Nichols algebra. In Section 3A, we prove that if the set of PBW generators is finite, the associated generalized Cartan matrix is of finite type. So in Section 3B we obtain all the standard braidings associated to Nichols algebras of finite dimension.

Section 4 is devoted to PBW bases of Nichols algebras of standard braided vector spaces with finite Cartan matrix. In Section 4A we prove that there is exactly one PBW generator whose degree corresponds to each positive root associated to the finite Cartan matrix. We give a set of PBW generators in Section 4B, following a nice presentation from [Lalonde and Ram 1995]. As a consequence, we compute the dimension in Section 4C.

The main result of this paper is the explicit presentation by generators and relations of Nichols algebras of standard braided vector spaces with finite Cartan matrix, given in Section 5. It relies on the explicit PBW basis and transformation described in Section 2C. Section 5A states some relations for Nichols algebras of standard braidings and proves facts about the coproduct. Sections 5B-5D contain the explicit presentation for types $A_{\theta}, B_{\theta}$ and $G_{2}$, respectively. For this, we establish relations among the elements of the PBW basis, inspired in [Andruskiewitsch and Dăscălescu 2005] and [Graña 2000]. We finally prove the presentation in the case of Cartan type in Section 5E. To our knowledge, this is the first self-contained exposition of Nichols algebras of braided vector spaces of Cartan type.

Notation. We fix an algebraically closed field $k$ of characteristic 0 ; all vector spaces, Hopf algebras and tensor products are considered over k.

For each $N>0, \mathbb{G}_{N}$ denotes the set of primitive $N$-th roots of unity in k .
Given $n \in \mathbb{N}$ and $q \in \mathrm{k}, q \notin \bigcup_{0 \leq j \leq n} \mathbb{G}_{j}$, we define

$$
\binom{n}{j}_{q}=\frac{(n)_{q}!}{(k)_{q}!(n-k)_{q}!}, \quad \text { where }(n)_{q}!=\prod_{j=1}^{n}(k)_{q}, \quad \text { and }(k)_{q}=\sum_{j=0}^{k-1} q^{j}
$$

We define

$$
\mathfrak{q}_{h}(t):=\frac{t^{h}-1}{t-1} \in \mathrm{k}[t], \quad h \in \mathbb{N} ; \quad \mathfrak{q}_{\infty}(t):=\frac{1}{1-t}=\sum_{s=0}^{\infty} t^{s} \in \mathrm{k} \llbracket t \rrbracket .
$$

For each $\theta \in \mathbb{N}$ and each $n=\left(n_{1}, \ldots, n_{\theta}\right) \in \mathbb{Z}^{\theta}$, we set $x^{n}=x_{1}^{n_{1}} \cdots x_{\theta}^{n_{\theta}} \in$ $\mathrm{k} \llbracket x_{1}^{ \pm 1}, \ldots, x_{\theta}^{ \pm 1} \rrbracket$. For each $\mathbb{Z}^{\theta}$-graded vector spaces $\mathfrak{B}$, we denote by $\mathcal{H}_{\mathfrak{B}}=$ $\sum_{n \in \mathbb{Z}^{\theta}} \operatorname{dim} \mathfrak{B}^{n} x^{n}$ the Hilbert series associated to $\mathfrak{B}$.

Let $C=\bigoplus_{n \in \mathbb{N}_{0}} C_{i+j}$ be a $\mathbb{N}_{0}$-graded coalgebra, with projections $\pi_{n}: C \rightarrow C_{n}$. Given $i, j \geq 0$, we denote by

$$
\Delta_{i, j}:=\left(\pi_{i} \otimes \pi_{j}\right) \circ \Delta: C_{i+j} \rightarrow C_{i} \otimes C_{j}
$$

the $(i, j)$-th component of the comultiplication.

## 1. PBW bases

Let $A$ be an algebra, $P, S \subset A$ and $h: S \mapsto \mathbb{N} \cup\{\infty\}$. Let also $<$ be a linear order on $S$. Let us denote by $B(P, S,<, h)$ the set

$$
\left\{p s_{1}^{e_{1}} \ldots s_{t}^{e_{t}}: t \in \mathbb{N}_{0}, s_{1}>\cdots>s_{t}, s_{i} \in S, 0<e_{i}<h\left(s_{i}\right), p \in P\right\}
$$

If $B(P, S,<, h)$ is a linear basis of $A$, then we say that $(P, S,<, h)$ is a set of $P B W$ generators with height $h$, and that $B(P, S,<, h)$ is a $P B W$ basis of $A$. Occasionally, we shall simply say that $S$ is a PBW basis of $A$.

In this section, following [Kharchenko 1999], we describe an appropriate PBW basis of a braided graded Hopf algebra $\mathfrak{B}=\bigoplus_{n \in \mathbb{N}} \mathfrak{B}^{n}$ such that $\mathfrak{B}^{1} \cong V$, where $V$ is a braided vector space of diagonal type. This applies in particular, to the Nichols algebra $\mathfrak{B}(V)$. In Section 1A we recall the classical construction of Lyndon words. Let $V$ be a vector space together with a fixed basis. Then there is a basis of the tensor algebra $T(V)$ by certain words satisfying a special condition, called Lyndon words. Each Lyndon word has a canonical decomposition as a product of a pair of smaller Lyndon words, called the Shirshov decomposition.

We briefly recall the notions of a braided vector space ( $V, c$ ) of diagonal type and of a Nichols algebra in Section 1B. In Section 1C we recall the definition of the hyperletter $[l]_{c}$, for any Lyndon word $l$; this is the braided commutator of the hyperletters corresponding to the words in the Shirshov decomposition. Hyperletters are a set of generators for a PBW basis of $T(V)$ and their classes form a PBW basis of $\mathfrak{B}$.

1A. Lyndon words. Let $\theta \in \mathbb{N}$. Let $X$ be a set with $\theta$ elements and fix an enumeration $x_{1}, \ldots, x_{\theta}$ of $X$; this induces a total order on $X$. Let $\mathbb{X}$ be the corresponding vocabulary (the set of words with letters in $X$ ) and consider the lexicographical order on $\mathbb{X}$.

Definition 1.1. An element $u \in \mathbb{X}, u \neq 1$, is called a Lyndon word if $u$ is smaller than any of its proper ends; that is, if $u=v w, v, w \in \mathbb{X}-\{1\}$, then $u<w$. The set of Lyndon words is denoted by $L$.

We shall need the following properties of Lyndon words.
(1) Let $u \in \mathbb{X}-X$. Then $u$ is Lyndon if and only if for any representation $u=u_{1} u_{2}$, with $u_{1}, u_{2} \in \mathbb{X}$ not empty, one has $u_{1} u_{2}=u<u_{2} u_{1}$.
(2) Any Lyndon word begins by its smallest letter.
(3) If $u_{1}, u_{2} \in L, u_{1}<u_{2}$, then $u_{1} u_{2} \in L$.

The basic Theorem about Lyndon words, due to Lyndon, says that any word $u \in \mathbb{X}$ has a unique decomposition

$$
\begin{equation*}
u=l_{1} l_{2} \ldots l_{r} \tag{1-1}
\end{equation*}
$$

with $l_{i} \in L, l_{r} \leq \cdots \leq l_{1}$, as a product of nonincreasing Lyndon words. This is called the Lyndon decomposition of $u \in \mathbb{X}$; the $l_{i} \in L$ appearing in the decomposition (1-1) are called the Lyndon letters of $u$.

The lexicographical order of $\mathbb{X}$ turns out to be the same as the lexicographical order in the Lyndon letters. Namely, if $v=l_{1} \ldots l_{r}$ is the Lyndon decomposition of $v$, then $u<v$ if and only if
(i) the Lyndon decomposition of $u$ is $u=l_{1} \ldots l_{i}$, for some $1 \leq i<r$, or
(ii) the Lyndon decomposition of $u$ is $u=l_{1} \ldots l_{i-1} l l_{i+1}^{\prime} \ldots l_{s}^{\prime}$, for some $1 \leq i<r$, $s \in \mathbb{N}$ and $l, l_{i+1}^{\prime}, \ldots, l_{s}^{\prime}$ in $L$, with $l<l_{i}$.
Here is another useful characterization of Lyndon words.
Lemma 1.2 [Kharchenko 1999, p. 6]. Let $u \in \mathbb{X}-X$. Then $u \in L$ if and only if there exist $u_{1}, u_{2} \in L$ with $u_{1}<u_{2}$ such that $u=u_{1} u_{2}$.
Definition 1.3. Let $u \in L-X$. A decomposition $u=u_{1} u_{2}$, with $u_{1}, u_{2} \in L$ such that $u_{2}$ is the smallest end among those proper nonempty ends of $u$ is called the Shirshov decomposition of $u$.

Let $u, v, w \in L$ be such that $u=v w$. Then $u=v w$ is the Shirshov decomposition of $u$ if and only if either $v \in X$, or else if $v=v_{1} v_{2}$ is the Shirshov decomposition of $v$, then $w \leq v_{2}$.

1B. Braided vector spaces of diagonal type and Nichols algebras. A braided vector space is a pair $(V, c)$, where $V$ is a vector space and $c \in \operatorname{Aut}(V \otimes V)$ is a solution of the braid equation

$$
(c \otimes \mathrm{id})(\mathrm{id} \otimes c)(c \otimes \mathrm{id})=(\mathrm{id} \otimes c)(c \otimes \mathrm{id})(\mathrm{id} \otimes c)
$$

We extend the braiding to $c: T(V) \otimes T(V) \rightarrow T(V) \otimes T(V)$ in the usual way. If $x, y \in T(V)$, the braided commutator is

$$
\begin{equation*}
[x, y]_{c}:=\text { multiplication } \circ(\mathrm{id}-c)(x \otimes y) . \tag{1-2}
\end{equation*}
$$

Assume that $\operatorname{dim} V<\infty$ and pick a basis $X=\left\{x_{1}, \ldots, x_{\theta}\right\}$ of $V$; we may then identify $\mathrm{k} \mathbb{\mathbb { }}$ with $T(V)$. We consider the following gradings of the algebra $T(V)$ :
(i) The usual $\mathbb{N}_{0}$-grading $T(V)=\bigoplus_{n \geq 0} T^{n}(V)$. If $\ell$ denotes the length of a word in $\mathbb{X}$, then $T^{n}(V)=\bigoplus_{x \in \mathbb{X}, \ell(x)=n} \mathrm{k} x$.
(ii) Let $\mathbf{e}_{1}, \ldots, \mathbf{e}_{\theta}$ be the canonical basis of $\mathbb{Z}^{\theta}$. Then $T(V)$ is also $\mathbb{Z}^{\theta}$-graded, where the degree is determined by $\operatorname{deg} x_{i}=\mathbf{e}_{i}, 1 \leq i \leq \theta$.
A braided vector space $(V, c)$ is of diagonal type with respect to the basis $x_{1}, \ldots x_{\theta}$ if there exist $q_{i j} \in \mathrm{k}^{\times}$such that $c\left(x_{i} \otimes x_{j}\right)=q_{i j} x_{j} \otimes x_{i}, 1 \leq i, j \leq \theta$. Let $\chi: \mathbb{Z}^{\theta} \times \mathbb{Z}^{\theta} \rightarrow \mathrm{k}^{\times}$be the bilinear form determined by $\chi\left(\mathbf{e}_{i}, \mathbf{e}_{j}\right)=q_{i j}, 1 \leq i, j \leq \theta$. Then

$$
\begin{equation*}
c(u \otimes v)=\chi(\operatorname{deg} u, \operatorname{deg} v) v \otimes u \tag{1-3}
\end{equation*}
$$

for any $u, v \in \mathbb{X}$, where $q_{u, v}=\chi(\operatorname{deg} u, \operatorname{deg} v) \in \mathrm{k}^{\times}$. In this case, the braided commutator satisfies a "braided" Jacobi identity as well as braided derivation properties, namely

$$
\begin{align*}
{\left[[u, v]_{c}, w\right]_{c} } & =\left[u,[v, w]_{c}\right]_{c}-\chi(\alpha, \beta) v[u, w]_{c}+\chi(\beta, \gamma)[u, w]_{c} v  \tag{1-4}\\
{[u, v w]_{c} } & =[u, v]_{c} w+\chi(\alpha, \beta) v[u, w]_{c}  \tag{1-5}\\
{[u v, w]_{c} } & =\chi(\beta, \gamma)[u, w]_{c} v+u[v, w]_{c} \tag{1-6}
\end{align*}
$$

for any homogeneous $u, v, w \in T(V)$, of degrees $\alpha, \beta, \gamma \in \mathbb{N}^{\theta}$, respectively.
We denote by ${ }_{H}^{H_{Ð}} \mathscr{D}$ the category of Yetter-Drinfeld module over $H$, where $H$ is a Hopf algebra with bijective antipode. Any $V \in{ }_{H}^{H} \mathscr{O} \mathscr{D}$ becomes a braided vector space [Montgomery 1993]. If $H$ is the group algebra of a finite abelian group, then any $V \in{ }_{H}^{H_{\mathscr{O}}} \mathfrak{D}$ is a braided vector space of diagonal type. Indeed, $V=\bigoplus_{g \in \Gamma, \chi \in \widehat{\Gamma}} V_{g}^{\chi}$, where $V_{g}^{\chi}=V^{\chi} \cap V_{g}$ with $V_{g}=\{v \in V \mid \delta(v)=g \otimes v\}$ and $V^{\chi}=\{v \in V \mid g \cdot v=\chi(g) v$ for all $g \in \Gamma\}$. The braiding is given by $c(x \otimes y)=\chi(g) y \otimes x$, for all $x \in V_{g}, g \in \Gamma, y \in V^{\chi}, \chi \in \widehat{\Gamma}$.

Reciprocally, any braided vector space of diagonal type can be realized as a Yetter-Drinfeld module over the group algebra of an abelian group.

If $V \in{ }_{H}^{H} Y \mathscr{D}$, the tensor algebra $T(V)$ admits a unique structure of graded braided Hopf algebra in ${ }_{H}^{H} y \mathscr{D}$ such that $V \subseteq \mathscr{P}(V)$. Following [Andruskiewitsch and Schneider 2002b], we consider the class $\mathfrak{S}$ of all the homogeneous two-sided ideals $I \subseteq T(V)$ such that

- $I$ is generated by homogeneous elements of degree $\geq 2$,
- $I$ is a Yetter-Drinfeld submodule of $T(V)$, and
- $I$ is a Hopf ideal: $\Delta(I) \subset I \otimes T(V)+T(V) \otimes I$.

The Nichols algebra $\mathfrak{B}(V)$ associated to $V$ is the quotient of $T(V)$ by the maximal element $I(V)$ of $\mathfrak{S}$.

Let $(V, c)$ be a braided vector space of diagonal type, and assume that $q_{i j}=q_{j i}$ for all $i, j$. Let $\Gamma$ be the free abelian group of $\operatorname{rank} \theta$, with basis $g_{1}, \ldots, g_{\theta}$, and define the characters $\chi_{1}, \ldots, \chi_{\theta}$ of $\Gamma$ by

$$
\chi_{j}\left(g_{i}\right)=q_{i j}, \quad 1 \leq i, j \leq \theta .
$$

Consider $V$ as a Yetter-Drinfeld module over $\mathrm{k} \Gamma$ by defining $x_{i} \in V_{g_{i}}^{\chi_{i}}$.
Proposition 1.4 [Lusztig 1993, Proposition 1.2.3; Andruskiewitsch and Schneider 2002b, Proposition 2.10]. Let $a_{1}, \ldots, a_{\theta} \in \mathrm{k}^{\times}$. There is a unique bilinear form $(\mid): T(V) \times T(V) \rightarrow \mathrm{k}$ such that $(1 \mid 1)=1$,

$$
\begin{align*}
\left(x_{i} \mid x_{j}\right) & =\delta_{i j} a_{i} \text { for all } i, j  \tag{1-7}\\
\left(x \mid y y^{\prime}\right) & =\left(x_{(1)} \mid y\right)\left(x_{(2)} \mid y^{\prime}\right) \text { for all } x, y, y^{\prime} \in T(V)  \tag{1-8}\\
\left(x x^{\prime} \mid y\right) & =\left(x \mid y_{(1)}\right)\left(x^{\prime} \mid y_{(2)}\right) \text { for all } x, x^{\prime}, y \in T(V) \tag{1-9}
\end{align*}
$$

This form is symmetric and also satisfies

$$
\begin{equation*}
(x \mid y)=0 \quad \text { for all } x \in T(V)_{g}, y \in T(V)_{h}, g, h \in \Gamma, g \neq h . \tag{1-10}
\end{equation*}
$$

The quotient $T(V) / I(V)$, where

$$
I(V):=\{x \in T(V):(x \mid y)=0 \text { for all } y \in T(V)\}
$$

is the radical of the form, is canonically isomorphic to the Nichols algebra of $V$. Thus, ( | ) induces a nondegenerate bilinear form on $\mathfrak{B}(V)$ denoted by the same name.

If $(V, c)$ is of diagonal type, the ideal $I(V)$ is $\mathbb{Z}^{\theta}$-homogeneous, since it is the radical of a bilinear form in which the different $\mathbb{Z}^{\theta}$-homogeneous components are orthogonal; see [Andruskiewitsch and Schneider 2004, Proposition 2.10]. Hence $\mathfrak{B}(V)$ is $\mathbb{Z}^{\theta}$-graded. The following statement, that we include for later reference, is well-known.

Lemma 1.5. Let $V$ be a braided vector space of diagonal type, and consider its Nichols algebra $\mathfrak{B}(V)$.
(a) If $q_{i i}$ is a root of unity of order $N>1$, then $x_{i}^{N}=0$.
(b) If $i \neq j$, then $\left(\operatorname{ad}_{c} x_{i}\right)^{r}\left(x_{j}\right)=0$ if and only if

$$
(r)_{q_{i i}}!\prod_{0 \leq k \leq r-1}\left(1-q_{i i}^{k} q_{i j} q_{j i}\right)=0 .
$$

(c) If $i \neq j$ and $q_{i j} q_{j i}=q_{i i}^{r}$, for some $r \leq 0$, then $\left(\operatorname{ad}_{c} x_{i}\right)^{1-r}\left(x_{j}\right)=0$.

1C. PBW basis of a quotient of the tensor algebra by a Hopf ideal. Let ( $V, c$ ) be a braided vector space with a basis $X=\left\{x_{1}, \ldots, x_{\theta}\right\}$; identify $T(V)$ with kX . There is an important graded endomorphism [ $]_{c}$ of $k \mathbb{X}$ given by

$$
[u]_{c}:= \begin{cases}u & \text { if } u=1 \text { or } u \in X \\ {\left[[v]_{c},[w]_{c}\right]_{c}} & \text { if } u \in L, \ell(u)>1 \\ \quad \text { and } u=v w \text { is the Shirshov decomposition } \\ {\left[u_{1}\right]_{c} \ldots\left[u_{t}\right]_{c}} & \text { if } u \in \mathbb{X}-L \text { with Lyndon decomposition } u=u_{1} \ldots u_{t}\end{cases}
$$

Now assume that $(V, c)$ is of diagonal type with respect to the basis $x_{1}, \ldots, x_{\theta}$, with matrix $\left(q_{i j}\right)$.

Definition 1.6. The hyperletter corresponding to $l \in L$ is the element $[l]_{c}$. A hyperword is a word in hyperletters, and a monotone hyperword is a hyperword of the form $W=\left[u_{1}\right]_{c}^{k_{1}} \ldots\left[u_{m}\right]_{c}^{k_{m}}$, where $u_{1}>\cdots>u_{m}$.
Remark 1.7. If $u \in L$, then $[u]_{c}$ is a homogeneous polynomial with coefficients in $\mathbb{Z}\left[q_{i j}\right]$ and $[u]_{c} \in u+\mathrm{k} \mathbb{X}_{>u}^{\ell(u)}$.

The hyperletters inherit the order from the Lyndon words; this induces in turn an ordering in the hyperwords (the lexicographical order on the hyperletters). Now, given monotone hyperwords $W, V$, it can be shown that

$$
W=\left[w_{1}\right]_{c} \ldots\left[w_{m}\right]_{c}>V=\left[v_{1}\right]_{c} \ldots\left[v_{t}\right]_{c}
$$

where $w_{1} \geq \cdots \geq w_{r}, \quad v_{1} \geq \cdots \geq v_{s}$, if and only if

$$
w=w_{1} \ldots w_{m}>v=v_{1} \ldots v_{t} .
$$

Furthermore, the principal word of the polynomial $W$, when decomposed as sum of monomials, is $w$ with coefficient 1 .

Theorem 1.8 [Rosso 1999]. Let $m, n \in L$, with $m<n$. Then the braided commutator $\left[[m]_{c},[n]_{c}\right]_{c}$ is a $\mathbb{Z}\left[q_{i j}\right]$-linear combination of monotone hyperwords $\left[l_{1}\right]_{c}, \ldots$, $\left[l_{r}\right]_{c}, l_{i} \in L$, such that

- the hyperletters of those hyperwords satisfy $n>l_{i} \geq m n$,
- $[\mathrm{mn}]_{c}$ appears in the expansion with a nonzero coefficient, and
- any hyperword appearing in this decomposition satisfies

$$
\operatorname{deg}\left(l_{1} \ldots l_{r}\right)=\operatorname{deg}(m n)
$$

A crucial result of Rosso describes the behavior of the coproduct of $T(V)$ in the basis of hyperwords.

Lemma 1.9 [Rosso 1999]. Let $u \in \mathbb{X}$, and $u=u_{1} \ldots u_{r} v^{m}, v, u_{i} \in L, v<u_{r} \leq$ $\cdots \leq u_{1}$ the Lyndon decomposition of $u$. Then

$$
\begin{aligned}
& \Delta\left([u]_{c}\right)=1 \otimes[u]_{c}+\sum_{i=0}^{m}\binom{m}{i}_{q_{v, v}}\left[u_{1}\right]_{c} \ldots\left[u_{r}\right]_{c}[v]_{c}^{i} \otimes[v]_{c}^{m-i} \\
&+\sum_{\substack{l_{1} \geq \cdots \geq l_{p}>v, l_{i} \in L \\
0 \leq j \leq m}} x_{l_{1}, \ldots, l_{p}}^{(j)} \otimes\left[l_{1}\right]_{c} \ldots\left[l_{p}\right]_{c}[v]_{c}^{j},
\end{aligned}
$$

where each $x_{l_{1}, \ldots, l_{p}}^{(j)}$ is $\mathbb{Z}^{\theta}$-homogeneous and

$$
\operatorname{deg}\left(x_{l_{1}, \ldots, l_{p}}^{(j)}\right)+\operatorname{deg}\left(l_{1} \ldots l_{p} v^{j}\right)=\operatorname{deg}(u) .
$$

As in [Ufer 2004], we consider another order in $\mathbb{X}$; it is implicit in [Kharchenko 1999].

Definition 1.10. Let $u, v \in \mathbb{X}$. We say that $u \succ v$ if and only if either $\ell(u)<\ell(v)$, or else $\ell(u)=\ell(v)$ and $u>v$ (lexicographical order). This $\succ$ is a total order, called the deg-lex order.

Note that the empty word 1 is the maximal element for $\succ$. Also, this order is invariant by right and left multiplication.

Let now $I$ be a proper ideal of $T(V)$, and set $R=T(V) / I$. Let $\pi: T(V) \rightarrow R$ be the canonical projection. Consider the subset of $\mathbb{X}$ given by

$$
G_{I}:=\left\{u \in \mathbb{X}: u \notin \mathrm{k} \mathbb{X}_{>u}+I\right\} .
$$

(a) If $u \in G_{I}$ and $u=v w$, then $v, w \in G_{I}$.
(b) Any word $u \in G_{I}$ factorizes uniquely as a nonincreasing product of Lyndon words in $G_{I}$.

Proposition 1.11 ([Kharchenko 1999]; see also [Rosso 1999]). The set $\pi\left(G_{I}\right)$ is a basis of $R$.

In what follows, $I$ is a Hopf ideal. We seek to find a PBW basis by hyperwords of the quotient $R$ of $T(V)$. For this, we look at the set

$$
\begin{equation*}
S_{I}:=G_{I} \cap L . \tag{1-11}
\end{equation*}
$$

We then define the function $h_{I}: S_{I} \rightarrow\{2,3, \ldots\} \cup\{\infty\}$ by

$$
\begin{equation*}
h_{I}(u):=\min \left\{t \in \mathbb{N}: u^{t} \in \mathrm{k} \mathbb{X}_{\succ u^{t}}+I\right\} . \tag{1-12}
\end{equation*}
$$

The next result plays a fundamental role in this paper.

Theorem 1.12 [Kharchenko 1999]. Keep the notation above. Then

$$
B_{I}^{\prime}:=B\left(\{1+I\},\left[S_{I}\right]_{c}+I,<, h_{I}\right)
$$

is a PBW basis of $H=T(V) / I$.
The next three results are consequences of Theorem 1.12; see [Kharchenko 1999] for their proofs.

Corollary 1.13. A word $u$ belongs to $G_{I}$ if and only if the corresponding hyperletter $[u]_{c}$ is not a linear combination, modulo $I$, of hyperwords $[w]_{c}, w \succ u$, where all the hyperwords have their hyperletters in $S_{I}$.

Proposition 1.14. In the conditions of the Theorem 1.12, if $v \in S_{I}$ is such that $h_{I}(v)<\infty$, then $q_{v, v}$ is a root of unity. In this case, if $t$ is the order of $q_{v, v}$, then $h_{I}(v)=t$.

Corollary 1.15. If $h_{I}(v):=h<\infty$, then $[v]^{h}$ is a linear combination of hyperwords $[w]_{c}, w \succ v^{h}$.

## 2. Transformations of braided graded Hopf algebras

In Section 2C, we shall introduce a transformation over certain graded braided Hopf algebras, generalizing [Heckenberger 2006b, Proposition 1]. It is an instrumental step in the proof of Theorem 5.25, one of the main results of this article.

2A. Preliminaries on braided graded Hopf algebras. Let $H$ be the group algebra of an abelian group $\Gamma$. Let $V \in{ }_{H}^{H}$ y $\mathscr{D}$ with a basis $X=\left\{x_{1}, \ldots, x_{\theta}\right\}$ such that $x_{i} \in V_{g_{i}}^{\chi_{i}}, 1 \leq i \leq \theta$. Let $q_{i j}=\chi_{j}\left(g_{i}\right)$, so that $c\left(x_{i} \otimes x_{j}\right)=q_{i j} x_{j} \otimes x_{i}, 1 \leq i, j \leq \theta$.

We fix an ideal $I$ in the class $\mathfrak{S}$; we assume that $I$ is $\mathbb{Z}^{\theta}$-homogeneous. Let $\mathfrak{B}:=T(V) / I$ : this is a braided graded Hopf algebra, $\mathfrak{B}^{0}=\mathrm{k} 1$ and $\mathfrak{B}^{1}=V$. By definition of $I(V)$, there exists a canonical epimorphism of braided graded Hopf algebras $\pi: \mathfrak{B} \rightarrow \mathfrak{B}(V)$. Let $\sigma_{i}: \mathfrak{B} \rightarrow \mathfrak{B}$ be the algebra automorphism given by the action of $g_{i}$.

For the proof of the next result, see [Andruskiewitsch and Schneider 2002b, 2.8], for example.

Proposition 2.1. (1) For each $1 \leq i \leq \theta$, there exists a uniquely determined (id, $\sigma_{i}$ )-derivation $D_{i}: \mathfrak{B} \rightarrow \mathfrak{B}$ with $D_{i}\left(x_{j}\right)=\delta_{i, j}$ for all $j$.
(2) $I=I(V)$ if and only if $\bigcap_{i=1}^{\theta} \operatorname{ker} D_{i}=\mathrm{k} 1$.

These operators are defined for each $x \in \mathfrak{B}^{k}, k \geq 1$ by the formula

$$
\Delta_{n-1,1}(x)=\sum_{i=1}^{\theta} D_{i}(x) \otimes x_{i}
$$

Analogously, we can define operators $F_{i}: \mathfrak{B} \rightarrow \mathfrak{B}$ by $F_{i}(1)=0$ and

$$
\Delta_{1, n-1}(x)=\sum_{i=1}^{\theta} x_{i} \otimes F_{i}(x) \quad \text { for all } x \in \bigoplus_{k>0} \mathfrak{B}^{k}
$$

Let $\chi$ be as in Section 1B. Consider the action $\triangleright$ of $k \mathbb{Z}^{\theta}$ on $\mathfrak{B}$ given by

$$
\begin{equation*}
\mathbf{e}_{i} \triangleright b=\chi\left(\mathbf{u}, \mathbf{e}_{i}\right) b, \quad b \text { homogeneous of degree } \mathbf{u} \in \mathbb{Z}^{\theta} . \tag{2-1}
\end{equation*}
$$

Such operators $F_{i}$ satisfy $F_{i}\left(x_{j}\right)=\delta_{i, j}$ for all $j$, and

$$
F_{i}\left(b_{1} b_{2}\right)=F_{i}\left(b_{1}\right) b_{2}+\left(\mathbf{e}_{i} \triangleright b_{1}\right) F_{i}\left(b_{2}\right), \quad b_{1}, b_{2} \in \mathfrak{B} .
$$

Let $z_{r}^{(i j)}:=\left(\operatorname{ad}_{c} x_{i}\right)^{r}\left(x_{j}\right), i, j \in\{1, \ldots, \theta\}, i \neq j$ and $r \in \mathbb{N}_{0}$.
Remark 2.2. The operators $D_{i}, F_{i}$ satisfy

$$
\begin{align*}
& D_{i}\left(x_{i}^{n}\right)=(n)_{q_{i i}} x_{i}^{n-1},  \tag{2-2}\\
& D_{i}\left(\left(\operatorname{ad}_{c} x_{i}\right)^{r}\left(x_{j_{1}} \ldots x_{j_{s}}\right)\right)=0 \text { for } r, s \geq 0, j_{k} \neq i,  \tag{2-3}\\
& D_{j}\left(z_{r}^{(i j)}\right)=\prod_{k=0}^{r-1}\left(1-q_{i i}^{k} q_{i j} q_{j i}\right) x_{i}^{r} \text { for } r \geq 0,  \tag{2-4}\\
& F_{i}\left(z_{m}^{(i j)}\right)=(m)_{q_{i i}}\left(1-q_{i i}^{m-1} q_{i j} q_{j i}\right) z_{m-1}^{(i j)},  \tag{2-5}\\
& F_{j}\left(z_{m}^{(i j)}\right)=0, m \geq 1 . \tag{2-6}
\end{align*}
$$

The proof of the first three identities is as in [Andruskiewitsch and Schneider 2004, Lemma 3.7]; the proof of the last two is by induction on $m$.

For each pair $1 \leq i, j \leq \theta, i \neq j$, we define

$$
\begin{align*}
M_{i, j}(\mathfrak{B}) & :=\left\{\left(\operatorname{ad}_{c} x_{i}\right)^{m}\left(x_{j}\right): m \in \mathbb{N}\right\}  \tag{2-7}\\
m_{i j} & :=\min \left\{m \in \mathbb{N}_{0}:(m+1)_{q_{i i}}\left(1-q_{i i}^{m} q_{i j} q_{j i}\right)=0\right\} \tag{2-8}
\end{align*}
$$

Then either $q_{i i}^{m_{i j}} q_{i j} q_{j i}=1$, or $q_{i i}^{m_{i j}+1}=1$, if $q_{i i}^{m} q_{i j} q_{j i} \neq 1$ for all $m=0,1, \ldots, m_{i j}$, or such $m_{i j}$ does not exist, in which case we consider $m_{i j}=\infty$.

If $\mathfrak{B}=\mathfrak{B}(V)$, we write simply $M_{i, j}=M_{i, j}(\mathfrak{B}(V))$. Note that $\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}+1} x_{j}=0$ and $\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}} x_{j} \neq 0$, by Lemma 1.5, so

$$
\left|M_{i, j}\right|=m_{i j}+1
$$

By Theorem 1.12, the braided graded Hopf algebra $\mathfrak{B}$ has a PBW basis consisting of homogeneous elements (with respect to the $\mathbb{Z}^{\theta}$-grading). As in [Heckenberger 2006b], we can even assume that
$\circledast$ The height of a PBW generator $[u], \operatorname{deg}(u)=d$, is finite if and only if $2 \leq$ $\operatorname{ord}\left(q_{u, u}\right)<\infty$, and in such case, $h_{I(V)}(u)=\operatorname{ord}\left(q_{u, u}\right)$.

This is possible because if the height of $[u], \operatorname{deg}(u)=d$, is finite, then $2 \leq$ $\operatorname{ord}\left(q_{u, u}\right)=m<\infty$, by Proposition 1.14. And if $2 \leq \operatorname{ord}\left(q_{u, u}\right)=m<\infty$, but $h_{I(V)}(u)$ is infinite, we can add $[u]^{m}$ to the PBW basis: in this case, $h_{I(V)}(u)=$ $\operatorname{ord}\left(q_{u, u}\right)$, and $q_{u^{m}, u^{m}}=q_{u, u}^{m^{2}}=1$.

Let $\Delta^{+}(\mathfrak{B}) \subseteq \mathbb{N}^{n}$ be the set of degrees of the generators of the PBW basis, counted with their multiplicities and let also $\Delta(\mathfrak{B})=\Delta^{+}(\mathfrak{B}) \cup\left(-\Delta^{+}(\mathfrak{B})\right)$ : $\Delta^{+}(\mathfrak{B})$ is independent of the choice of the PBW basis with the property $\circledast$ (see [Andruskiewitsch and Angiono 2008, Lemma 2.18] for a proof of this statement).

In what follows, we write

$$
q_{\alpha}:=\chi(\alpha, \alpha), \quad N_{\alpha}:=\operatorname{ord} q_{\alpha}, \quad \alpha \in \Delta^{+}(\mathfrak{B}) .
$$

2B. Auxiliary results. Let $I$ be $\mathbb{Z}^{\theta}$-homogeneous ideal in $\mathfrak{S}$ and $\mathfrak{B}=T(V) / I$ as in Section 2A. We shall use repeatedly the following fact.

In what follows, we use the convention ord $1=1$.
Remark 2.3. If $x_{i}^{N}=0$ in $\mathfrak{B}$ with $N$ minimal (this is called the order of nilpotency of $x_{i}$ ), then $q_{i i}$ is a root of 1 of order $N$. Hence $\left(\operatorname{ad}_{c} x_{i}\right)^{N} x_{j}=0$.

The following result extends (18) in the proof of [Heckenberger 2006b, Proposition 1].
Lemma 2.4. For $i \in\{1, \ldots, \theta\}$, let $\mathscr{K}_{i}$ be the subalgebra generated by $\bigcup_{j \neq i} M_{i, j}(\mathfrak{B})$ and denote by $n_{i}$ the order of $q_{i i}$. Then there are isomorphisms of graded vector spaces

- $\operatorname{ker}\left(D_{i}\right) \cong \mathscr{K}_{i} \otimes \mathrm{k}\left[x_{i}^{n_{i}}\right]$, if $1<\operatorname{ord} q_{i i}<\infty$ but $x_{i}$ is not nilpotent, or
- $\operatorname{ker}\left(D_{i}\right) \cong \mathscr{K}_{i}$, if ord $q_{i i}$ is the order of nilpotency of $x_{i}$ or $q_{i i}=1$.

Moreover,

$$
\begin{equation*}
\mathfrak{B} \cong \mathscr{K}_{i} \otimes \mathrm{k}\left[x_{i}\right] \tag{2-9}
\end{equation*}
$$

Proof. We assume for simplicity $i=1$ and consider the PBW basis obtained in the Theorem 1.12. Now $x_{1} \in S_{I}$, and it is the least element of $S_{I}$, so each element of $B_{I}^{\prime}$ is of the form $\left[u_{1}\right]^{s_{1}} \ldots\left[u_{k}\right]^{s_{k}} x_{1}^{s}$, with $u_{k}<\cdots<u_{1}, u_{i} \in S_{I} \backslash\left\{x_{1}\right\}, 0<s_{i}<$ $h_{I}\left(u_{i}\right), 0 \leq s<h_{I}\left(x_{1}\right)$. Call $S^{\prime}=S_{I} \backslash\left\{x_{1}\right\}$, and

$$
B_{2}:=B\left(1+I,\left[S^{\prime}\right]_{c}+I,<,\left.h_{I}\right|_{S^{\prime}}\right),
$$

that is, the PBW set generated by $\left[S^{\prime}\right]_{c}+I$, whose height is the restriction of the height of the PBW basis corresponding to $S^{\prime}$. We have

$$
\mathfrak{B} \cong \mathrm{k} B_{2} \otimes \mathrm{k}\left[x_{1}\right]
$$

By (2-3), any $\left(\operatorname{ad}_{c} x_{1}\right)^{r}\left(x_{j}\right) \in \operatorname{ker}\left(D_{1}\right)$; as $D_{1}$ is a skew-derivation, we have $\mathscr{K}_{1} \subseteq \operatorname{ker}\left(D_{1}\right)$.

Also, $\mathrm{ad}_{c} x_{1}$ is a ( $\sigma_{1}, \mathrm{id}$ )-derivation of $\mathfrak{B}$. This derivation restricts to an endomorphism of the algebra $\mathscr{K}_{1}$, because if we apply $\mathrm{ad}_{c} x_{1}$ to the generators of $\mathscr{K}_{1}$, we obtain another generators (or 0).

We shall prove by induction on the length of $u$ that $[u]_{c} \in \mathscr{K}_{1}$ for each $u \in L \backslash\left\{x_{1}\right\}$. If $u=x_{j}, j>1$, then $[u]_{c}=x_{j} \in \mathscr{K}_{1}$. Now let $u \in L \backslash\left\{x_{1}\right\}$ be of length greater than 1 , and $(v, w)$ its Lyndon decomposition. Then:

- If $v \neq x_{1}$, then $[v]_{c},[w]_{c} \in \mathscr{K}_{1}$ by induction hypothesis, so

$$
[u]_{c}=[v]_{c}[w]_{c}-\chi(\operatorname{deg} v, \operatorname{deg} w)[w]_{c}[v]_{c} \in \mathscr{K}_{1},
$$

because $\mathscr{K}_{1}$ is a subalgebra.

- If $v=x_{1}$, then $[u]_{c}=\operatorname{ad}_{c} x_{1}\left([w]_{c}\right) \subset \operatorname{ad}_{c} x_{1}\left(\mathscr{K}_{1}\right) \subseteq \mathscr{K}_{1}$, because by induction hypothesis $[w]_{c} \in \mathscr{K}_{1}$.

Then we prove that $[L]_{c} \backslash\left\{x_{1}\right\} \subseteq \mathscr{K}_{1}$, and $B_{2}$ is generated by $[L]_{c} \backslash\left\{x_{1}\right\}$; that is, $\mathrm{k} B_{2} \subseteq \mathscr{K}_{1}$, and $D_{1}\left(B_{2}\right)=0$.

If $u \in \operatorname{ker}\left(D_{1}\right)$, we can write $[u]_{c}=\sum_{w \in B_{t}^{\prime}} \alpha_{w}[w]_{c}$. If $w$ does not end with $x_{1}$, then $w \in B_{2}$, and $D_{1}\left([w]_{c}\right)=0$. But if $w=u_{w} x_{1}^{t_{w}},\left[u_{w}\right]_{c} \in B_{2}, 0<t_{w}<h_{I}\left(x_{1}\right)$, we have

$$
D_{1}\left([w]_{c}\right)=\left(t_{w}\right)_{q_{11}^{-1}}\left[u_{w}\right]_{c} x_{1}^{t_{w}-1},
$$

where $\left(t_{w}\right)_{q_{11}^{-1}} \neq 0$ if $n_{i}$ does not divide $t_{w}$. Then

$$
0=D_{1}\left([u]_{c}\right)=\sum_{w \in B_{I}^{\prime} / t_{w}>0} \alpha_{w}\left(t_{w}\right)_{q_{11}^{-1}}\left[u_{w}\right]_{c} x_{1}^{t_{w}-1}
$$

But $\left[u_{w}\right]_{c} x_{1}^{t_{w}-1} \in B_{2}$, and $B_{2}$ is a basis, so $\alpha_{w}=0$ for each $w$ such that $n_{i}$ does not divide $t_{w}$. Then $\operatorname{ker}\left(D_{1}\right)=\mathscr{K}_{1} \mathrm{k}\left[x_{i}^{n_{i}}\right]$, so $\operatorname{ker}\left(D_{1}\right) \simeq \mathscr{K}_{1} \otimes \mathrm{k}\left[x_{i}^{n_{i}}\right]$ as k -vector spaces. This fact and the first part conclude the proof.

2C. Transformations of certain braided graded Hopf algebras. Let $I$ be $\mathbb{Z}^{\theta}$ homogeneous ideal in $\mathfrak{S}$ and $\mathfrak{B}=T(V) / I$ as in the previous subsections. We fix $i \in\{1, \ldots, \theta\}$.

Remark 2.5. ord $q_{i i}=\min \left\{k \in \mathbb{N}: F_{i}^{k}=0\right\}$, if $q_{i i} \neq 1$.
Proof. If $k \in \mathbb{N}$, then $F_{i}\left(x_{i}^{k}\right)=(k)_{q_{i i}} x_{i}^{k-1}$, and for all $k \in \mathbb{N}$,

$$
F_{i}^{k}\left(x_{i}^{k}\right)=(k)_{q_{i i}^{-1}}!
$$

That is, if $F_{i}^{k}=0$, then $(k)_{q_{i i}^{-1}}!=0$. Hence ord $q_{i i} \leq \min \left\{k \in \mathbb{N}: F_{i}^{k}=0\right\}$. Reciprocally, if $q_{i i}$ is a root of unity of order $k$, then $F_{i}^{k}\left(x_{i}^{t}\right)=0$ for all $t \geq k$ by the previous claim, and $F_{i}^{k}\left(x_{i}^{t}\right)=0$ for all $t<k$ by degree arguments. Since $F_{i}\left(x_{j}\right)=0$ for $j \neq i, F_{i}^{k}=0$.

We now extend some considerations in [Heckenberger 2006b, p. 180]. We consider the Hopf algebra defined by
$H_{i}:=\left\{\begin{array}{lc}\mathrm{k}\left\langle y, e_{i}, e_{i}^{-1} \mid e_{i} y-q_{i i}^{-1} y e_{i}, y^{N_{i}}\right\rangle & \text { where } N_{i} \text { is the order of nilpotency } \\ \text { of } x_{i} \text { in } \mathfrak{B}, \text { if } x_{i} \text { is nilpotent, } \\ \mathrm{k}\left\langle y, e_{i}, e_{i}^{-1} \mid e_{i} y-q_{i i}^{-1} y e_{i}\right\rangle & \text { if } x_{i} \text { is not nilpotent, }\end{array}\right.$
together with $\Delta\left(e_{i}\right)=e_{i} \otimes e_{i}, \Delta(y)=e_{i} \otimes y+y \otimes 1$.
Notice that $\Delta$ is well-defined by Remark 2.3. We also consider the action $\triangleright$ of $H_{i}$ on $\mathfrak{B}$ given by

$$
e_{i} \triangleright b=\chi\left(\mathbf{u}, \mathbf{e}_{i}\right) b, \quad y \triangleright b=F_{i}(b),
$$

if $b$ is homogeneous of degree $\mathbf{u} \in \mathbb{N}^{\theta}$, extending the previous one defined in (2-1). The action is well-defined by Remark 2.3 and because

$$
\left(e_{i} y\right) \triangleright b=e_{i} \triangleright\left(F_{i}(b)\right)=q_{i i}^{-1} F_{i}\left(e_{i} \triangleright b\right)=\left(q_{i i}^{-1} y e_{i}\right) \triangleright b \quad \text { for } b \in \mathfrak{B} .
$$

It is easy to see that $\mathfrak{B}$ is an $H_{i}$-module algebra; hence we can form

$$
\mathscr{A}_{i}:=\mathfrak{B} \# H_{i} .
$$

Also, if we denote explicitly by $\cdot$ the multiplication in $\mathscr{A}_{i}$, we have

$$
\begin{equation*}
(1 \# y) \cdot(b \# 1)=\left(e_{i} \triangleright b \# 1\right) \cdot(1 \# y)+F_{i}(b) \# 1 \quad \text { for all } b \in \mathfrak{B} \tag{2-10}
\end{equation*}
$$

As in [Heckenberger 2006b], $\mathscr{A}_{i}$ is a left Yetter-Drinfeld module over $\mathrm{k} \Gamma$, where the action and the coaction are given by

$$
\begin{array}{rlrl}
g_{k} \cdot x_{j} \# 1 & =q_{k j} x_{j} \# 1, & g_{k} \cdot 1 \# y=q_{k i}^{-1} 1 \# y, & g_{k} \cdot 1 \# e_{i}=1 \# e_{i}, \\
\delta\left(x_{j} \# 1\right) & =g_{j} \otimes x_{j} \# 1, & \delta(1 \# y)=g_{i}^{-1} \otimes 1 \# y, & \\
\delta\left(1 \# e_{i}\right)=1 \otimes 1 \# e_{i},
\end{array}
$$

for each pair $k, j \in\{1, \ldots, \theta\}$. Also, $\mathscr{A}_{i}$ is a $\mathrm{k} \Gamma$-module algebra.
We now prove a generalization of [Heckenberger 2006b, Proposition 1] in the more general context of our braided Hopf algebras $\mathfrak{B}$. Although the general strategy of the proof is similar as in loc. cit., many points need slightly different argumentations here.

Theorem 2.6. Keep the notation above. Assume that $M_{i, j}(\mathfrak{B})$ is finite and

$$
\begin{equation*}
\left|M_{i, j}(\mathfrak{B})\right|=m_{i j}+1, \quad j \in\{1, \ldots, \theta\}, j \neq i \tag{2-11}
\end{equation*}
$$

(1) Let $V_{i}$ be the vector subspace of $\mathscr{A}_{i}$ generated by

$$
\left\{\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}}\left(x_{j}\right) \# 1: j \neq i\right\} \cup\{1 \# y\}
$$

The subalgebra $s_{i}(\mathfrak{B})$ of $\mathscr{A}_{i}$ generated by $V_{i}$ is a graded algebra such that $s_{i}(\mathfrak{B})^{1} \cong V_{i}$. There exist skew derivations $Y_{i}: s_{i}(\mathfrak{B}) \rightarrow s_{i}(\mathfrak{B})$ such that, for all $b_{1}, b_{2} \in s_{i}(\mathfrak{B})$, and $l, j \in\{1, \ldots, \theta\}, j \neq i$,

$$
\begin{align*}
& Y_{j}\left(b_{1} b_{2}\right)=b_{1} Y_{j}\left(b_{2}\right)+Y_{j}\left(b_{2}\right)\left(g_{i}^{-m_{i j}} g_{j}^{-1} \cdot b_{2}\right),  \tag{2-12}\\
& Y_{i}\left(b_{1} b_{2}\right)=b_{1} Y_{i}\left(b_{2}\right)+Y_{i}\left(b_{1}\right)\left(g_{i}^{-1} \cdot b_{1}\right),  \tag{2-13}\\
& Y_{l}\left(\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}}\left(x_{j}\right) \# 1\right)=\delta_{l j}, \quad Y_{l}(1 \# y)=\delta_{l i} . \tag{2-14}
\end{align*}
$$

(2) Set $N_{i}:=\left\{n \in \mathbb{N}: n \mathbf{e}_{i} \in \Delta(\mathfrak{B})\right\}$ (by the previous remarks, $N_{i}=\{1\}$ or $N_{i}=$ $\left.\left\{1, h_{i}\right\}\right)$. The Hilbert series of $s_{i}(\mathfrak{B})$ satisfies

$$
\begin{equation*}
\mathscr{H}_{s_{i}(\mathfrak{B})}=\left(\prod_{\alpha \in \Delta^{+}(\mathfrak{B}) \backslash N_{i} \mathbf{e}_{i}} \mathfrak{q}_{h_{\alpha}}\left(X^{s_{i}(\alpha)}\right)\right)\left(\prod_{s \in N_{i}} \mathfrak{q}_{h_{s \mathfrak{e}_{i}}}\left(x_{i}^{s}\right)\right) . \tag{2-15}
\end{equation*}
$$

Therefore, if $s_{i}(\mathfrak{B})$ is a graded braided Hopf algebra,

$$
\Delta^{+}\left(s_{i}(\mathfrak{B})\right)=\left\{s_{i}\left(\Delta^{+}(\mathfrak{B})\right) \backslash-N_{i} \mathbf{e}_{i}\right\} \cup N_{i} \mathbf{e}_{i} .
$$

(3) If $\mathfrak{B}=\mathfrak{B}(V)$, the algebra $s_{i}(\mathfrak{B})$ is isomorphic to the Nichols algebra $\mathfrak{B}\left(V_{i}\right)$.

Proof. (i) Note that $V_{i}$ is a Yetter-Drinfeld submodule over $\mathrm{k} \Gamma$ of $\mathscr{A}_{i}$. Now, $\mathscr{A}_{i} \cong \mathfrak{B} \otimes H_{i}$ as graded vector spaces. Let $\mathscr{K}_{i}$ be the subalgebra generated by $\bigcup_{j \neq i} M_{i, j}(\mathfrak{B})$, as in Lemma 2.4. Then $s_{i}(\mathfrak{B}) \subseteq \mathscr{K}_{i} \otimes \mathrm{k}[y]$, since $F_{i}$ is a skewderivation and $F_{i}\left(z_{k}^{(i j)}\right)=(k)_{q_{i i}}\left(1-q_{i i}^{k-1} q_{i j} q_{j i}\right) z_{k-1}^{(i j)}$, by (2-5). From (2-10),

$$
(1 \# y) \cdot\left(z_{m_{i j}}^{(i j)} \# 1\right)=\left(z_{m_{i j}}^{(i j)} \# 1\right) \cdot(1 \# y)+F_{i}\left(z_{m_{i j}}^{(i j)}\right) \# 1
$$

Also, since $m_{i j}+1=\left|M_{i, j}(\mathfrak{B})\right|$, we have $\left(m_{i j}\right)_{q_{i i}}\left(1-q_{i i}^{m_{i j}-1} q_{i j} q_{j i}\right) \neq 0$, so $z_{m_{i j}-1}^{(i j)} \# 1$ lies in $s_{i}(\mathfrak{B})$, and by induction each $z_{k}^{(i j)} \# 1$, for $k=0, \ldots, m_{i j}-1$, is an element of $s_{i}(\mathfrak{B})$. Then $\mathscr{K}_{i} \otimes \mathrm{k}[y] \subseteq s_{i}(\mathfrak{B})$, and therefore

$$
\begin{equation*}
s_{i}(\mathfrak{B})=\mathscr{K}_{i} \otimes \mathrm{k}[y] . \tag{2-16}
\end{equation*}
$$

Thus, $s_{i}(\mathfrak{B})$ is a graded algebra in ${ }_{\mathrm{k} \Gamma}^{\mathrm{k}} \mathscr{y} \mathscr{D}$ with $s_{i}(\mathfrak{B})^{1}=V_{i}$. We have to find the skew derivations $Y_{l} \in \operatorname{End}\left(s_{i}(\mathfrak{B})\right), l=1, \ldots, \theta$. Set $Y_{i}:=\left.g_{i}^{-1} \circ \operatorname{ad}\left(x_{i} \# 1\right)\right|_{s_{i}(\mathfrak{B})}$. Then, for each $b \in \mathscr{K}_{i}$ and each $j \neq i$,

$$
\begin{aligned}
& \operatorname{ad}\left(x_{i} \# 1\right)(b \# 1)=\left(\operatorname{ad}_{c} x_{i}\right)(b) \# 1, \\
& \operatorname{ad}\left(x_{i} \# 1\right)\left(\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}}\left(x_{j}\right) \# 1\right)=\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}+1}\left(x_{j}\right) \# 1=0 .
\end{aligned}
$$

Also,

$$
\begin{aligned}
Y_{i}(1 \# y) & =g_{i}^{-1} \cdot\left(\left(x_{i} \# 1\right) \cdot(1 \# y)-\left(g_{i} \cdot(1 \# y)\right) \cdot\left(x_{i} \# 1\right)\right) \\
& =g_{i}^{-1} \cdot\left(x_{i} \# y+1-q_{i i}\left(q_{i i}^{-1} x_{i} \# y\right)\right)=1 .
\end{aligned}
$$

Thus $Y_{i} \in \operatorname{End}\left(s_{i}(\mathfrak{B})\right)$ satisfies (2-14).

Therefore, $\operatorname{ad}\left(x_{i} \# 1\right)\left(b_{1} b_{2}\right)=\operatorname{ad}\left(x_{i} \# 1\right)\left(b_{1}\right) b_{2}+\left(g_{i} \cdot b_{1}\right) \operatorname{ad}\left(x_{i} \# 1\right)\left(b_{2}\right)$, for each pair $b_{1}, b_{2} \in s_{i}(\mathfrak{B})$, so we conclude that $\operatorname{ad}\left(x_{i} \# 1\right)\left(s_{i}(\mathfrak{B})\right) \subseteq s_{i}(\mathfrak{B})$, and $Y_{i} \in$ $\operatorname{End}\left(s_{i}(\mathfrak{B})\right)$ satisfies (2-13).

Before proving that $Y_{i}$ satisfies (2-12), we need to establish some preliminary facts. Let us fix $j \neq i$, and let $z_{k}^{(i j)}=\left(\operatorname{ad}_{c} x_{i}\right)^{k}\left(x_{j}\right)$ as before. We define inductively

$$
\hat{z}_{0}^{(i j)}:=D_{j}, \quad \hat{z}_{k+1}^{(i j)}:=D_{i} \hat{z}_{k}^{(i j)}-q_{i i}^{k} q_{i j} \hat{z}_{k+1}^{(i j)} D_{i} \in \operatorname{End}(\mathfrak{B}) .
$$

We calculate

$$
\begin{aligned}
\lambda_{i j} & :=\hat{z}_{m_{i j}}^{(i j)}\left(z_{m_{i j}}^{(i j)}\right)=\sum_{s=0}^{m_{i j}} a_{s} D_{i}^{m_{i j}-s} D_{j} D_{i}^{s}\left(z_{m_{i j}}^{(i j)}\right) \\
& =\left(D_{i}\right)^{m_{i j}}\left(D_{j}\right)\left(z_{m_{i j}}^{(i j)}\right)=\alpha_{m_{i j}}\left(m_{i j}\right)_{q_{i i}}!\in \mathrm{k}^{\times}
\end{aligned}
$$

where $a_{s}=(-1)^{k}\binom{m}{k}_{q_{i i}} q_{i i}^{k(k-1) / 2} q_{i j}^{k}$.
Note that $\left(D_{i}\right)^{m_{i j}+1} D_{j}(b)=0$ for all $b \in M_{i, k}, k \neq i, j$, and that

$$
\left(D_{i}\right)^{m_{i j}+1} D_{j}\left(z_{r}^{(i j)}\right)=\left(D_{i}\right)^{m_{i j}+1}\left(q_{j i}^{-r} \alpha_{r} x_{i}^{r}\right)=0 \quad \text { for all } r \leq m_{i j}
$$

so $\left(D_{i}\right)^{m_{i j}+1} D_{j}\left(\mathscr{K}_{i}\right)=0$. This implies that $\hat{z}_{m_{i j}}^{(i j)}(b) \in \mathscr{K}_{i}$, for each $b \in \mathscr{K}_{i}$. Now define $Y_{j} \in \operatorname{End}\left(s_{i}(\mathfrak{B})\right)$ by

$$
Y_{j}\left(b \# y^{m}\right):=q_{i i}^{m m_{i j}} q_{j i}^{m} \lambda_{i j}^{-1} \hat{z}_{m_{i j}}^{(i j)}(b) \# y^{m} \quad \text { for } b \in \mathscr{K}_{i}, m \in \mathbb{N} .
$$

We have $Y_{j}(1 \# y)=0$, and moreover $Y_{j}\left(\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i l}}\left(x_{l}\right) \# 1\right)=0$ if $l \neq i, j$. By the choice of $\lambda_{i j}, Y_{j}\left(\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}}\left(x_{j}\right) \# 1\right)=1$.

Now, using that $D_{k}\left(g_{l} \cdot b\right)=q_{k l} g_{l} \cdot\left(D_{k}(b)\right)$ for each $b \in \mathfrak{B}$ and $k, l \in\{1, \ldots, \theta\}$, we prove inductively that for $b_{1}, b_{2} \in \mathscr{K}_{i}$,

$$
\hat{z}_{k}^{(i j)}\left(b_{1} b_{2}\right)=b_{1} \hat{z}_{k}^{(i j)}\left(b_{2}\right)+\hat{z}_{k}^{(i j)}\left(b_{1}\right)\left(g_{i}^{k} g_{j} \cdot b_{2}\right)
$$

Hence,

$$
\begin{aligned}
Y_{j}\left(b_{1} \# 1 \cdot b_{2} \# 1\right) & =Y_{j}\left(b_{1} b_{2} \# 1\right)=\lambda_{i j}^{-1} \hat{z}_{m_{i j}}\left(b_{1} b_{2}\right) \# 1 \\
& =b_{2} \# 1 \cdot Y_{j}\left(b_{2} \# 1\right)+Y_{j}\left(b_{1} \# 1\right) \cdot\left(g_{i}^{m_{i j}} g_{j} \cdot\left(b_{2} \# 1\right)\right)
\end{aligned}
$$

By induction on the degree we prove that $F_{i}$ commutes with $D_{i}, D_{j}$, so

$$
\hat{z}_{m_{i j}}^{(i j)}\left(F_{i}(b)\right)=F_{i}\left(\hat{z}_{m_{i j}}^{(i j)}(b)\right) \quad \text { for all } b \in \mathfrak{B} .
$$

Consider $b \in \mathscr{K}_{i} \subseteq \operatorname{ker}\left(D_{i}\right)$,

$$
\begin{aligned}
Y_{j}(b \# 1 \cdot 1 \# y) & =Y_{j}(b \# y)=q_{i i}^{m_{i j}} q_{j i} \hat{z}_{m_{i j}}^{(i j)}(b) \# y \\
& =b \# 1 \cdot Y_{j}(1 \# y)+Y_{j}(b \# 1) \cdot\left(g_{i}^{m_{i j}} g_{j} \cdot(1 \# y)\right),
\end{aligned}
$$

where we use that $Y_{j}(1 \# y)=0$. Since,

$$
b_{1} \# 1 \cdot b_{2} \# y^{t}=b_{1} \# 1 \cdot b_{2} \# 1 \cdot(1 \# y)^{t},
$$

(2-12) is valid for products of this form. To prove it in the general case, note that

$$
\left(b_{1} \# y^{t}\right) \cdot\left(b_{2} \# y^{s}\right)=\left(b_{1} \# 1\right) \cdot(1 \# y)^{t} \cdot\left(b_{2} \# y^{s}\right)
$$

At this point, we have to prove (2-12) for $b \in \mathscr{K}_{i} \operatorname{ker}\left(D_{i}\right), s \in \mathbb{N}$ :

$$
\begin{aligned}
& Y_{j}(1 \#\left.y \cdot b \# y^{s}\right) \\
& \quad=Y_{j}\left(F_{i}(b) \# y^{s}+\left(e_{i} \triangleright b \# y\right) \cdot 1 \# y\right) \\
& \quad=q_{i i}^{m_{i j}^{s}} q_{j i}^{s} \lambda_{i j}^{-1} \hat{z}_{m_{i j}}^{(i j)}\left(F_{i}(b)\right) \# y^{s}+q_{i i}^{m_{i j}(s+1)} q_{j i}^{s+1} \lambda_{i j}^{-1} \cdot \hat{z}_{m_{i j}}^{(i j)}\left(e_{i} \triangleright b\right) \# y^{s+1} \\
& \quad=F_{i}\left(q_{i i}^{m_{i j}(s+1)} q_{j i}^{s+1} \lambda_{i j}^{-1} \hat{z}_{m_{i j}}^{(i j)}(b)\right) \# y^{s}+q_{i i}^{m_{i j}} q_{j i}\left(e_{i} \triangleright\left(q_{i i}^{m_{i j}^{s}} q_{j i}^{s} \lambda_{i j}^{-1} \hat{z}_{m_{i j}}^{(i j)}(b)\right) \# y^{s}\right) \\
& \quad=(1 \# y) \cdot Y_{j}\left(b \# y^{s}\right) \\
& \quad=1 \# y \cdot Y_{j}\left(b \# y^{s}\right)+Y_{j}(1 \# y) \cdot\left(g_{i}^{m_{i j}} g_{j} \cdot b \# y^{s}\right),
\end{aligned}
$$

where we use that $\hat{z}_{m_{i j}}^{(i j)}\left(e_{i} \triangleright b\right)=q_{i i}^{m_{i j}} q_{j i} e_{i} \triangleright\left(\hat{z}_{m_{i j}}^{(i j)}(b)\right)$.
(ii) The algebra $H_{i}$ is $\mathbb{Z}^{\theta}$-graded, with

$$
\operatorname{deg} y=-\mathbf{e}_{i}, \quad \operatorname{deg} e_{i}^{ \pm 1}=0 .
$$

Since $\mathfrak{B}$ and $H_{i}$ are graded and (2-10) holds, the algebra $\mathscr{A}_{i}$ is $\mathbb{Z}^{\theta}$-graded.
Consider the abstract basis $\left\{u_{j}\right\}_{j \in\{1, \ldots, \theta\}}$ of $V_{i}$. With the grading $\operatorname{deg} u_{j}=\mathbf{e}_{j}$, the algebra $\mathfrak{B}\left(V_{i}\right)$ is $\mathbb{Z}^{\theta}$-graded. Consider also the algebra homomorphism $\Omega$ : $T\left(V_{i}\right) \rightarrow s_{i}(\mathfrak{B})$ given by

$$
\Omega\left(u_{j}\right):= \begin{cases}\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}}\left(x_{j}\right) & \text { if } j \neq i, \\ y & \text { if } j=i .\end{cases}
$$

By part (i) of the theorem, $\Omega$ is an epimorphism, so it induces an isomorphism between $s_{i}(\mathfrak{B})^{\prime}:=T\left(V_{i}\right) / \operatorname{ker} \Omega$ and $s_{i}(\mathfrak{B})$, which we also denote by $\Omega$. We have

$$
\begin{aligned}
& \operatorname{deg} \Omega\left(u_{j}\right)=\operatorname{deg}\left(\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}}\left(x_{j}\right)\right)=\mathbf{e}_{j}+m_{i j} \mathbf{e}_{i}=s_{i}\left(\operatorname{deg} \mathbf{u}_{j}\right) \text { if } j \neq i, \\
& \operatorname{deg} \Omega\left(u_{i}\right)=\operatorname{deg}(y)=-\mathbf{e}_{i}=s_{i}\left(\operatorname{deg} \mathbf{u}_{i}\right) .
\end{aligned}
$$

Since $\Omega$ is an algebra homomorphism, we have $\operatorname{deg}(\Omega(\mathbf{u}))=s_{i}(\operatorname{deg}(\mathbf{u}))$ for all $\mathbf{u} \in s_{i}(\mathfrak{B})^{\prime}$. Since $s_{i}^{2}=\mathrm{id}, s_{i}(\operatorname{deg}(\Omega(\mathbf{u})))=\operatorname{deg}(\mathbf{u})$ for all $\mathbf{u} \in s_{i}(\mathfrak{B})^{\prime}$, and $\mathfrak{H}_{s_{i}(\mathfrak{B})^{\prime}}=$ $s_{i}\left(\mathfrak{H}_{s_{i}(\mathfrak{B})}\right)$.

From this point on, the proof goes exactly as in [Andruskiewitsch and Angiono 2008, Theorem 3.2].
(iii) This is Proposition 1 in [Heckenberger 2006b].

By Theorem 2.6, the initial braided vector space with matrix $\left(q_{k j}\right)_{1 \leq k, j \leq \theta}$ is transformed into another braided vector space of diagonal type $V_{i}$, with matrix $\left(\tilde{q}_{k j}\right)_{1 \leq k, j \leq \theta}$, where $\tilde{q}_{j k}=q_{i i}^{m_{i j} m_{i k}} q_{i k}^{m_{i j}} q_{j i}^{m_{i k}} q_{j k}$ for $j, k \in\{1, \ldots, \theta\}$.

If $j \neq i$, then $\widetilde{m}_{i j}=\min \left\{m \in \mathbb{N}:(m+1)_{\tilde{q}_{i i}}\left(\tilde{q}_{i i}^{m} \tilde{q}_{i j} \tilde{q}_{j i}=0\right)\right\}=m_{i j}$.
For later use in Section 5, we recall a result from [Andruskiewitsch et al. 2008], adapted to diagonal braided vector spaces.

Lemma 2.7 [Andruskiewitsch et al. 2008, Lemma 2.8(ii)]. Let $V$ be a diagonal braided vector space and $I$ a $\mathbb{Z}^{\theta}$-homogeneous ideal of $T(V)$. Set $\mathfrak{B}:=T(V) / I$ and assume that for all $i \in\{1, \ldots, \theta\}$ there exist (id, $\sigma_{i}$ )-derivations $D_{i}: \mathfrak{B} \rightarrow \mathfrak{B}$ with $D_{i}\left(x_{j}\right)=\delta_{i, j}$ for all $j$. Then $I \subseteq I(V)$.

That is, the canonical surjective algebra morphisms from $T(V)$ onto $\mathfrak{B}$ and $\mathfrak{B}(V)$ induce a surjective algebra morphism $\mathfrak{B} \rightarrow \mathfrak{B}(V)$.

## 3. Standard braidings

Heckenberger [2006a] has classified diagonal braidings whose set of PBW generators is finite. Standard braidings form an special subclass, which includes properly braidings of Cartan type.

We first recall the definition of a standard braiding from [Andruskiewitsch and Angiono 2008], and the notion of a Weyl groupoid, introduced in [Heckenberger 2006b]. Then we present the classification of standard braidings, and compare them with [Heckenberger 2006a].

Like Heckenberger, we use the generalized Dynkin diagram associated to a braided vector space of diagonal type, with matrix $\left(q_{i j}\right)_{1 \leq i, j \leq \theta}$ : this is a graph with $\theta$ vertices, each labeled with the corresponding $q_{i i}$, and an edge between two vertices $i, j$ labeled with $q_{i j} q_{j i}$ if this scalar is different from 1 . So two braided vector spaces of diagonal type have the same generalized Dynkin diagram if and only if they are twist equivalent. We shall assume that the generalized Dynkin diagram is connected, by [Andruskiewitsch and Schneider 2000, Lemma 4.2].

Summarizing, the main result of this section says:
Theorem 3.1. Any standard braiding is twist equivalent with one or more of

- a braiding of Cartan type,
- a braiding of type $A_{\theta}$ listed in Proposition 3.9,
- a braiding of type $B_{\theta}$ listed in Proposition 3.10, or
- a braiding of type $G_{2}$ listed in Proposition 3.11.

The generalized Dynkin diagrams appearing in Propositions 3.9 and 3.10 correspond to rows 1, 2, 3, 4, 5, 6 in [Heckenberger 2006a, Table C]. The generalized Dynkin diagrams in Proposition 3.11 are (T8) in [Heckenberger 2008, Section 3]. However, our classification does not rely on Heckenberger's papers.

3A. The Weyl groupoid and standard braidings. Let $E=\left(\mathbf{e}_{1}, \ldots, \mathbf{e}_{\theta}\right)$ be the canonical basis of $\mathbb{Z}^{\theta}$. Consider an arbitrary matrix $\left(q_{i j}\right)_{1 \leq i, j \leq \theta} \in\left(\mathrm{k}^{\times}\right)^{\theta \times \theta}$, and fix once and for all the bilinear form $\chi: \mathbb{Z}^{\theta} \times \mathbb{Z}^{\theta} \rightarrow \mathrm{k}^{\times}$determined by

$$
\begin{equation*}
\chi\left(\mathbf{e}_{i}, \mathbf{e}_{j}\right)=q_{i j}, \quad 1 \leq i, j \leq \theta . \tag{3-1}
\end{equation*}
$$

If $F=\left(\mathbf{f}_{1}, \ldots, \mathbf{f}_{\theta}\right)$ is another ordered basis of $\mathbb{Z}^{\theta}$, then we set $\tilde{q}_{i j}=\chi\left(\mathbf{f}_{i}, \mathbf{f}_{j}\right)$, $1 \leq i, j \leq \theta$. We call $\left(\tilde{q}_{i j}\right)$ the braiding matrix with respect to the basis $F$. Fix $i \in\{1, \ldots, \theta\}$. If $1 \leq i, j \leq \theta$, we consider the set

$$
\widetilde{M}_{i j}:=\left\{m \in \mathbb{N}_{0}:(m+1)_{\tilde{q}_{i i}}\left(\tilde{q}_{i i}^{m} \tilde{q}_{i j} \tilde{q}_{j i}-1\right)=0\right\} .
$$

If this set is nonempty, its minimal element is denoted $\tilde{m}_{i j}$ (which of course depends on the basis $F$ ). Define also $\tilde{m}_{i i}=2$. Let $s_{i, F} \in \mathrm{GL}\left(\mathbb{Z}^{\theta}\right)$ be the pseudoreflection given by $s_{i, F}\left(\mathbf{f}_{j}\right):=\mathbf{f}_{j}+\tilde{m}_{i j} \mathbf{f}_{i}$, for $j \in\{1, \ldots, \theta\}$.

Let $G$ be a group acting on a set $X$. We define the transformation groupoid as $G \times X$ with the operation given by $(g, x)(h, y)=(g h, y)$ if $x=h(y)$, but undefined otherwise.

Definition 3.2. Consider the set $\mathfrak{X}$ of all ordered bases of $\mathbb{Z}^{\theta}$, and the canonical action of $\operatorname{GL}\left(\mathbb{Z}^{\theta}\right)$ over $\mathfrak{X}$. The Weyl groupoid $W(\chi)$ of the bilinear form $\chi$ is the smallest subgroupoid of the transformation groupoid $\operatorname{GL}\left(\mathbb{Z}^{\theta}\right) \times \mathfrak{X}$ that satisfies following properties:

- (id, $E) \in W(\chi)$,
- if $(\mathrm{id}, F) \in W(\chi)$ and $s_{i, F}$ is defined, then $\left(s_{i, F}, F\right) \in W(\chi)$.

Let $\mathfrak{P}(\chi)=\{F:(\mathrm{id}, F) \in W(\chi)\}$ be the set of points of the $\operatorname{groupoid} W(\chi)$. The set

$$
\begin{equation*}
\Delta(\chi)=\bigcup_{F \in \mathfrak{P}(\chi)} F \tag{3-2}
\end{equation*}
$$

is called the generalized root system ${ }^{1}$ associated to $\chi$.
We record for later use the following evident facts.
Remark 3.3. Take $i \in\{1, \ldots, \theta\}$ such that $s_{i, E}$ is defined. Set $F=s_{i, E}(E)$ and let $\left(\tilde{q}_{i j}\right)$ be the braiding matrix with respect to the basis $F$. Assume that

[^1]- $q_{i i}=-1$ (so $m_{i k}=0$ if $q_{i k} q_{k i}=1$ or $m_{i k}=1$, for each $k \neq i$ );
- there exists $j \neq i$ such that $q_{j j} q_{j i} q_{i j}=1$ (that is, $m_{i j}=m_{j i}=1$ ).

Then $\tilde{q}_{j j}=-1$.
Proof. Simply, $\tilde{q}_{j j}=q_{i i} q_{i j} q_{j i} q_{j j}=q_{i i}=-1$.
Remark 3.4. If the $m_{i j}$ satisfy $q_{i i}^{m_{i j}} q_{i j} q_{j i}=1$ for all $j \neq i$, the braiding of $V_{i}$ is twist equivalent with the corresponding to $V$.

Define $\alpha: W(\chi) \rightarrow \operatorname{GL}(\theta, \mathbb{Z})$ by $\alpha(s, F)=s$ if $(s, F) \in W(\chi)$, and denote by $W_{0}(\chi)$ the subgroup generated by the image of $\alpha$.
Definition 3.5. [Andruskiewitsch and Angiono 2008] We say that $\chi$ is standard if for any $F \in \mathfrak{P}(\chi)$, the integers $m_{r j}$ are defined, for all $1 \leq r, j \leq \theta$, and the integers $m_{r j}$ for the bases $s_{i, F}(F)$ coincide with those for $F$ for all $i, r, j$. Clearly it is enough to assume this for the canonical basis $E$.

We now assume that $\chi$ is standard. We set $C:=\left(a_{i j}\right) \in \mathbb{Z}^{\theta \times \theta}$, where $a_{i j}=-m_{i j}$; this is a generalized Cartan matrix.

Proposition 3.6 [Andruskiewitsch and Angiono 2008]. $W_{0}(\chi)=\left\langle s_{i, E}: 1 \leq i \leq \theta\right\rangle$. Furthermore $W_{0}(\chi)$ acts freely and transitively on $\mathfrak{P}(\chi)$.

Hence, $W_{0}(\chi)$ is a Coxeter group, and $W_{0}(\chi)$ and $\mathfrak{P}(\chi)$ have the same cardinality.

Lemma 3.7 [Andruskiewitsch and Angiono 2008]. The following are equivalent:
(1) The groupoid $W(\chi)$ is finite.
(2) The set $\mathfrak{P}(\chi)$ is finite.
(3) The generalized root system $\Delta(\chi)$ is finite.
(4) The group $W_{0}(\chi)$ is finite.
(5) The Cartan matrix $C$ is symmetrizable and of finite type.

We shall prove in Theorem 4.1, that if $\Delta(\chi)$ is finite, the matrix $C$ is symmetrizable, hence of finite type. Thus $\mathfrak{B}(V)$ is of finite dimension if and only if the Cartan matrix $C$ is of finite type.

3B. Classification of standard braidings. We now classify standard braidings such that the Cartan matrix is of finite type. We begin with types $C_{\theta}, D_{\theta}, E_{l}(l=6,7,8)$ and $F_{4}$ : these standard braidings are necessarily of Cartan type.
Proposition 3.8. Let $V$ be a braided vector space of standard type, $\operatorname{set} \theta=\operatorname{dim} V$, and let $C=\left(a_{i j}\right)_{i, j \in\{1, \ldots, \theta\}}$ be the corresponding Cartan matrix, of type $C_{\theta}, D_{\theta}$, $E_{l}(l=6,7,8)$ or $F_{4}$. Then $V$ is of Cartan type (associated to the corresponding matrix of finite type).

Proof. Let $V$ be standard of type $C_{\theta}, \theta \geq 3$.

$$
\begin{equation*}
\circ^{1}-\circ^{2}-\circ^{3} \ldots \quad o^{\theta-2}-\ldots \circ^{\theta-1} \Longleftarrow \circ^{\theta} \tag{3-3}
\end{equation*}
$$

Note that $q_{\theta-1, \theta-1} \neq-1$ by Remark 3.3 and the assumption $m_{\theta-1, \theta}=2$. Since $m_{\theta-1, \theta-2}=1, q_{\theta-1, \theta-1} q_{\theta-1, \theta-2} q_{\theta-2, \theta-1}=1$. Using Remark 3.3 when $i=\theta-$ $2, j=\theta-1$, since $\tilde{q}_{\theta-1, \theta-1} \neq-1$ when we transform by $s_{\theta-2}$ (since the new braided vector space is also standard), we have $q_{\theta-2, \theta-2} \neq-1$, so

$$
q_{\theta-2, \theta-2} q_{\theta-2, \theta-1} q_{\theta-1, \theta-2}=q_{\theta-2, \theta-2} q_{\theta-2, \theta-3} q_{\theta-3, \theta-2}=1,
$$

and $q_{\theta-1, \theta-1}=q_{\theta-2, \theta-2}$. Inductively,

$$
q_{k k} q_{k, k-1} q_{k-1, k}=q_{k k} q_{k, k+1} q_{k+1, k}=q_{11} q_{12} q_{21}=1, \quad k=2, \ldots, \theta-1
$$

and $q_{11}=q_{22}=\ldots=q_{\theta-1, \theta-1}$. So we look at $q_{\theta \theta}$ : since $m_{\theta, \theta-1}=1$, we have $q_{\theta \theta}=-1$ or $q_{\theta \theta} q_{\theta, \theta-1} q_{\theta-1, \theta}=1$. If $q_{\theta \theta}=-1$, transforming by $s_{\theta}$, we have

$$
\tilde{q}_{\theta-1, \theta-1}=-q^{-1}, \quad \tilde{q}_{\theta-1, \theta} \tilde{q}_{\theta, \theta-1}=q^{2}
$$

and $q^{2}=-1$ since $m_{\theta-1, \theta-2}=1$. Then

$$
q_{\theta \theta} q_{\theta, \theta-1} q_{\theta-1, \theta}=1, \quad q_{\theta \theta}=q^{2},
$$

and the braiding is of Cartan type in both cases.
Let $V$ be standard of type $D_{\theta}, \theta \geq 4$.
We prove the statement by induction on $\theta$. Let $V$ be standard of type $D_{4}$, and suppose that $q_{22}=-1$. Let $\left(\tilde{q}_{i j}\right)$ the braiding matrix with respect to $F=s_{2, E}(E)$. We calculate for each pair $j \neq k \in\{1,3,4\}$ :

$$
\tilde{q}_{j k} \tilde{q}_{k j}=\left((-1) q_{2 k} q_{j 2} q_{j k}\right)\left((-1) q_{2 j} q_{k 2} q_{k j}\right)=\left(q_{2 k} q_{k 2}\right)\left(q_{2 j} q_{j 2}\right),
$$

where we use that $q_{j k} q_{k j}=1$. Since also $\tilde{q}_{j k} \tilde{q}_{k j}=1$, we have $q_{2 k} q_{k 2}=\left(q_{2 j} q_{j 2}\right)^{-1}$ for $j \neq k$, so $q_{2 k} q_{k 2}=-1, k=1,3,4$, since $q_{2 k} q_{k 2} \neq 1$. In this case, the braiding is of Cartan type, with $q=-1$. Suppose then $q_{22} \neq-1$. From the fact that $m_{2 j}=1$, we have

$$
q_{22} q_{2 j} q_{j 2}=1, \quad j=1,3,4
$$

For each $j$, applying Remark 3.3 , we see that $q_{j j} \neq-1$ (since $\tilde{q}_{22} \neq-1$ ), so $q_{j j} q_{2 j} q_{j 2}=1$, for $j=1,3,4$, and the braiding is of Cartan type.

$$
\begin{equation*}
\circ^{1}-\circ^{2}-\circ^{3} \ldots \quad o^{\theta-2}-o^{\theta} \tag{3-4}
\end{equation*}
$$

We now suppose the statement valid for $\theta$. Let $V$ be a standard braided vector space of type $D_{\theta+1}$. The subspace generated by $x_{2}, \ldots, x_{\theta+1}$ is a standard braided vector space associated to the matrix $\left(q_{i j}\right)_{i, j=2, \ldots, \theta+1}$, of type $D_{\theta}$, so it is of Cartan type. To finish, apply Remark 3.3 with $i=1, j=2$, to conclude that $V$ is of Cartan type with $q=-1$, or, if $q_{22} \neq-1$, we have $q_{11} \neq-1$ and $q_{11} q_{12} q_{21}=1$, and in this case it is of Cartan type too (because also $q_{1 k} q_{k 1}=1$ when $k>2$ ).

Let $V$ be standard of type $E_{6}$. Note that $1,2,3,4,5$ determine a braided vector subspace, which is standard of type $D_{5}$, hence of Cartan type. To prove that $q_{66} q_{65} q_{56}=1$, we use Remark 3.3 as above.


If $V$ is standard of type $E_{7}$ or $E_{8}$, we proceed similarly by reduction to $E_{6}$ or $E_{7}$, respectively.


Let $V$ be standard of type $F_{4}$. Vertices 2, 3, 4 determine a braided subspace, which is standard of type $C_{3}$, so the $q_{i j}$ satisfy the corresponding relations. Let $\left(\tilde{q}_{i j}\right)$ the braiding matrix with respect to $F=s_{2, E}(E)$. Since $\tilde{q}_{13} \tilde{q}_{31}=1$ and $q_{22} q_{23} q_{32}=1$, we have $q_{22} q_{12} q_{21}=1$.

$$
\begin{equation*}
\circ^{1}-o^{2} \Longrightarrow o^{3}-o^{4} \tag{3-8}
\end{equation*}
$$

Now, if we suppose $q_{11}=-1$, applying Remark 3.3 we have $q_{22}=-1=q_{21} q_{12}$, and the corresponding vector space is of Cartan type $F_{4}$, associated to $q \in \mathbb{G}_{4}$. If $q_{11} \neq-1$, then $q_{11} q_{12} q_{21}=1$, and the space it again is of Cartan type.

To finish the classification of standard braidings, we describe the standard braidings that are not of Cartan type. They are associated to Cartan matrices of type $A_{\theta}, B_{\theta}$ or $G_{2}$.

We use a notation similar to the one in [Heckenberger 2006a] for a special kind of braiding of type $A_{\theta}$ (here we emphasize the positions where $q_{i i}=-1$, which we use to compute the dimension of the corresponding Nichols algebra); $\mathscr{C}\left(\theta, q ; i_{1}, \ldots, i_{j}\right)$ corresponds to the generalized Dynkin diagram

$$
\begin{equation*}
\circ^{1}-\circ^{2}-o^{3} \ldots \quad o^{\theta-1}-o^{\theta} \tag{3-9}
\end{equation*}
$$

where the following equations hold:

- $q=q_{\theta-1, \theta} q_{\theta, \theta-1} q_{\theta \theta}^{2}$,
- $\left(q_{\theta \theta}+1\right)\left(q_{\theta \theta} q_{\theta-1, \theta} q_{\theta, \theta-1}-1\right)=\left(q_{11}+1\right)\left(q_{11} q_{12} q_{21}-1\right)=0$;
- $-q_{i i}=q_{i-1, i} q_{i, i-1} q_{i+1, i} q_{i, i+1}=1$ if $i \in\left\{i_{1}, \ldots, i_{j}\right\}$.
- $q_{i i} q_{i-1, i} q_{i, i-1}=q_{i i} q_{i+1, i} q_{i, i+1}=1$, otherwise.

Then $q_{i i}=-1$ if and only if $q_{i-1, i} q_{i, i-1}=\left(q_{i+1, i} q_{i, i+1}\right)^{-1}$.
Proposition 3.9. Let $V$ be a braided vector space of diagonal type. Then $V$ is standard of type $A_{\theta}$ if and only if its generalized Dynkin diagram is of the form

$$
\begin{equation*}
\mathscr{C}\left(\theta, q ; i_{1}, \ldots, i_{j}\right) \tag{3-10}
\end{equation*}
$$

This braiding is of Cartan type if and only if $j=0$, or $j=n$ with $q=-1$.
Proof. Let $V$ be a braided vector space of standard $A_{\theta}$ type. For each vertex $i$, with $1<i<\theta$, we have $q_{i i}=-1$ or $q_{i i} q_{i, i-1} q_{i-1, i}=q_{i i} q_{i, i+1} q_{i+1, i}=1$, and similar formulas hold for $i=1, \theta$. So suppose that $1<i<\theta$ and $q_{i i}=-1$. We transform by $s_{i}$ and obtain

$$
\tilde{q}_{i-1, i+1}=-q_{i, i+1} q_{i-1, i} q_{i-1, i+1}, \quad \tilde{q}_{i+1, i-1}=-q_{i, i-1} q_{i+1, i} q_{i+1, i-1},
$$

and using that $m_{i-1, i+1}=\widetilde{m}_{i-1, i+1}=0$, we have

$$
q_{i-1, i+1} q_{i+1, i-1}=1, \quad \tilde{q}_{i-1, i+1} \tilde{q}_{i+1, i-1}=1,
$$

so we deduce that $q_{i, i+1} q_{i+1, i}=\left(q_{i, i-1} q_{i-1, i}\right)^{-1}$. Then the corresponding matrix $\left(q_{i j}\right)$ is of the form (3-10).

Now consider $V$ of the form (3-10). Assume $q_{i i}=q^{ \pm 1}$; if we transform by $s_{i}$, the braided vector space $V_{i}$ is twist equivalent with $V$ by Remark 3.4. Thus, $\widetilde{m}_{i j}=m_{i j}$.

Assume $q_{i i}=-1$. We transform by $s_{i}$ and calculate

$$
\tilde{q}_{j j}=(-1)^{m_{i j}^{2}}\left(q_{i j} q_{j i}\right)^{m_{i j}} q_{j j}= \begin{cases}q_{j j} & \text { if }|j-i|>1 \\ (-1) q^{\mp 1} q^{ \pm 1}=-1 & \text { if } j=i \pm 1, q_{j j}=q^{ \pm 1} \\ (-1) q^{ \pm 1}(-1)=q^{ \pm 1} & \text { if } j=i \pm 1, q_{j j}=-1\end{cases}
$$

Also, $\tilde{q}_{i j} \tilde{q}_{j i}=q_{i j} q_{j i}$ if $|j-i|>1$ and $\tilde{q}_{i j} \tilde{q}_{j i}=q_{i j}^{-1} q_{j i}^{-1}$ if $|j-i|=1$; moreover

$$
\tilde{q}_{k j} \tilde{q}_{j k}=\left(q_{i k} q_{k i}\right)^{m_{i j}}\left(q_{i j} q_{j i}\right)^{m_{i k}} q_{k j} q_{j k}= \begin{cases}q_{k j} q_{j k} & \text { if }|j-i| \text { or }|k-i|>1 \\ 1 & \text { if } j=i-1, k=i+1\end{cases}
$$

Then $V_{i}$ has a braiding of the above form too, and $\left(-m_{i j}\right)$ corresponds to the finite Cartan matrix of type $A_{\theta}$, so it is a standard braiding of type $A_{\theta}$. Thus this is the complete family of standard braidings of type $A_{\theta}$.
Proposition 3.10. Let $V$ a diagonal braided vector space. Then $V$ is standard of type $B_{\theta}$ if and only if its generalized Dynkin diagram is of one of these forms:
(a) $\stackrel{\zeta q^{-1}}{\bigcirc} \xrightarrow{\bigcirc}$ with $\zeta \in \mathbb{G}_{3}, q \neq \zeta(\theta=2)$;
(b) $\mathscr{C}\left(\theta-1, q^{2} ; i_{1}, \ldots, i_{j}\right) \quad q^{-2} q \quad$ with $q \neq 0,-1, \quad 0 \leq j \leq \theta-1$;
(c)


This braiding is of Cartan type if and only if it is as in (b) and $j=0$.
Proof. First we analyze the case $\theta=2$. Let $V$ a standard braided vector space of type $B_{2}$. There are several possibilities:

- $q_{11}^{2} q_{12} q_{21}=q_{22} q_{21} q_{12}=1$ : this braiding is of Cartan type, with $q=q_{11}$. Note that $q \neq-1$. This braiding has the form (b) with $\theta=2, j=0$.
- $q_{11}^{2} q_{12} q_{21}=1, q_{22}=-1$. We transform by $s_{2}$, obtaining

$$
\tilde{q}_{11}=-q_{11}^{-1}, \quad \tilde{q}_{12} \tilde{q}_{21}=q_{12}^{-1} q_{21}^{-1}
$$

Thus $\tilde{q}_{11}^{2} \tilde{q}_{12} \tilde{q}_{21}=1$. It has the form (b) with $j=1$.

- $q_{11} \in \mathbb{G}_{3}, q_{22} q_{21} q_{12}=1$. We transform by $s_{1}$, obtaining

$$
\tilde{q}_{22}=q_{11} q_{12} q_{21}, \quad \tilde{q}_{12} \tilde{q}_{21}=q_{11}^{2} q_{12}^{-1} q_{21}^{-1}
$$

So $\tilde{q}_{22} \tilde{q}_{21} \tilde{q}_{12}=1$, which is the case (a).

- $q_{11} \in \mathbb{G}_{3}, q_{22}=-1$ : we transform by $s_{1}$, obtaining

$$
\tilde{q}_{22}=-q_{12}^{2} q_{21}^{2} q_{11}, \quad \tilde{q}_{12} \tilde{q}_{21}=q_{11}^{2} q_{12}^{-1} q_{21}^{-1}
$$

If we transform by $s_{2}$,

$$
\tilde{q}_{11}=-q_{12} q_{21} q_{11}, \quad \tilde{q}_{12} \tilde{q}_{21}=q_{12}^{-1} q_{21}^{-1} .
$$

So $q_{12} q_{21}= \pm q_{11}$, and we discard the case $q_{12} q_{21}=q_{11}$ because it has been considered before. The braiding has the form (c) with $j=0$, and is standard.

Conversely, all braidings (a), (b) and (c) are standard of type $B_{2}$.
Now let $V$ be of type $B_{\theta}$, with $\theta \geq 3$. The first $\theta-1$ vertices determine a braiding of standard type $A_{\theta-1}$, and the last two determine a braiding of standard type $B_{2}$; so we have to glue the possible such braidings. The possible cases are the two presented in Proposition 3.10, plus


But if we transform by $s_{\theta}$, we obtain

$$
\tilde{q}_{\theta-1, \theta-1}=\zeta q^{-1}, \quad \tilde{q}_{\theta-1, \theta-2} \tilde{q}_{\theta-2, \theta-1}=q^{-1}
$$

so $1=\tilde{q}_{\theta-1, \theta-1} \tilde{q}_{\theta-1, \theta-2} \tilde{q}_{\theta-2, \theta-1}$ and we obtain $q= \pm \zeta^{-1}$, or $\tilde{q}_{\theta-1, \theta-1}=-1$. Then $q=-\zeta^{-1}$ or $q=-1$, so it is of some of the above forms.

To prove that (b) and (c) are standard braidings, we use the following fact: if $m_{i j}=0$ (that is, $q_{i j} q_{j i}=1$ ) and we transform by $s_{i}$, then

$$
\tilde{q}_{j j}=q_{j j} \quad \text { and } \quad \tilde{q}_{j k} \tilde{q}_{j k}=q_{j k} q_{k j} \quad \text { for } k \neq i
$$

In this case, $m_{i j}=0$ if $|i-j|>1$; if, on the contrary, $j=i \pm 1$, we use the fact that the subdiagram determined by these two vertices is standard of type $B_{2}$ or type $A_{2}$. So this is the complete family of all twist equivalence classes of standard braidings of type $B_{\theta}$.

Proposition 3.11. Let $V$ a braided vector space of diagonal type. Then $V$ is standard of type $G_{2}$ if and only if its generalized Dynkin diagram is one of the following:


This braiding is of Cartan type if and only if it is as in (a).
Proof. Let $V$ be a standard braiding of type $G_{2}$. There are four possible cases:

- $q_{11}^{3} q_{12} q_{21}=1, q_{22} q_{21} q_{12}=1$ : this braiding is of Cartan type, as in (a), with $q=q_{11}$. If $q$ is a root of unity, then ord $q \geq 4$ because $m_{12}=3$.
- $q_{11}^{3} q_{12} q_{21}=1, q_{22}=-1$ : we transform by $s_{2}$, obtaining

$$
\tilde{q}_{11}=-q_{11}^{-2}, \quad \tilde{q}_{12} \tilde{q}_{21}=q_{12}^{-1} q_{21}^{-1}
$$

If $1=\tilde{q}_{11}^{3} \tilde{q}_{12} \tilde{q}_{21}=-q_{11}^{-3}$, then $q_{12} q_{21}=-1$, and the braiding is of Cartan type with $q_{11} \in \mathbb{G}_{6}$. If not, $1=\tilde{q}_{11}^{4}=q_{11}^{-8}$ and ord $\tilde{q}_{11}=4$, so ord $q_{11}=8$. Then we can express the braiding in the form of the third diagram in (b).

- $q_{11} \in \mathbb{G}_{4}, q_{22} q_{21} q_{12}=1$ : we transform by $s_{1}$, obtaining

$$
\tilde{q}_{22}=q_{11} q_{12}^{2} q_{21}^{2}, \quad \tilde{q}_{12} \tilde{q}_{21}=-q_{12}^{-1} q_{21}^{-1}
$$

If $1=\tilde{q}_{22} \tilde{q}_{21} \tilde{q}_{12}=-q_{11} q_{12} q_{21}$, we have $q_{11}^{3} q_{12} q_{21}=1$ because $q_{11}^{2}=-1$, and this is a braiding of Cartan type. So consider now the case $-1=\tilde{q}_{22}=q_{11} q_{12}^{2} q_{21}^{2}$, from which $q_{22}^{2}=q_{11}^{-1}$ and $q_{22} \in \mathbb{G}_{8}$. Then we obtain a braiding of the form of the first diagram in (b).

- $q_{11} \in \mathbb{G}_{4}, q_{22}=-1$ : we transform by $s_{2}$, obtaining

$$
\tilde{q}_{11}=-q_{12} q_{21} q_{11}, \quad \tilde{q}_{12} \tilde{q}_{21}=q_{12}^{-1} q_{21}^{-1} .
$$

If $\tilde{q}_{11} \in \mathbb{G}_{4}$, then $\left(q_{12} q_{21}\right)^{4}=1$. Moreover $q_{12} q_{21} \neq 1$ and $q_{12} q_{21} \neq q_{11}^{-1}$ because $m_{12}=3$. So $q_{12} q_{21}=-1$ or $q_{12} q_{21}=q_{11}=q_{11}^{-3}$; but these cases have been considered already. There remains to analyze the case

$$
1=\tilde{q}_{11}^{3} \tilde{q}_{12} \tilde{q}_{21}=q_{11} q_{12}^{2} q_{21}^{2},
$$

which we can express in the form of the second diagram in (b), for some $\zeta \in \mathbb{G}_{8}$. A simple calculation proves that these braidings are of standard type, so they are all the standard braidings of type $G_{2}$.

## 4. Nichols algebras of standard braided vector spaces

In this section we study Nichols algebras associated to standard braidings. We assume that the Dynkin diagram is connected, as in Section 3. In Section 4A we prove that the set $\Delta^{+}(\mathfrak{B}(V))$ is in bijection with $\Delta_{C}^{+}$, the set of positive roots associated with the finite Cartan matrix $C$.

We describe an explicit set of generators in Section 4B, following [Lalonde and Ram 1995]. We adapt their proof since they work on enveloping algebras of simple Lie algebras. In Section 4C, we calculate the dimension of Nichols algebra associated to a standard braided vector space, type by type.

4A. PBW bases of Nichols algebras. We start with a result analogous to [Heckenberger 2006b, Theorem 1], but for braidings of standard type.

Theorem 4.1. Let $V$ be a braided vector space of standard type with Cartan matrix $C$. Then the set $\Delta(\mathfrak{B}(V))$ is finite if and only if the Cartan matrix $C$ is symmetrizable and of finite type.

Proof. Since we assume $V$ of standard type, $\Delta(\mathfrak{B}(V))$ coincides with the set of real roots corresponding to the matrix $C$ by [Heckenberger 2006b, Proposition 1], where we identify corresponding simple roots. Hence, if $C$ is not symmetrizable or not of finite type, the set of real roots is infinite by the classification of finite Coxeter groups, and hence $\Delta(\mathfrak{B}(V))$ is infinite.

Conversely, let $C$ be symmetrizable and of finite type. Then the set of real roots is finite. Take $\alpha \in \Delta(\mathfrak{B}(V))$ and let $k \in \mathbb{N}, i_{1}, \ldots, i_{k} \in\{1, \ldots, \theta\}$ be a sequence of integers such that $s_{i_{1}} \cdots s_{i_{k}}$ is a longest element in $W_{0}(\chi)$. Since all roots are positive or negative, there exists $l \in\{1, \ldots, k\}$ such that $\beta=s_{i_{l+1}} \cdots s_{i_{k}}(\alpha)$ is positive and $s_{i_{l}}(\beta)$ is negative. But then $\beta=\alpha_{i_{l}}$, and $\alpha=s_{i_{k}} \cdots s_{i_{l+1}}\left(\alpha_{i_{l}}\right)$ is a real root. Thus $\Delta(\mathfrak{B}(V))$ is finite.

Corollary 4.2. Let $V$ be a braided vector space of standard type, $\operatorname{set} \theta=\operatorname{dim} V$, and let $C=\left(a_{i j}\right)_{i, j \in\{1, \ldots, \theta\}}$ be the corresponding generalized Cartan matrix of finite type.
(a) $\phi\left(\Delta_{C}\right)=\Delta(\mathfrak{B}(V))$, where as before $\phi: \mathbb{Z} \pi \rightarrow \mathbb{Z}^{\theta}$ is the $\mathbb{Z}$-linear map determined by $\phi\left(\alpha_{i}\right):=\mathbf{e}_{i}$.
(b) The multiplicity of each root in $\Delta(\mathfrak{B}(V))$ is one.

Proof. Statement (a) follows from the proof of Theorem 4.1.
Using this condition, since each root is of the form $\beta=w\left(\alpha_{i}\right)$ for some $w \in W$ and $i \in\{1, \ldots, \theta\}$, we conclude by applying a certain sequence of transformations $s_{i}$ that this is the degree corresponding to a generator of the corresponding Nichols algebra, so the multiplicity (which is invariant under these transformations) is 1.

4B. Explicit generators for a PBW basis. In view of Corollary 4.2, we restrict our attention to finding one Lyndon word for each positive root of the root system associated with the corresponding finite Cartan matrix.

Proposition 4.3 [Lalonde and Ram 1995, Proposition 2.9]. Let l be an element of $S_{I}$. Then $l$ is of the form $l=l_{1} \ldots l_{k} a$, for some $k \in \mathbb{N}_{0}$, where

- $l_{i} \in S_{I}$ for each $i=1, \ldots, k$;
- $l_{i}$ is a beginning of $l_{i-1}$ for each $i>1$; and
- a is a letter.

Also, if $l=u v$ is the Shirshov decomposition, then $u, v \in S_{I}$.
In what follows, we describe a set of Lyndon words for each Cartan matrix of finite type $C$.

Consider $\alpha=\sum_{j=1}^{\theta} a_{j} \alpha_{j} \in \Delta^{+}$and let $l_{\alpha} \in S_{I}$ be such that $\operatorname{deg} l_{\alpha}=\alpha$. Let $l_{\alpha}=l_{\beta_{1}} \ldots l_{\beta_{k}} x_{s}$ be a decomposition as above, where $s \in\{1, \ldots, \theta\}$ and $\operatorname{deg} l_{\beta_{j}}=\beta_{j}$. Since each $l_{\beta_{j}}$ is a beginning of $l_{\beta_{j-1}}$, all the words begin with the same letter $x^{\prime}$, which satisfies $x^{\prime}<x_{s}$ because $l$ is a Lyndon word. Therefore $x^{\prime}$ is the least letter of $l$, so

$$
x^{\prime}=x_{i}, \quad i=\min \left\{j: a_{j} \neq 0\right\} \quad \Longrightarrow \quad \alpha=\sum_{j=i}^{\theta} a_{j} \alpha_{j} .
$$

Then $k \leq a_{i} \leq 3$, for the order given in (3-9), (3-4), (3-5), (3-6), (3-7), (3-8) (the value $a_{i}=3$ appears only when $C$ is of type $G_{2}$ ).

Now, each $l_{\beta_{j}}$ lies in $S_{I}$, so $\beta_{j} \in \Delta^{+}$; i.e., it corresponds to a term of the PBW basis. Also $\sum_{j=1}^{k} \beta_{j}+\alpha_{s}=\alpha$. If $k=2$, we have $\beta_{1}-\beta_{2}=\sum_{j=1}^{\theta} b_{j} \alpha_{j}$ and $b_{j} \geq 0$, because $\beta_{2}$ is a beginning of $\beta_{1}$ (an analogous claim is valid when the matrix is of type $G_{2}$ and $k=3$ ). With these rules we define inductively Lyndon words for a PBW basis corresponding with a standard braiding for a fixed order on the letters. This is done as in [Lalonde and Ram 1995], but taking care that in that reference Serre relations are used; here we have quantum Serre relations, and some quantum binomial coefficients may be zero.
Type $A_{\theta}$ : In this case, the roots are of the form

$$
\mathbf{u}_{i, j}:=\sum_{k=i}^{j} \alpha_{k}, \quad 1 \leq i \leq j \leq \theta
$$

By induction on $s=j-i$, we have

$$
l_{\mathbf{u}_{i, j}}=x_{i} x_{i+1} \ldots x_{j} .
$$

This is because when $s=0$ we have $i=j$, and the unique possibility is $l_{\mathbf{u}_{i, i}}=x_{i}$. If we remove the last letter (when $j-i>0$ ), we must obtain a Lyndon word, so the last letter must be $x_{j}$.
Type $B_{\theta}$ : For convenience, we use the following vertex numbering:

$$
\begin{equation*}
\circ^{1} \Longleftarrow \circ^{2}-\circ^{3} \ldots \quad \circ^{\theta-1}-\circ^{\theta} . \tag{4-1}
\end{equation*}
$$

The roots are of the form $\mathbf{u}_{i, j}:=\sum_{k=i}^{j} \alpha_{k}$, or

$$
\mathbf{v}_{i, j}:=2 \sum_{k=1}^{i} \alpha_{k}+\sum_{k=i+1}^{j} \alpha_{k} .
$$

In the first case we have $l_{\mathbf{u}_{i, j}}=x_{i} x_{i+1} \ldots x_{j}$, as above. In the second case, if $j=i+1$, we must have $x_{i+1}$ as the last letter to obtain a decomposition in two words $x_{1} \cdots x_{i}$; if $j>i+1$, the last letter must be $x_{j}$, so we obtain

$$
l_{\mathbf{v}_{i, j}}=x_{1} x_{2} \ldots x_{i} x_{1} x_{2} \ldots x_{j}
$$

$\underline{\text { Type } C_{\theta}}$ : The roots are of the form $\mathbf{u}_{i, j}:=\sum_{k=i}^{j} \alpha_{k}$, or

$$
\mathbf{w}_{i, j}:=\sum_{k=i}^{j-1} \alpha_{k}+2 \sum_{k=j}^{\theta-1} \alpha_{k}+\alpha_{\theta}, \quad i \leq j<\theta
$$

As before, $l_{\mathbf{u}_{i, j}}=x_{i} x_{i+1} \ldots x_{j}$. Now, if $i<j$, the least letter $x_{i}$ has degree 1 , so if we remove the last letter, we obtain a Lyndon word; that is, $\mathbf{w}_{i, j}-x_{s}$ is a root, and then $x_{s}=x_{j}$, so

$$
l_{\mathbf{w}_{i, j}}=x_{i} x_{i+1} \ldots x_{\theta-1} x_{\theta} x_{\theta-1} \ldots x_{j}
$$

When $i=j, a_{i}=2$, so there are one or two Lyndon words $\beta_{j}$ as before. Since $\mathbf{w}-x_{s}$ is not a root, for $s=i+1, \ldots, \theta$, and $i<s$, there are two Lyndon words $\beta_{1} \geq \beta_{2}$, and $\beta_{1}+\beta_{2}=2 \sum_{k=i}^{\theta-1} \alpha_{k}$. The only possibility is $\beta_{1}=\beta_{2}=x_{i} x_{i+1} \ldots x_{\theta-1}$; that is,

$$
l_{\mathbf{w}_{i, i}}=x_{i} x_{i+1} \ldots x_{\theta-1} x_{i} x_{i+1} \ldots x_{\theta-1} x_{\theta}
$$

$\underline{\text { Type } D_{\theta}}$ : the roots are of the form $\mathbf{u}_{i, j}:=\sum_{k=i}^{j} \alpha_{k}, 1 \leq i \leq j \leq \theta$, or

$$
\begin{aligned}
\mathbf{z}_{i, j} & :=\sum_{k=i}^{j-1} \alpha_{k}+2 \sum_{k=j}^{\theta-2} \alpha_{k}+\alpha_{\theta-1}+\alpha_{\theta}, i<j \leq \theta-2 \\
\overline{\mathbf{z}}_{i} & :=\sum_{k=i}^{\theta-2} \alpha_{k}+\alpha_{\theta}, \quad 1 \leq i \leq \theta-2
\end{aligned}
$$

As above, $l_{\mathbf{u}_{i, j}}=x_{i} x_{i+1} \ldots x_{j}$ if $j \leq n-1$. When the roots are of type $\overline{\mathbf{z}}_{i}$, we have $s=\theta$, since $\overline{\mathbf{z}}_{i}-x_{s}$ must be a root (if $x_{s}$ is the last letter); thus $l_{\overline{\mathbf{z}}_{i}}=x_{i} x_{i+1} \ldots x_{\theta-2} x_{\theta}$ is the unique possibility.

Now, when $\alpha=\mathbf{u}_{i, \theta}$, the last letter is $x_{\theta-1}$ or $x_{\theta}$ : if it is $x_{\theta}$, we have $l_{\mathbf{u}_{i, \theta}}=$ $x_{i} x_{i+1} \ldots x_{\theta-1} x_{\theta}$. Since $m_{\theta-1, \theta}=0$, we have $x_{\theta-1} x_{\theta}=q_{\theta-1, \theta} x_{\theta} x_{\theta-1}$, so

$$
x_{i} x_{i+1} \ldots x_{\theta-1} x_{\theta} \equiv x_{i} x_{i+1} \ldots x_{\theta-2} x_{\theta} x_{\theta-1} \quad \bmod I
$$

and then $x_{i} x_{i+1} \ldots x_{\theta-1} x_{\theta} \notin S_{I}$. So, $l_{\mathbf{u}_{i, \theta}}=x_{i} \ldots x_{\theta-2} x_{\theta} x_{\theta-1}$.
In the last case, note that if $j=n-2$, the unique possibility is $\beta_{t}$ as before, because the least letter $x_{i}$ has degree 1 and $x_{s}=x_{\theta-2}$ (since $\alpha-\alpha_{s}$ is a root). Hence $l_{\mathbf{z}_{i, \theta-2}}=x_{i} \ldots x_{\theta-2} x_{\theta} x_{\theta-1} x_{\theta-2}$, and inductively,

$$
l_{\mathbf{z}_{i, j}}=x_{i} \ldots x_{\theta-2} x_{\theta} x_{\theta-1} x_{\theta-2} \ldots x_{j}
$$

Type $E_{6}$ : Let $\alpha=\sum_{j=1}^{6} a_{j} \alpha_{j}$. If $a_{6}=0, \alpha$ corresponds to the Dynkin subdiagram of type $D_{5}$ determined by $1,2,3,4,5$, and we obtain $l_{\alpha}$ as above. If $a_{1}=0$ then $\alpha$ corresponds to the Dynkin subdiagram of type $D_{5}$ determined by 2, 3, 4, 5, 6; the numbering is different from the one given in (3-4). Anyway, the roots are defined in a similar way, and we obtain the same list as in [Lalonde and Ram 1995, Fig.1]. If $a_{4}=0$, then $\alpha$ corresponds to the Dynkin subdiagram of type $A_{5}$ determined by $1,2,3,5,6$.

So we restrict our attention to the case $a_{i} \neq 0, i=1,2,3,4,5,6$. We consider each case in turn:

- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+\alpha_{4}+\alpha_{5}+\alpha_{6}$ : since $a_{1}=1, \alpha-\alpha_{s}=\beta_{1}$ is a root, where $\alpha_{s}$ is the last letter. Then $s=2$ or $s=6$. In the second case, $l_{\beta_{1}}=x_{1} x_{2} x_{3} x_{4} x_{5}$, but using that $x_{2} x_{3}=q_{23} x_{3} x_{2}$, we have $x_{1} x_{2} x_{3} x_{4} x_{5} \notin S_{I}$. So $s=2$, and $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{2}$.
- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+2 \alpha_{4}+\alpha_{5}+\alpha_{6}$ : from $a_{1}=1$, we note that $\alpha-\alpha_{s}=\beta_{1}$ is a root. Then $s=4$, and $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{2} x_{4}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+2 \alpha_{4}+\alpha_{5}+\alpha_{6}$ : since $a_{1}=1, \alpha-\alpha_{s}=\beta_{1}$ is a root. So $s=3$, and $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{2} x_{4} x_{3}$.
- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+2 \alpha_{4}+2 \alpha_{5}+\alpha_{6}$ : since $a_{1}=1, \alpha-\alpha_{s}=\beta_{1}$ is a root. The only possibility is $s=5$, and $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{2} x_{4} x_{5}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+2 \alpha_{4}+2 \alpha_{5}+\alpha_{6}$ : as above $a_{1}=1$, and $\alpha-\alpha_{s}=\beta_{1}$ is a root. So $s=3$, and $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{2} x_{4} x_{5} x_{3}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+2 \alpha_{5}+\alpha_{6}$ : since $a_{1}=1, \alpha-\alpha_{s}=\beta_{1}$ is a root. Then $s=4$ and $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{2} x_{4} x_{5} x_{3} x_{4}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+2 \alpha_{5}+\alpha_{6}$ : since $a_{1}=1, \alpha-\alpha_{s}=\beta_{1}$ is a root. So $s=2$, and $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{2} x_{4} x_{5} x_{3} x_{4}$.
Type $E_{7}$ : If $\alpha=\sum_{j=1}^{7} a_{j} \alpha_{j}$ and $a_{7}=0$, the root corresponds to the subdiagram of type $D_{6}$ determined by $1,2,3,4,5,6$, and we obtain $l_{\alpha}$ as above. If $a_{1}=0$, it corresponds to the subdiagram of type $E_{6}$ determined by $2,3,4,5,6,7$. If $a_{5}=0$, then $\alpha$ corresponds to the subdiagram of type $A_{6}$ determined by $1,2,3,4,6,7$.

As above, consider each case where $a_{i} \neq 0, i=1,2,3,4,5,6,7$ :

- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+\alpha_{4}+\alpha_{5}+\alpha_{6}+\alpha_{7}$ : since $a_{1}=1, \alpha-\alpha_{s}=\beta_{1}$ is a root, if $\alpha_{s}$ is the last letter. Then $s=2$ or $s=7$. In the second case, $l_{\beta_{1}}=x_{1} x_{2} x_{3} x_{4} x_{5} x_{6}$, but from $x_{2} x_{3}=q_{23} x_{3} x_{2}$, we have $x_{1} x_{2} x_{3} x_{4} x_{5} x_{6} x_{7} \notin S_{I}$. So $s=2$, and $l_{\alpha}=$ $x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2}$.
- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+2 \alpha_{4}+\alpha_{5}+\alpha_{6}+\alpha_{7}$ : now $s=4$, 7. We discard the case $s=7$ since $m_{47}=0$; for the case $s=4$ we have $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+2 \alpha_{4}+\alpha_{5}+\alpha_{6}+\alpha_{7}$ : as above, $s=3$, 7 , but we discard $s=7$ since $m_{37}=0$, so $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{3}$.
- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+2 \alpha_{4}+2 \alpha_{5}+\alpha_{6}+\alpha_{7}$ : now $s=5,7$, and we discard the case $s=7$ because $m_{57}=0$, so $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+2 \alpha_{4}+2 \alpha_{5}+\alpha_{6}+\alpha_{7}$ : now $s=3,7$, and as above we discard the case $s=7$, so $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{3}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+2 \alpha_{5}+\alpha_{6}+\alpha_{7}$ : now $s=4$, and therefore we have $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{3} x_{4}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+2 \alpha_{5}+\alpha_{6}+\alpha_{7}$ : now $s=2$, as above, and $l_{\alpha}=$ $x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{3} x_{4} x_{2}$.
- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+2 \alpha_{4}+2 \alpha_{5}+2 \alpha_{6}+\alpha_{7}$ : as above, the unique possibility is $s=6$, so $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+2 \alpha_{4}+2 \alpha_{5}+2 \alpha_{6}+\alpha_{7}: s=3, l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6} x_{3}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+2 \alpha_{5}+2 \alpha_{6}+\alpha_{7}: s=4, l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6} x_{3} x_{4}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+2 \alpha_{5}+2 \alpha_{6}+\alpha_{7}: s=2$, and in this case we obtain $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6} x_{3} x_{4} x_{2}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+3 \alpha_{5}+2 \alpha_{6}+\alpha_{7}: s=5$, and in this case we obtain $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6} x_{3} x_{4} x_{5}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+2 \alpha_{3}+3 \alpha_{4}+3 \alpha_{5}+2 \alpha_{6}+\alpha_{7}$ : as above, $s=2$, and we get $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6} x_{3} x_{4} x_{5} x_{2}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+2 \alpha_{3}+4 \alpha_{4}+3 \alpha_{5}+2 \alpha_{6}+\alpha_{7}: s=4$, and in this case we obtain $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6} x_{3} x_{4} x_{5} x_{2} x_{4}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+3 \alpha_{3}+4 \alpha_{4}+3 \alpha_{5}+2 \alpha_{6}+\alpha_{7}: s=3$, and in this case we obtain $l_{\alpha}=x_{1} x_{3} x_{4} x_{5} x_{6} x_{7} x_{2} x_{4} x_{5} x_{6} x_{3} x_{4} x_{5} x_{2} x_{4} x_{3}$.
- $\alpha=2 \alpha_{1}+2 \alpha_{2}+3 \alpha_{3}+4 \alpha_{4}+3 \alpha_{5}+2 \alpha_{6}+\alpha_{7}$ : now there are one or two words $\beta_{j}$. Since $\alpha-\alpha_{s} \in \Delta^{+}$if and only if $s=1$ and $x_{1}$ is not the last letter (because it is the least letter), there are two words $\beta_{j}$. So looking at the roots we obtain $s=7$, and $l_{\alpha}=\left(x_{1} x_{3} x_{4} x_{5} x_{6} x_{2} x_{4} x_{5} x_{3} x_{4} x_{2}\right)\left(x_{1} x_{3} x_{4} x_{5} x_{6}\right) x_{7}$

Type $E_{8}$ : Consider $\alpha=\sum_{j=1}^{8} a_{j} \alpha_{j}$; if $a_{8}=0$, the root corresponds to the subdiagram of type $D_{7}$ determined by $1,2,3,4,5,6,7$, and we obtain $l_{\alpha}$ as in that case. If $a_{1}=0$, it corresponds to the subdiagram of type $E_{7}$ determined by $2,3,4,5,6,7,8$. If $a_{6}=0$, then $\alpha$ corresponds to a subdiagram of type $A_{7}$ determined by $1,2,3,4,5,7,8$.

So, we consider the case $a_{i} \neq 0, i=1,2,3,4,5,6,7,8$, and solve it case by case in a similar way as for $E_{7}$, by induction on the height.
Type $F_{4}$ : Now $\alpha=\sum_{j=1}^{4} a_{j} \alpha_{j}$. If $a_{4}=0$, then it corresponds to the subdiagram of type $B_{3}$ determined by $1,2,3$, so we obtain $l_{\alpha}$ as before. If $a_{1}=0, \alpha$ corresponds to the subdiagram of type $C_{3}$ determined by $2,3,4$.

So consider the case $a_{i} \neq 0, i=1,2,3,4$ :

- $\alpha=\alpha_{1}+\alpha_{2}+\alpha_{3}+\alpha_{4}: a_{1}=1$, so $\alpha-\alpha_{s}=\beta_{1}$ is a root, where $\alpha_{s}$ is the last letter. Then $s=4$, and $l_{\alpha}=x_{1} x_{2} x_{3} x_{4}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+\alpha_{4}: a_{1}=1$, so $\alpha-\alpha_{s}=\beta_{1}$ is a root. Now $s=3$ or $s=4$. If $s=4$, then $l_{\alpha}=x_{1} x_{2} x_{3}^{2} x_{4}$. But $m_{34}=2$, so

$$
x_{3}^{2} x_{4} \equiv q_{34}\left(1+q_{33}\right) x_{3} x_{4} x_{3}-q_{33} q_{34} x_{4} x_{3}^{2} \quad \bmod I
$$

and $x_{1} x_{2} x_{3}^{2} x_{4} \notin S_{I}$, a contradiction. So $s=3$, and we have $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3}$.

- $\alpha=\alpha_{1}+2 \alpha_{2}+2 \alpha_{3}+\alpha_{4}: a_{1}=1$, and as above, $s=2$ or $s=4$ : if $s=4$, then $l_{\alpha}=x_{1} x_{2} x_{3}^{2} x_{2} x_{4}$, but it is not an element of $S_{I}$, because $x_{2} x_{4} \equiv q_{24} x_{2} x_{4} \bmod I$. Then $s=2$, and $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{2}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+3 \alpha_{3}+\alpha_{4}: a_{1}=1$, so $s=3$, and we have $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{2} x_{3}$.
- $\alpha=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+2 \alpha_{4}: a_{1}=1$, so $s=4$, and $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{4}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+2 \alpha_{3}+2 \alpha_{4}: a_{1}=1$, so $s=2$ or $s=4$, but we discard the case $s=4$ since $x_{2} x_{4} \equiv q_{24} x_{2} x_{4} \bmod I$. So, $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{4} x_{2}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+3 \alpha_{3}+2 \alpha_{4}: a_{1}=1$, so $s=3$, and $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{4} x_{2} x_{3}$.
- $\alpha=\alpha_{1}+2 \alpha_{2}+4 \alpha_{3}+2 \alpha_{4}: a_{1}=1$, so $s=3$, and $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{4} x_{2} x_{3}^{2}$.
- $\alpha=\alpha_{1}+3 \alpha_{2}+4 \alpha_{3}+2 \alpha_{4}: a_{1}=1$, so $s=2$, and $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{4} x_{2} x_{3}^{2} x_{2}$.
- $\alpha=2 \alpha_{1}+3 \alpha_{2}+4 \alpha_{3}+2 \alpha_{4}: a_{1}=2$, and there are one or two Lyndon words $\beta_{j}$. If there is only one, $\beta_{1}=\alpha-\alpha_{s} \in \Delta^{+}$. The only possibility is $s=1$, but it contradicts that $l_{\alpha}$ is a Lyndon word. Hence there exist $\beta_{1}, \beta_{2} \in \Delta^{+}$such that $\beta_{1}+\beta_{2}=\alpha-\alpha_{s}$, and $\beta_{2}$ is a beginning of $\beta_{1}$. So $s=2$ and $\beta_{1}=\beta_{2}=\alpha_{1}+\alpha_{2}+2 \alpha_{3}+\alpha_{4}$, i.e., $l_{\alpha}=x_{1} x_{2} x_{3} x_{4} x_{3} x_{1} x_{2} x_{3} x_{4} x_{3} x_{2}$.

Type $G_{2}$ : the roots are $\alpha_{1}, \alpha_{2}, \alpha_{1}+\alpha_{2}, 2 \alpha_{1}+\alpha_{2}, 3 \alpha_{1}+\alpha_{2}, 3 \alpha_{1}+2 \alpha_{2}$ :

$$
l_{\alpha_{1}}=x_{1}, \quad l_{\alpha_{2}}=x_{2}, \quad l_{m \alpha_{1}+\alpha_{2}}=x_{1}^{m} x_{2}, \quad m=1,2,3 .
$$

If $\alpha=3 \alpha_{1}+2 \alpha_{2}$, the last letter is $x_{2}$. If we suppose $\beta_{1}=3 \alpha_{1}+\alpha_{2}$, then $l_{\alpha}=x_{1}^{3} x_{2}^{2}$, but

$$
\left(\operatorname{ad} x_{2}\right)^{2} x_{1}=x_{2}^{2} x_{1}-q_{21}\left(1+q_{22}\right) x_{2} x_{1} x_{2}+q_{22} q_{21} x_{1} x_{2}^{2} \equiv 0 \quad \bmod I
$$

so we have

$$
x_{1}^{3} x_{2}^{2} \equiv\left(q_{22}^{-1}+1\right) x_{1}^{2} x_{2} x_{1} x_{2}-q_{22}^{-1} q_{21}^{-1} x_{1}^{2} x_{2}^{2} x_{1} \quad \bmod I,
$$

and then $l_{\alpha}=x_{1}^{3} x_{2}^{2} \notin S_{I}$ because $q_{22}^{-1} q_{21}^{-1} \neq 0$, so there are at least two words $\beta_{j}$. Analogously, if we suppose that there are three words $\beta_{j}$, we obtain $l_{\beta_{1}}=l_{\beta_{2}}=$ $x_{1}>l_{\beta_{3}}=x_{1} x_{2}$ since $\beta_{1} \geq \beta_{2} \geq \beta_{3}$ and $\beta_{1}+\beta_{2}+\beta_{3}=3 \alpha_{1}+\alpha_{2}$; moreover $l_{\alpha}=x_{1}^{3} x_{2}^{2} \notin S_{I}$. So there are two Lyndon words of degree $\beta_{1} \geq \beta_{2}$, and the unique possibility is $\beta_{1}=2 \alpha_{1}+\alpha_{2}, \beta_{2}=\alpha_{1}$; that is, $l_{\alpha}=x_{1}^{2} x_{2} x_{1} x_{2}$.

4C. Dimensions of Nichols algebras of standard braidings. We begin with the standard braidings of types $C_{\theta}, D_{\theta}, E_{6}, E_{7}, E_{8}, F_{4}$, which are of Cartan type.
Proposition 4.4. Let $V$ a braided vector space of Cartan type, with $q_{44} \in \mathbb{G}_{N}$ if $V$ is of type $F_{4}$ and $q_{11} \in \mathbb{G}_{N}$ otherwise, in each case for some $N \in \mathbb{N}$. The dimension of the associated Nichols algebra $\mathfrak{B}(V)$ is as follows:
$\underline{\text { Type } C_{\theta}:} \operatorname{dim} \mathfrak{B}(V)= \begin{cases}N^{\theta^{2}} & \text { for } N \text { odd, }, \\ N^{\theta^{2}} / 2^{\theta} & \text { for } N \text { even } ;\end{cases}$

Type $F_{4}: \operatorname{dim} \mathfrak{B}(V)= \begin{cases}N^{24} & \text { for } N \text { odd, } \\ N^{24} / 2^{12} & \text { for } N \text { even; }\end{cases}$
Types $D_{\theta}, E_{6}, E_{7}, E_{8}: \quad \operatorname{dim} \mathfrak{B}(V)=N^{\left|\Delta^{+}\right|}$.
The last case corresponds to simply laced Dynkin diagrams.
Proof. If $N$ is odd, then $\operatorname{ord} q^{2}=\operatorname{ord} q=N$, but if $N$ is even, we have $\operatorname{ord} q^{2}=N / 2$. Since the braiding is of Cartan type,

$$
q_{s_{i}(\alpha)}=\chi\left(s_{i}(\alpha), s_{i}(\alpha)\right)=\tilde{\chi}(\alpha, \alpha)=\chi(\alpha, \alpha)=q_{\alpha} .
$$

Using this, we just have to determine how many roots there are in the orbit of each simply root.

When $V$ is of type $C_{\theta}$, we have $q_{i i}=q$, except for $q_{\theta \theta}=q^{2}$. The roots in the orbit of $\alpha_{\theta}$ by the action of the Weyl group are $q_{\mathbf{w}_{i i}}$ for $1 \leq i<\theta$, and the others are in the orbit of $\alpha_{j}$, for some $j<\theta$. Hence there are $\theta$ roots such that $q_{\alpha}=q^{2}$, and $q_{\alpha}=q$ for the rest.

When $V$ is of type $F_{4}$, we have $q_{11}=q_{22}=q^{2}$ and $q_{33}=q_{44}=q$. There are exactly 12 roots in the union of orbits corresponding to $\alpha_{1}$ and $\alpha_{2}$, and the other 12 are in the union of orbits corresponding to $\alpha_{3}$ and $\alpha_{4}$. So

$$
\left|\left\{\alpha \in \Delta^{+}: q_{\alpha}=q\right\}\right|=\left|\left\{\alpha \in \Delta^{+}: q_{\alpha}=q^{2}\right\}\right|=12
$$

When $V$ is of type $D$ or $E$, all the $q_{\alpha}$ equal $q$ because $q_{i i}=q$, for all $1 \leq i \leq \theta$. The formula for the dimension follows from Theorem 2.6(ii) and Corollary 4.2.

Now we treat the types $A_{\theta}, B_{\theta}$ and $G_{2}$.
Proposition 4.5. Let $V$ be a standard braided vector space of type $A_{\theta}$ as in Proposition 3.9. The associated Nichols algebra $\mathfrak{B}(V)$ is of finite dimension if and only if $q$ is a root of unity of order $N \geq 2$. In this case,

$$
\begin{equation*}
\operatorname{dim} \mathfrak{B}(V)=2^{\binom{\theta+1}{2}-\binom{t}{2}-\binom{\theta+1-t}{2}} N^{\binom{t}{2}+\binom{\theta+1-t}{2}}, \tag{4-2}
\end{equation*}
$$

where $t=\theta+1-\sum_{k=1}^{j}(-1)^{j-k} i_{k}$.
Proof. First, $q$ is a root of unity of order $N \geq 2$ because the height of each PBW generator is finite. To calculate the dimension, recall that from Corollary 4.2, we have to determine $q_{\alpha}$ for $\alpha \in \Delta_{C}$. As before, $\mathbf{u}_{i j}=\sum_{k=i}^{j} \mathbf{e}_{k}, i \leq j$, and we have

$$
\Delta(\mathfrak{B}(V))=\left\{\mathbf{u}_{i j}: 1 \leq i \leq j \leq \theta\right\} .
$$

If $1 \leq i \leq j \leq \theta$, we define

$$
\kappa_{i j}:=\operatorname{card}\left\{k \in\{i, \ldots, j\}: q_{k k}=-1\right\} .
$$

We prove by induction on $j-i$ that

- if $\kappa_{i j}$ is odd, then $q_{\mathbf{u}_{i j}}=-1$;
- if $\kappa_{i j}$ is even, then $q_{\mathbf{u}_{i j}}=q_{j, j+1}^{-1} q_{j+1, j}^{-1}$.

Here $q_{\theta, \theta+1} q_{\theta+1, \theta}=q_{\theta \theta}^{-2} q_{\theta, \theta-1}^{-1} q_{\theta-1, \theta}^{-1}$.
If $j-i=0$, then $q_{\mathbf{u}_{i i}}=q_{i i}$; in this case, $\kappa_{i i}=1$ if $q_{i i}=-1$ or $\kappa_{i i}=0$ if $q_{i i}=\left(q_{i, i+1} q_{i+1, i}\right)^{-1} \neq-1$. Now assume this is valid for a certain $j$, and calculate it for $j+1$ :

$$
\begin{aligned}
q_{\mathbf{u}_{i, j+1}} & =\chi\left(\mathbf{u}_{i j}+\mathbf{e}_{j+1}, \mathbf{u}_{i j}+\mathbf{e}_{j+1}\right)=q_{\mathbf{u}_{i j}} \chi\left(\mathbf{u}_{i j}, \mathbf{e}_{j+1}\right) \chi\left(\mathbf{e}_{j+1}, \mathbf{u}_{i j}\right) q_{j+1, j+1} \\
& =q_{\mathbf{u}_{i j}} q_{j, j+1} q_{j+1, j} q_{j+1, j+1} \\
& = \begin{cases}q_{\mathbf{u}_{i j}} & \text { if } q_{j+1, j+1} \neq-1\left(\kappa_{i, j+1}=\kappa_{i j}\right), \\
(-1) q q^{-1}=-1 & \text { if } q_{j+1, j+1}=-1, \kappa_{i j} \text { even, } \\
(-1) q(-1)=q & \text { if } q_{j+1, j+1}=-1, \kappa_{i j} \text { odd. }\end{cases}
\end{aligned}
$$

This proves the inductive step; to calculate the dimension of $\mathfrak{B}(V)$ we have to calculate the number of $\mathbf{u}_{i j}$ such that

$$
q_{\mathbf{u}_{i j}}=q_{i, i+1}^{-1} q_{i+1, i}^{-1}=q^{ \pm 1}
$$

that is, $\operatorname{card}\left\{\kappa_{i j}: i \leq j, \kappa_{i j}\right.$ even $\}$.
We consider an $1 \times(\theta+1)$ board, numbered from 1 to $\theta+1$, and recursively paint its squares white or black: square $\theta+1$ is white, and square $i$ has the same color as square $i+1$ if and only if $q_{i i} \neq-1$. The possible colorings of this board are in bijective correspondence with the choices of $1 \leq i_{1}<\cdots<i_{j} \leq \theta$ for all $j$ (the positions where we put a -1 in the corresponding $q_{i i}$ of the braiding), and the number of white squares is

$$
t=1+\left(\theta-i_{j}\right)+\left(i_{j-1}-i_{j-2}\right)+\cdots=\theta+1-\sum_{k=1}^{j}(-1)^{j-k} i_{k}
$$

Thus $\operatorname{card}\left\{\kappa_{i j}: i \leq j, \kappa_{i j}\right.$ even\} is the number of pairs $(a, b)$ (where $a=i$ and $b=j+1$ ) such that $1 \leq a<b \leq \theta+1$ and the squares in positions $a$ and $b$ are of the same color; this number is $\binom{t}{2}+\binom{\theta+1-t}{2}$. This yields (4-2).

Proposition 4.6. Let $V$ be a standard braided vector space of type $B_{\theta}$ as in Proposition 3.10. If the braiding is as in cases (a) or (b) of that proposition, the associated Nichols algebra $\mathfrak{B}(V)$ has finite dimension if and only if $q$ is a root of unity of order $N \geq 2$ in case (a), or $N>2$ in case (b).

When finite, the dimension of $\mathfrak{B}(V)$ is as follows, where $t=\theta-\sum_{k=1}^{j}(-1)^{j-k} i_{k}$ :

- If the braiding is as in (a) of Proposition 3.10,

$$
\operatorname{dim} \mathfrak{B}(V)= \begin{cases}3^{3} N^{2} & \text { if } 3 \text { does not divide } N \\ 3^{2} N^{2} & \text { if } 3 \text { divides both } N \text { and } \operatorname{ord}\left(\zeta^{-1} q\right) \\ 3 N^{2} & \text { if } 3 \text { divides } N \text { but not } \operatorname{ord}\left(\zeta^{-1} q\right)\end{cases}
$$

- If the braiding is as in (b), then $0 \leq j \leq d-1$ and

$$
\operatorname{dim} \mathfrak{B}(V)= \begin{cases}2^{2 t(\theta-t)+\theta} k^{\theta^{2}-2 t \theta+2 t^{2}} & \text { if } N=2 k \\ 2^{(2 t+1)(\theta-t)+1} N^{\theta^{2}-2 t \theta+2 t^{2}} & \text { if } N \text { is odd }\end{cases}
$$

- If the braiding is as in (c), then

$$
\operatorname{dim} \mathfrak{B}(V)=2^{\theta(\theta-1)} 3^{\theta^{2}-2 t \theta+2 t^{2}}
$$

Proof. It is clear that $q$ should be a root of unity if $\operatorname{dim} \mathfrak{B}(V)$ is finite.
We now calculate $\operatorname{dim} \mathfrak{B}(V)$. From Corollary 4.2, we have to determine the $q_{\alpha}$ for $\alpha \in \Delta_{C}$, and multiply their orders. As before, $\mathbf{u}_{i j}=\sum_{k=i}^{j} \mathbf{e}_{k}$ for $1 \leq i \leq j \leq \theta$ and $\mathbf{v}_{i j}=2 \sum_{k=1}^{i} e_{k}+\sum_{k=i+1}^{j} e_{k}=2 e_{1, i}+e_{i+1, j}$ for $1 \leq i<j$; hence

$$
\Delta(\mathfrak{B}(V))=\left\{\mathbf{u}_{i j}: 1 \leq i \leq j \leq \theta\right\} \cup\left\{\mathbf{v}_{i j}: 1 \leq i<j \leq \theta\right\} .
$$

We calculate $q_{\mathbf{u}_{i j}}, 1<i \leq j \leq \theta$ as above, because they correspond to a braiding of standard $A_{\theta-1}$ type. We also calculate

$$
\begin{aligned}
q_{\mathbf{v}_{i j}} & =\chi\left(\mathbf{v}_{i j}, \mathbf{v}_{i j}\right)=\chi\left(\mathbf{u}_{1 i}, \mathbf{u}_{1 i}\right)^{4} \chi\left(\mathbf{u}_{1 i}, \mathbf{u}_{i+1, j}\right)^{2} \chi\left(\mathbf{u}_{i+1, j}, \mathbf{u}_{1 i}\right)^{2} q_{\mathbf{u}_{i+1, j}} \\
& =q_{11}^{4} q_{12}^{2} q_{21}^{2}\left(\prod_{k=2}^{i} q_{k k}^{2} q_{k-1, k} q_{k-1, k} q_{k+1, k} q_{k+1, k}\right)^{2} q_{\mathbf{u}_{i+1, j}}=q_{\mathbf{u}_{i+1, j}}
\end{aligned}
$$

where we have used the equalities $q_{i j} q_{j i}=1$ if $|i-j|>1, q_{11}^{4} q_{12}^{2} q_{21}^{2}=1$, and $q_{k k}^{2} q_{k-1, k} q_{k-1, k} q_{k+1, k} q_{k+1, k}=1$ if $2 \leq k \leq \theta-1$. To calculate the other $q_{\alpha}$ 's, we analyze each case:
(a) Note that $q_{\mathbf{e}_{1}}=\zeta, q_{\mathbf{e}_{1}+\mathbf{e}_{2}}=\zeta, q_{2 \mathbf{e}_{1}+\mathbf{e}_{2}}=\zeta q^{-1}, q_{\mathbf{e}_{2}}=q$. Setting $N^{\prime}=\operatorname{ord}\left(\zeta^{-1} q\right)$, we have $N^{\prime}=3 N$ if 3 does not divide $N ; N^{\prime}=N$ if 3 divides both $N$ and $N^{\prime}$; and $N^{\prime}=N / 3$ if 3 divides $N$ but not $N^{\prime}$ (since $q=\zeta \rho$, with $\rho \in \mathbb{G}_{N^{\prime}}$ ).
(b) We have $q_{\mathbf{u}_{1 k}}=q^{-1} q_{\mathbf{u}_{2 k}}$. This equals $q^{2} q^{-1}=q$ if $\kappa_{2 k}$ is even, and $-q^{-1}$ if $\kappa_{2 k}$ is odd; moreover $q_{11}=q$. Also, $\kappa_{2 k}$ is even if and only if $j \in\left\{i_{j}+1, \theta\right\}$, or $i \in\left\{i_{j-2}+1, i_{j-1}\right\}$, and so on. Then, with

$$
t=\left(\theta-i_{j}\right)+\left(i_{j-1}-i_{j-2}\right)+\cdots=\theta-\sum_{k=1}^{j}(-1)^{j-k} i_{k}
$$

as in the statement of the proposition, there are $t$ numbers such that $\kappa_{i, \theta-1}$ is even. There are $2\left(\binom{t}{2}+\binom{\theta-t}{2}\right)$ roots such that $q_{\alpha}=q^{2}, 2\left(\binom{\theta}{2}-\binom{t}{2}-\binom{\theta-t}{2}\right)$ roots such
that $q_{\alpha}=-1, t+1$ roots such that $q_{\alpha}=q$ and $\theta-1-t$ roots such that $q_{\alpha}=-q^{-1}$. If $N=2 k$, then $\operatorname{ord}\left(-q^{-1}\right)=2 k$ and $\operatorname{ord}\left(q^{2}\right)=k$, so

$$
\begin{aligned}
\operatorname{dim} \mathfrak{B}(V) & =2^{(\theta-1) \theta-t(t-1)-(\theta-t)(\theta-t-1)} k^{t(t-1)+(\theta-t)(\theta-t-1)}(2 k)^{\theta} \\
& =2^{2 t(\theta-t)+\theta} k^{\theta^{2}-2 t \theta+2 t^{2}}
\end{aligned}
$$

If $N$ is odd, then $\operatorname{ord}\left(-q^{-1}\right)=2 N$ and $\operatorname{ord}\left(q^{2}\right)=N$, so

$$
\begin{aligned}
\operatorname{dim} \mathfrak{B}(V)= & 2^{\theta(\theta-1)-t(t-1)-(\theta-t)(\theta-1-t)} N^{t(t-1)+(\theta-t)(\theta-1-t)+t+1} \\
& (2 N)^{\theta-1-t}=2^{(2 t+1)(\theta-t)+1} N^{\theta^{2}-2 t \theta+2 t^{2}}
\end{aligned}
$$

(c) In a similar way, we have $q_{\mathbf{u}_{1 i}}=\left(-\zeta^{2}\right) q_{\mathbf{u}_{2 i} i}$, which equals $\left(-\zeta^{2}\right)^{2}=\zeta$ if $\kappa_{2 i}$ is even, and $(-1)\left(-\zeta^{2}\right)=\zeta^{2}$ if $\kappa_{2 i}$ is odd; moreover $q_{11}=\zeta$. There are $2\left(\binom{t}{2}+\binom{\theta-t}{2}\right)$ roots such that $q_{\alpha}=-\zeta^{2}, 2\left(\binom{\theta}{2}-\binom{t}{2}-\binom{\theta-t}{2}\right)$ roots such that $q_{\alpha}=-1, t+1$ roots such that $q_{\alpha}=\zeta$ and $\theta-1-t$ roots such that $q_{\alpha}=\zeta^{2}$. Since ord $\zeta=\operatorname{ord} \zeta^{2}=3$ and $\operatorname{ord}\left(-\zeta^{2}\right)=6$, we have

$$
\begin{aligned}
\operatorname{dim} \mathfrak{B}(V) & =2^{\theta(\theta-1)-t(t-1)-(\theta-t)(\theta-1-t)} 6^{t(t-1)+(\theta-t)(\theta-1-t)} 3^{\theta} \\
& =2^{\theta(\theta-1)} 3^{\theta^{2}-2 t \theta+2 t^{2}} .
\end{aligned}
$$

Proposition 4.7. Let $V$ be a standard braided vector space of type $G_{2}$ as in Proposition 3.11. If the braiding is as in case (a) of that proposition, the associated Nichols algebra $\mathfrak{B}(V)$ is of finite dimension if and only if $q$ is a root of unity of order $N \geq 4$.

When finite, the dimension of $\mathfrak{B}(V)$ is as follows:

- In case (a) of Proposition 3.11,

$$
\operatorname{dim} \mathfrak{B}(V)= \begin{cases}N^{6} & \text { if } 3 \text { does not divide } N \\ N^{6} / 27 & \text { if 3 divides } N\end{cases}
$$

- In case $(\mathrm{b}), \operatorname{dim} \mathfrak{B}(V)=2^{12}$.

Proof. For (a) note that $q$ is a root of unity because $x_{1}$ has finite height, and $q_{\alpha}=q$ if $\alpha \in\left\{e_{1}, e_{1}+e_{2}, 2 e_{1}+e_{2}\right\}$, while $q_{\alpha}=q^{3}$ if $\alpha \in\left\{e_{2}, 3 e_{1}+e_{2}, 3 e_{1}+2 e_{2}\right\}$.

Case (b) can be checked as follows:

| type | $q_{x_{2}}$ | $q_{x_{1} x_{2}}$ | $q_{x_{1}^{3} x_{2}^{2}}$ | $q_{x_{1}^{2} x_{2}}$ | $q_{x_{1}^{3} x_{2}}$ | $q_{x_{1}}$ | $\operatorname{dim} \mathfrak{B}(V)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{array}{cc} \zeta^{2} & \zeta \zeta^{-1} \\ 0 & 0 \end{array}$ | 8 | 4 | 2 | 8 | 2 | 4 | $2^{12}$ |
| $\stackrel{\zeta^{2}}{\zeta^{3}-1}$ | 2 | 8 | 2 | 4 | 8 | 4 | $2^{12}$ |
| $\begin{array}{ccc} \zeta & \zeta^{5}-1 \\ 0 & 0 \end{array}$ | 2 | 4 | 8 | 4 | 2 | 8 | $2^{12}$ |

This completes the proof.

## 5. Presentation by generators and relations of Nichols algebras of standard braided vector spaces

In this section we give presentations for the Nichols algebras of standard braided vector spaces. We start with some technical results about relations and PBW bases in Section 5A; also we calculate the coproduct of some hyperwords in $T(V)$. In Sections 5B, 5C and 5D we express the braided commutator of two PBW generators as a combination of elements of the PBW basis under some assumptions. Then we obtain the desired presentation with a proof similar to the ones in [Andruskiewitsch and Dăscălescu 2005] and [Andruskiewitsch and Schneider 2002b]. In Section 5E we solve the problem when the braiding is of Cartan type using the transformation in Section 2C.

For rank two, a set of (not necessarily minimal) relations is given in Theorem 4 of [Heckenberger 2007].

5A. Some general relations. Let $V$ be a standard braided vector space with connected Dynkin diagram and let $C$ be the corresponding Cartan matrix. In what follows we assume that $C$ is symmetrizable and of finite type. Let $x_{1}, \ldots, x_{\theta}$ be an ordered basis of $V$ and $\left\{x_{\alpha}: \alpha \in \Delta^{+}(\mathfrak{B}(V))\right\}$ a set of PBW generators as in the previous section. Here $x_{\alpha} \in \mathfrak{B}(V)$ is, by abuse of notation, the image by the canonical projection of $x_{\alpha} \in T(V)$, the hyperword corresponding to a Lyndon word $l_{\alpha}$. As before, we write

$$
q_{\alpha}:=\chi(\alpha, \alpha) \quad \text { and } \quad N_{\alpha}:=\operatorname{ord} q_{\alpha} \quad \text { for } \alpha \in \Delta^{+}(\mathfrak{B}(V)) .
$$

Each $x_{\alpha}$ is homogeneous and has the same degree as $l_{\alpha}$. Also,

$$
\begin{equation*}
x_{\alpha} \in T(V)_{g_{\alpha}}^{\chi_{\alpha}}, \tag{5-1}
\end{equation*}
$$

where $g_{\alpha}=g_{1}^{b_{1}} \ldots g_{\theta}^{b_{\theta}}$ and $\chi_{\alpha}=\chi_{1}^{b_{1}} \ldots \chi_{\theta}^{b_{\theta}}$ if $\alpha=b_{1} \mathbf{e}_{1}+\cdots+b_{\theta} \mathbf{e}_{\theta}$.
Proposition 5.1. If the matrix of the braiding is symmetric, the PBW basis is orthogonal with respect to the bilinear form in Proposition 1.4.

Proof. We must prove that $(u \mid v)=0$, where $u \neq v$ are ordered products of PBW generators (we also allow powers greater than the corresponding heights). We argue by induction on $k:=\max \{\ell(u), \ell(v)\}$. If $k=1$, then $v$ is some $x_{j}$ and $u$ is either 1 or $x_{i}$; since $\left(x_{i} \mid x_{j}\right)=\delta_{i j}$ for all $i, j \in\{1, \ldots, \theta\}$, the proposition holds in this case.

Suppose the statement is valid when the length of both words is less than $k$, and let $u, v \in B_{I(V)}$ be distinct hyperwords such that one (or both) has length $k$. If both are hyperletters, they have different degrees $\alpha \neq \beta \in \mathbb{Z}^{\theta}$, so $u=x_{\alpha}, v=x_{\beta}$, and $\left(x_{\alpha} \mid x_{\beta}\right)=0$, since the homogeneous components are orthogonal for $(\mid)$.

Suppose that $u=x_{\alpha}$ and $v=x_{\beta_{1}}^{h_{1}} \ldots x_{\beta_{m}}^{h_{m}}$, for some $x_{\beta_{1}}>\cdots>x_{\beta_{m}}$. If $u$ and $v$ have different $\mathbb{Z}^{\theta}$-degrees, they are orthogonal. Hence we assume that $\alpha=\sum_{j=1}^{m} h_{m} \beta_{m}$. By [Bourbaki 1968, VI, Proposition 19], we can reorder the $\beta_{i}$ 's, using $h_{i}$ copies of $\beta_{i}$, in such a way that each partial sum is a root. By [Rosso 1999, Proposition 21], the order induced by the Lyndon words $l_{\alpha}$ is convex (the order on Lyndon words used there is the same as ours). Therefore $\beta_{m}<\alpha$. Using Lemma 1.9 and (1-8),
$(u \mid v)=\left(x_{\alpha} \mid w\right)\left(1 \mid x_{\beta_{m}}\right)+(1 \mid w)\left(x_{\alpha_{n}} \mid x_{\beta_{m}}\right)+\sum_{\substack{l_{1} \geq \cdots \geq l_{p}>\alpha \\ l_{i} \in L}}\left(x_{l_{1}, \ldots, l_{p}} \mid w\right)\left(\left[l_{1}\right]_{c} \cdots\left[l_{p}\right]_{c} \mid x_{\beta_{m}}\right)$,
where $v=w x_{\beta_{n}}$. Note that $\left(1 \mid x_{\beta_{m}}\right)=(1 \mid w)=0$. Also, $\left[l_{1}\right]_{c} \cdots\left[l_{p}\right]_{c}$ is a linear combination of greater hyperwords of the same degree and an element of $I(V)$. From the inductive hypothesis and the fact that $I(V)$ is the radical of the bilinear form, we see that $\left(\left[l_{1}\right]_{c} \cdots\left[l_{p}\right]_{c} \mid x_{\beta_{m}}\right)=0$.

Now consider

$$
\begin{aligned}
& u=x_{\alpha_{1}}^{j_{1}} \ldots x_{\alpha_{n}}^{j_{n}} \text { with } x_{\alpha_{1}}>\ldots>x_{\alpha_{n}}, \\
& v=x_{\beta_{1}}^{h_{1}} \ldots x_{\beta_{m}}^{h_{m}} \text { with } x_{\beta_{1}}>\ldots>x_{\beta_{m}} .
\end{aligned}
$$

Since the bilinear form is symmetric, we may as well assume that $x_{\alpha_{n}} \leq x_{\beta_{m}}$. Using Lemma 1.9 and (1-8), we obtain

$$
\begin{aligned}
&(u \mid v)=(w \mid 1)\left(x_{\alpha_{n}} \mid v\right)+\sum_{i=0}^{h_{m}}\binom{h_{m}}{i}_{q_{\beta_{m}}}\left(w \mid x_{\beta_{1}}^{h_{1}} \ldots x_{\beta_{m-1}}^{h_{m-1}} x_{\beta_{m}}^{i}\right)\left(x_{\alpha_{n}} \mid x_{\beta_{m}}^{h_{m}-i}\right) \\
&+\sum_{\substack{l_{1} \geq \cdots \geq l_{p}>l, l_{i} \in L \\
0 \leq j \leq m}}\left(w \mid x_{l_{1}, \ldots, l_{p}}^{(j)}\right)\left(x_{\alpha_{n}} \mid\left[l_{1}\right]_{c} \ldots\left[l_{p}\right]_{c}\left[x_{\beta_{m}}\right]_{c}^{j}\right)
\end{aligned}
$$

where $w=x_{\alpha_{1}}^{h_{1}} \ldots x_{\alpha_{m}}^{h_{m}-1}$. Note that in the first summand, $(w \mid 1)=0$. In the last sum, $\left(x_{\alpha_{n}} \mid\left[l_{1}\right]_{c} \ldots\left[l_{p}\right]_{c}\left[x_{\beta_{m}}\right]_{c}^{j}\right)$ vanishes, because by earlier results $\left[l_{1}\right]_{c} \ldots\left[l_{p}\right]_{c}\left[x_{\beta_{m}}\right]_{c}^{j}$ is a combination of hyperwords of the PBW basis greater or equal than it and an element of $I(V)$, then we use induction hypothesis and the fact that $I(V)$ is the radical of this bilinear form. Since $x_{\alpha_{n}}, x_{\beta_{m}}^{h_{m}-i}$ are different elements of the PBW basis for $h_{m}-i \neq 1$, we have

$$
(u \mid v)=\left(h_{m}\right)_{q_{\beta_{m}}}\left(w \mid x_{\beta_{1}}^{h_{1}} \ldots x_{\beta_{m-1}}^{h_{m-1}} x_{\beta_{m}}^{h_{m}-1}\right)\left(x_{\alpha_{n}} \mid x_{\beta_{m}}\right)
$$

This is clearly zero if $\alpha_{n} \neq \beta_{m}$. To see that it is zero also if $\alpha_{n}=\beta_{m}$, note that in that case $w$ and $x_{\beta_{1}}^{h_{1}} \ldots x_{\beta_{m-1}}^{h_{m-1}} x_{\beta_{m}}^{h_{m}-1}$ are different products of PBW generators, and use the induction hypothesis.

Corollary 5.2. If $\alpha \in \Delta^{+}(\mathfrak{B}(V))$, then $x_{\alpha}^{N_{\alpha}}=0$.

Proof. Let $\left(q_{i j}\right)$ be symmetric. If $u=x_{\alpha_{1}}^{j_{1}} \ldots x_{\alpha_{n}}^{j_{n}}, x_{\alpha_{1}}>\cdots>x_{\alpha_{n}}$, then

$$
\begin{equation*}
(u \mid u)=\prod_{i=1}^{n}\left(j_{i}\right)_{q_{\alpha_{i}}}!\left(x_{\alpha_{i}} \mid x_{\alpha_{i}}\right)^{j_{i}}, \tag{5-2}
\end{equation*}
$$

where $\left(x_{\alpha} \mid x_{\alpha}\right) \neq 0$ for all $\alpha \in \Delta^{+}(\mathfrak{B}(V))$.
If we consider $u=x_{\alpha}^{N_{\alpha}}$, we have $(u \mid v)=0$ for each $v$ in the PBW basis (because $v$ is an ordered product of $x_{\beta}$ 's different from $u$ ), and $(u \mid u)=0$ since $q_{\alpha} \in \mathbb{G}_{N_{\alpha}}$. Also, $\left(I(V) \mid x_{\alpha}^{N_{\alpha}}\right)=0$, because it is the radical of this bilinear form, so $\left(T(V) \mid x_{\alpha}^{N_{\alpha}}\right)=0$, and then $x_{\alpha}^{N_{\alpha}} \in I(V)$. That is, we have $x_{\alpha}^{N_{\alpha}}=0$ in $\mathfrak{B}(V)$.

For the general case, recall that a diagonal braiding is twist equivalent to a braiding with a symmetric matrix [Andruskiewitsch and Schneider 2002a, Theorem 4.5]. Also, there exists a linear isomorphism between the corresponding Nichols algebras. The corresponding $x_{\alpha}$ are related by a nonzero scalar, because they are an iteration of braided commutators between the hyperwords.

In what follows, $\mathfrak{J}$ denotes the family of $\mathbb{Z}^{\theta}$-graded (hence $\mathbb{N}$-graded) ideals of $T(V)$ that are generated by their components of degree $>1$. For each $I \in \mathfrak{J}$, $\mathfrak{B}=T(V) / I$ is a $\mathbb{Z}^{\theta}$-graded algebra such that $\mathfrak{B}^{0}=\mathrm{k} 1$ and $\mathfrak{B}^{1} \simeq V$.

We shall need some technical results about graded algebras between $T(V)$ and $\mathfrak{B}(V)$. We start with three lemmas dealing with the presence of some important roots in $\Delta(\mathfrak{B})$. Remember that a Lyndon word is a PBW generator in $\mathfrak{B}=T(V) / I$ if it is not a linear combination of greater words modulo $I$ in $T(V)$. We shall relate the absence of some roots in $\Delta(\mathfrak{B})$ (meaning that the Lyndon words of such degrees are linear combinations of greater words modulo $I$ ) with the validity of certain relations in $\mathfrak{B}$.

Lemma 5.3. Let $i, j \in\{1, \ldots, \theta\}$ be distinct, and consider $I \in \mathfrak{J}, \mathfrak{B}=T(V) / I$. Let $D_{k}, k=1, \ldots, \theta$, be skew derivations of $\mathfrak{B}$ as in Proposition 2.1, and assume that $x_{i}^{N}=0$ if $q_{i i}^{n} q_{i j} q_{j i} \neq 1$ for all $n \in \mathbb{N}_{0}$ (where $\left.N=\operatorname{ord} q_{i i}\right)$.

There exists $m \in \mathbb{N}$ such that $x_{i}^{m} x_{j}$ is a linear combination of greater hyperwords (for a fixed order such that $x_{i}<x_{j}$ ) modulo I if and only if, in $\mathfrak{B}$.

$$
\begin{equation*}
\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i j}+1} x_{j}=0 \tag{5-3}
\end{equation*}
$$

Proof. If $\left(\mathrm{ad}_{c} x_{i}\right)^{m} x_{j}=0$, there exist $a_{k} \in \mathrm{k}$ such that

$$
0=\left[x_{i}^{m} x_{j}\right]_{c}=\left(\operatorname{ad}_{c} x_{i}\right)^{m} x_{j}=x_{i}^{m} x_{j}+\sum_{k=0}^{m-1} a_{k} x_{i}^{k} x_{j} x_{i}^{m-k}
$$

Conversely, suppose there exists $m \in \mathbb{N}$ such that $x_{i}^{m} x_{j}$ is a linear combination of greater hyperwords modulo $I$. Let

$$
n=\min \left\{m \in \mathbb{N}: x_{i}^{m} x_{j} \text { is a linear combination of greater hyperwords }\right\} .
$$

If $x_{i}^{n}=0$, then $q_{i i}$ is a root of unity. In this case, if $N$ is the order of $q_{i i}$, then $x_{i}^{N}=0$ and $x_{i}^{N-1} \neq 0$. Also,

$$
\left(\operatorname{ad}_{c} x_{i}\right)^{N} x_{j}=x_{i}^{N} x_{j}+\sum_{s=1}^{N-1}\binom{N}{s}_{q_{i i}}+x_{j} x_{i}^{N}=0
$$

because $\binom{N}{s}_{q_{i i}}=0$ for $0<s<N$. Hence, we can assume $x_{i}^{n} \neq 0$ and $(n)_{q_{i i}}!\neq 0$.
Note that $\left[x_{i}^{n-k} x_{j} x_{i}^{k}\right]_{c}=\left[x_{i}^{n-k} x_{j}\right]_{c} x_{i}^{k}$. Since $\mathfrak{B}$ is graded, $x_{i}^{n} x_{j}$ is a linear combination of terms $x_{i}^{n-k} x_{j} x_{i}^{k}, 0 \leq k<n$. Hence there exist $\alpha_{k} \in \mathrm{k}$ such that

$$
\left[x_{i}^{n} x_{j}\right]_{c}=\sum_{k=1}^{n} \alpha_{k}\left[x_{i}^{n-k} x_{j}\right]_{c} x_{i}^{k} .
$$

Applying $D_{i}$ we obtain

$$
0=D_{i}\left(\left[x_{i}^{n} x_{j}\right]_{c}\right)=\sum_{k=1}^{n} \alpha_{k} D_{i}\left(\left[x_{i}^{n-k} x_{j}\right]_{c} x_{i}^{k}\right)=\sum_{k=1}^{n} \alpha_{k}(k)_{q_{i i}}\left[x_{i}^{n-k} x_{j}\right]_{c} x_{i}^{k}
$$

By the hypothesis about $n, \alpha_{1}=0$. Since $(n)_{q_{i}}!\neq 0$, applying $D_{i}$ several times we conclude that $\alpha_{k}=0$ for $k=2, \ldots, n$. Hence $\left[x_{i}^{n} x_{j}\right]_{c}=0$.

Recall that (5-3) holds in $\mathfrak{B}(V)$, for $1 \leq i \neq j \leq \theta$.
The second lemma is related to Dynkin diagrams of a standard braiding which have two consecutive simple edges.

Lemma 5.4. Let $I \in \mathfrak{J}$ and $\mathfrak{B}=T(V) / I$. Assume that

- there exist skew derivations $D_{k}$ in $\mathfrak{B}$ as in Proposition 2.1;
- there exist different $j, k, l \in\{1, \ldots, \theta\}$ such that $m_{k j}=m_{k l}=1, m_{j l}=0$;
- $\left(\operatorname{ad} x_{k}\right)^{2} x_{j}=\left(\operatorname{ad} x_{k}\right)^{2} x_{l}=\left(\operatorname{ad} x_{j}\right) x_{l}=0$ hold in $\mathfrak{B}$;
- $x_{k}^{2}=0$ if $q_{k k} q_{k j} q_{j k} \neq 1$ or $q_{k k} q_{k l} q_{l k} \neq 1$.
(1) If we order the letters $x_{1}, \ldots, x_{\theta}$ such that $x_{j}<x_{k}<x_{l}$, then $x_{j} x_{k} x_{l} x_{k}$ is a linear combination of greater words modulo I if and only if, in $\mathfrak{B}$,

$$
\begin{equation*}
\left[\left(\operatorname{ad} x_{j}\right)\left(\operatorname{ad} x_{k}\right) x_{l}, x_{k}\right]_{c}=0 \tag{5-4}
\end{equation*}
$$

(2) If $V$ is standard and $q_{k k} \neq-1$, then (5-4) holds in $\mathfrak{B}$.
(3) If $V$ is standard and $\operatorname{dim} \mathfrak{B}(V)<\infty$, then (5-4) holds in $\mathfrak{B}=\mathfrak{B}(V)$.

Proof. (1) $(\Leftarrow)$ If (5-4) holds, then $x_{j} x_{k} x_{l} x_{k}$ is a linear combination of greater words, by Remark 1.7, and

$$
\left[x_{j} x_{k} x_{l} x_{k}\right]_{c}=\left[\left[x_{j} x_{k} x_{l}\right]_{c}, x_{k}\right]_{c}=\left[\left(\operatorname{ad} x_{j}\right)\left(\operatorname{ad} x_{k}\right) x_{l}, x_{k}\right]_{c} .
$$

$(\Rightarrow)$ If $x_{j} x_{k} x_{l} x_{k}$ is a linear combination of greater words, then the hyperword $\left[x_{j} x_{k} x_{l} x_{k}\right]_{c}$ is a linear combination of hyperwords corresponding to words greater than $x_{j} x_{k} x_{l} x_{k}$ (of the same degree, because $\mathfrak{B}$ is homogeneous); this follows from Remark 1.7. Since $\left(\operatorname{ad} x_{k}\right)^{2} x_{j}=\left(\operatorname{ad} x_{k}\right)^{2} x_{l}=\left(\operatorname{ad} x_{j}\right) x_{l}=0$, we do not consider hyperwords with $x_{j} x_{k}^{2}, x_{k}^{2} x_{l}$ and $x_{j} x_{l}$ as factors of the corresponding words. Then [ $\left.x_{j} x_{k} x_{l} x_{k}\right]_{c}$ is a linear combination of

$$
\begin{aligned}
{\left[x_{k} x_{l} x_{k} x_{j}\right]_{c} } & =\left[x_{k} x_{l}\right]_{c} x_{k} x_{j}, & {\left[x_{l} x_{k} x_{j} x_{k}\right]_{c} } & =x_{l} x_{k}\left[x_{j} x_{k}\right]_{c}, \\
{\left[x_{k} x_{j} x_{k} x_{l}\right]_{c} } & =x_{k}\left[x_{j} x_{k} x_{l}\right]_{c}, & {\left[x_{l} x_{k}^{2} x_{j}\right]_{c} } & =x_{l} x_{k}^{2} x_{j} .
\end{aligned}
$$

Since $D_{j}\left(\left[x_{j} x_{k} x_{l} x_{k}\right]_{c}\right)=D_{j}\left(x_{k}\left[x_{j} x_{k} x_{l}\right]_{c}\right)=D_{j}\left(x_{l} x_{k}\left[x_{j} x_{k}\right]_{c}\right)=0$, in that linear combination there are no hyperwords ending in $x_{j}$; indeed,

$$
D_{j}\left(\left[x_{k} x_{l}\right]_{c} x_{k} x_{j}\right)=\left[x_{k} x_{l}\right]_{c} x_{k}, \quad D_{j}\left(x_{l} x_{k}^{2} x_{j}\right)=x_{l} x_{k}^{2}
$$

and $\left[x_{k} x_{l}\right]_{c} x_{k}, x_{l} x_{k}^{2}$ are linearly independent. Therefore, there exist $\alpha, \beta \in \mathrm{k}$ such that

$$
\left[x_{j} x_{k} x_{l} x_{k}\right]_{c}=\alpha x_{l} x_{k}\left[x_{j} x_{k}\right]_{c}+\beta x_{k}\left[x_{j} x_{k} x_{l}\right]_{c}
$$

Applying $D_{l}$, we have

$$
0=\alpha q_{k j} q_{k k} x_{l}\left[x_{j} x_{k}\right]_{c}+\alpha\left(1-q_{k j} q_{j k}\right) x_{l} x_{k} x_{j}+\beta q_{k k} q_{k j} q_{k l}\left[x_{j} x_{k} x_{l}\right]_{c}
$$

Now $x_{l}\left[x_{j} x_{k}\right]_{c}, x_{l} x_{k} x_{j}$ and $\left[x_{j} x_{k} x_{l}\right]_{c}$ are linearly independent by Lemma 2.7, so $\alpha=\beta=0$.
(2) We assume that some quantum Serre relations hold in $\mathfrak{B}$; using them we get

$$
\begin{aligned}
x_{j} x_{k} x_{l} x_{k}= & q_{k l}^{-1}\left(1+q_{k k}\right)^{-1} x_{j} x_{k}^{2} x_{l}+q_{k k} q_{k j}\left(1+q_{k k}\right)^{-1} x_{j} x_{l} x_{k}^{2} \\
=q_{k k}^{-1} q_{k j}^{-1} q_{k l}^{-1} x_{k} x_{j} x_{k} x_{l}+q_{k k}^{-1} q_{k j}^{-1} q_{k l}^{-1}(1+ & \left.+q_{k k}\right)^{-1} x_{k}^{2} x_{j} x_{l} \\
& +q_{k k} q_{k l} q_{j k}\left(1+q_{k k}\right)^{-1} x_{l} x_{j} x_{k}^{2} .
\end{aligned}
$$

It follows that $x_{k} x_{j} x_{k} x_{l} \notin G_{I}$ for an order such that $x_{j}<x_{k}<x_{l}$. Also, $x_{j} x_{l} x_{k}^{2} \notin G_{I}$, since $\left(\operatorname{ad}_{c} x_{j}\right) x_{l}=0$ and (5-4) is valid by part (1).
(3) If $V$ is a standard braided vector space satisfying the conditions of the lemma, consider $V_{k}$ as the braided vector space obtained transforming by $s_{k}$. Then $\widetilde{m}_{j l}=0$. Therefore $\mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}\left(\mathfrak{B}\left(V_{k}\right)\right)$, so $s_{k}\left(\mathbf{e}_{j}+\mathbf{e}_{l}\right)=2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B}(V))$. It follows that $x_{j} x_{k} x_{l} x_{k}$ is a linear combination of greater words, since it is a Lyndon word when we consider an order such that $x_{j}<x_{k}<x_{l}$.

We now prove two relations involving the double edge in the Dynkin diagram of a standard braiding of type $B_{\theta}$.

Lemma 5.5. Let $I \in \mathfrak{J}$ and $\mathfrak{B}=T(V) / I$. Assume that

- there exist $j \neq k \in\{1, \ldots, \theta\}$ such that $m_{k j}=2, m_{j k}=1$;
- there exist skew derivations as in Proposition 2.1;
- the following relations hold in $\mathfrak{B}$ :

$$
\begin{align*}
& \left(\operatorname{ad} x_{k}\right)^{3} x_{j}=\left(\operatorname{ad} x_{j}\right)^{2} x_{k}=0  \tag{5-5}\\
& x_{k}^{3}=x_{j}^{2}=0 \quad \text { if } q_{k k}^{3}=q_{j j}^{2}=1
\end{align*}
$$

(1) If we order the letters $x_{1}, \ldots, x_{\theta}$ such that $x_{k}<x_{j}$, then $x_{k}^{2} x_{j} x_{k} x_{j}$ is a linear combination of greater words modulo I if and only if, in $\mathfrak{B}$,

$$
\begin{equation*}
\left[\left(\operatorname{ad} x_{k}\right)^{2} x_{j},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c}=0 \tag{5-6}
\end{equation*}
$$

(2) If $V$ is standard, $q_{j j} \neq-1$ and $q_{k k}^{2} q_{k j} q_{j k}=1$, then (5-6) holds in $\mathfrak{B}$.
(3) If $V$ is standard and $\operatorname{dim} \mathfrak{B}(V)<\infty$, then (5-6) holds in $\mathfrak{B}=\mathfrak{B}(V)$.

Proof. $(1)(\Leftarrow)$ If (5-6) holds in $\mathfrak{B}$, then $x_{k}^{2} x_{j} x_{k} x_{j}$ is a linear combination of greater words. This follows from Remark 1.7, and

$$
\left[x_{k}^{2} x_{j} x_{k} x_{j}\right]_{c}=\left[\left[x_{k}^{2} x_{j}\right]_{c},\left[x_{k} x_{j}\right]_{c}\right]_{c}=\left[\left(\operatorname{ad} x_{k}\right)^{2} x_{j},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c}
$$

$(\Rightarrow)$ If $x_{k}^{2} x_{j} x_{k} x_{j}$ is a linear combination of greater words, then $\left[x_{k}^{2} x_{j} x_{k} x_{j}\right]_{c}$ is a linear combination of hyperwords corresponding to words greater than $x_{k}^{2} x_{j} x_{k} x_{j}$ (of the same degree, because $\mathfrak{B}$ is homogeneous).

First, there are no hyperwords whose corresponding words have factors $x_{k}^{3} x_{j}$ or $x_{k} x_{j}^{2}$, by (5-5). Since $\left[x_{k}^{2} x_{j} x_{k} x_{j}\right]_{c} \in \operatorname{ker} D_{k}$ and

$$
\begin{aligned}
D_{k}\left(x_{j}\left[x_{k}^{2} x_{j}\right]_{c} x_{k}\right) & =x_{j}\left[x_{k}^{2} x_{j}\right]_{c} \\
D_{k}\left(\left[x_{k} x_{j}\right]_{c}^{2} x_{k}\right) & =\left[x_{k} x_{j}\right]_{c}^{2}, \\
D_{k}\left(x_{j}\left[x_{k} x_{j}\right]_{c} x_{k}^{2}\right) & =\left(1+q_{k k}\right) x_{j}\left[x_{k} x_{j}\right]_{c} x_{k}
\end{aligned}
$$

in that linear combination there are no hyperwords ending in $x_{k}$, except $x_{j}^{2} x_{k}^{3}$ if $q_{k k} \in \mathbb{G}_{3}$. We consider $q_{j j} \neq-1$ if $q_{k k} \in \mathbb{G}_{3}$, since otherwise $x_{j}^{2} x_{k}^{3}=0$ by assumption. Then there exist $\alpha, \alpha^{\prime} \in \mathrm{k}$ such that

$$
\left[x_{k}^{2} x_{j} x_{k} x_{j}\right]_{c}=\alpha\left[x_{k} x_{j} x_{k}^{2} x_{j}\right]_{c}+\alpha^{\prime} x_{j}^{2} x_{k}^{3}=\alpha\left[x_{k} x_{j}\right]_{c}\left[x_{k}^{2} x_{j}\right]_{c}+\alpha^{\prime} x_{j}^{2} x_{k}^{3}
$$

We prove by direct calculation that $D_{j}\left(\left[x_{k}^{2} x_{j} x_{k} x_{j}\right]_{c}\right)=0$. Applying $D_{j}$ to the previous equality,

$$
\begin{aligned}
0= & \alpha^{\prime}\left(1+q_{j j}\right) x_{j} x_{k}^{3}+\chi\left(\mathbf{e}_{k}+\mathbf{e}_{j}, 2 \mathbf{e}_{k}+\mathbf{e}_{j}\right) \alpha\left(\operatorname{ad} x_{k}\right)^{2}\left(x_{j}\right) x_{k} \\
& +\left(1-q_{k j} q_{j k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) \alpha\left(\operatorname{ad} x_{k}\right)\left(x_{j}\right) x_{k}^{2},
\end{aligned}
$$

where we use that $\left(\operatorname{ad} x_{k}\right)^{3}\left(x_{j}\right)=0$ and

$$
x_{k}\left(\operatorname{ad} x_{k}\right)^{m}\left(x_{j}\right)=\left(\operatorname{ad} x_{k}\right)^{m+1}\left(x_{j}\right)+q_{k k}^{m} q_{k j}\left(\operatorname{ad} x_{k}\right)^{m}\left(x_{j}\right) x_{k}
$$

Since $\left(1-q_{k j} q_{j k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) \neq 0$ and $\left(\operatorname{ad} x_{k}\right)^{2}\left(x_{j}\right) x_{k},\left(\operatorname{ad} x_{k}\right)\left(x_{j}\right) x_{k}^{2}, x_{j} x_{k}^{3}$ are linearly independent, it follows that $\alpha=\alpha^{\prime}=0$.
(2) Using $\left(\operatorname{ad} x_{j}\right)^{2} x_{k}=0$ in the first equality and $\left(\operatorname{ad} x_{k}\right)^{3} x_{j}=0$ in the last expression,

$$
\begin{aligned}
x_{k}^{2} x_{j} x_{k} x_{j} & =\left(1+q_{j j}\right)^{-1} q_{j k}^{-1} x_{k}^{2} x_{j}^{2} x_{k}+\left(1+q_{j j}\right)^{-1} q_{j k} q_{j j} x_{k}^{3} x_{j}^{2} \\
& \in(3)_{q_{k k}}\left(1+q_{j j}\right)^{-1} q_{k j} q_{j k} q_{j j} x_{k}^{2} x_{j} x_{k} x_{j}+\mathrm{k} \mathbb{X}_{>x_{k}^{2} x_{j} x_{k} x_{j}}
\end{aligned}
$$

Suppose that $(3)_{q_{k k}}\left(1+q_{j j}\right)^{-1} q_{k j} q_{j k} q_{j j}=1$; that is, $(3)_{q_{k k}}=\left(1+q_{j j}\right)$. Then $q_{j j}=q_{k k}+q_{k k}^{2}$, so

$$
1=q_{j j} q_{k j} q_{j k}=q_{k k} q_{k j} q_{j k}+q_{k k}^{2} q_{k j} q_{j k}=q_{k k} q_{k j} q_{j k}+1
$$

which is a contradiction since $q_{k k} q_{k j} q_{j k} \in \mathrm{k}^{\times}$. It follows that $x_{k}^{2} x_{j} x_{k} x_{j}$ is a linear combination of greater words, so (5-6) follows by previous item.
(3) If $V$ is a standard braided vector space, and we consider $V_{j}$ as the braided vector space obtained transforming by $s_{j}$, then $\widetilde{m}_{k j}=2$. Therefore, $3 \mathbf{e}_{k}+\mathbf{e}_{j} \notin \Delta^{+}\left(\mathfrak{B}\left(V_{k}\right)\right)$, so $s_{j}\left(3 \mathbf{e}_{k}+\mathbf{e}_{j}\right)=3 \mathbf{e}_{k}+2 \mathbf{e}_{j} \notin \Delta^{+}(\mathfrak{B}(V))$. Since $x_{k}^{2} x_{j} x_{k} x_{j}$ is a Lyndon word of degree $3 \mathbf{e}_{k}+2 \mathbf{e}_{j}$ if $x_{k}<x_{j}$, then it is a linear combination of greater words.

Lemma 5.6. Let $I \in \mathfrak{J}$ and $\mathfrak{B}=T(V) / I$. Assume that

- there exist different $j, k, l \in\{1, \ldots, \theta\}$ such that $m_{k j}=2, m_{j k}=m_{j l}=m_{l j}=1$, $m_{k l}=0$;
- there exist skew derivations in $\mathfrak{B}$ as in Proposition 2.1;
- the following relations hold in $\mathfrak{B}:(5-4),(5-6)$,

$$
\begin{align*}
& \left(\operatorname{ad} x_{k}\right)^{3} x_{j}=\left(\operatorname{ad} x_{j}\right)^{2} x_{k}=\left(\operatorname{ad} x_{j}\right)^{2} x_{l}=\left(\operatorname{ad} x_{k}\right) x_{l}=0, \\
& x_{k}^{3}=x_{j}^{2}=0 \text { if } q_{k k}^{3}=q_{j j}^{2}=1 \tag{5-7}
\end{align*}
$$

(1) If we order the letters $x_{1}, \ldots, x_{\theta}$ so that $x_{k}<x_{j}<x_{l}$, then $x_{k}^{2} x_{j} x_{l} x_{k} x_{j}$ is a linear combination of greater words modulo I if and only if, in $\mathfrak{B}$,

$$
\begin{equation*}
\left[\left(\operatorname{ad} x_{k}\right)^{2}\left(\operatorname{ad} x_{j}\right) x_{l},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c}=0 \tag{5-8}
\end{equation*}
$$

(2) If $V$ is a standard braided vector space and $q_{k k} \notin \mathbb{G}_{3}, q_{j j} \neq-1$, then (5-8) holds in $\mathfrak{B}$.
(3) If $V$ is standard and $\operatorname{dim} \mathfrak{B}(V)<\infty$, then (5-8) holds in $\mathfrak{B}(V)$.

Proof. (1) $(\Leftarrow)$ As in the last two lemmas, if (5-8) is valid, then $x_{k}^{2} x_{j} x_{l} x_{k} x_{j}$ is a linear combination of greater words, by Remark 1.7, and

$$
\left[x_{k}^{2} x_{j} x_{l} x_{k} x_{j}\right]_{c}=\left[\left(\operatorname{ad} x_{k}\right)^{2}\left(\operatorname{ad} x_{j}\right) x_{l},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c} .
$$

$(\Rightarrow)$ Suppose that $x_{k}^{2} x_{j} x_{l} x_{k} x_{j}$ is a linear combination of greater words. Then [ $\left.x_{k}^{2} x_{j} x_{l} x_{k} x_{j}\right]_{c}$ is a linear combination of hyperwords corresponding to words greater than $x_{k}^{2} x_{j} x_{l} x_{k} x_{j}$ (of the same degree, because $\mathfrak{B}$ is homogeneous). We discard those words which have $x_{k} x_{l}, x_{k}^{3} x_{j}, x_{k} x_{j}^{2}, x_{j}^{2} x_{l}, x_{k} x_{j} x_{l} x_{j}$ and $x_{k}^{2} x_{j} x_{k} x_{j}$, in view of our hypotheses about $\mathfrak{B}$.

Since $D_{k}\left(\left[x_{k}^{2} x_{j} x_{l} x_{k} x_{j}\right]_{c}\right)=0$, the coefficients of hyperwords corresponding to words ending in $x_{k}$ are 0 , as in Lemma 5.5, except for $\left[x_{j} x_{l}\right]_{c} x_{j} x_{k}^{3}, x_{l} x_{j}^{2} x_{k}^{3}$, if $q_{k k} \in \mathbb{G}_{3}$. Thus

$$
\begin{aligned}
{\left[x_{k}^{2} x_{j} x_{l} x_{k} x_{j}\right]_{c}=\alpha\left[x_{k} x_{j}\right]_{c}\left[x_{k}^{2} x_{j} x_{l}\right]_{c} } & +\beta\left[x_{k} x_{j} x_{l}\right]_{c}\left[x_{k}^{2} x_{j}\right]_{c} \\
& +\gamma x_{l}\left[x_{k} x_{j}\right]_{c}\left[x_{k}^{2} x_{j}\right]_{c}+\mu\left[x_{j} x_{l}\right]_{c} x_{j} x_{k}^{3}+v x_{l} x_{j}^{2} x_{k}^{3}
\end{aligned}
$$

By direct calculation, $D_{j}\left(\left[x_{k}^{2} x_{j} x_{l} x_{k} x_{j}\right]_{c}\right)=D_{j}\left(\left[x_{k}^{2} x_{j} x_{l}\right]_{c}\right)=D_{j}\left(\left[x_{k} x_{j} x_{l}\right]_{c}\right)=0$, so applying $D_{j}$ to the previous equality we get

$$
\begin{aligned}
& 0=\alpha q_{j k}^{2} q_{j j} q_{j l} x_{j}\left[x_{k}^{2} x_{j} x_{l}\right]_{c}+\beta\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k k}^{2} q_{k j} q_{j k}\right)\left[x_{k} x_{j} x_{l}\right]_{c} x_{k}^{2} \\
& +\gamma\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k k}^{2} q_{k j} q_{j k}\right) x_{l}\left[x_{k} x_{j}\right]_{c} x_{k}^{2}+\gamma q_{j k}^{2} q_{j j} x_{l} x_{j}\left[x_{k}^{2} x_{j}\right]_{c} \\
& +\mu\left[x_{j} x_{l}\right]_{c} x_{k}^{3}+v\left(1+q_{j j}\right) x_{l} x_{j} x_{k}^{3}
\end{aligned}
$$

Note that $v=0$ if $q_{j j} \neq-1$; otherwise, $x_{j}^{2}=0$ by hypothesis, so we can discard this last summand. The other hyperwords appearing in this expression are linearly independent, since the corresponding words are linearly independent by Lemma 2.7. Thus $\alpha=\beta=\gamma=\mu=0$.
(2) If $q_{k k} \notin \mathbb{G}_{3}$ and $q_{j j} \neq-1$, then $x_{k}^{2} x_{j} x_{l} x_{k} x_{j}$ is a linear combination of greater words, as can be seen using the quantum Serre relations in a way similar to that in Lemma 5.6. Now apply part (1).
(3) If $V$ is a standard braided vector space, consider $V_{k}$ as the braided vector space obtained transforming by $s_{k}$. Then $\widetilde{m}_{k j}=2$. Therefore, $\mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}\left(\mathfrak{B}\left(V_{k}\right)\right)$ by Lemma 5.5, so $s_{k}\left(\mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}\right)=3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B}(V))$. Since $x_{k}^{2} x_{j} x_{l} x_{k} x_{j}$ is a Lyndon word, it follows that it is a linear combination of greater words, and we apply (1).

We now give explicit formulas for the comultiplication of these hyperwords.
Lemma 5.7. Consider the structure of graded braided Hopf algebra of $T(V)$ (see Section 2A). For all $k \neq j$,

$$
\begin{align*}
\Delta\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)=\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j} \otimes 1 & +1 \otimes\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j} \\
& +\prod_{1 \leq t \leq m_{k j}}\left(1-q_{k k}^{t} q_{k j} q_{j k}\right) x_{k}^{m_{i j}+1} \otimes x_{j} \tag{5-9}
\end{align*}
$$

Proof. We have $F_{k}\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)=0$ by the definition of $m_{k j}$ and (2-5). Also, $F_{l}\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)$ for $l \neq k$ by (2-6) and the properties of $F_{l}$, so

$$
\Delta_{1, m_{k j}}\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)=\sum_{l=1}^{\theta} x_{l} \otimes F_{l}\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)=0 .
$$

Now $D_{k}\left(\left[x_{k}^{i} x_{j}\right]_{c} x_{k}^{s-i}\right)=0$ from (2-3), and from (2-4)

$$
D_{j}\left(\left[x_{k}^{i} x_{j}\right]_{c} x_{k}^{s-i}\right)=\prod_{1 \leq t \leq m_{k j}}\left(1-q_{k k}^{t} q_{k j} q_{j k}\right) x_{k}^{m_{i j}+1}
$$

so we deduce that

$$
\Delta_{m_{k j}, 1}\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)=\prod_{1 \leq t \leq m_{k j}}\left(1-q_{k k}^{t} q_{k j} q_{j k}\right) x_{k}^{m_{i j}+1} \otimes x_{j}
$$

Since hyperwords form a basis of $T(V)$, we can write, for each $1<s<m_{k j}$,

$$
\begin{aligned}
& \Delta_{m_{k j}+1-s, s}\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right) \\
&=\sum_{t=0}^{m_{k j}+1-s} \varepsilon_{s t}\left[x_{k}^{t} x_{j}\right]_{c} x_{k}^{m_{k j}+1-s-t} \otimes x_{k}^{s}+\sum_{p=0}^{s} \rho_{s p} x_{k}^{m_{k j}+1-s} \otimes\left[x_{k}^{s-p} x_{j}\right]_{c} x_{k}^{p}
\end{aligned}
$$

for some $\varepsilon_{s t}, \rho_{s p} \in \mathrm{k}$. Then, for each $0 \leq t \leq m_{k j}+1-s$,

$$
\begin{aligned}
0 & =\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j} \mid\left[x_{k}^{t} x_{j}\right]_{c} x_{k}^{m_{k j}+1-t} x_{k}^{s}\right) \\
& =\left(\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)_{(1)} \mid\left[x_{k}^{t} x_{j}\right]_{c} x_{k}^{m_{k j}+1-t-s}\right)\left(\left(\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j}\right)_{(2)} \mid x_{k}^{s}\right) \\
& =\varepsilon_{s t}\left(\left[x_{k}^{t} x_{j}\right]_{c} x_{k}^{m_{k j}+1-t-s} \mid\left[x_{k}^{t} x_{j}\right]_{c} x_{k}^{m_{k j}+1-t-s}\right)\left(x_{k}^{s} \mid x_{k}^{s}\right) \\
& =\varepsilon_{s t}\left(m_{k j}+1-s-t\right)_{q_{k k}}!(s)_{q_{k k}}!\left(\left[x_{k}^{t} x_{j}\right]_{c} \mid\left[x_{k}^{t} x_{j}\right]_{c}\right),
\end{aligned}
$$

where we have used that $\left(\operatorname{ad} x_{k}\right)^{m_{k j}+1} x_{j} \in I(V)$ for the first equality, (1-8) for the second, (1-10) and the orthogonality between increasing products of hyperwords for the third, and (5-2) for the last. Since

$$
\left(m_{k j}+1-s-t\right)_{q_{k k}}!(s)_{q_{k k}}!\left(\left[x_{k}^{t} x_{j}\right]_{c} \mid\left[x_{k}^{t} x_{j}\right]_{c}\right) \neq 0
$$

we conclude that $\varepsilon_{s t}=0$ for all $0 \leq t \leq m_{k j}+1-s$. In a similar way, $\rho_{s p}=0$ for all $0 \leq p \leq s$, so we obtain (5-9).
Lemma 5.8. Let $\mathfrak{B}$ be a braided graded Hopf algebra provided with an inclusion of braided vector spaces $V \hookrightarrow \mathscr{P}(\mathfrak{B})$. Assume that

- there exist $1 \leq j \neq k \neq l \leq \theta$ such that $m_{k j}=m_{k l}=1, m_{j l}=0$;
- $\left(\operatorname{ad} x_{k}\right)^{2} x_{j}=\left(\operatorname{ad} x_{k}\right)^{2} x_{l}=\left(\operatorname{ad} x_{j}\right) x_{l}=0$ in $\mathfrak{B}$;
- $x_{k}^{2}=0$ if $q_{k k} q_{k j} q_{j k} \neq 1$ or $q_{k k} q_{k l} q_{l k} \neq 1$.

Then $u:=\left[\left(\operatorname{ad} x_{j}\right)\left(\operatorname{ad} x_{k}\right) x_{l}, x_{k}\right]_{c} \in \mathscr{P}(\mathfrak{B})$.

Proof. From (2-3), $D_{j}(u)=0$. Also, $D_{k}\left(\left(\operatorname{ad} x_{j}\right)\left(\operatorname{ad} x_{k}\right) x_{l}\right)=0$, so

$$
D_{k}(u)=\left(1-q_{k k}^{2} q_{j k} q_{k j} q_{k l} q_{l k}\right)\left(\operatorname{ad} x_{j}\right)\left(\operatorname{ad} x_{k}\right) x_{l}=0
$$

From (2-4) and the properties of $D_{l}$ we have

$$
\begin{aligned}
D_{l}(u) & =q_{l k}\left(1-q_{k l} q_{l k}\right)\left[x_{j} x_{k}\right]_{c} x_{k}-q_{j k} q_{k k} q_{l k}\left(1-q_{k l} q_{l k}\right) x_{k}\left[x_{j} x_{k}\right]_{c} \\
& =q_{l k}\left(1-q_{l k} q_{k l}\right)\left[\left[x_{j} x_{k}\right]_{c}, x_{k}\right]_{c}=0 .
\end{aligned}
$$

Then $\Delta_{31}(u)=0$. From (2-6) and the properties of $F_{k}$ and $F_{l}$, we have $F_{k}(u)=$ $F_{l}(u)=0$. Using (2-5), we have

$$
\begin{aligned}
F_{j}(u) & =\left(1-q_{j k} q_{k j}\right)\left[x_{k} x_{l}\right]_{c} x_{k}-q_{j k} q_{k k} q_{l k} q_{k j}\left(1-q_{j k} q_{k j}\right) x_{k}\left[x_{k} x_{l}\right]_{c} \\
& =\left(1-q_{l k} q_{k l}\right)\left(1-q_{k j} q_{j k} q_{k k}^{2} q_{l k} q_{j k}\right)\left[x_{k} x_{l}\right]_{c} x_{k}=0 .
\end{aligned}
$$

Thus $\Delta_{13}(u)=0$ as well.
Also, we have

$$
\Delta(u)=\Delta\left(\left(\operatorname{ad} x_{j}\right)\left(\operatorname{ad} x_{k}\right) x_{l}\right) \Delta\left(x_{k}\right)-q_{\mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{j}, \mathbf{e}_{j}} \Delta\left(x_{k}\right) \Delta\left(\left(\operatorname{ad} x_{j}\right)\left(\operatorname{ad} x_{k}\right) x_{l}\right)
$$

and looking at the terms in $\mathfrak{B}^{2} \otimes \mathfrak{B}^{2}$,

$$
\begin{aligned}
& \Delta_{2,2}(u)=\left(1-q_{l k} q_{k l}\right)\left[x_{j} x_{k}\right]_{c} \otimes\left(x_{l} x_{k}-q_{k j} q_{j k} q_{k k}^{2} q_{l k} x_{k} x_{l}\right) \\
& \quad+\left(1-q_{k j} q_{j k}\right) q_{l k} q_{k k}\left(x_{j} x_{k}-q_{j k} x_{k} x_{j}\right) \otimes\left[x_{k} x_{l}\right]_{c} \\
&=\left(1-q_{k j} q_{j k}-\left(1-q_{l k} q_{k l}\right) q_{k k} q_{j k} q_{k j}\right) q_{l k} q_{k k}\left[x_{j} x_{k}\right]_{c} \otimes\left[x_{k} x_{l}\right]_{c} .
\end{aligned}
$$

Now a calculation shows that $u \in \mathscr{P}(\mathfrak{B})$ :

$$
\begin{aligned}
1-q_{k j} q_{j k}-\left(1-q_{l k} q_{k l}\right) q_{k k} q_{j k} q_{k j} & =1-q_{k j} q_{j k}-q_{k k} q_{j k} q_{k j}+q_{k k}^{-1} \\
& =q_{k k}^{-1}\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right)=0
\end{aligned}
$$

Lemma 5.9. Let $\mathfrak{B}$ be a braided graded Hopf algebra provided with an inclusion of braided vector spaces $V \hookrightarrow \mathscr{P}(\mathfrak{B})$. Assume that

- there exist $1 \leq k \neq j \leq \theta$ such that $m_{k j}=2, m_{j k}=1$;
- $\left(\operatorname{ad} x_{s}\right)^{m_{s t}+1} x_{t}=0$, for all $1 \leq s \neq t \leq \theta$ in $\mathfrak{B}$;
- $x_{s}^{m_{s t}+1}=0$ for each $s$ such that $q_{s s}^{m_{s t}} q_{s t} q_{t s} \neq 1$, for some $t \neq s$.
(a) If $v:=\left[\left(\operatorname{ad} x_{k}\right)^{2} x_{j},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c}$, there exists $b \in \mathrm{k}$ such that

$$
\begin{equation*}
\Delta(v)=v \otimes 1+1 \otimes v+b\left(1-q_{k k}^{2} q_{k j}^{2} q_{j k}^{2} q_{j j}\right) x_{k}^{3} \otimes x_{j}^{2} \tag{5-10}
\end{equation*}
$$

(b) Assume there exist $l \neq j, k$ such that $m_{j l}=m_{l j}=1, m_{k l}=m_{l k}=0$, and that (5-4) is valid in $\mathfrak{B}$. Set

$$
w:=\left[\left(\operatorname{ad} x_{k}\right)^{2}\left(\operatorname{ad} x_{j}\right) x_{l},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c}
$$

Then there exist constants $b_{1}, b_{2} \in \mathrm{k}$ such that

$$
\begin{equation*}
\Delta(w)=w \otimes 1+1 \otimes w+b_{1} v \otimes x_{l}+b_{2}\left(1-q_{k k}^{2} q_{k j} q_{j k}\right) x_{k}^{3} \otimes\left(\left(\operatorname{ad} x_{j}\right) x_{l}\right) x_{j} \tag{5-11}
\end{equation*}
$$

Proof. (a) $F_{j}(v)=0$ since $v$ is a braided commutator of two elements in $\operatorname{ker} F_{j}$. Using (1-4) we have $\left[\left(\operatorname{ad} x_{k}\right)^{2} x_{j}, x_{j}\right]_{c}=q_{k j}\left(q_{j j}-q_{k k}\right)\left[x_{k} x_{j}\right]_{c}^{2}$, so we calculate

$$
\begin{aligned}
F_{k}(v)= & \left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right)\left[x_{k} x_{j}\right]_{c}^{2}-q_{k k}^{2} q_{k j}^{2} q_{j k} q_{j j}\left(1-q_{k j} q_{j k}\right) x_{j}\left[x_{k}^{2} x_{j}\right]_{c} \\
& +q_{k k}^{2} q_{j k}\left(1-q_{k j} q_{j k}\right)\left[x_{k}^{2} x_{j}\right]_{c} x_{j}-q_{k k}^{3} q_{k j}^{2} q_{j k}^{2} q_{j j}\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right)\left[x_{k} x_{j}\right]_{c}^{2} \\
= & q_{k k}^{2} q_{j k} q_{k j}\left(1-q_{k j} q_{j k}\right)\left(q_{j j}-q_{k k}\right) \\
& \quad+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k k}^{3} q_{k j}^{2} q_{j k}^{2} q_{j j}\right)\left[x_{k} x_{j}\right]_{c}^{2},
\end{aligned}
$$

which vanishes since the coefficient of $\left[x_{k} x_{j}\right]_{c}^{2}$ is zero for each possible braiding. Thus

$$
\Delta_{1,4}(v)=x_{k} \otimes F_{k}(v)=0
$$

Also, $D_{k}(v)=0$, and a calculation gives

$$
\begin{aligned}
& D_{j}(v)=\left(1-q_{k j} q_{j k}\right)\left(\left[x_{k}^{2} x_{j}\right] x_{k}+\left(1-q_{k k} q_{k j} q_{j k}\right) q_{j k} q_{j j} x_{k}^{2}\left[x_{k} x_{j}\right]_{c}\right. \\
& \left.\quad-q_{k k}^{2} q_{k j}^{2} q_{j k} q_{j j}\left(1-q_{k k} q_{k j} q_{j k}\right)\left[x_{k} x_{j}\right]_{c} x_{k}^{2}-q_{k k}^{2} q_{k j}^{2} q_{j k}^{3} q_{j j}^{2} x_{k}\left[x_{k}^{2} x_{j}\right]\right) \\
& =\left(1+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k} q_{j j}-q_{k k}^{4} q_{k j}^{3} q_{j k}^{3} q_{j j}^{2}\right) \\
& \quad\left(1-q_{k j} q_{j k}\right)\left[x_{k}^{2} x_{j}\right] x_{k},
\end{aligned}
$$

where we have reordered the hyperwords and used that $\left(\operatorname{ad} x_{k}\right)^{3} x_{j}=0$; also,

$$
\begin{equation*}
1+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k} q_{j j}-q_{k k}^{4} q_{k j}^{3} q_{j k}^{3} q_{j j}^{2}=0 \tag{5-12}
\end{equation*}
$$

by calculation for each possible braiding. Thus

$$
\Delta_{4,1}(v)=D_{j}(v) \otimes x_{j}=0
$$

To finish, we use the fact that $\Delta(v)$ equals

$$
\Delta\left(\left(\operatorname{ad}_{c} x_{k}\right)^{2} x_{j}\right) \Delta\left(\left(\operatorname{ad}_{c} x_{k}\right) x_{j}\right)-\chi\left(2 e_{k}+e_{j}, e_{k}+e_{j}\right) \Delta\left(\left(\operatorname{ad}_{c} x_{k}\right) x_{j}\right) \Delta\left(\left(\operatorname{ad}_{c} x_{k}\right)^{2} x_{j}\right)
$$

Looking at the terms in $\mathfrak{B}^{3} \otimes \mathfrak{B}^{2}$ and $\mathfrak{B}^{2} \otimes \mathfrak{B}^{3}$, and using the definition of the braided commutator, we obtain

$$
\begin{aligned}
& \Delta_{32}(v) \\
& \begin{array}{r}
=\left(1-q_{k k}^{4} q_{k j}^{3} q_{j k}^{3} q_{j j}^{2}\right)\left[x_{k}^{2} x_{j}\right]_{c} \otimes\left[x_{k} x_{j}\right]_{c}
\end{array} \\
& \quad+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k} q_{j j}\left(x_{k}\left[x_{k} x_{j}\right]_{c}-q_{k k} q_{k j}\left[x_{k} x_{j}\right]_{c} x_{k}\right) \otimes\left[x_{k} x_{j}\right]_{c} \\
& \quad+\left(1-q_{k j} q_{j k}\right)^{2}\left(1-q_{k k}^{2} q_{k j} q_{j k}\right)\left(1-q_{k k}^{2} q_{k j}^{2} q_{j k}^{2} q_{j j}\right) x_{k}^{3} \otimes x_{j}^{2} \\
& =\left(1+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k} q_{j j}-q_{k k}^{4} q_{k j}^{3} q_{j k}^{3} q_{j j}^{2}\right)\left[x_{k}^{2} x_{j}\right]_{c} \otimes\left[x_{k} x_{j}\right]_{c} \\
& \\
& +b_{1}\left(1-q_{k k}^{2} q_{k j}^{2} q_{j k}^{2} q_{j j}\right) x_{k}^{3} \otimes x_{j}^{2} .
\end{aligned}
$$

Also,

$$
\begin{aligned}
& \Delta_{23}(v)=\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k j} q_{j k}\right) x_{k}^{2} \\
& \otimes\left(\left(1+q_{k k}\right) q_{k k} q_{j k}\left[x_{k} x_{j}\right]_{c} x_{j}-\right.\left(1+q_{k k}\right) q_{k k}^{2} q_{k j}^{2} q_{j k}^{2} q_{j j} x_{j}\left[x_{k} x_{j}\right]_{c} \\
&\left.+x_{j}\left[x_{k} x_{j}\right]_{c}-q_{k k}^{4} q_{k j}^{2} q_{j k}^{3} q_{j j}\left[x_{k} x_{j}\right]_{c} x_{j}\right) \\
&=\left(1-q_{k k}^{4} q_{k j}^{3} q_{j k}^{3} q_{j j}^{2}+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k} q_{j j}\right)
\end{aligned} \quad \begin{aligned}
\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k j} q_{j k}\right) x_{k}^{2} \otimes x_{j}\left[x_{k} x_{j}\right]_{c} .
\end{aligned}
$$

Using (5-12), we obtain (5-10).
(b) We set $y=\left(\operatorname{ad} x_{k}\right)^{2}\left(\operatorname{ad} x_{j}\right) x_{l}$ and $z=\left(\operatorname{ad} x_{k}\right) x_{j}$. Note that $\Delta(w)=\Delta(y) \Delta(z)-$ $\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) \Delta(z) \Delta(y)$ and that

$$
\begin{aligned}
& \Delta(y)=y \otimes 1+\left(1-q_{j l} q_{l j}\right)\left(\operatorname{ad} x_{k}\right)^{2} x_{j} \otimes x_{l} \\
& \quad+\left(1-q_{k j} q_{j k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) x_{k}^{2} \otimes\left(\operatorname{ad} x_{j}\right) x_{l} \\
& \quad+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) x_{k} \otimes\left(\operatorname{ad} x_{k}\right)\left(\operatorname{ad} x_{j}\right) x_{l}+1 \otimes y,
\end{aligned}
$$

$\Delta(z)=z \otimes 1+\left(1-q_{k j} q_{j k}\right) x_{k} \otimes x_{j}+1 \otimes z$.
From (2-3) we have $D_{k}(w)=0$, and from (2-4),

$$
\begin{aligned}
D_{l}(w) & =\left(1-q_{l j} q_{j l}\right) q_{l k} q_{l j}\left[\left(\operatorname{ad} x_{k}\right)^{2} x_{j},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c} \\
D_{j}(w) & =-\left(1-q_{k j} q_{j k}\right) q_{k k}^{-2} q_{k j}^{-1} q_{k l}^{-1}\left(\operatorname{ad} x_{k}\right)^{3}\left(\operatorname{ad} x_{j}\right) x_{l} \\
& =-\left(1-q_{k j} q_{j k}\right) q_{k k}^{-2} q_{k j}^{-1} q_{k l}^{-1}\left[\left(\operatorname{ad} x_{k}\right)^{3} x_{j}, x_{l}\right]_{c}=0,
\end{aligned}
$$

where in the last equality we used (1-4) and the vanishing of $\left[x_{k}, x_{l}\right]_{c}=0$. It follows that

$$
\Delta_{51}(w)=\left(1-q_{l j} q_{j l}\right) q_{l k} q_{l j}\left[\left(\operatorname{ad} x_{k}\right)^{2} x_{j},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c} \otimes x_{l} .
$$

Also, $F_{j}(z)=F_{j}(y)=F_{l}(z)=F_{l}(y)=0$ by (2-6) and the properties of these skew derivations, so $F_{j}(w)=F_{l}(w)=0$. We now calculate

```
\(F_{k}(w)\)
    \(=\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right)\left[x_{k} x_{j} x_{l}\right]_{c}\left[x_{k} x_{j}\right]_{c}+q_{k k}^{2} q_{j k} q_{l k}\left(1-q_{k j} q_{j k}\right)\left[x_{k}^{2} x_{j} x_{l}\right]_{c} x_{j}\)
        \(-\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right)\)
        \(\left(\left(1-q_{k j} q_{j k}\right) x_{j}\left[x_{k}^{2} x_{j} x_{l}\right]_{c}+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{j k}\left[x_{k} x_{j} x_{l}\right]_{c}\left[x_{k} x_{j}\right]_{c}\right)\)
    \(=q_{k k}^{2} q_{j k} q_{l k}\left(1-q_{k j} q_{j k}\right)\left[\left[x_{k}^{2} x_{j} x_{l}\right]_{c}, x_{j}\right]_{c}\)
                        \(-\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k}^{3} q_{k j}^{2} q_{j k}^{2} q_{j j} q_{l j} q_{l k}\left[\left[x_{k} x_{j}\right]_{c},\left[x_{k} x_{j} x_{l}\right]_{c}\right]_{c}\)
    \(=q_{k k}^{2} q_{k j} q_{j k} q_{j j} q_{l j} q_{l k}\)
        \(\left(1-q_{k j} q_{j k}-\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k}\right)\left[\left[x_{k} x_{j}\right]_{c},\left[x_{k} x_{j} x_{l}\right]_{c}\right]_{c}\)
    \(=0\),
```

where we used (1-4) and (5-4) in the third equality, and we calculate that

$$
\begin{equation*}
1-q_{k j} q_{j k}-\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k}=0 \tag{5-13}
\end{equation*}
$$

for each possible standard braiding. It follows that $\Delta_{15}(w)=0$.
We find each of the other terms of $\Delta(w)$ by direct calculation. First,

$$
\begin{aligned}
& \Delta_{42}(w) \\
& \qquad=\left(1-\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) \chi\left(\mathbf{e}_{k}+\mathbf{e}_{j}, 2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right)\right) y \otimes z \\
&+\left(1-q_{k j} q_{j k}\right)\left(1-q_{l j} q_{j l}\right) \\
& \quad\left(q_{l k}\left[x_{k}^{2} x_{j}\right]_{c} x_{k} \otimes x_{l} x_{j}-\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) q_{j k}^{2} q_{j j} x_{k}\left[x_{k}^{2} x_{j}\right]_{c} \otimes x_{j} x_{l}\right) \\
&+\left(1-q_{k j} q_{j k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) \\
& \quad\left(\chi\left(\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) x_{k}^{2} z-\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) z x_{k}^{2}\right) \otimes\left[x_{j} x_{l}\right]_{c} \\
&=\left(1-q_{k j} q_{j k}\right) q_{l k}\left(1-q_{j k} q_{k j}+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) q_{k k} q_{k j} q_{j k}\right) \\
& \quad\left[x_{k}^{2} x_{j}\right]_{c} x_{k} \otimes\left[x_{j} x_{l}\right]_{c},
\end{aligned}
$$

which is seen to equal 0 . In a similar way we calculate

$$
\begin{aligned}
& \Delta_{33}(w) \\
&=\left(1-q_{l j} q_{j l}\right)\left[x_{k}^{2} x_{j}\right] \otimes\left(x_{l} z-\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) \chi\left(\mathbf{e}_{k}+\mathbf{e}_{j}, \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right) z x_{l}\right) \\
&+\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right) \chi\left(\mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right)\left(x_{k} z-q_{k k} q_{k j} z x_{k}\right) \otimes\left[x_{k} x_{j} x_{l}\right]_{c} \\
&+\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k j} q_{j k}\right)^{2} x_{k}^{3} \\
& \quad \otimes\left(\chi\left(\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}\right)\left[x_{j} x_{l}\right]_{c} x_{j}-\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) \chi\left(\mathbf{e}_{j}, 2 \mathbf{e}_{k}\right) x_{j}\left[x_{j} x_{l}\right]_{c}\right) \\
&=\left(\left(1+q_{k k}\right)\left(1-q_{k k} q_{k j} q_{j k}\right)-q_{k k} q_{k j} q_{j k} q_{j j}\left(1-q_{l j} q_{j l}\right)\right) \\
& \chi\left(\mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right)\left[x_{k}^{2} x_{j}\right]_{c} \otimes\left[x_{k} x_{j} x_{l}\right]_{c} \\
&+\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k j} q_{j k}\right)^{2}\left(1-q_{k k}^{2} q_{k j} q_{j k}\right) x_{k}^{3} \otimes\left[x_{j} x_{l}\right]_{c} x_{j},
\end{aligned}
$$

and the coefficient of $\left[x_{k}^{2} x_{j}\right]_{c} \otimes\left[x_{k} x_{j} x_{l}\right]_{c}$ is zero (we calculate it for each possible standard braiding). Finally,

$$
\begin{aligned}
& \Delta_{24}(w) \\
& =\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k j} q_{j k}\right) x_{k}^{2} \\
& \otimes\left(\left(1+q_{k k}\right) \chi\left(\mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}\right)\left[x_{k} x_{j} x_{l}\right]_{c} x_{j}\right. \\
& -\left(1+q_{k k}\right) \chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) q_{j k} x_{j}\left[x_{k} x_{j} x_{l}\right]_{c} \\
& \left.-\chi\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) \chi\left(\mathbf{e}_{k}+\mathbf{e}_{j}, 2 \mathbf{e}_{k}\right)\left[\left[x_{k} x_{j}\right]_{c},\left[x_{j} x_{l}\right]_{c}\right]_{c}\right) \\
& =\left(1-q_{k k} q_{k j} q_{j k}\right)\left(1-q_{k j} q_{j k}\right) \chi\left(\mathbf{e}_{j}+\mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}\right) q_{k j} \\
& \left(q_{k k}\left(1-q_{k k} q_{k j} q_{j k}\right)-q_{j j}\left(1-q_{j l} q_{l j}\right)\right) x_{k}^{2} \otimes x_{j}\left[x_{k} x_{j} x_{l}\right]_{c} \\
& =0 .
\end{aligned}
$$

From these calculations, we obtain (5-11).

5B. Presentation when the type is $\boldsymbol{A}_{\boldsymbol{\theta}}$. We now assume $V$ is a standard braided vector space of type $A_{\theta}$ and $\mathfrak{B}$ a $\mathbb{Z}^{\theta}$-graded algebra, provided with an inclusion of vector spaces $V \hookrightarrow \mathfrak{B}^{1}=\bigoplus_{1 \leq j \leq \theta} \mathfrak{B}^{\mathbf{e}_{j}}$. We can extend the braiding to $\mathfrak{B}$ by setting

$$
c(u \otimes v)=\chi(\alpha, \beta) v \otimes u, \quad u \in \mathfrak{B}^{\alpha}, v \in \mathfrak{B}^{\beta}, \alpha, \beta \in \mathbb{N}^{\theta}
$$

We assume that on $\mathfrak{B}$ we have

$$
\begin{array}{rl}
x_{i}^{2}=0 & \text { if } q_{i i}=-1, \\
\operatorname{ad}_{c} x_{i}\left(x_{j}\right)=0 & \text { if }|j-i|>1, \\
\left(\operatorname{ad}_{c} x_{i}\right)^{2}\left(x_{j}\right)_{c}=0 & \text { if }|j-i|=1, \\
{\left[\left(\operatorname{ad}_{c} x_{i}\right)\left(\operatorname{ad}_{c} x_{i+1}\right) x_{i+2}, x_{i+1}\right]_{c}=0} & 2 \leq i \leq \theta-1 .
\end{array}
$$

Using the same notation as in Section 4B,

$$
x_{\mathbf{e}_{i}}=x_{i}, \quad x_{\mathbf{u}_{i, j}}:=\left[x_{i}, x_{\mathbf{u}_{i+1, j}}\right]_{c} \quad(i<j) .
$$

Lemma 5.10. Let $1 \leq i \leq j<p \leq r \leq \theta$. The following relations hold in $\mathfrak{B}$ :

$$
\begin{align*}
{\left[x_{\mathbf{u}_{i j}}, x_{\mathbf{u}_{p r}}\right]_{c} } & =0, p-j \geq 2 ;  \tag{5-14}\\
{\left[x_{\mathbf{u}_{i j}}, x_{\mathbf{u}_{j+1, r}}\right]_{c} } & =x_{\mathbf{u}_{i r}} . \tag{5-15}
\end{align*}
$$

Proof. Note that $x_{\mathbf{u}_{p r}}$ belongs to the subalgebra generated by $x_{p}, \ldots, x_{r}$, and $\left[x_{\mathbf{u}_{i j}}, x_{s}\right]_{c}=0$, for each $p \leq s \leq r$. Equation (5-14) follows from this.

We prove (5-15) by induction on $j-i$ : if $i=j$, it is exactly the definition of $x_{\mathbf{u}_{i r}}$. To prove the inductive step, we use the inductive hypothesis, (5-14) and (1-4) (the braided Jacobi identity) to obtain

$$
\begin{aligned}
{\left[x_{\mathbf{u}_{i, j+1}}, x_{\mathbf{u}_{j+2, r}}\right]_{c} } & =\left[\left[x_{\mathbf{u}_{i j}}, x_{i+1}\right]_{c}, x_{\mathbf{u}_{j+2, r}}\right]_{c}=\left[x_{\mathbf{u}_{i j}},\left[x_{i+1}, x_{\mathbf{u}_{j+2, r}}\right]_{c}\right]_{c} \\
& =\left[x_{\mathbf{u}_{i j}}, x_{\mathbf{u}_{j+1, r}}\right]_{c}=x_{\mathbf{u}_{i r} r},
\end{aligned}
$$

and (5-15) is also proved.
Lemma 5.11. If $i<p \leq r<j$, the following relation holds in $\mathfrak{B}$ :

$$
\begin{equation*}
\left[x_{\mathbf{u}_{i j}}, x_{\mathbf{u}_{p r}}\right]_{c}=0 . \tag{5-16}
\end{equation*}
$$

Proof. When $p=r=j-1$ and $i=j-2$, note that this is exactly

$$
\left[\left(\operatorname{ad}_{c} x_{i}\right)\left(\operatorname{ad}_{c} x_{i+1}\right) x_{i+2}, x_{i+1}\right]_{c}=0
$$

Then, by (1-4),

$$
\left[x_{\mathbf{u}_{i-1}, j}, x_{j-1}\right]_{c}=\left[\left[x_{i-1}, x_{\mathbf{u}_{i, j}}\right]_{c}, x_{j-1}\right]_{c}=\left[x_{i-1},\left[x_{\mathbf{u}_{i, j}}, x_{j-1}\right]_{c}\right]_{c} .
$$

We assume that $j-i>2$, so $\left[x_{i-1}, x_{j-1}\right]_{c}=0$ by the hypothesis on $\mathfrak{B}$. Now we prove the case $p=r=j-1$ by induction on $p-i$.

Using (1-4) and (5-15), we also have

$$
\begin{aligned}
{\left[x_{\mathbf{u}_{i, j+1}}, x_{p}\right]_{c}=} & {\left[\left[x_{\mathbf{u}_{i, j}}, x_{j+1}\right]_{c}, x_{p}\right]_{c}=\left[x_{\mathbf{u}_{i, j}},\left[x_{j+1}, x_{p}\right]_{c}\right]_{c} } \\
& +q_{j+1, p}\left[x_{\mathbf{u}_{i, j}}, x_{j-1}\right]_{c} x_{j+1}-\chi\left(\mathbf{u}_{i, j}, \mathbf{e}_{j+1}\right) x_{j+1}\left[x_{\mathbf{u}_{i, j}}, x_{j-1}\right]_{c}
\end{aligned}
$$

so using that $\left[x_{j+1}, x_{p}\right]_{c}=0$ if $j>p$, by induction on $j-p$ we prove (5-16) for the case $p=r$.

For the general case, we use (1-4) one more time as follows

$$
\begin{aligned}
{\left[x_{\mathbf{u}_{i, j}}, x_{\mathbf{u}_{p, r+1}}\right]_{c} } & =\left[x_{\mathbf{u}_{i, j}},\left[x_{\mathbf{u}_{p r}}, x_{r+1}\right]_{c}\right]_{c}=\left[\left[x_{\mathbf{u}_{i, j}}, x_{\mathbf{u}_{p r}}\right]_{c}, x_{r+1}\right]_{c} \\
& -\chi\left(\mathbf{u}_{p r}, \mathbf{e}_{r+1}\right)\left[x_{\mathbf{u}_{i j}}, x_{r+1}\right]_{c} x_{\mathbf{u}_{p r}}+\chi\left(\mathbf{u}_{i j}, \mathbf{u}_{p r}\right) x_{\mathbf{u}_{p r}}\left[x_{\mathbf{u}_{i j}}, x_{r+1}\right]_{c},
\end{aligned}
$$

and we prove (5-16) by induction on $r-p$.
Lemma 5.12. The following relations hold in $\mathfrak{B}$ :

$$
\begin{align*}
{\left[x_{\mathbf{u}_{i j}}, x_{\mathbf{u}_{i p}}\right]_{c}=0 } & \text { if } i \leq j<p,  \tag{5-17}\\
{\left[x_{\mathbf{u}_{i j}}, x_{\mathbf{u}_{p j}}\right]_{c}=0 } & \text { if } i<p \leq j . \tag{5-18}
\end{align*}
$$

Proof. To prove (5-17), note that if $i=j=p-1$, we have

$$
\left[x_{\mathbf{u}_{i i}}, x_{\mathbf{u}_{i, i+1}}\right]_{c}=\left[x_{i},\left[x_{i}, x_{i+1}\right]_{c}\right]_{c}=\left(\operatorname{ad} x_{i}\right)^{2} x_{i+1}=0 .
$$

Since $\left[x_{i}, x_{\mathbf{u}_{i+2, p}}\right]_{c}=0$ for each $p>i+1$ by (5-14), we use (1-4), the previous case and (5-15) to obtain

$$
\left[x_{\mathbf{u}_{i i}}, x_{\mathbf{u}_{i p}}\right]_{c}=\left[x_{\mathbf{u}_{i i}},\left[x_{\mathbf{u}_{i, i+1}}, x_{\mathbf{u}_{i+2, p}}\right]_{c}\right]_{c}=0
$$

Now, if $i<j<p$, from (5-14) and the relations between the $q_{s t}$ we obtain

$$
\left[x_{\mathbf{u}_{i+1, j}}, x_{\mathbf{u}_{i p}}\right]_{c}=-\chi\left(\mathbf{u}_{i p}, \mathbf{u}_{i+1, j}\right)\left[x_{\mathbf{u}_{i p}}, x_{\mathbf{u}_{i+1, j}}\right]_{c}=0 .
$$

Using (1-4) and the previous case we conclude

$$
\left[x_{\mathbf{u}_{i j}}, x_{\mathbf{u}_{i p}}\right]_{c}=\left[\left[x_{\mathbf{u}_{i i}}, x_{\mathbf{u}_{i+1, j}}\right]_{c}, x_{\mathbf{u}_{i p}}\right]_{c}=0
$$

The proof of (5-18) is analogous.
Lemma 5.13. If $i<p \leq r<j$, the following relation holds in $\mathfrak{B}$ :

$$
\begin{equation*}
\left[x_{\mathbf{u}_{i} r}, x_{\mathbf{u}_{p j}}\right]_{c}=\chi\left(\mathbf{u}_{i r}, \mathbf{u}_{p r}\right)\left(1-q_{r, r+1} q_{r+1, r}\right) x_{\mathbf{u}_{p r}} x_{\mathbf{u}_{i j}} . \tag{5-19}
\end{equation*}
$$

Proof. We calculate

$$
\begin{aligned}
{\left[x_{\mathbf{u}_{i r}}, x_{\mathbf{u}_{p j}}\right]_{c} } & =\left[x_{\mathbf{u}_{i r}},\left[x_{\mathbf{u}_{p r}}, x_{\mathbf{u}_{r+1, j}}\right]_{c}\right]_{c} \\
& =\chi\left(\mathbf{u}_{i r}, \mathbf{u}_{p r}\right) x_{\mathbf{u}_{p r}} x_{\mathbf{u}_{i j}}-\chi\left(\mathbf{u}_{p r}, \mathbf{u}_{r+1, j}\right) x_{\mathbf{u}_{i j}} x_{\mathbf{u}_{p r}} \\
& =\left(\chi\left(\mathbf{u}_{i r}, \mathbf{u}_{p r}\right)-\chi\left(\mathbf{u}_{i j}, \mathbf{u}_{p r}\right) \chi\left(\mathbf{u}_{p r}, \mathbf{u}_{r+1, j}\right)\right) x_{\mathbf{u}_{p r}} x_{\mathbf{u}_{i j}} \\
& =\chi\left(\mathbf{u}_{i r}, \mathbf{u}_{p r}\right)\left(1-\chi\left(\mathbf{u}_{p r}, \mathbf{u}_{r+1, j}\right) \chi\left(\mathbf{u}_{r+1, j}, \mathbf{u}_{p r}\right)\right) x_{\mathbf{u}_{p r}} x_{\mathbf{u}_{i j}},
\end{aligned}
$$

where we have used (5-15) in the first equality, (1-4) in the second, (5-18) in the third and the relation between the $q_{i j}$ in the last.

We now prove the main theorem of this subsection, namely, the presentation by generators and relations of the Nichols algebra associated to $V$.
Theorem 5.14. Let $V$ be a standard braided vector space of type $A_{\theta}$, where $\theta=$ $\operatorname{dim} V$, and let $C=\left(a_{i j}\right)_{i, j \in\{1, \ldots, \theta\}}$ be the corresponding Cartan matrix of type $A_{\theta}$.

The Nichols algebra $\mathfrak{B}(V)$ is presented by the generators $x_{i}, 1 \leq i \leq \theta$, and the relations

$$
\begin{array}{rlrl}
x_{\alpha}^{N_{\alpha}} & =0, & \alpha \in \Delta^{+} \\
\operatorname{ad}_{c}\left(x_{i}\right)^{1-a_{i j}}\left(x_{j}\right) & =0, & i \neq j \\
{\left[\left(\operatorname{ad} x_{j-1}\right)\left(\operatorname{ad} x_{j}\right) x_{j+1}, x_{j}\right]_{c}} & =0, & & 1<j<\theta, q_{j j}=-1 .
\end{array}
$$

The following elements constitute a basis of $\mathfrak{B}(V)$ :
$x_{\beta_{1}}^{h_{1}} x_{\beta_{2}}^{h_{2}} \ldots x_{\beta_{P}}^{h_{P}}$, where $0 \leq h_{j}<N_{\beta_{j}}$ where $\beta_{j} \in S_{I}$, for $1 \leq j \leq P$.
Proof. From Corollary 4.2 and the definitions of the $x_{\alpha}$, we know that the last statement about the PBW basis is true.

Let $\mathfrak{B}$ be the algebra presented by generators $x_{1}, \ldots, x_{\theta}$ and the relations in the statement of the theorem. From Lemmas 5.3, 5.4 and Corollary 5.2 we have a canonical epimorphism $\phi: \mathfrak{B} \rightarrow \mathfrak{B}(V)$. The last relation also holds in $\mathfrak{B}$ for $q_{j j} \neq 1$, by Lemma 5.4(2).

The rest is similar to the proofs of [Andruskiewitsch and Dăscălescu 2005, Lemma 3.7] and [Andruskiewitsch and Schneider 2002b, Lemma 6.12]. Consider the subspace $\mathscr{I}$ of $\mathfrak{B}$ generated by the elements in (5-20). Using Lemmas 5.10, $5.11,5.12$ and 5.13 we prove that $\mathscr{I}$ is an ideal. But $1 \in \mathscr{I}$, so $\mathscr{I}=\mathfrak{B}$.

The images under $\phi$ of the elements in (5-20) form a basis of $\mathfrak{B}(V)$, so $\phi$ is an isomorphism.

The presentation and dimension of $\mathfrak{B}(V)$ agree with the results presented in [Andruskiewitsch and Dăscălescu 2005] and [Andruskiewitsch and Schneider 2002b].

5C. Presentation when the type is $\boldsymbol{B}_{\boldsymbol{\theta}}$. We now assume $V$ is a standard braided vector space of type $B_{\theta}$ and $\mathfrak{B}$ is a $\mathbb{Z}^{\theta}$-graded algebra, provided with an inclusion of vector spaces $V \hookrightarrow \mathfrak{B}^{1}=\bigoplus_{1 \leq j \leq \theta} \mathfrak{B}^{\mathbf{e}_{j}}$. Then we can extend the braiding to $\mathfrak{B}$. We assume the following relations in $\mathfrak{B}$ :

$$
\begin{aligned}
x_{i}^{2}=0 & \text { if } q_{i i}=-1 \\
x_{1}^{3}=0 & \text { if } q_{11} \in \mathbb{G}_{3} \\
\left(\operatorname{ad}_{c} x_{i}\right) x_{j}=0 & \text { if }|j-i|>1, \\
\left(\operatorname{ad}_{c} x_{i}\right)^{2} x_{j}=0 & \text { if }|j-i|=1 \text { and } i \neq 1,
\end{aligned}
$$

$$
\begin{aligned}
{\left[\left(\operatorname{ad}_{c} x_{i}\right)\left(\operatorname{ad}_{c} x_{i+1}\right) x_{i+2}, x_{i+1}\right]_{c} } & =0 \quad \text { if } 2 \leq i \leq \theta \\
\left(\operatorname{ad}_{c} x_{1}\right)^{3} x_{2} & =0 \\
{\left[\left(\operatorname{ad}_{c} x_{1}\right)^{2} x_{2},\left(\operatorname{ad}_{c} x_{1}\right) x_{2}\right]_{c} } & =0 \\
{\left[\left(\operatorname{ad} x_{1}\right)^{2}\left(\operatorname{ad} x_{2}\right) x_{3},\left(\operatorname{ad} x_{1}\right) x_{2}\right]_{c} } & =0
\end{aligned}
$$

Using the same notation as in Section 4B,

$$
x_{\mathbf{v}_{i j}}=\left[x_{\mathbf{u}_{1 i}}, x_{\mathbf{u}_{1 j}}\right]_{c}, \quad 1 \leq i<j \leq \theta .
$$

From the proof of the relations corresponding the $A_{\theta}$ case, we know that (5-14), (5-15), (5-16), (5-18) and (5-19) hold for $i \geq 1$, but for relation (5-17) we must assume $i>1$.

Lemma 5.15. Suppose $1 \leq s<t$ and $1<k \leq j$. The following relations hold in $\mathfrak{B}$ :

$$
\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{k j}}\right]_{c} \begin{cases}=0 & \text { if } t+1<k, \\ =x_{\mathbf{v}_{s j}} & \text { if } t+1=k<j, \\ =0 & \text { if } s+1<k \leq j \leq t, \\ =\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{k t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{u}_{k t}} x_{\mathbf{v}_{s j}} & \text { if } s+1<k \leq t<j, \\ =\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{s+1, j}\right) x_{\mathbf{v}_{j t}} & \text { if } s+1=k \leq j<t, \\ =\left(\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{s+1, t}\right)-\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 t}\right)\right) x_{\mathbf{u}_{1 t}}^{2} & \text { if } s+1=k, j=t, \\ \in \mathrm{k} x_{\mathbf{v}_{t j}}+\mathrm{k} x_{\mathbf{u}_{1 j}} x_{\mathbf{u}_{1 t}}+\mathrm{k} x_{\mathbf{u}_{s+1, j}} x_{\mathbf{v}_{s j}} & \text { if } s+1=k \leq t<j, \\ =\gamma_{s t}^{k j} x_{\mathbf{u}_{k s}} x_{\mathbf{v}_{j t}} & \text { if } k \leq s<j \leq t, \\ \in \mathrm{k} x_{\mathbf{u}_{k s}} x_{\mathbf{v}_{t j}}+\mathrm{k} x_{\mathbf{u}_{k s}} x_{\mathbf{u}_{1 j}} x_{\mathbf{u}_{1 t t}}+\mathrm{k} x_{\mathbf{u}_{k t}} x_{\mathbf{v}_{s j}} & \text { if } k \leq s<t<j, \\ =0 & \text { if } k \leq j \leq s,\end{cases}
$$

where $\gamma_{s t}^{k j}=\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{k j}\right) \chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{k s}\right)\left(1-q_{s, s+1} q_{s+1, s}\right)$.
Proof. The first, third and last equalities follow from the vanishing of $\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{u}_{k j}}\right]_{c}$ and $\left[x_{\mathbf{u}_{1 t}}, x_{\mathbf{u}_{k j}}\right]_{c}=0$, using (5-14), (5-16), (5-17) or (5-18) as the case maybe, together with (1-4).

For the second case, we use that $\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{u}_{t+1, j}}\right]_{c}=0$, (5-15) and (1-4) to obtain $x_{\mathbf{v}_{s j}}=\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{u}_{1 j}}\right]_{c}=\left[x_{\mathbf{u}_{1 s}},\left[x_{\mathbf{u}_{1 t}}, x_{\mathbf{u}_{t+1, j}}\right]_{c}\right]_{c}=\left[\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{u}_{1 t}}\right]_{c}, x_{\mathbf{u}_{t+1, j}}\right]_{c}=\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{t+1, j}}\right]_{c}$.

For the fourth, we use (1-4) and the third case to calculate

$$
\begin{aligned}
{\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{k j}}\right]_{c} } & =\left[x_{\mathbf{v}_{s t}},\left[x_{\mathbf{u}_{k t}}, x_{\mathbf{u}_{t+1, j}}\right]_{c}\right]_{c} \\
& =\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{k t}\right) x_{\mathbf{u}_{k t}} x_{\mathbf{v}_{s j}}-\chi\left(\mathbf{u}_{k t}, \mathbf{u}_{t+1, j}\right) x_{\mathbf{v}_{s j}} x_{\mathbf{u}_{k t}} \\
& =\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{k t}\right)\left(1-\chi\left(\mathbf{u}_{k t}, \mathbf{u}_{t+1, j}\right) \chi\left(\mathbf{u}_{t+1, j}, \mathbf{u}_{k t}\right)\right) x_{\mathbf{u}_{k t}} x_{\mathbf{v}_{s j}} .
\end{aligned}
$$

For the fifth, note that $\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{s+1, j}\right)^{-1}=\chi\left(\mathbf{u}_{s+1, j}, \mathbf{u}_{1 t}\right)$. Then use (5-15), (5-16) and (1-4) to prove that

$$
\begin{aligned}
{\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{s+1, j}}\right]_{c} } & =\left[\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{u}_{1 t}}\right]_{c}, x_{\mathbf{u}_{s+1, j}}\right]_{c} \\
& =\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{s+1, j}\right) x_{\mathbf{u}_{1 j}} x_{\mathbf{u}_{1 t}}-\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{u}_{1 s}} \\
& =\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{s+1, j}\right)\left(x_{\mathbf{u}_{1 j}} x_{\mathbf{u}_{1 t}}-\chi\left(\mathbf{u}_{1 j}, \mathbf{u}_{1 t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{u}_{1 s}}\right) .
\end{aligned}
$$

The sixth case is similar.
For the seventh case, we use (1-4), (1-5) and the previous case to calculate

$$
\begin{aligned}
{\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{s+1, j}}\right]_{c}=} & {\left[x_{\mathbf{v}_{s t}},\left[x_{\mathbf{u}_{s+1, t},}, x_{\mathbf{u}_{t+1, j}}\right]_{c}\right]_{c} } \\
= & \left(\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{s+1, t}\right)-\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 t}\right)\right)\left[x_{\mathbf{u}_{1 t}}^{2}, x_{\mathbf{u}_{t+1, j}}\right] \\
& \quad+\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{s+1, t}\right) x_{\mathbf{u}_{s+1, t}} x_{\mathbf{v}_{s j}}-\chi\left(\mathbf{u}_{s+1, t}, \mathbf{u}_{t+1, j}\right) x_{\mathbf{v}_{s j}} x_{\mathbf{u}_{s+1, t}} \\
= & \left(\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{s+1, t}\right)-\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 t}\right)\right)\left(\left(x_{\mathbf{v}_{t j}}+\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{1 j}\right) x_{\mathbf{u}_{1 j}} x_{\mathbf{u}_{1 t}}\right)\right. \\
& \left.\quad+\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{t+1, j}\right) x_{\mathbf{u}_{1 j}} x_{\mathbf{u}_{1 t}}\right)-\chi\left(\mathbf{u}_{s+1, t}, \mathbf{u}_{t+1, j}\right) x_{\mathbf{v}_{t j}} \\
& \quad+\left(\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{s+1, t}\right)-\chi\left(\mathbf{u}_{s+1, t}, \mathbf{u}_{t+1, j}\right) \chi\left(\mathbf{v}_{s j}, \mathbf{u}_{s+1, t}\right)\right) x_{\mathbf{u}_{s+1, t}} x_{\mathbf{v}_{s j}} .
\end{aligned}
$$

We use the previous cases, (5-16) and (5-19) to calculate for the eighth case

$$
\begin{aligned}
{\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{k j}}\right]_{c}=} & {\left[\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{u}_{1 t}}\right]_{c}, x_{\mathbf{u}_{k j}}\right]_{c} } \\
= & \chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{k j}\right)\left(\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{k s}\right)\left(1-q_{s, s+1} q_{s+1, s}\right) x_{\mathbf{u}_{k s}} x_{\mathbf{u}_{1 j}}\right) x_{\mathbf{u}_{1 t}} \\
& \quad-\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 t}\right) x_{\mathbf{u}_{1 t}}\left(\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{k s}\right)\left(1-q_{s, s+1} q_{s+1, s}\right) x_{\mathbf{u}_{k s}} x_{\mathbf{u}_{1 j}}\right) \\
= & \gamma_{s t}^{k j} x_{\mathbf{u}_{k s}}\left(x_{\mathbf{u}_{1 j}} x_{\mathbf{u}_{1 t}}-\chi\left(\mathbf{u}_{1 j}, \mathbf{u}_{1 t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{u}_{1 j}}\right) .
\end{aligned}
$$

To conclude, we prove the ninth case in a similar way:

$$
\begin{aligned}
{\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{k j}}\right]_{c}=} & {\left[x_{\mathbf{v}_{s t}},\left[x_{\mathbf{u}_{k t}}, x_{\mathbf{u}_{t+1, j}}\right]_{c}\right]_{c} } \\
= & \gamma_{s t}^{k t}\left(1-q_{\mathbf{v}_{1 t}}\right)\left[x_{\mathbf{u}_{k s}} x_{\mathbf{u}_{1 t}}^{2}, x_{\mathbf{u}_{t+1, j}}\right] \\
& \quad+\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{k, t}\right) x_{\mathbf{u}_{k t}} x_{\mathbf{v}_{s j}}-\chi\left(\mathbf{u}_{k t}, \mathbf{u}_{t+1, j}\right) x_{\mathbf{v}_{s j}} x_{\mathbf{u}_{k t}} .
\end{aligned}
$$

We consider the remaining commutator $\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{j k}}\right]_{c}$ : when $j=1$.
Lemma 5.16. Let $s<t$ in $\{1, \ldots, \theta\}$. The following relations hold in $\mathfrak{B}$ :

$$
\begin{align*}
& {\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{u}_{1 k}}\right]_{c}=0 \quad \text { if } s<k \leq t,}  \tag{5-21}\\
& {\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{v}_{s t}}\right]_{c}=0 .} \tag{5-22}
\end{align*}
$$

Proof. By assumption we have

$$
\begin{aligned}
& {\left[x_{\mathbf{v}_{12}}, x_{\mathbf{u}_{12}}\right]_{c}=\left[\left(\operatorname{ad}_{c} x_{1}\right)^{2} x_{2},\left(\operatorname{ad}_{c} x_{1}\right) x_{2}\right]_{c}=0,} \\
& {\left[x_{\mathbf{v}_{13}}, x_{\mathbf{u}_{12}}\right]_{c}=\left[\left(\operatorname{ad}_{c} x_{1}\right)^{2}\left(\operatorname{ad}_{c} x_{2}\right) x_{3},\left(\operatorname{ad}_{c} x_{1}\right) x_{2}\right]_{c}=0}
\end{aligned}
$$

For $t \geq 4,\left[x_{\mathbf{u}_{4} t}, x_{\mathbf{u}_{12}}\right]_{c}=0$ by (5-14), and using (1-4),

$$
\left[x_{\mathbf{v}_{1 t}}, x_{\mathbf{u}_{12}}\right]_{c}=\left[\left[x_{\mathbf{v}_{13}}, x_{\mathbf{u}_{4 t}}\right]_{c}, x_{\mathbf{u}_{12}}\right]_{c}=0
$$

For each $k \leq t$ we have $\left[x_{\mathbf{u}_{1 t}}, x_{\mathbf{u}_{3 k}}\right]_{c}=\left[x_{1}, x_{\mathbf{u}_{3 k}}\right]_{c}=0$, so $\left[x_{\mathbf{v}_{1 t}}, x_{\mathbf{u}_{3 k}}\right]_{c}=0$. Using (1-4) and (5-15) we have

$$
\left[x_{\mathbf{v}_{1 t}}, x_{\mathbf{u}_{1 k}}\right]_{c}=\left[x_{\mathbf{v}_{1 t}},\left[x_{\mathbf{u}_{12}}, x_{\mathbf{u}_{3 k}}\right]_{c}\right]_{c}=0
$$

Now consider $2 \leq s \leq k$. Since $\left[x_{\mathbf{v}_{1 t}}, x_{\mathbf{u}_{1 k}}\right]_{c}=\left[x_{\mathbf{u}_{2} s}, x_{\mathbf{u}_{1 k}}\right]_{c}=0$ by previous results and (5-16), we conclude from (1-5) and Lemma 5.15 that (5-21) is valid in the general case.

To prove (5-22), we have for $s=1, t=2$

$$
\left[x_{\mathbf{u}_{11}}, x_{\mathbf{v}_{12}}\right]_{c}=\left[x_{1}, x_{\mathbf{v}_{12}}\right]_{c}=\left(\operatorname{ad}_{c} x_{1}\right)^{3} x_{2}=0
$$

Using that $\left[x_{1}, x_{\mathbf{u}_{3} t}\right]_{c}=0$ if $t \geq 3$ and (1-4), we deduce that

$$
\left[x_{\mathbf{u}_{11}}, x_{\mathbf{v}_{1 t}}\right]_{c}=\left[x_{1},\left[x_{\mathbf{v}_{12}}, x_{\mathbf{u}_{3 t}}\right]_{c}\right]_{c}=0
$$

If $1<s<t$ we have, by the previous case,

$$
\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{v}_{1 t}}\right]_{c}=-\chi\left(x_{\mathbf{u}_{1 s}}, x_{\mathbf{v}_{1 t}}\right)\left[x_{\mathbf{v}_{1 t}}, x_{\mathbf{u}_{1 s}}\right]_{c}=0
$$

By (5-18), $\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{u}_{2 s}}\right]_{c}=0$. Also, $\left[x_{\mathbf{v}_{1 t}}, x_{\mathbf{u}_{2 s}}\right]_{c}=\chi\left(\mathbf{u}_{1 t}, \mathbf{u}_{2 s}\right) x_{\mathbf{v}_{s t}}$, by Lemma 5.15. Equation (5-22) follows by (1-4) and the last three equalities.

Lemma 5.17. Let $s<k<t$. The following relations hold in $\mathfrak{B}$ :

$$
\begin{align*}
& {\left[x_{\mathbf{v}_{s k}}, x_{\mathbf{u}_{1 t}}\right]_{c}=\chi\left(\mathbf{v}_{s k}, \mathbf{u}_{1 k}\right)\left(1-q_{k, k+1} q_{k+1, k}\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{v}_{s t}},}  \tag{5-23}\\
& {\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{v}_{k t}}\right]_{c}=\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 k}\right)\left(1+q_{\mathbf{u}_{1 k}}\right)\left(1-q_{k, k+1} q_{k+1, k}\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{v}_{s t}} .} \tag{5-24}
\end{align*}
$$

Proof. The proof follows by (1-4), the second case of Lemma 5.15 and (5-22):

$$
\begin{aligned}
{\left[x_{\mathbf{v}_{s k}}, x_{\mathbf{u}_{1 t}}\right]_{c} } & =\left[x_{\mathbf{v}_{s k}},\left[x_{\mathbf{u}_{1 k}}, x_{\mathbf{u}_{k+1, t}}\right]_{c}\right]_{c} \\
& =\chi\left(\mathbf{v}_{s k}, \mathbf{u}_{1 k}\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{v}_{s t}}-\chi\left(\mathbf{u}_{1 k}, \mathbf{u}_{k+1, t}\right) x_{\mathbf{v}_{s t}} x_{\mathbf{u}_{1 k}} \\
& =\chi\left(\mathbf{v}_{s k}, \mathbf{u}_{1 k}\right)\left(1-\chi\left(\mathbf{u}_{1 k}, \mathbf{u}_{k+1, t}\right) \chi\left(\mathbf{u}_{k+1, t}, \mathbf{u}_{1 k}\right)\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{v}_{s t}}, \\
{\left[x_{\mathbf{u}_{1 s}}, x_{\mathbf{v}_{k t}}\right]_{c} } & =\left[x_{\mathbf{u}_{1 s}},\left[x_{\mathbf{u}_{1 k}}, x_{\mathbf{u}_{1 t}}\right]_{c}\right]_{c} \\
& =\left[x_{\mathbf{v}_{s k}}, x_{\mathbf{u}_{1 t}}\right]_{c}+\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 k}\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{v}_{s t}}-\chi\left(\mathbf{u}_{1 k}, \mathbf{u}_{1 t}\right) x_{\mathbf{v}_{s t}} x_{\mathbf{u}_{1 k}} \\
& =\chi\left(\mathbf{u}_{1 s}, \mathbf{u}_{1 k}\right)\left(q_{\mathbf{u}_{1 k}}\left(1-q_{k, k+1} q_{k+1, k}\right)+1-q_{k, k+1} q_{k+1, k}\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{v}_{s t}} .
\end{aligned}
$$

We next deal with the expression of the commutator of two words of type $x_{\mathbf{v}_{s t}}$.

Lemma 5.18. Let $s<t$ and $s \leq k<j$, with $k \neq s$ or $j \neq t$. The following relations hold in $\mathfrak{B}$ :
$\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{v}_{k j}}\right]_{c} \begin{cases}=0 & \text { if } k<j \leq t, \\ =0 & \text { if } k=s, t<j, \\ =\chi\left(\mathbf{v}_{s t}, \mathbf{v}_{k t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{v}_{k t}} x_{\mathbf{v}_{s j}} & \text { if } k<t<j, \\ =\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right)^{2}\left(1-q_{t, t+1} q_{t+1, t}\right) & \left(1-q_{\mathbf{u}_{1 t}} q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{u}_{1 t}}^{2} x_{\mathbf{v}_{s j}} \\ & \text { if } k=t<j, \\ \in \mathrm{k} x_{\mathbf{v}_{t j}} x_{\mathbf{v}_{s k}}+\mathrm{k} x_{\mathbf{v}_{t k}} x_{\mathbf{v}_{s j}}+\mathrm{k} x_{\mathbf{u}_{1 k}} x_{\mathbf{u}_{1 t}} x_{\mathbf{v}_{s j}} & \text { if } t<k<j,\end{cases}$
Proof. The first and second equalities follow from (1-4) and (5-21), (5-22), respectively. For the third, we use the previous one and (1-4):

$$
\begin{aligned}
& {\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{v}_{k j}}\right]_{c}} \\
& =\left[x_{\mathbf{v}_{s t}},\left[x_{\mathbf{u}_{1 k}}, x_{\mathbf{u}_{1 j}}\right]_{c}\right]_{c} \\
& =\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 k}\right) x_{\mathbf{u}_{1 k}}\left(\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{v}_{s j}}\right) \\
& -\chi\left(\mathbf{u}_{1 k}, \mathbf{u}_{1 j}\right)\left(\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{v}_{s j}}\right) x_{\mathbf{u}_{1 k}} \\
& =\left(1-q_{t, t+1} q_{t+1, t}\right)\left(\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 k}\right) \chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{u}_{1 t}} x_{\mathbf{v}_{s j}}\right. \\
& \left.-\chi\left(\mathbf{u}_{1 k}, \mathbf{u}_{1 j}\right) \chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right) \chi\left(\mathbf{v}_{s j}, \mathbf{u}_{1 k}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{u}_{1 k}} x_{\mathbf{v}_{s j}}\right) \\
& =\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 k}\right) \chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right)\left(x_{\mathbf{u}_{1 k}} x_{\mathbf{u}_{1 k}}-\chi\left(\mathbf{u}_{1 k}, \mathbf{u}_{1 t}\right) x_{\mathbf{u}_{1 k}} x_{\mathbf{u}_{1 k}}\right) x_{\mathbf{v}_{s j}} .
\end{aligned}
$$

The fourth case is similar to the previous one.
To prove the last case we use (1-4) and Lemma 5.17:

$$
\begin{aligned}
{\left[x_{\mathbf{v}_{s t}}, x_{\mathbf{v}_{k j}}\right]_{c}=} & {\left[x_{\mathbf{v}_{s t}},\left[x_{\mathbf{u}_{1 k},}, x_{\mathbf{u}_{1 j}}\right]_{c}\right]_{c} } \\
= & {\left[\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{v}_{s k}}, x_{\mathbf{u}_{1 j}}\right]_{c} } \\
& +\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 k}\right) x_{\mathbf{u}_{1 k}}\left(\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{v}_{s j}}\right) \\
& \quad-\chi\left(\mathbf{u}_{1 k}, \mathbf{u}_{1 j}\right)\left(\chi\left(\mathbf{v}_{s t}, \mathbf{u}_{1 t}\right)\left(1-q_{t, t+1} q_{t+1, t}\right) x_{\mathbf{u}_{1 t}} x_{\mathbf{v}_{s j}}\right) x_{\mathbf{u}_{1 k}} .
\end{aligned}
$$

The proof is finished using (1-5) and the previous identities.
Theorem 5.19. Let $V$ be a standard braided vector space of type $B_{\theta}$, where $\theta=$ $\operatorname{dim} V$, and let $C=\left(a_{i j}\right)_{i, j \in\{1, \ldots, \theta\}}$ be the corresponding Cartan matrix of type $B_{\theta}$.

The Nichols algebra $\mathfrak{B}(V)$ is presented by the generators $x_{i}, 1 \leq i \leq \theta$, and the relations

$$
\begin{array}{rlrl}
x_{\alpha}^{N_{\alpha}} & =0, & \alpha \in \Delta^{+} ; \\
\operatorname{ad}_{c}\left(x_{i}\right)^{1-a_{i j}}\left(x_{j}\right) & =0, & i \neq j ; \\
{\left[\left(\operatorname{ad} x_{j-1}\right)\left(\operatorname{ad} x_{j}\right) x_{j+1}, x_{j}\right]_{c}} & =0, & & 1<j<\theta, q_{j j}=-1 ; \\
{\left[\left(\operatorname{ad} x_{1}\right)^{2} x_{2},\left(\operatorname{ad} x_{1}\right) x_{2}\right]_{c}} & =0, & & q_{11} \in \mathbb{G}_{3} \text { or } q_{22}=-1 ; \\
{\left[\left(\operatorname{ad} x_{1}\right)^{2}\left(\operatorname{ad} x_{2}\right) x_{3},\left(\operatorname{ad} x_{1}\right) x_{2}\right]_{c}} & =0, & q_{11} \in \mathbb{G}_{3} \text { or } q_{22}=-1 .
\end{array}
$$

The following elements constitute a basis of $\mathfrak{B}(V)$ :

$$
\begin{equation*}
x_{\beta_{1}}^{h_{1}} x_{\beta_{2}}^{h_{2}} \ldots x_{\beta_{P}}^{h_{P}}, \quad \text { where } 0 h_{j}<N_{\beta_{j}}-1 \text { if } \beta_{j} \in S_{I}, \text { for } 1 \leq j \leq P . \tag{5-25}
\end{equation*}
$$

Proof. The proof is analogous to that of Theorem 5.14, since by the previous lemmas we can express the commutator of two generators $x_{\alpha}<x_{\beta}$ as a linear combination of monotone hyperwords whose greater hyperletter is great or equal to $x_{\beta}$.

5D. Presentation when the type is $\boldsymbol{G}_{\mathbf{2}}$. We now consider standard braidings of type $G_{2}$, with $m_{12}=3, m_{21}=1$.

Lemma 5.20. Let $\mathfrak{B}:=T(V) / I$, for some $I \in \mathfrak{S}$, and suppose that

$$
\begin{equation*}
x_{1}^{\operatorname{ord} q_{11}}=0, \quad x_{2}^{\operatorname{ord} q_{22}}=0, \quad\left(\operatorname{ad} x_{1}\right)^{4} x_{2}=\left(\operatorname{ad} x_{2}\right)^{2} x_{1}=0 \tag{5-26}
\end{equation*}
$$

in $\mathfrak{B}$. Then
(a) $\left[x_{1}^{3} x_{2} x_{1} x_{2}\right]_{c}=0$ in $\mathfrak{B} \Longleftrightarrow 4 e_{1}+2 e_{2} \notin \Delta^{+}(\mathfrak{B})$.

Assume further that the equivalent conditions in (a) hold. Then
(b) $\left[\left(\operatorname{ad} x_{1}\right)^{3} x_{2},\left(\operatorname{ad} x_{1}\right)^{2} x_{2}\right]_{c}=0$ in $\mathfrak{B} \Longleftrightarrow 5 e_{1}+2 e_{2} \notin \Delta^{+}(\mathfrak{B})$ and
(c) $\left[\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c},\left[x_{1} x_{2}\right]_{c}\right]_{c}=0$ in $\mathfrak{B} \Longleftrightarrow 4 e_{1}+3 e_{2} \notin \Delta^{+}(\mathfrak{B})$.

Assume also that the equivalent conditions in (b) and those in (c) hold. Then
(d) $\left[\left[x_{1}^{2} x_{2}\right]_{c},\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right]_{c}=0$ in $\mathfrak{B} \Longleftrightarrow 5 e_{1}+3 e_{2} \notin \Delta^{+}(\mathfrak{B})$.

In particular, all these relations hold when $V$ is a standard braiding and $\mathfrak{B}=$ $\mathfrak{B}(V)$ is finite-dimensional.

Proof. Take the ordering $x_{1}<x_{2}$, and consider a PBW basis as in Theorem 1.12. Define $\gamma_{k}:=\prod_{0 \leq j \leq k-1}\left(1-q_{11}^{j} q_{12} q_{21}\right)$.
(a) If $\left[x_{1}^{3} x_{2} x_{1} x_{2}\right]_{c}=0$, then $4 e_{1}+2 e_{2} \notin \Delta^{+}(\mathfrak{B})$ since there are no possible Lyndon words in $S_{I}: x_{1}^{3} x_{2} x_{1} x_{2}$ is the unique Lyndon word such that $x_{1}^{3} x_{2}$ and $x_{1} x_{2}^{2}$ are not factors, and it is not in $S_{I}$ by assumption.

Conversely, if $4 e_{1}+2 e_{2} \notin \Delta^{+}(\mathfrak{B})$, then $\left[x_{1}^{3} x_{2} x_{1} x_{2}\right]_{c}$ is a linear combination of greater hyperwords, and $\left[x_{1} x_{2} x_{1}^{3} x_{2}\right]_{c}$ and $\left[x_{1}^{2} x_{1}^{2} x_{2}\right]$ are the only greater hyperwords that are not in $S_{I}$ and do not end in $x_{1}$ (we discard words ending in $x_{1}$ since $\left[x_{1}^{3} x_{2} x_{1} x_{2}\right]_{c}$ is in ker $D_{1}$ ). Taking their Shirshov decomposition, we see that there exist $\alpha, \beta \in \mathrm{k}$ such that

$$
\begin{equation*}
\left[x_{1}^{3} x_{2} x_{1} x_{2}\right]_{c}-\alpha\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{3} x_{2}\right]_{c}-\beta\left[x_{1}^{2} x_{2}\right]_{c}^{2}=0 \tag{5-27}
\end{equation*}
$$

Note that $\left[x_{1}^{3} x_{2} x_{1} x_{2}\right]_{c}=\operatorname{ad} x_{1}\left(\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right)$, so by direct calculation,

$$
D_{2}\left(\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right)=0 .
$$

Apply $D_{2}$ to both sides of equality (5-27) and express the result as a linear combination of $\left[x_{1}^{3} x_{2}\right]_{c} x_{1},\left[x_{1}^{2} x_{2}\right]_{c} x_{1}^{2}$ and $\left[x_{1} x_{2}\right]_{c} x_{1}^{3}$. The coefficient of $\left[x_{1} x_{2}\right]_{c} x_{1}^{3}$ is

$$
\alpha\left(1-q_{12} q_{21}\right)\left(1-q_{11} q_{12} q_{21}\right)
$$

so $\alpha=0$. Note also that $D_{1}^{2} D_{2}\left(\left[x_{-1} 1^{3} x_{2} x_{1} x_{2}\right]_{c}\right)=0$; but

$$
D_{1}^{2} D_{2}\left(\left[x_{1}^{2} x_{2}\right]_{c}^{2}\right)=\left(1-q_{12} q_{21}\right)\left(1-q_{11} q_{12} q_{21}\right)\left(1+q_{11}\right)\left(q_{2 e_{1}+e_{2}}+1\right)\left[x_{1}^{2} x_{2}\right]_{c} .
$$

Looking at the proof of Proposition 4.7, we see that $q_{2 e_{1}+e_{2}} \neq-1$, so $\beta=0$.
(b) Assuming (5-26) and the condition in (a), the only possible Lyndon word of degree $5 e_{1}+2 e_{j}$ is $x_{1}^{3} x_{2} x_{1}^{2} x_{2}$, and

$$
\left[x_{1}^{2} x_{2} x_{1} x_{2} x_{1} x_{2}\right]_{c}=\left[\left(\operatorname{ad} x_{1}\right)^{3} x_{2},\left(\operatorname{ad} x_{1}\right)^{2} x_{2}\right]_{c} .
$$

Then we proceed as before. One implication is clear. For the other, if $5 e_{1}+2 e_{j} \notin$ $\Delta^{+}(\mathfrak{B})$, there exists $\alpha \in \mathrm{k}$ such that

$$
\left[\left(\operatorname{ad} x_{1}\right)^{3} x_{2},\left(\operatorname{ad} x_{1}\right)^{2} x_{2}\right]_{c}=\alpha\left(\operatorname{ad} x_{1}\right)^{2} x_{2}\left(\operatorname{ad} x_{1}\right)^{3} x_{2}
$$

Now we apply $D_{2}$ and express the equality as a linear combination of $\left(\operatorname{ad} x_{1}\right)^{3} x_{2} x_{1}^{2}$ and $\left(\operatorname{ad} x_{1}\right)^{2} x_{2} x_{1}^{3}$ (using the hypothesis that $\left.\left(\operatorname{ad} x_{1}\right)^{4} x_{2}=0\right)$; the coefficient of $\left(\operatorname{ad} x_{1}\right)^{2} x_{2} x_{1}^{3}$ is $\alpha \gamma_{3}$, so $\alpha=0$.
(c) The proof is similar. Since we are considering Lyndon words not having $x_{1}^{3} x_{2}$ or $x_{1} x_{2}^{2}$ as a factor, the only possible Lyndon word of degree $4 e_{1}+3 e_{j}$ is $x_{1}^{2} x_{2} x_{1} x_{2} x_{1} x_{2}$, and

$$
\left[x_{1}^{2} x_{2} x_{1} x_{2} x_{1} x_{2}\right]_{c}=\left[\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c},\left[x_{1} x_{2}\right]_{c}\right]_{c}
$$

If $4 e_{1}+3 e_{j} \notin \Delta^{+}(\mathfrak{B})$, there exist $\alpha_{i} \in \mathrm{k}$ such that

$$
\begin{aligned}
& {\left[x_{1}^{2} x_{2}\left(x_{1} x_{2}\right)^{2}\right]_{c}} \\
& \quad=\alpha_{1}\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}+\alpha_{2}\left[x_{1} x_{2}\right]_{c}^{2}\left[x_{1}^{2} x_{2}\right]_{c}+\alpha_{3} x_{2}\left[x_{1}^{2} x_{2}\right]_{c}^{2}+\alpha_{4} x_{2}\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{3} x_{2}\right]_{c}
\end{aligned}
$$

since, as above, we are discarding words greater than $x_{1}^{2} x_{2} x_{1} x_{2} x_{1} x_{2}$ ending in $x_{1}$; we also discard words with factors $x_{1}^{4} x_{2}, x_{1} x_{2}^{2}, x_{1}^{3} x_{2} x_{1}^{2} x_{2}$, by the assumption on $\mathfrak{B}$. We apply $D_{2}$ to this equality. Using the definition of the braided commutator, we express the hyperletter just considered as a linear combination of elements of the PBW basis, having degree $4 e_{1}+2 e_{2}$.

The coefficient of $x_{2}\left[x_{1} x_{2}\right]_{c} x_{1}^{3}$ is $\alpha_{4} \gamma_{3}$ since this PBW generator appears only in the expression of $D_{2}\left(x_{2}\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{3} x_{2}\right]_{c}\right)$. Thus $\alpha_{4}=0$.

Using this fact, we see that the coefficient of $x_{2}\left[x_{1}^{3} x_{2}\right]_{c} x_{1}$ is

$$
\alpha_{3} \gamma_{2}\left(1+q_{11}\right) q_{11}^{2} q_{12} q_{21}^{2} q_{22}
$$

since this term appears only in the expression of $D_{j}\left(x_{2}\left[x_{1}^{2} x_{2}\right]_{c}^{2}\right)$. Thus $\alpha_{3}=0$.

Next, the coefficient of $\left[x_{1} x_{2}\right]_{c}^{2} x_{1}^{2}$ is $\alpha_{2} \gamma_{2}$, so $\alpha_{2}=0$. Now we calculate the coefficient of $\left[x_{1}^{2} x_{2}\right]_{c}^{2}$ :

$$
\alpha_{1} \gamma_{2}\left(\chi\left(\mathbf{e}_{1}, 5 \mathbf{e}_{1}+\mathbf{e}_{2}\right)-\chi\left(2 \mathbf{e}_{1}+\mathbf{e}_{2}, \mathbf{e}_{1}+\mathbf{e}_{2}\right)\right)=\alpha_{1} \gamma_{2} q_{11} q_{12}\left(q_{11}^{3}-q_{22} q_{12} q_{21}\right)
$$

Since $q_{11}^{3} \neq q_{22} q_{12} q_{21}$ for each standard braiding, we conclude that $\alpha_{1}=0$.
(d) If the conditions in (b) and (c) hold, the only possible Lyndon word of degree $5 e_{1}+3 e_{2}$ not having $x_{1}^{4} x_{2}$ or $x_{1} x_{2}^{2}$ as factors is $x_{1}^{2} x_{2} x_{1}^{2} x_{2} x_{1} x_{2}$, and

$$
\left[x_{1}^{2} x_{2} x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}=\left[\left[x_{1}^{2} x_{2}\right]_{c},\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right]_{c}
$$

This hyperword is not in $S_{I}$ if and only if there exist $v_{i} \in \mathrm{k}$ such that

$$
\begin{align*}
{\left[x_{1}^{2} x_{2} x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}=v_{1}\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}[ } & {\left[x_{1}^{2} x_{2}\right]_{c}+v_{2}\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{2} x_{2}\right]_{c}^{2} } \\
& +v_{3}\left[x_{1} x_{2}\right]_{c}^{2}\left[x_{1}^{3} x_{2}\right]_{c}+v_{4} x_{2}\left[x_{1}^{2} x_{2}\right]_{c}\left[x_{1}^{3} x_{2}\right]_{c} . \tag{5-28}
\end{align*}
$$

Apply $D_{2}$ and note that $D_{2}\left(\left[x_{1}^{2} x_{2} x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right)=0$ under the hypotheses on $\mathfrak{B}$. Then express the resulting sum as a linear combination of elements of the PBW basis, which have degree $5 e_{1}+2 e_{2}$.

The hyperword $x_{2}\left[x_{1}^{2} x_{2}\right] x_{1}^{3}$ appears only for $D_{2}\left(x_{2}\left[x_{1}^{2} x_{2}\right]_{c}\left[x_{1}^{3} x_{2}\right]_{c}\right)$, and its coefficient is $\nu_{4} \gamma_{3}$, and since $\gamma_{3} \neq 0$ we conclude that $\nu_{4}=0$.

Analogously, $\left[x_{1} x_{2}\right]_{c}^{2} x_{1}^{3}$ appears only for $\left[x_{1} x_{2}\right]_{c}^{2}\left[x_{1}^{3} x_{2}\right]_{c}$ (due to $v_{4}=0$ ). Its coefficient is $\nu_{3} \gamma_{3}$, so $\nu_{3}=0$.

Note that $D_{1}^{2} D_{2}\left(\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right)=0$. We apply $D_{1}^{2} D_{2}$ to the expression (5-28), and obtain

$$
0=v_{1} \gamma_{2}\left(1+q_{11}\right)\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}+v_{2} \gamma_{2}\left(1+q_{11}\right)\left(1+q_{2 \mathbf{e}_{1}+\mathbf{e}_{2}}\right)\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{2} x_{2}\right]_{c}
$$

The terms $\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}$ and $\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{2} x_{2}\right]_{c}$ are linearly independent, since they are linearly independent in $\mathfrak{B}(V)$, and we have a surjection $\mathfrak{B} \rightarrow \mathfrak{B}(V)$. Then

$$
v_{1} \gamma_{2}\left(1+q_{11}\right)=v_{2} \gamma_{2}\left(1+q_{11}\right)\left(1+q_{2 \mathbf{e}_{1}+\mathbf{e}_{2}}\right)=0
$$

But for standard braidings of type $G_{2}$ we note that $q_{11}, q_{2 \mathbf{e}_{1}+\mathbf{e}_{2}} \neq-1$ and $\gamma_{2} \neq 0$, so $v_{1}=v_{2}=0$.

The last statement is true since

$$
\Delta^{+}(\mathfrak{B}(V))=\left\{e_{1}, e_{1}+e_{2}, 2 e_{1}+e_{2}, 3 e_{1}+e_{2}, 3 e_{1}+2 e_{2}, e_{2}\right\}
$$

if the braiding is standard of type $G_{2}$.
Remark 5.21. Let $V$ be a standard braided vector space of type $G_{2}$ and let $\mathfrak{B}$ be a braided graded Hopf algebra satisfying the hypotheses of Lemma 5.20. In a similar way to Lemma 5.5 , if $q_{11} \notin \mathbb{G}_{4}$ and $q_{22} \neq-1$, then $5 e_{1}+2 e_{2}, 4 e_{1}+2 e_{2} 4 e_{1}+$ $3 e_{2}, 5 e_{1}+3 e_{2} \notin \Delta^{+}(\mathfrak{B})$.

This follows because $x_{1}^{3} x_{2} x_{1}^{2} x_{2}, x_{1}^{2} x_{2} x_{1} x_{2} x_{1} x_{2}, x_{1}^{2} x_{2} x_{1}^{2} x_{2} x_{1} x_{2} \notin S_{I}$, using the quantum Serre relations as in the lemma cited.

Theorem 5.22. Let $V$ be a standard braided vector space of type $G_{2}$. The Nichols algebra $\mathfrak{B}(V)$ is presented by the generators $x_{1}, x_{2}$ and the relations

$$
\begin{equation*}
\operatorname{ad}_{c}\left(x_{1}\right)^{4}\left(x_{2}\right)=\operatorname{ad}_{c}\left(x_{2}\right)^{2}\left(x_{1}\right)=0, \quad x_{\alpha}^{N_{\alpha}}=0, \alpha \in \Delta^{+} \tag{5-29}
\end{equation*}
$$

and, if $q_{11} \in \mathbb{G}_{4}$ or $q_{22}=-1$,

$$
\begin{align*}
{\left[\left(\operatorname{ad} x_{1}\right)^{3} x_{2},\left(\operatorname{ad} x_{1}\right)^{2} x_{2}\right]_{c} } & =0  \tag{5-30}\\
{\left[x_{1},\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right]_{c} } & =0  \tag{5-31}\\
{\left[\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c},\left[x_{1} x_{2}\right]_{c}\right]_{c} } & =0  \tag{5-32}\\
{\left[\left[x_{1}^{2} x_{2}\right]_{c},\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right]_{c} } & =0 \tag{5-33}
\end{align*}
$$

The following elements constitute a basis of $\mathfrak{B}(V)$ :
$x_{2}^{h_{e_{2}}}\left[x_{1} x_{2}\right]_{c}^{h_{e_{1}+e_{2}}}\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}^{h_{3 e_{1}}+2 e_{2}}\left[x_{1}^{2} x_{2}\right]_{c}^{h_{2 e_{1}+e_{2}}}\left[x_{1}^{3} x_{2}\right]_{c}^{h_{3 e_{1}+e_{2}}} x_{1}^{h_{e_{1}}}, \quad 0 \leq h_{\alpha} \leq N_{\alpha}-1$.

Proof. The statement about the PBW basis follows from Corollary 4.2 and the definitions of the $x_{\alpha}$.

Let $\mathfrak{B}$ be the algebra presented by the generators $x_{1}, x_{2}$ and the relations (5-29)-(5-33). From Lemma 5.20 and Corollary 5.2, we have a canonical epimorphism of algebras $\phi: \mathfrak{B} \rightarrow \mathfrak{B}(V)$.

Consider the subspace $I$ of $\mathfrak{B}$ generated by the elements in (5-34). We prove by induction on the sum $S$ of the $h_{\alpha}$ 's of a such product $M$ that $x_{1} M \in \mathscr{I}$; moreover, we prove that it is a linear combination of products whose first hyperletter is less than or equal to the first hyperletter of $M$. If $S=0$, we have $M=1$.

- If $M=x_{1}^{N_{1}}$, then $x_{1} M=x_{1}^{N_{1}+1}$, which is zero if $N_{1}=\operatorname{ord} x_{1}-1$.
- If $M=\left[x_{1}^{3} x_{2}\right]_{c} M^{\prime}$, then we use that $x_{1}\left[x_{1}^{3} x_{2}\right]_{c}=q_{11}^{3} q_{12}\left[x_{1}^{3} x_{2}\right]_{c} x_{1}$ to prove that $x_{1} M$ lies in $\mathscr{I}$ and either is zero or begins with $\left[x_{1}^{3} x_{2}\right]_{c}$.
- If $M=\left[x_{1}^{2} x_{2}\right]_{c} M^{\prime}$, we have

$$
x_{1}\left[x_{1}^{2} x_{2}\right]_{c}=\left[x_{1}^{3} x_{2}\right]_{c}+q_{11}^{2} q_{12}\left[x_{1}^{2} x_{2}\right]_{c} x_{1}
$$

We use the inductive step and relation (5-30) to prove that $x_{1} M$ lies in $\Phi$ and is either zero or a linear combination of hyperwords starting with a hyperletter less than or equal to $\left[x_{1}^{2} x_{2}\right]_{c}$.

- If $M=\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c} M^{\prime}$, we deduce from (5-31) that

$$
x_{1}\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}=\chi\left(\mathbf{e}_{1}, 3 \mathbf{e}_{1}+2 \mathbf{e}_{2}\right)\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c} x_{1}
$$

using also (5-32) and (5-33), we prove that $x_{1} M$ lies in $\mathscr{I}$ and is either zero or a linear combination of hyperwords that starting with a hyperletter less than or equal to $\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}$.

- If $M=\left[x_{1} x_{2}\right]_{c} M^{\prime}$, observe that

$$
x_{1}\left[x_{1} x_{2}\right]_{c}=\left[x_{1}^{2} x_{2}\right]_{c}+q_{11} q_{12}\left[x_{1} x_{2}\right]_{c} x_{1}
$$

Using the inductive step together with (5-31), (5-32), and the equality

$$
\left[x_{1}^{2} x_{2}\right]_{c}\left[x_{1} x_{2}\right]_{c}=\left[\left[x_{1}^{2} x_{2}\right]_{c},\left[x_{1} x_{2}\right]_{c}\right]_{c}+\chi\left(2 \mathbf{e}_{1}+\mathbf{e}_{2}, \mathbf{e}_{1}+\mathbf{e}_{2}\right)\left[x_{1} x_{2}\right]_{c}\left[x_{1}^{2} x_{2}\right]_{c},
$$

by the definition of braided commutator, we prove that $x_{1} M$ lies in $\mathscr{I}$ and is either zero or a linear combination of hyperwords starting with a hyperletter less than or equal to $\left[x_{1} x_{2}\right]_{c}$.

- If $M=x_{2} M^{\prime}$, we use the equalities $x_{1} x_{2}=\left[x_{1} x_{2}\right]_{c}+q_{12} x_{2} x_{1}$ and $\left[\left[x_{1} x_{2}\right]_{c}, x_{2}\right]_{c}=$ 0 to prove that $x_{1} M$ lies in $\mathscr{I}$ and is either zero or a linear combination of hyperwords.

Now, $x_{2} M$ is a product of nonincreasing hyperwords or is zero, for each element in (5-34), so $\mathscr{I}$ is an ideal of $\mathfrak{B}$ containing 1 ; hence $\mathscr{I}=\mathfrak{B}$. Since the elements in (5-34) are a basis of $\mathfrak{B}(V)$, the map $\phi$ is an isomorphism.

5E. Presentation when the braiding is of Cartan type. In this subsection, we present the Nichols algebra of a diagonal braiding vector space of Cartan type with matrix $\left(q_{i j}\right)$, by generators and relations. This was established in [Andruskiewitsch and Schneider 2002a, Theorem 4.5] assuming that $q_{i i}$ has odd order and that order is not divisible by 3 if $i$ belongs to a component of type $G_{2}$. The proof in loc. cit. combines a reduction to symmetric $\left(q_{i j}\right)$ by twisting, with results from [Andersen et al. 1994] and [De Concini and Procesi 1993]. We also note that some particular instances were already proved earlier in this section.

Fix a standard braided vector space $V$ with connected Dynkin diagram and an $i \in\{1, \ldots, \theta\}$. Suppose that $\mathfrak{B}$ is a quotient by an ideal $I \in \mathfrak{S}$ of $T(V)$. Assume moreover that $V$ is not of type $G_{2}$ and that
(5-3) holds in $\mathfrak{B}$ if $1 \leq i \neq j \leq \theta ;$
(5-4) holds in $\mathfrak{B}$ if $m_{k j}=m_{k l}=1$ and $m_{j l}=0$;
(5-6) holds in $\mathfrak{B}$ if $m_{k j}=2$ and $m_{j k}=1$;
(5-8) holds in $\mathfrak{B}$ if $m_{k j}=2, m_{j k}=m_{j l}=1$ and $m_{k l}=0$.
Note that if (5-3) holds in an algebra with derivations $D_{k}$, then (2-11) holds also, by Lemma 2.7. By Theorem 2.6, we have an algebra $s_{i}(\mathfrak{B})$ provided with skew derivations $D_{i}$. We set $\tilde{x}_{k}=\left(\operatorname{ad}_{c} x_{i}\right)^{m_{i k}}\left(x_{k}\right) \# 1 \in s_{i}(\mathfrak{B})$, for $k \neq i$, and $\tilde{x}_{i}=1 \# y$. The elements generate $s_{i}(\mathfrak{B})^{1}$ as a vector space.

Lemma 5.23. Conditions (5-35)-(5-38) are satisfied with $s_{i}(\mathfrak{B})$ in lieu of $\mathfrak{B}$.
Proof of (5-35). Each $m \mathbf{e}_{k}+e_{j}, 0 \leq m \leq m_{k j}$ is an element of $\Delta\left(\mathfrak{B}\left(V_{i}\right)\right)$, so $s_{i}\left(m \mathbf{e}_{k}+\mathbf{e}_{j}\right) \in \Delta(\mathfrak{B}(V))$. Since we have a surjective morphism of braided graded Hopf algebras $\mathfrak{B} \rightarrow \mathfrak{B}(V)$, we have $\Delta(\mathfrak{B}(V)) \subseteq \Delta(\mathfrak{B})$.

From Lemma 5.3, $\left(\operatorname{ad}_{c} \tilde{x}_{k}\right)^{m} \tilde{x}_{j}=0$ if and only if $\tilde{x}_{k}^{m} \tilde{x}_{j}$ is a linear combination of greater words, for an order in which $\tilde{x}_{k}<\tilde{x}_{j}$ (since we are considering the Cartan case, the condition about the ordering of the $\tilde{x}_{j}$ is satisfied). Note that $\tilde{x}_{k}^{m} \tilde{x}_{j}$ is the unique Lyndon word of degree $m \mathbf{e}_{k}+e_{j}$. Then, by the relation (2-15) between the Hilbert series of $\mathfrak{B}$ and $s_{i}(\mathfrak{B})$, the validity of (5-3) for $s_{i}(\mathfrak{B})$ is equivalent to the condition

$$
s_{i}\left(\left(m_{k j}+1\right) \mathbf{e}_{k}+\mathbf{e}_{j}\right) \notin \Delta^{+}(\mathfrak{B}) .
$$

(a) When $k=i \neq j$, this says that $-\mathbf{e}_{i}+\mathbf{e}_{j} \notin \Delta^{+}(\mathfrak{B})$, so (5-3) holds.
(b) To prove (5-3) for $s_{i}(\mathfrak{B})$ when $j=i$, we show case by case that

$$
\left(m_{k i}+1\right) \mathbf{e}_{k}+\left(\left(m_{k i}+1\right) m_{i k}-1\right) \mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B}) .
$$

- If $m_{k i}=m_{i k}=0$, we have $\mathbf{e}_{k}-\mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B})$.
- If $m_{k i}=m_{i k}=1$, then $2 \mathbf{e}_{k}+\mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B})$, because $\left(\operatorname{ad} x_{k}\right)^{2} x_{i}=0$.
- If $m_{k i}=1$ and $m_{i k}=2$, then $2 \mathbf{e}_{k}+3 \mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B})$, since we can apply Lemma 5.5 to $\mathfrak{B}$, which satisfies (5-6) by assumption.
- If $m_{k i}=2$ and $m_{i k}=1$, then $3 \mathbf{e}_{k}+2 \mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B})$, as before.

Thus (5-3) holds for each $k \neq i$.
(c) Now consider $\theta \geq 3$ and $k, j \neq i$.

- If $m_{i k}=m_{i j}=0$, then $s_{i}\left(m \mathbf{e}_{k}+\mathbf{e}_{j}\right)=m \mathbf{e}_{k}+\mathbf{e}_{j}$, and $\left(m_{k j}+1\right) \mathbf{e}_{k}+\mathbf{e}_{j} \notin \Delta^{+}(\mathfrak{B})$, since the quantum Serre relation holds in $\mathfrak{B}$.
- If $m_{i k}=1$ and $m_{i j}=0$, then $s_{i}\left(m \mathbf{e}_{k}+\mathbf{e}_{j}\right)=m \mathbf{e}_{i}+m \mathbf{e}_{k}+\mathbf{e}_{j}$. If we assume $x_{j}<x_{i}<x_{k}$ and look at the possible Lyndon words in $S_{I}$, from (5-3), these words have no factors $x_{i}^{2} x_{k}, x_{j} x_{i}$, so the only possibility is $x_{j}\left(x_{k} x_{i}\right)^{m}$.
- If $m_{k j}=0$, then $x_{j} x_{k} x_{i}=q_{j k} x_{k} x_{j} x_{i}$, so $x_{j} x_{k} x_{i} \notin S_{I}$.
- If $m_{k j}=1$, then $x_{j} x_{k} x_{l} x_{k} \notin S_{I}$ when $m_{k i}=1$, since (5-4) is valid in $\mathfrak{B}$; while if $m_{k i}=2$ we have $q_{k k} \neq-1$ and

$$
\begin{aligned}
x_{j}\left(x_{k} x_{i}\right)^{2}= & \left(1+q_{k k}\right)^{-1} q_{k i}^{-1} x_{j} x_{k}^{2} x_{i}^{2}+\left(1+q_{k k}\right)^{-1} q_{k i} q_{k k}^{2} x_{j} x_{i} x_{k}^{2} x_{i} \\
= & q_{k i}^{-1} q_{k j}^{-1} q_{k k}^{-2} x_{k} x_{j} x_{k} x_{i}^{2}+\left(1+q_{k k}\right)^{-1} q_{k i}^{-1} q_{k j}^{-2} q_{k k}^{-2} x_{k}^{2} x_{j} x_{i}^{2} \\
& +\left(1+q_{k k}\right)^{-1} q_{k i} q_{k k}^{2} q_{j i} x_{i} x_{j} x_{k}^{2} x_{i}
\end{aligned}
$$

In both cases, $x_{j}\left(x_{k} x_{i}\right)^{2} \notin S_{I}$.

- If $m_{k j}=2$, then $m_{k i}=m_{j k}=1$ and $q_{k k} \neq-1$. The proof is similar to the previous case.
- If $m_{i k}=2, m_{i j}=0$, then $s_{i}\left(m \mathbf{e}_{k}+\mathbf{e}_{j}\right)=2 m \mathbf{e}_{i}+m \mathbf{e}_{k}+\mathbf{e}_{j}$ and $m_{k j}=0,1$. When $m_{k j}=0$, the proof is clear as above. When $m_{k j}=1$, for $j<k<i$ and considering only the quantum Serre relations, the only possible Lyndon word is $x_{j}\left(x_{k} x_{i}^{2}\right)^{2}$. But since $\left[\left[x_{i}^{2} x_{k}\right]_{c},\left[x_{i} x_{k}\right]_{c}\right]_{c}=0$, we deduce that such a word is not in $S_{I}$.
- If $m_{i k}=0, m_{i j}=1$, then $s_{i}\left(m \mathbf{e}_{k}+\mathbf{e}_{j}\right)=\mathbf{e}_{i}+m \mathbf{e}_{k}+\mathbf{e}_{j}$. If $k<i<j$, note that from $x_{k} x_{i}, x_{k}^{m_{k j}+1} x_{j} \notin S_{I}$, there are no Lyndon words of degree $\mathbf{e}_{i}+\left(m_{k j}+1\right) \mathbf{e}_{k}+\mathbf{e}_{j}$ in $S_{I}$.
- If $m_{i k}=0, m_{i j}=2$, then $s_{i}\left(m \mathbf{e}_{k}+\mathbf{e}_{j}\right)=2 \mathbf{e}_{i}+m \mathbf{e}_{k}+\mathbf{e}_{j}$, and the proof is analogous to the previous case.
- If $m_{i k}=m_{i j}=1$, then $m_{k j}=0$, and $s_{i}\left(\mathbf{e}_{k}+\mathbf{e}_{j}\right)=2 \mathbf{e}_{i}+\mathbf{e}_{k}+\mathbf{e}_{j}$, which is not in $\Delta^{+}(\mathfrak{B})$ from Lemma 5.4.
- If $m_{i k}=2, m_{i j}=1$ (it is analogous to $m_{i k}=1, m_{i j}=2$ ), then $m_{k j}=0$ and $s_{i}\left(\mathbf{e}_{k}+\mathbf{e}_{j}\right)=3 \mathbf{e}_{i}+\mathbf{e}_{k}+\mathbf{e}_{j}$. In this way we get $q_{i i} \neq-1$, and if $x_{k}<x_{i}<x_{j}$ the unique Lyndon word without $x_{i}^{2} x_{j}$ or $x_{k} x_{i}^{3}$ as factors is

$$
\begin{aligned}
x_{k} x_{i}^{2} x_{j} x_{i}=\left(1+q_{i i}\right)^{-1} & q_{i j}^{-1} x_{k} x_{i}^{3} x_{j}+\left(1+q_{i i}\right)^{-1} q_{i i}^{2} q_{i j} x_{k} x_{i} x_{j} x_{i}^{2} \\
& \in \mathrm{k}\left(x_{i} x_{k} x_{i}^{2} x_{j}\right)+\mathrm{k}\left(x_{i}^{2} x_{k} x_{i} x_{j}\right)+\mathrm{k}\left(x_{i}^{3} x_{k} x_{j}\right)+\mathrm{k}\left(x_{k} x_{i} x_{j} x_{i}^{2}\right)
\end{aligned}
$$

using the quantum Serre relations; hence there are no Lyndon words of degree $3 \mathbf{e}_{i}+\mathbf{e}_{k}+\mathbf{e}_{j}$ in $S_{I}$.

So, (5-3) holds, for each $k, j \neq i, k \neq j$.
Proof of (5-36). Assume $m_{k j}=m_{k l}=1$. We prove case by case that

$$
s_{i}\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right) \notin \Delta^{+}(\mathfrak{B}) .
$$

- If $m_{i j}=m_{i k}=m_{i l}=0$, then $s_{i}\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right)=2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}$, so it follows from Lemma 5.4, because $2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B})$.
- If $m_{i j} \neq 0$ (analogously, if $m_{i l} \neq 0$ ), then $m_{i k}=m_{i l}=0$, because there are no cycles in the Dynkin diagram. Then $s_{i}\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right)=2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}+m_{i j} \mathbf{e}_{i}$. If we consider $x_{k}<x_{l}<x_{j}<x_{i}$, using the equalities $x_{k} x_{i}=q_{k i} x_{i} x_{k}, x_{j} x_{l}=q_{j l} x_{l} x_{j}$ and $x_{l} x_{i}=q_{l i} x_{i} x_{l}$, and also that $x_{k}^{2} x_{l}, x_{k}^{2} x_{j} \notin S_{I}$, we conclude that no possible Lyndon words of degree $2 e_{k}+e_{j}+e_{l}+m_{i j} e_{i}$ can be an element of $S_{I}$, except $x_{k} x_{l} x_{k} x_{j} x_{i}^{m_{i j}}$; but this, too, is not an element of $S_{I}$, because $x_{k} x_{l} x_{k} x_{j} \notin S_{I}$. Hence $2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}+m_{i j} \mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B})$.
- If $m_{i k}=1$, and therefore $m_{i j}=m_{i l}=0$, then $s_{i}\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right)=2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}+$ $2 m_{i k} \mathbf{e}_{i}$. If we consider $x_{l}<x_{i}<x_{k}<x_{j}$, using the equalities $x_{j} x_{i}=q_{j i} x_{i} x_{j}$,
$x_{j} x_{l}=q_{j l} x_{l} x_{j}$ and $x_{l} x_{i}=q_{l i} x_{i} x_{l}$, and also that $x_{k}^{2} x_{l}, x_{k}^{2} x_{j} \notin S_{I}$, we discard as before all possible Lyndon words of degree $2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}+2 m_{i k} \mathbf{e}_{i}$, except $x_{l} x_{k} x_{j} x_{k} x_{i}^{2 m_{i j}}$; but this is not an element of $S_{I}$, because $x_{k} x_{l} x_{k} x_{j} \notin S_{I}$. Thus $2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}+2 m_{i j} \mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B})$.
- If $i=j$ (analogously, if $i=l$ ), then $s_{j}\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right)=2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B})$ if $m_{j k}=1$ by Lemma 5.4, or $s_{j}\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right)=2 \mathbf{e}_{k}+3 \mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B})$ if $m_{j k}=2$ by Lemma 5.5.
- If $i=k$, then $s_{k}\left(2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}\right)=\mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B})$, since $m_{j l}=0$.

Also, if $\mathbf{u} \in\left\{\mathbf{e}_{k}+\mathbf{e}_{j}, \mathbf{e}_{k}+\mathbf{e}_{l}, \mathbf{e}_{k}, \mathbf{e}_{j}, \mathbf{e}_{l}\right\}$, then $\mathbf{u} \in \Delta\left(\mathfrak{B}\left(V_{i}\right)\right)$, so $s_{i}(\mathbf{u}) \in \Delta(\mathfrak{B}(V))$. The canonical surjective algebra morphisms from $T(V)$ to $\mathfrak{B}$ and $\mathfrak{B}(V)$ induce a surjective algebra morphism $\mathfrak{B} \rightarrow \mathfrak{B}(V)$, so $\Delta(\mathfrak{B}(V)) \subseteq \Delta(\mathfrak{B})$; in particular, each $s_{i}(\mathbf{u})$ lies in $\Delta(\mathfrak{B})$.

Consider a basis as in Proposition 1.11 for an order such that $x_{j}<x_{k}<x_{l}$. From Lemma 2.7, $x_{j} x_{k}, x_{k} x_{l}, x_{j} x_{k} x_{l}$ are elements of this basis, since they are not linear combinations of greater words modulo $I_{i}$, the ideal of $T\left(V_{i}\right)$ such that $s_{i}(\mathfrak{B})=$ $T\left(V_{i}\right) / I_{i}$. In the same way, $\left(x_{k} x_{l}\right)\left(x_{j} x_{k}\right), x_{l} x_{k}\left(x_{j} x_{k}\right),\left(x_{k} x_{l}\right) x_{k} x_{j}, x_{k}\left(x_{j} x_{k} x_{l}\right), x_{l} x_{k}^{2} x_{j}$ (if $x_{k}^{2} \neq 0$ ) are elements of this basis, where the parenthesis indicates the Lyndon decomposition as nonincreasing products of Lyndon words. Also, $x_{j} x_{l}, x_{j} x_{k}^{2}, x_{k}^{2} x_{l}$ are not in this basis, by (5-3). By the relation (2-15) between Hilbert series and the fact that $2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l} \notin s_{i}\left(\Delta^{+}(\mathfrak{B})\right)$, we note that $x_{j} x_{k} x_{l} x_{k}$ is not an element of the basis. Thus this word is a linear combination of greater words. By Lemma 5.4 , this implies that (5-4) holds in $s_{i}(\mathfrak{B})$.

Proof of (5-37). As before, we prove first that $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}\right) \notin \Delta^{+}(\mathfrak{B})$ case by case:

- If $m_{i k}=m_{i j}=0$, then $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}\right)=3 \mathbf{e}_{k}+2 \mathbf{e}_{j} \notin \Delta^{+}(\mathfrak{B})$ by assumption.
- If $m_{i k}=0, m_{i j}=1$, then $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}\right)=2 \mathbf{e}_{i}+3 \mathbf{e}_{k}+2 \mathbf{e}_{j}$. If we consider an order such that $x_{k}<x_{i}<x_{j}$, a Lyndon word of degree $2 e_{i}+3 e_{k}+2 e_{j}$ in $S_{I}$ begins with $x_{k}$, and $x_{k} x_{i}$ is not a factor, because $x_{k} x_{i}=q_{k i} x_{i} x_{j}$. Thus the possible Lyndon words with these conditions are $x_{k}^{2} x_{j} x_{i} x_{k} x_{j} x_{i}$ and $x_{k}^{2} x_{j} x_{k} x_{j} x_{i}^{2}$; the first is not in $S_{I}$ because from (5-4) for $j, k, i$ we can express $x_{j} x_{i} x_{k} x_{j}$ as a linear combination of greater words, and the second is not in $S_{I}$ because $x_{k}^{2} x_{j} x_{k} x_{j} \notin S_{I}$.
- If $m_{i k}=1, m_{i j}=0$, then $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}\right)=3 \mathbf{e}_{i}+3 \mathbf{e}_{k}+2 \mathbf{e}_{j}$. If we consider an order such that $x_{j}<x_{i}<x_{k}$, a Lyndon word of degree $3 e_{i}+3 e_{k}+2 e_{j}$ in $S_{I}$ begins with $x_{j}$, and $x_{j} x_{i}$ is not a factor. Using that also $x_{i}^{2} x_{k}, x_{j}^{2} x_{k} \notin S_{I}$, the possible Lyndon word under these conditions is $x_{j} x_{k} x_{i} x_{j} x_{k} x_{i} x_{k} x_{i}$. But from the condition on the $m_{r s}$, we are in cases $C_{\theta}$ or $F_{4}$, and we use that $\left(\operatorname{ad} x_{i}\right)^{2} x_{k}=0$, $q_{i i} \neq-1$ to replace $x_{i} x_{k} x_{i}$ by a linear combination of $x_{i}^{2} x_{k}$ and $x_{k} x_{i}^{2}$, and also use $x_{j} x_{i}=q_{j i} x_{i} x_{j}$, so we conclude that $x_{j} x_{k} x_{i} x_{j} x_{k} x_{i} x_{k} x_{i} \notin S_{I}$.
- If $i=j$, then $s_{j}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}\right)=3 \mathbf{e}_{k}+\mathbf{e}_{j} \notin \Delta^{+}(\mathfrak{B})$, since $m_{k j}=2$.
- If $i=k$, then $s_{k}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}\right)=\mathbf{e}_{k}+2 \mathbf{e}_{j} \notin \Delta^{+}(\mathfrak{B})$, since $m_{j k}=1$.

If $\mathbf{v} \in\left\{\mathbf{e}_{k}+\mathbf{e}_{j}, 2 \mathbf{e}_{k}+\mathbf{e}_{j}, \mathbf{e}_{k}, \mathbf{e}_{j}\right\}$, then $\mathbf{v} \in \Delta\left(\mathfrak{B}\left(V_{i}\right)\right)$, so $s_{i}(\mathbf{v}) \in \Delta(\mathfrak{B}(V))$. Since $\Delta(\mathfrak{B}(V)) \subseteq \Delta(\mathfrak{B})$; in particular, each $\mathbf{v}$ lies in $s_{i}(\Delta(\mathfrak{B}))$.

As in (a), consider a basis as in Proposition 1.11 for an order such that $x_{k}<x_{j}$. In a similar way, $x_{k} x_{j}, x_{k}^{2} x_{j}$ are elements of this basis, but $x_{k}^{3} x_{j}$ and $x_{k} x_{j}^{2}$ are not in this basis by (5-3). By Lemma 2.7, $\left(x_{k} x_{j}\right)\left(x_{k}^{2} x_{j}\right), x_{j}\left(x_{k}^{2} x_{j}\right) x_{k},\left(x_{k} x_{j}\right)^{2} x_{k}, x_{j}\left(x_{k} x_{j}\right) x_{k}^{2}$, $x_{j}^{2} x_{k}^{3}$ (the last if $x_{j}^{2}, x_{k}^{3} \neq 0$ ) are not linear combinations of greater words modulo $I_{i}$, so they are elements of the chosen basis. By the relation (2-15) between Hilbert series and the fact that $3 \mathbf{e}_{k}+2 \mathbf{e}_{j} \notin s_{i}\left(\Delta^{+}(\mathfrak{B})\right)$, the Lyndon word $x_{k}^{2} x_{j} x_{k} x_{j}$ is not an element of the basis. Thus this word is a linear combination of greater words, and by Lemma 5.5, this implies that (5-6) holds in $s_{i}(\mathfrak{B})$.

Proof of (5-38). We prove case by case that

$$
s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}\right) \notin \Delta^{+}(\mathfrak{B}) .
$$

- If $m_{i k}=m_{i j}=m_{i l}=0$, then $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}\right)=3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}$, and this is not in $\Delta^{+}(\mathfrak{B})$ by Lemma 5.6.
- If $i \neq j, k, l$ and $m_{i k} \neq 0$, the only possibility is $m_{i k}=m_{k i}=1$, so $V$ is of type $F_{4}$. Thus $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}\right)=3 \mathbf{e}_{i}+3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}$. For the order $x_{l}<x_{j}<x_{k}<x_{i}$, the only possible Lyndon word without the factors $x_{l} x_{j}^{2}, x_{l} x_{k}, x_{l} x_{i}, x_{j}^{2} x_{k}, x_{j} x_{i}$, $x_{k} x_{i}^{2}, x_{k}^{2} x_{i}$ is $x_{l} x_{j} x_{k} x_{i} x_{j} x_{k} x_{i} x_{k} x_{i}$. Using the quantum Serre relations and the fact that $q_{i i}=q_{k k} \neq-1$, we see that this Lyndon word is not in $S_{I}$. Thus $3 \mathbf{e}_{i}+3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B})$.
- $i \neq j, k, l$ and $m_{i j} \neq 0$ : there are no standard braided vector spaces with these values.
- If $i \neq j, k, l$ and $m_{i l} \neq 0$, the unique possibility is $m_{i l}=m_{l i}=1$. In this case $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}\right)=3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}+\mathbf{e}_{i}$. If we consider $x_{k}<x_{j}<x_{l}<x_{i}$, the only possible Lyndon word of this degree without the factors $x_{k} x_{l}, x_{k} x_{i}, x_{j} x_{i}$, $x_{k}^{3} x_{j}, x_{k} x_{j}^{2}$ is $x_{k}^{2} x_{j} x_{l} x_{i} x_{k} x_{i}$. But by assumption,

$$
\left[\left[x_{k}^{2} x_{j} x_{l}\right]_{c},\left[x_{k} x_{j}\right]_{c}\right]_{c}=\left[x_{i},\left[x_{k} x_{j}\right]_{c}\right]_{c}=0
$$

so $\left[x_{k}^{2} x_{j} x_{l} x_{i} x_{k} x_{i}\right]_{c}=\left[\left[x_{k}^{2} x_{j} x_{l} x_{i}\right]_{c},\left[x_{k} x_{j}\right]_{c}\right]_{c}=0$, and $x_{k}^{2} x_{j} x_{l} x_{i} x_{k} x_{i} \notin S_{I}$.

- If $i=k$, then $s_{i}\left(3 \mathbf{e}_{i}+2 \mathbf{e}_{j}+\mathbf{e}_{l}\right)=\mathbf{e}_{i}+2 \mathbf{e}_{j}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B})$, by Lemma 5.4.
- If $i=j$, then $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{i}+\mathbf{e}_{l}\right)=3 \mathbf{e}_{k}+2 \mathbf{e}_{i}+\mathbf{e}_{l} \notin \Delta^{+}(\mathfrak{B})$, by Lemma 5.6.
- If $i=k$, then $s_{i}\left(3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{i}\right)=\mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{i} \notin \Delta^{+}(\mathfrak{B})$, as before.

Now, if $\mathbf{w} \in\left\{\mathbf{e}_{k}, \mathbf{e}_{j}, \mathbf{e}_{l}, \mathbf{e}_{k}+\mathbf{e}_{j}, \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, 2 \mathbf{e}_{k}+\mathbf{e}_{j}, 2 \mathbf{e}_{k}+\mathbf{e}_{j}+\mathbf{e}_{l}, 2 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l}\right\}$, then $\mathbf{w} \in \Delta\left(\mathfrak{B}\left(V_{i}\right)\right)$, so $s_{i}(\mathbf{w}) \in \Delta(\mathfrak{B}(V))$, hence $s_{i}(\mathbf{w}) \in \Delta(\mathfrak{B})$.

Consider a basis as in Proposition 1.11 for an order such that $x_{k}<x_{j}<x_{l}$. Then $x_{j} x_{k}$ and $x_{k} x_{l}$ are elements of this basis. We know that $x_{k} x_{l}, x_{k}^{3} x_{j}, x_{k} x_{j}^{2}$, $x_{k} x_{j} x_{l} x_{k}, x_{k}^{2} x_{j} x_{k} x_{j}$ are not elements of the basis, since (5-3), (5-4) and (5-6) hold in $\mathfrak{B}$. By Lemma 2.7, the relation (2-15) between Hilbert series and the fact that $3 \mathbf{e}_{k}+2 \mathbf{e}_{j}+\mathbf{e}_{l} \notin s_{i}\left(\Delta^{+}(\mathfrak{B})\right)$, the Lyndon word $x_{k}^{2} x_{j} x_{l} x_{k} x_{j}$ is not an element of the basis. Thus this word is a linear combination of greater words. By Lemma 5.6, this implies that (5-8) holds in $s_{i}(\mathfrak{B})$.

This concludes the proof of Lemma 5.23. Note also that $s_{i}(\mathfrak{B})$ is of the same type as $\mathfrak{B}$.

Let $V$ be of a type different from $G_{2}$. We define the algebra $\hat{\mathfrak{B}}(V):=T(V) / \Im(V)$, where $\mathfrak{I}(V)$ is the two-sided ideal of $T(V)$ generated by

- $\left(\operatorname{ad}_{c} x_{k}\right)^{m_{k j}+1} x_{j}, k \neq j$;
- $\left[\left(\operatorname{ad}_{c} x_{j}\right)\left(\operatorname{ad}_{c} x_{k}\right) x_{l}, x_{k}\right]_{c}, l \neq k \neq j, q_{k k}=-1, m_{k j}=m_{k l}=1$;
- $\left[\left(\operatorname{ad}_{c} x_{k}\right)^{2} x_{j},\left(\operatorname{ad}_{c} x_{k}\right) x_{j}\right]_{c}, k \neq j, q_{k k} \in \mathbb{G}_{3}$ or $q_{j j}=-1, m_{k j}=2, m_{j k}=1$;
- $\left[\left(\operatorname{ad}_{c} x_{k}\right)^{2}\left(\operatorname{ad}_{c} x_{j}\right) x_{l},\left(\operatorname{ad}_{c} x_{k}\right) x_{j}\right]_{c}, k \neq j \neq l, q_{k k} \in \mathbb{G}_{3}$ or $q_{j j}=-1, m_{k j}=2$, $m_{j k}=m_{j l}=1$.
(Compare with the definitions in Section 4 of [Andruskiewitsch and Schneider 2002a].) Since $V$ is of Cartan type, $\mathfrak{I}(V)$ is a Hopf ideal, by Lemmas 5.7-5.9. Since $\mathfrak{I}(V)$ also is $\mathbb{Z}^{\theta}$-homogeneous, we have $\Im(V) \in \mathfrak{S}$.

By Lemmas 5.4-5.6, the canonical epimorphism $T(V) \rightarrow \mathfrak{B}(V)$ induces an epimorphism of braided graded Hopf algebras

$$
\begin{equation*}
\pi_{V}: \hat{\mathfrak{B}}(V) \rightarrow \mathfrak{B}(V) . \tag{5-39}
\end{equation*}
$$

Also, $\hat{\mathfrak{B}}(V)$ satisfies the conditions in Theorem 2.6 for each $i \in\{1, \ldots, \theta\}$, so we can transform it.

Lemma 5.24. With the notation above, $s_{i}(\hat{\mathfrak{B}}(V)) \cong \hat{\mathfrak{B}}\left(V_{i}\right)$.
Proof. By Lemma 5.23, the relations defining $\mathfrak{I}\left(V_{i}\right)$ are satisfied in $s_{i}(\hat{\mathfrak{B}}(V))$. Thus the canonical projections from $T\left(V_{i}\right)$ onto $\hat{\mathfrak{B}}\left(V_{i}\right)$ and $s_{i}(\hat{\mathfrak{B}}(V))$ induce a surjective algebra map $\hat{\mathfrak{B}}\left(V_{i}\right) \rightarrow s_{i}(\hat{\mathfrak{B}}(V))$. Conversely, each relation defining $\mathfrak{I}(V)$ is satisfied in $s_{i}\left(\hat{\mathfrak{B}}\left(V_{i}\right)\right)$, so we have the following situation:


From the relation (2-15) between Hilbert series, we have, for each $\mathbf{u} \in \mathbb{N}^{\theta}$,

$$
\operatorname{dim} s_{i}(\hat{\mathfrak{B}}(V))^{\mathbf{u}}=\sum_{\substack{k \in \mathbb{N}: \mathbf{u}-k \mathbf{e}_{i} \in \mathbb{N}^{\theta} \\ s_{i}\left(\mathbf{u}-k \mathbf{e}_{i}\right) \in \mathbb{N}^{\theta}}} \operatorname{dim} \hat{\mathfrak{B}}(V)^{s_{i}\left(\mathbf{u}-k \mathbf{e}_{i}\right)}
$$

and a analogous relation for $\operatorname{dim} s_{i}\left(\hat{\mathfrak{B}}\left(V_{i}\right)\right)^{\mathbf{u}}$. But in view of the previous surjections we have

$$
\operatorname{dim} s_{i}(\hat{\mathfrak{B}}(V))^{\mathbf{u}} \leq \operatorname{dim} \hat{\mathfrak{B}}\left(V_{i}\right)^{\mathbf{u}}, \quad \operatorname{dim} s_{i}\left(\hat{\mathfrak{B}}\left(V_{i}\right)\right)^{\mathbf{u}} \leq \operatorname{dim} \hat{\mathfrak{B}}(V)^{\mathbf{u}}
$$

for each $\mathbf{u} \in \mathbb{N}^{\theta}$. Since $s_{i}^{2}=\mathrm{id}$, each of these inequalities is in fact an equality, and $s_{i}(\hat{\mathfrak{B}}(V))=\hat{\mathfrak{B}}\left(V_{i}\right)$.

We are now able to prove one of the main results of this paper.
Theorem 5.25. Let $V$ be a braided vector space of Cartan type, of dimension $\theta$, and $C=\left(a_{i j}\right)_{i, j \in\{1, \ldots, \theta\}}$ the corresponding finite Cartan matrix, where $a_{i j}:=-m_{i j}$.

The Nichols algebra $\mathfrak{B}(V)$ is presented by the generators $x_{i}$, for $1 \leq i \leq \theta$, and the relations

$$
\begin{gather*}
x_{\alpha}^{N_{\alpha}}=0, \quad \alpha \in \Delta^{+}  \tag{5-40}\\
\operatorname{ad}_{c}\left(x_{k}\right)^{1-a_{k j}}\left(x_{j}\right)=0, \quad k \neq j \tag{5-41}
\end{gather*}
$$

If there exist $j \neq k \neq l$ such that $m_{k j}=m_{k l}=1, q_{k k}=-1$, then

$$
\begin{equation*}
\left[\left(\operatorname{ad} x_{k}\right) x_{j},\left(\operatorname{ad} x_{k}\right) x_{l}\right]_{c}=0 \tag{5-42}
\end{equation*}
$$

If there exist $k \neq j$ such that $m_{k j}=2, m_{j k}=1, q_{k k} \in \mathbb{G}_{3}$ or $q_{j j}=-1$, then

$$
\begin{equation*}
\left[\left(\operatorname{ad} x_{k}\right)^{2} x_{j},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c}=0 \tag{5-43}
\end{equation*}
$$

If there exist $k \neq j \neq l$ such that $m_{k j}=2, m_{j k}=m_{j l}=1, q_{k k} \in \mathbb{G}_{3}$ or $q_{j j}=-1$, then

$$
\begin{equation*}
\left[\left(\operatorname{ad} x_{k}\right)^{2}\left(\operatorname{ad} x_{j}\right) x_{l},\left(\operatorname{ad} x_{k}\right) x_{j}\right]_{c}=0 \tag{5-44}
\end{equation*}
$$

If $\theta=2, V$ if of type $G_{2}$, and $q_{11} \in \mathbb{G}_{4}$ or $q_{22}=-1$, then

$$
\begin{align*}
{\left[\left(\operatorname{ad} x_{1}\right)^{3} x_{2},\left(\operatorname{ad} x_{1}\right)^{2} x_{2}\right]_{c} } & =0  \tag{5-45}\\
{\left[x_{1},\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right]_{c} } & =0  \tag{5-46}\\
{\left[\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c},\left[x_{1} x_{2}\right]_{c}\right]_{c} } & =0  \tag{5-47}\\
{\left[\left[x_{1}^{2} x_{2}\right]_{c},\left[x_{1}^{2} x_{2} x_{1} x_{2}\right]_{c}\right]_{c} } & =0 \tag{5-48}
\end{align*}
$$

The following elements constitute a basis of $\mathfrak{B}(V)$ :

$$
x_{\beta_{1}}^{h_{1}} x_{\beta_{2}}^{h_{2}} \ldots x_{\beta_{P}}^{h_{P}}, \quad \text { where } 0 \leq h_{j} \leq N_{\beta_{j}}-1 \text {, if } \beta_{j} \in S_{I}, \text { for } 1 \leq j \leq P
$$

Proof. We may assume that $C$ is connected. For $V$ of type $G_{2}$, the result was proved in Theorem 5.22. So we can assume $m_{k j} \neq 3, k \neq j$.

The statement about the PBW basis was proved in Corollary 4.2; see the definition of the $x_{\alpha}$ in Section 4B.

Consider the images of the $x_{\alpha}$ in $\hat{\mathfrak{B}}(V)$; they correspond in $\mathfrak{B}(V)$ with the $x_{\alpha}$, and are PBW generators for a basis constructed as in Theorem 1.12, considering the same order in the letters. As we observed in (5-39), there exists a surjective morphism of braided Hopf algebras $\hat{\mathfrak{B}}(V) \rightarrow \mathfrak{B}(V)$, so

$$
\Delta(\mathfrak{B}(V)) \subseteq \Delta(\hat{\mathfrak{B}}(V)) .
$$

Also, $\hat{\mathfrak{B}}(V)$ satisfies the conditions in Theorem 2.6 for each $i \in\{1, \ldots, \theta\}$, so we can transform it. By Lemma 5.24 , the new algebra is $\hat{\mathfrak{B}}\left(V_{i}\right)$, so we can continue. Consider the sets

$$
\hat{\Delta}:=\bigcup\left\{\Delta\left(s_{i_{1}} \ldots s_{i_{k}} \hat{\mathfrak{B}}\right): k \in \mathbb{N}, 1 \leq i_{1}, \ldots, i_{k} \leq \theta\right\}, \quad \hat{\Delta}^{+}:=\Delta \cap \mathbb{N}^{\theta} ;
$$

$\hat{\Delta}$ is invariant by the $s_{i}$. Also, $\Delta(\mathfrak{B}(V)) \subseteq \Delta$, and

$$
\Delta\left(s_{i_{1}} \ldots s_{i_{k}} \hat{\mathfrak{B}}(V)\right)=s_{i_{1}} \ldots s_{i_{k}} \Delta(\hat{\mathfrak{B}}(V))
$$

Consider $\alpha \in \hat{\Delta}^{+} \backslash \Delta^{+}(\mathfrak{B}(V))$. Suppose that $\alpha$ is not of the form $m \alpha_{i}$ for $m \in \mathbb{N}$ and $i \in\{1, \ldots, \theta\}$, and that it is of minimal height among such roots. For each $s_{i}$, since $\alpha$ is not a multiple of $\alpha_{i}$, we have $s_{i}(\alpha) \in \Delta^{+} \backslash \Delta^{+}(\mathfrak{B}(V))$; hence $\operatorname{deg} s_{i}(\alpha)-\operatorname{deg} \alpha \geq 0$. But $\alpha=\sum_{i=1}^{\theta} b_{i} \mathbf{e}_{i}$, so $\sum_{i=1}^{\theta} b_{i} a_{i j} \leq 0$, and since $b_{i} \geq 0$, we have $\sum_{i, j=1}^{\theta} b_{i} a_{i j} b_{j} \leq 0$. This contradicts the fact that $\left(a_{i j}\right)$ is definite positive, and $\left(b_{i}\right) \geq 0,\left(b_{i}\right) \neq 0$.

Also, $m \mathbf{e}_{i} \in \Delta^{+}(\hat{\mathfrak{B}}) \Longleftrightarrow m=N_{\mathbf{e}_{i}}$ or $m=1$, since $x_{i}^{N_{e_{i}}} \neq 0$. Hence

$$
\Delta(\hat{\mathfrak{B}}(V))=\Delta(\mathfrak{B}(V)) \cup\left\{N_{\alpha} \alpha: \alpha \in \Delta(\mathfrak{B}(V))\right\} .
$$

This follows since by Corollary 4.2 each $\alpha \in \Delta^{+}(\mathfrak{B}(V))$ is of the form

$$
\alpha=s_{i_{1}} \cdots s_{i_{m}}\left(\mathbf{e}_{j}\right), \quad i_{1}, \ldots, i_{m}, j \in\{1, \ldots, \theta\} .
$$

Now, $N_{\mathbf{e}_{j}} \mathbf{e}_{j} \in \Delta(\hat{\mathfrak{B}}(V))$, so

$$
N_{\alpha} \alpha=N_{\mathbf{e}_{j}} \alpha=s_{i_{1}} \ldots s_{i_{m}}\left(N_{\mathbf{e}_{j}} \mathbf{e}_{j}\right) \in \Delta(\hat{\mathfrak{B}}(V)) .
$$

Also, each degree $N_{\alpha} \alpha$ has multiplicity one in $\Delta(\hat{\mathfrak{B}}(V))$.
Suppose there exist Lyndon words of degree $N_{\alpha} \alpha$, and consider one such word $u$ of minimal height. Let $u=v w$ be a Shirshov decomposition thereof, and put

$$
\beta:=\operatorname{deg} v, \gamma:=\operatorname{deg} w \in \Delta^{+}(\hat{\mathfrak{B}}(V))
$$

By the preceding assumption, $\beta, \gamma \in \Delta^{+}(\mathfrak{B}(V))$. Write

$$
\alpha=\sum_{k=1}^{\theta} a_{k} \mathbf{e}_{k}, \quad \beta=\sum_{k=1}^{\theta} b_{k} \mathbf{e}_{k}, \quad \gamma=\sum_{k=1}^{\theta} c_{k} \mathbf{e}_{k},
$$

so $N_{\alpha} a_{k}=b_{k}+c_{k}$, for each $k \in\{1, \ldots, \theta\}$. We can assume, by taking a subdiagram if necessary, that $a_{1}, a_{\theta} \neq 0$.

Now, if $V$ is of type $F_{4}$ and $\beta=2 \mathbf{e}_{1}+3 \mathbf{e}_{2}+4 \mathbf{e}_{3}+3 \mathbf{e}_{4}$, then $c_{1}=0, a_{1}=1$, $N_{\alpha}=2$, or $a_{1}=c_{1}=1, N_{\alpha}=3$, since $\alpha, \gamma \neq \beta$.

- If $N_{\alpha}=3$, then $3 a_{2}=3+c_{2}$. Hence $c_{2}=0$, so $c_{3}=c_{4}=0$, or $c_{2}=3$, and $c_{3}=4, c_{4}=2$. But in both cases we have a contradiction to $\alpha \in \mathbb{N}^{4}$.
- If $N_{\alpha}=2, c_{1}=0$, then $c_{2}$ and $c_{4}$ are odd, and $c_{3}$ is even and nonzero. The only possibility is $\gamma=\mathbf{e}_{2}+2 \mathbf{e}_{3}+\mathbf{e}_{4}$, so $\alpha=\mathbf{e}_{1}+2 \mathbf{e}_{2}+3 \mathbf{e}_{3}+2 \mathbf{e}_{4}$. But $q_{\alpha}=q \neq-1$, so $N_{\alpha} \neq 2$, which is a contradiction.

Thus we can assume $b_{1}, c_{1} \leq 1$ or $b_{\theta}, c_{\theta} \leq 1$, so $a_{1}=b_{1}=c_{1}=1$ or $a_{\theta}=b_{\theta}=$ $c_{\theta}=1$; in both cases, $N_{\alpha}=2$. For each possible $\beta$ with $b_{1} \neq 0$ (by the assumption that $a_{1} \neq 0$, we have $b_{1} \neq 0$ or $c_{1} \neq 0$ ), we look for $\gamma$ such that $\beta+\gamma$ has even coordinates. In types $A, D$ and $E$ there are no such pairs of roots. As for the other types:

- $B_{\theta}: \beta=\mathbf{v}_{i \theta}, \gamma=\mathbf{u}_{i+1, \theta}$. Then $\alpha=\mathbf{u}_{1 \theta}$, but $q_{\alpha}=q_{11} \neq-1$, which is a contradiction.
- $C_{\theta}: \beta=\mathbf{w}_{11}, \gamma=\mathbf{e}_{\theta}$. Then $\alpha=\mathbf{u}_{1 \theta}$, but $q_{\alpha}=q_{\theta \theta} \neq-1$, which is a contradiction.
- $F_{4}: \beta=\mathbf{e}_{1}+\mathbf{e}_{2}+2 \mathbf{e}_{3}+2 \mathbf{e}_{4}, \gamma=\mathbf{e}_{1}+\mathbf{e}_{2}$, or $\beta=\mathbf{e}_{1}+2 \mathbf{e}_{2}+2 \mathbf{e}_{3}+2 \mathbf{e}_{4}, \gamma=\mathbf{e}_{1}$.

In both cases, $\alpha=\mathbf{e}_{1}+\mathbf{e}_{2}+\mathbf{e}_{3}+\mathbf{e}_{4}$, but $q_{\alpha}=q \neq-1$, which is a contradiction.
Thus each root $N_{\alpha} \alpha$ corresponds to $x_{\alpha}^{N_{\alpha}}$, and each $x_{\alpha}$ has infinite height, as before. The elements

$$
x_{\beta_{1}}^{h_{1}} x_{\beta_{2}}^{h_{2}} \ldots x_{\beta_{P}}^{h_{P}}, \quad \text { where } 0 \leq h_{j}<\infty, \text { if } \beta_{j} \in S_{I}, \text { for } 1 \leq j \leq P \text {, }
$$

form a basis of $\hat{\mathfrak{B}}(V)$ as a vector space.
Now let $\bar{I}(V)$ be the ideal of $T(V)$ generated by the relations (5-41)-(5-44) and (5-40). We have $\mathfrak{I}(V) \subseteq \bar{I}(V) \subseteq I(V)$, so the corresponding projections induce a surjective morphism of algebras $\phi: \mathfrak{B} \rightarrow \mathfrak{B}(V)$, where $\mathfrak{B}:=T(V) / \bar{I}(V)$ :


Also, the elements

$$
x_{\beta_{1}}^{h_{1}} x_{\beta_{2}}^{h_{2}} \ldots x_{\beta_{P}}^{h_{P}}, \quad \text { where } 0 \leq h_{j}<N_{\beta_{j}} \text {, if } \beta_{j} \in S_{I} \text {, for } 1 \leq j \leq P,
$$

generate $\mathfrak{B}$ as a vector space, because they correspond to images of generators of $\hat{\mathfrak{B}}(V)$ and are nonzero (as before, each nonincreasing product of hyperwords such that $h_{j} \geq N_{\beta_{j}}$ is zero in $\mathfrak{B}$ ). But $\phi$ is surjective, and the corresponding images of these elements form a basis of $\mathfrak{B}(V)$, so $\phi$ is an isomorphism.

## Acknowledgments

I thank Nicolás Andruskiewitsch for his guidance, his important suggestions and his careful reading of this work. I also thank the referee for many useful comments, especially the suggestion to shorten the proofs of Lemma 2.4 and Theorem 4.1.

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Communicated by Susan Montgomery
Received 2008-04-03 Revised 2008-10-02 Accepted 2008-11-11

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[^0]:    MSC2000: primary 17B37; secondary 16W20, 16 W 30.
    Keywords: quantized enveloping algebras, Nichols algebras, automorphisms of noncommutative algebras, pointed Hopf algebras.

[^1]:    ${ }^{1}$ Following the traditional notation in the theory of Lie algebras, we should speak about systems of real roots, since in the case of braidings of symmetrizable Cartan type one would get just the real roots. But we prefer to follow the denomination in [Andruskiewitsch and Angiono 2008]

