## ANALYSIS \& PDE

Volume 6
No. $7>2013$

JEROME LEROUSSEAU AND NICOIAS LERAER

# CARIEMAN ESTMAIES FOR A MISOTROPIC EI II PIIC OPERATORS <br> WITH JUMPS AT AN INTERFACE 

# CARLEMAN ESTIMATES FOR ANISOTROPIC ELLIPTIC OPERATORS WITH JUMPS AT AN INTERFACE 

Jérôme Le Rousseau and Nicolas Lerner


#### Abstract

We consider a second-order self-adjoint elliptic operator with an anisotropic diffusion matrix having a jump across a smooth hypersurface. We prove the existence of a weight function such that a Carleman estimate holds true. We also prove that the conditions imposed on the weight function are sharp.


1. Introduction ..... 1601
2. Framework ..... 1611
3. Estimates for first-order factors ..... 1617
4. Proof of the Carleman estimate ..... 1623
5. Necessity of the geometric assumption on the weight function ..... 1634
Appendix ..... 1637
References ..... 1645

## 1. Introduction

1A. Carleman estimates. Let $P\left(x, D_{x}\right)$ be a differential operator defined on some open subset of $\mathbb{R}^{n}$. A Carleman estimate for this operator is the weighted a priori inequality

$$
\begin{equation*}
\left\|e^{\tau \varphi} P w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \gtrsim\left\|e^{\tau \varphi} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}, \tag{1-1}
\end{equation*}
$$

where the weight function $\varphi$ is real-valued with a nonvanishing gradient, $\tau$ is a large positive parameter, and $w$ is any smooth compactly supported function. This type of estimate was used for the first time by T. Carleman [1939] to handle uniqueness properties for the Cauchy problem for nonhyperbolic operators. To this day, it remains essentially the only method to prove unique continuation properties for ill-posed problems, ${ }^{1}$ and in particular to handle uniqueness of the Cauchy problem for elliptic operators with nonanalytic coefficients. ${ }^{2}$ This tool has been refined, polished and generalized by manifold authors.

[^0]A. P. Calderón [1958] gave a very important development of the Carleman method with a proof of an estimate of the form (1-1) using a pseudodifferential factorization of the operator, giving a new start to singular-integral methods in local analysis. L. Hörmander [1958; 1963, Chapter VIII] showed that local methods could provide the same estimates, with weaker assumptions on the regularity of the coefficients of the operator.

For instance, for second-order elliptic operators with real coefficients ${ }^{3}$ in the principal part, Lipschitz continuity of the coefficients suffices for a Carleman estimate to hold and thus for unique continuation across a $\mathscr{C}^{1}$ hypersurface. Naturally, pseudodifferential methods require more derivatives, at least tangentially, that is, essentially on each level surface of the weight function $\varphi$. Chapters 17 and 28 in [Hörmander 1985b] contain more references and results.

Furthermore, it was shown by A. Pliś [1963] that Hölder continuity is not enough to get unique continuation: he constructed a real homogeneous linear differential equation of second order and of elliptic type on $\mathbb{R}^{3}$ without the unique continuation property, although the coefficients are Hölder-continuous with any exponent less than one. The constructions by K. Miller [1974] and later by N. Mandache [1998] and N. Filonov [2001] showed that Hölder continuity is not sufficient to obtain unique continuation for second-order elliptic operators, even in divergence form (see also [Buonocore and Manselli 2000; Schulz 1998] for the particular two-dimensional case where boundedness is essentially enough to get unique continuation for elliptic equations in the case of $W^{1,2}$ solutions).

The results cited above are related to the regularity of the principal part of the second-order operator. For strong unique continuation properties for second-order operators with Lipschitz-continuous coefficients, many results are also available for differential inequalities with singular potentials, originating with the seminal work of D. Jerison and C. Kenig [1985]. The reader is also referred to the work of C. Sogge [1989] and some of the most recent and general results of H. Koch and D. Tataru [2001; 2002].

In more recent years, the field of applications of Carleman estimates has gone beyond the original domain. They are also used in the study of inverse problems (see, for example, [Bukhgeim and Klibanov 1981; Isakov 1998; Imanuvilov et al. 2003; Kenig et al. 2007]) and control theory for PDEs. Through unique continuation properties, they are used for the exact controllability of hyperbolic equations [Bardos et al. 1992]. They also yield the null controllability of linear parabolic equations [Lebeau and Robbiano 1995] and the null controllability of classes of semilinear parabolic equations [Fursikov and Imanuvilov 1996; Barbu 2000; Fernández-Cara and Zuazua 2000].

1B. Jump discontinuities. Although the situation seems to be almost completely clarified by the previous results, with a minimal and somewhat necessary condition on Lipschitz continuity, we are interested in the following second-order elliptic operator $\mathcal{L}$ :

$$
\begin{equation*}
\mathcal{L} w=-\operatorname{div}(A(x) \nabla w), \quad A(x)=\left(a_{j k}(x)\right)_{1 \leq j, k \leq n}=A^{T}(x), \quad \inf _{\|\xi\|_{\mathbb{R}^{n}=1}}\langle A(x) \xi, \xi\rangle>0, \tag{1-2}
\end{equation*}
$$

[^1]in which the matrix $A$ has a jump discontinuity across a smooth hypersurface. However, we shall impose some stringent - yet natural - restrictions on the domain of functions $w$, which will be required to satisfy some homogeneous transmission conditions, detailed in the next sections. Roughly speaking, this means that $w$ must belong to the domain of the operator, with continuity at the interface, so that $\nabla w$ remains bounded, and continuity of the flux across the interface, so that $\operatorname{div}(A \nabla w)$ remains bounded, avoiding in particular the occurrence of a simple or multiple layer at the interface. ${ }^{4}$
A. Doubova, A. Osses, and J.-P. Puel [Doubova et al. 2002] tackled that problem in the isotropic case (the matrix $A$ is $c$ Id for scalar $c$ ) with a monotonicity assumption: the observation takes place in the region where the diffusion coefficient $c$ is the "lowest". (The work of Doubova et al. [2002] concerns the case of a parabolic operator, but an adaptation to an elliptic operator is straightforward.) In the one-dimensional case, the monotonicity assumption was relaxed for general piecewise $\mathscr{C}^{1}$ coefficients by A. Benabdallah, Y. Dermenjian, and J. Le Rousseau [Benabdallah et al. 2007] and for coefficients with bounded variations [Le Rousseau 2007]. The case of an arbitrary dimension without any monotonicity condition in the elliptic case was solved by J. Le Rousseau and L. Robbiano [2010]: there the isotropic case is treated, as well as a particular case of anisotropic medium. An extension of their approach to the case of parabolic operators can be found in [Le Rousseau and Robbiano 2011]. A. Benabdallah, Y. Dermenjian, and J. Le Rousseau [Benabdallah et al. 2011] also tackled the situation in which the interface meets the boundary, a case that is typical of stratified media. They treat particular forms of anisotropic coefficients.

The purpose of the present article is to show that a Carleman estimate can be proven for any operator of type (1-2) without an isotropy assumption: $A(x)$ is a symmetric positive-definite matrix with a jump discontinuity across a smooth hypersurface. We also provide conditions on the Carleman weight function that are rather simple to handle, and we prove that they are sharp.

The approach we follow differs from that of [Le Rousseau and Robbiano 2010], where the authors base their analysis on the usual Carleman method for certain microlocal regions and on Calderón projectors for others. The regions they introduce are determined by the ellipticity or nonellipticity of the conjugated operator. The method in [Benabdallah et al. 2011] exploits a particular structure of the anisotropy that allows one to use Fourier series. The analysis is then close to that of [Le Rousseau and Robbiano 2010; 2011] in the sense that second-order operators are inverted in some frequency ranges. Here, our approach is somewhat closer to A. Calderón's original work [1958] on unique continuation: the conjugated operator is factored out in first-order (pseudodifferential) operators, for which estimates are derived. Naturally, the quality of these estimates depends on their elliptic or nonelliptic nature; we thus recover microlocal regions that correspond to those of [Le Rousseau and Robbiano 2010]. Such a factorization is also used in [Imanuvilov and Puel 2003] to address nonhomogeneous boundary conditions.

1C. Notation and statement of the main result. Let $\Omega$ be an open subset of $\mathbb{R}^{n}$ and let $\Sigma$ be a $\mathscr{C}^{\infty}$ oriented hypersurface of $\Omega$; we have the partition

$$
\begin{equation*}
\Omega=\Omega_{+} \cup \Sigma \cup \Omega_{-}, \quad \overline{\Omega_{ \pm}}=\Omega_{ \pm} \cup \Sigma, \quad \Omega_{ \pm} \text {open subsets of } \mathbb{R}^{n}, \tag{1-3}
\end{equation*}
$$

[^2]and we introduce the Heaviside-type functions
\[

$$
\begin{equation*}
H_{ \pm}=\mathbf{1}_{\Omega_{ \pm}} . \tag{1-4}
\end{equation*}
$$

\]

We consider the elliptic second-order operator

$$
\begin{equation*}
\mathcal{L}=D \cdot A D=-\operatorname{div}(A(x) \nabla) \quad(D=-i \nabla) \tag{1-5}
\end{equation*}
$$

where $A(x)$ is a symmetric positive-definite $n \times n$ matrix such that

$$
\begin{equation*}
A=H_{-} A_{-}+H_{+} A_{+}, \quad A_{ \pm} \in \mathscr{C}^{\infty}(\Omega) \tag{1-6}
\end{equation*}
$$

We shall consider functions $w$ of the type

$$
\begin{equation*}
w=H_{-} w_{-}+H_{+} w_{+}, \quad w_{ \pm} \in \mathscr{C}^{\infty}(\Omega) \tag{1-7}
\end{equation*}
$$

We have $d w=H_{-} d w_{-}+H_{+} d w_{+}+\left(w_{+}-w_{-}\right) \delta_{\Sigma} v$, where $\delta_{\Sigma}$ is the Euclidean hypersurface measure on $\Sigma$ and $v$ is the unit conormal vector field to $\Sigma$ pointing into $\Omega_{+}$. To remove the singular term, we assume

$$
\begin{equation*}
w_{+}=w_{-} \quad \text { at } \Sigma \tag{1-8}
\end{equation*}
$$

so that $A d w=H_{-} A_{-} d w_{-}+H_{+} A_{+} d w_{+}$and

$$
\operatorname{div}(A d w)=H_{-} \operatorname{div}\left(A_{-} d w_{-}\right)+H_{+} \operatorname{div}\left(A_{+} d w_{+}\right)+\left\langle A_{+} d w_{+}-A_{-} d w_{-}, v\right\rangle \delta_{\Sigma}
$$

Also, we shall assume that

$$
\begin{equation*}
\left\langle A_{+} d w_{+}-A_{-} d w_{-}, v\right\rangle=0 \quad \text { at } \Sigma \text {, that is, }\left\langle d w_{+}, A_{+} v\right\rangle=\left\langle d w_{-}, A_{-} v\right\rangle, \tag{1-9}
\end{equation*}
$$

so that

$$
\begin{equation*}
\operatorname{div}(A d w)=H_{-} \operatorname{div}\left(A_{-} d w_{-}\right)+H_{+} \operatorname{div}\left(A_{+} d w_{+}\right) \tag{1-10}
\end{equation*}
$$

Conditions (1-8)-(1-9) will be called transmission conditions on the function $w$, and we define the vector space

$$
\begin{equation*}
\mathcal{W}=\left\{H_{-} w_{-}+H_{+} w_{+}\right\}_{w_{ \pm} \in \mathscr{C} \infty(\Omega)}, \quad w_{ \pm} \text {satisfying (1-8)-(1-9). } \tag{1-11}
\end{equation*}
$$

Note that (1-8) is a continuity condition of $w$ across $\Sigma$ and (1-9) is concerned with the continuity of $\langle A d w, v\rangle$ across $\Sigma$, that is, the continuity of the flux of the vector field $A d w$ across $\Sigma$. A weight function suitable for observation from $\Omega_{+}$is defined as a Lipschitz continuous function $\varphi$ on $\Omega$ such that

$$
\begin{equation*}
\varphi=H_{-} \varphi_{-}+H_{+} \varphi_{+}, \quad \varphi_{ \pm} \in \mathscr{C}^{\infty}(\Omega), \quad \varphi_{+}=\varphi_{-}, \quad\left\langle d \varphi_{ \pm}, X\right\rangle>0 \quad \text { at } \Sigma, \tag{1-12}
\end{equation*}
$$

for any positively transverse vector field $X$ to $\Sigma$ (that is, $\langle v, X\rangle>0$ ).
Theorem 1.1. Let $\Omega, \Sigma, \mathcal{L}, \mathcal{W}$ be as in (1-3), (1-5), and (1-11). Then for any compact subset $K$ of $\Omega$, there exist a weight function $\varphi$ satisfying (1-12) and positive constants $C, \tau_{1}$ such that for all $\tau \geq \tau_{1}$ and
all $w \in \mathcal{W}$ with $\operatorname{supp} w \subset K$,

$$
\begin{align*}
& C\left\|e^{\tau \varphi} \mathcal{L} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \\
& \qquad \geq \tau^{3 / 2}\left\|e^{\tau \varphi} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{1 / 2}\left\|H_{+} e^{\tau \varphi} \nabla w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{1 / 2}\left\|H_{-} e^{\tau \varphi} \nabla w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \\
& \quad+\tau^{3 / 2}\left|\left(e^{\tau \varphi} w\right)_{\mid \Sigma}\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|\left(e^{\tau \varphi} \nabla w_{+}\right)_{\mid \Sigma}\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|\left(e^{\tau \varphi} \nabla w_{-}\right)_{\mid \Sigma}\right|_{L^{2}(\Sigma)} \tag{1-13}
\end{align*}
$$

Remark 1.2. The proof of Theorem 1.1 provides an explicit construction of the weight function $\varphi$. The precise properties of $\varphi$ are given in Section 2D, specifically (2-22), (2-24), and (2-26). The weight function is at first constructed only depending on $x_{n}$. Dependency upon the other variables, that is, convexification with respect to $\left\{x_{n}=0\right\}$, is introduced in Section 4E.

Remark 1.3. It is important to notice that whenever a true discontinuity occurs for the vector field $A v$, the space $\mathcal{W}$ does not contain $\mathscr{C}^{\infty}(\Omega)$ : the inclusion $\mathscr{C}^{\infty}(\Omega) \subset \mathcal{W}$ implies by (1-9) that for all $w \in \mathscr{C}^{\infty}(\Omega)$, $\left\langle d w, A_{+} v-A_{-} v\right\rangle=0$ at $\Sigma$, so that $A_{+} v=A_{-v}$ at $\Sigma$, which is continuity for $A v$. The Carleman estimate which is proven in the present paper naturally takes into account these transmission conditions on the function $w$, and it is important to keep in mind that the occurrence of a jump excludes many smooth functions from the space $\mathcal{W}$. On the other hand, we have $\mathcal{W} \subset \operatorname{Lip}(\Omega)$.

Remark 1.4. We also point out the geometric content of our assumptions, which do not depend on the choice of a coordinate system. For each $x \in \Omega$, the matrix $A(x)$ is a positive-definite symmetric mapping from $T_{x}(\Omega)^{*}$ onto $T_{x}(\Omega)$, so that $A(x) d w(x)$ belongs indeed to $T_{x}(\Omega)$ and $A d w$ is a vector field with an $L^{2}$ divergence (inequality (1-13) yields the $L^{2}$ bound by density).

1D. Examples of applications. We mention some applications of the Carleman estimate of Theorem 1.1, namely, controllability for parabolic equations and stabilization for hyperbolic equations.

Following [Lebeau and Robbiano 1995; Lebeau and Zuazua 1998] (see also [Le Rousseau and Robbiano 2010]), we first deduce the following interpolation inequality. With $\alpha \in\left(0, X_{0} / 2\right)$, we set $X=\left(0, X_{0}\right) \times \Omega$, $Y=\left(\alpha, X_{0}-\alpha\right) \times \Omega$.

Theorem 1.5. There exist $C \geq 0$ and $\delta \in(0,1)$ such that for $u \in H^{1}(X)$ that satisfies $u_{ \pm}=\left.u\right|_{\left(0, X_{0}\right) \times \Omega_{ \pm}} \in$ $H^{2}\left(\left(0, X_{0}\right) \times \Omega_{ \pm}\right)$,

$$
u_{+}=u_{-} \quad \text { and } \quad\left\langle d u_{+}, A_{+} \nu\right\rangle=\left\langle d u_{-}, A_{-} \nu\right\rangle \quad \text { at }\left(0, X_{0}\right) \times \Sigma,
$$

and

$$
\left.u\left(x_{0}, x\right)\right|_{x \in \partial \Omega}=0, \quad x_{0} \in\left(0, X_{0}\right), \quad \text { and } \quad u(0, x)=0, x \in \Omega,
$$

we have

$$
\|u\|_{H^{1}(Y)} \leq C\|u\|_{H^{1}(X)}^{\delta}\left(\left\|\left(D_{x_{0}}^{2}+\mathcal{L}\right) u\right\|_{L^{2}(X)}+\left\|\partial_{x_{0}} u(0, x)\right\|_{L^{2}(\omega)}\right)^{1-\delta}
$$

This interpolation inequality was first proven in [Lebeau and Robbiano 1995; Lebeau and Zuazua 1998] for second-order elliptic operators with smooth coefficients and in [Le Rousseau and Robbiano 2010] in the case of an isotropic diffusion coefficient with a jump at an interface. Here, a jump for the whole diffusion matrix is permitted.

Remark 1.6. In fact, the interpolation inequality of Theorem 1.5 rather follows from the nonhomogeneous version of Theorem 1.1 stated in Theorem 2.2 below.

From Theorem 1.5 we can prove an estimation of the loss of orthogonality for the eigenfunctions $\phi_{j}(x)$, $j \in \mathbb{N}$, of the operator $\mathcal{L}$, with Dirichlet boundary conditions, when these eigenfunctions are restricted to some subset $\omega$ of $\Omega$ (see [Lebeau and Zuazua 1998; Jerison and Lebeau 1999] and also [Le Rousseau and Lebeau 2012]). We denote by $\mu_{j}, j \in \mathbb{N}$, the associated eigenvalues, sorted in an increasing sequence.

Theorem 1.7. There exists $C>0$ such that for any $\left(a_{j}\right)_{j \in \mathbb{N}} \subset \mathbb{C}$, we have

$$
\begin{equation*}
\left(\sum_{\mu_{j} \leq \mu}\left|a_{j}\right|^{2}\right)^{1 / 2}=\left\|\sum_{\mu_{j} \leq \mu} a_{j} \phi_{j}\right\|_{L^{2}(\Omega)} \leq C e^{C \sqrt{\mu}}\left\|\sum_{\mu_{j} \leq \mu} a_{j} \phi_{j}\right\|_{L^{2}(\omega)}, \quad \mu>0 . \tag{1-14}
\end{equation*}
$$

In turn, this yields the following null-controllability result for the associated anisotropic parabolic equation with jumps in the coefficients across $\Sigma$ (see [Lebeau and Robbiano 1995; Lebeau and Zuazua 1998; Le Rousseau and Robbiano 2010] and also [Le Rousseau and Lebeau 2012]).

Theorem 1.8. For an arbitrary time $T>0$, an arbitrary nonempty open subset $\omega \subset \Omega$, and an initial condition $y_{0} \in L^{2}(\Omega)$, there exists $v \in L^{2}((0, T) \times \Omega)$ such that the solution $y$ of

$$
\begin{cases}\partial_{t} y+\mathcal{L} y=1_{\omega} u & \text { in }(0, T) \times \Omega  \tag{1-15}\\ y(t, x)=0 & \text { on }(0, T) \times \partial \Omega \\ y(0, x)=y_{0}(x) & \text { in } \Omega\end{cases}
$$

satisfies $y(T)=0$ almost everywhere in $\Omega$.
The interpolation inequality of Theorem 1.5 also yields the stabilization of the hyperbolic equation

$$
\begin{cases}\partial_{t t} y+\mathcal{L} y+a(x) \partial_{t} y=0 & \text { in }(0, T) \times \Omega  \tag{1-16}\\ y(t, x)=0 & \text { on }(0, T) \times \partial \Omega\end{cases}
$$

where $a$ is a nonvanishing nonnegative smooth function. From [Lebeau 1996; Lebeau and Robbiano 1997], we can obtain a resolvent estimate which in turn yields the following energy decay estimate.

Theorem 1.9 [Burq 1998, Theorem 3]. For all $k \in \mathbb{N}$, there exists $C>0$ such that

$$
\left\|\partial_{t} y(t)\right\|_{L^{2}(\Omega)}+\|y(t)\|_{H^{1}(\Omega)} \leq \frac{C}{[\log (2+t)]^{k}}\left(\left\|\partial_{t} y_{\mid t=0}\right\|_{D\left(\mathcal{L}^{k / 2}\right)}+\left\|y_{\mid t=0}\right\|_{D\left(\mathcal{L}^{(k+1) / 2}\right)}\right), \quad t>0
$$

for $y$ a solution to (1-16).
The same decay can also be obtained in the case of a boundary damping (see [Lebeau and Robbiano 1997]).

Remark 1.10. Exponential decay cannot be achieved if the set $\mathcal{O}=\{a>0\}$ does not satisfy the geometrical control condition of [Rauch and Taylor 1974; Bardos et al. 1992]. Because of the jump in the matrix coefficient $A(x)$ here, some bicharacteristics of the hyperbolic operators $\partial_{t t}+\mathcal{L}$ can be trapped in $\Omega_{+}$ or $\Omega_{-}$and may remain away from the stabilization region $\mathcal{O}$.

1E. Sketch of the proof. We provide in this subsection an outline of the main arguments used in our proof. To avoid technicalities, we somewhat simplify the geometric data and the weight function, keeping of course the anisotropy. We consider the operator

$$
\begin{equation*}
\mathcal{L}_{0}=\sum_{1 \leq j \leq n} D_{j} c_{j} D_{j}, \quad c_{j}(x)=H_{+} c_{j}^{+}+H_{-} c_{j}^{-}, \quad c_{j}^{ \pm}>0 \text { constants }, \quad H_{ \pm}=\mathbf{1}_{\left\{ \pm x_{n}>0\right\}}, \tag{1-17}
\end{equation*}
$$

with $D_{j}=\frac{\partial}{i \partial x_{j}}$, and the vector space $\mathcal{W}_{0}$ of functions $H_{+} w_{+}+H_{-} w_{-}, w_{ \pm} \in \mathscr{C}_{c}^{\infty}\left(\mathbb{R}^{n}\right)$, such that

$$
\begin{equation*}
\text { at } x_{n}=0, \quad w_{+}=w_{-}, \quad c_{n}^{+} \partial_{n} w_{+}=c_{n}^{-} \partial_{n} w_{-}\left(\text {transmission conditions across } x_{n}=0\right) . \tag{1-18}
\end{equation*}
$$

As a result, for $w \in \mathcal{W}_{0}$, we have $D_{n} w=H_{+} D_{n} w_{+}+H_{-} D_{n} w_{-}$and

$$
\begin{equation*}
\mathcal{L}_{0} w=\sum_{j}\left(H_{+} c_{j}^{+} D_{j}^{2} w_{+}+H_{-} c_{j}^{-} D_{j}^{2} w_{-}\right) \tag{1-19}
\end{equation*}
$$

We also consider a weight function ${ }^{5}$

$$
\begin{equation*}
\varphi=\underbrace{\left(\alpha_{+} x_{n}+\frac{\beta x_{n}^{2}}{2}\right)}_{\varphi_{+}} H_{+}+\underbrace{\left(\alpha_{-} x_{n}+\frac{\beta x_{n}^{2}}{2}\right)}_{\varphi_{-}} H_{-}, \quad \alpha_{ \pm}>0, \quad \beta>0 \tag{1-20}
\end{equation*}
$$

a positive parameter $\tau$, and the vector space $\mathcal{W}_{\tau}$ of functions $H_{+} v_{+}+H_{-} v_{-}, v_{ \pm} \in \mathscr{C}_{c}^{\infty}\left(\mathbb{R}^{n}\right)$, such that at $x_{n}=0$,

$$
\begin{align*}
v_{+} & =v_{-},  \tag{1-21}\\
c_{n}^{+}\left(D_{n} v_{+}+i \tau \alpha_{+} v_{+}\right) & =c_{n}^{-}\left(D_{n} v_{-}+i \tau \alpha_{-} v_{-}\right) \tag{1-22}
\end{align*}
$$

Observe that $w \in \mathcal{W}_{0}$ is equivalent to $v=e^{\tau \varphi} w \in W_{\tau}$. We have

$$
e^{\tau \varphi} \mathcal{L}_{0} w=\underbrace{e^{\tau \varphi} \mathcal{L}_{0} e^{-\tau \varphi}}_{\mathcal{L}_{\tau}}\left(e^{\tau \varphi} w\right)
$$

so that proving a weighted a priori estimate $\left\|e^{\tau \varphi} \mathcal{L}_{0} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \gtrsim\left\|e^{\tau \varphi} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}$ for $w \in \mathcal{W}_{0}$ amounts to getting $\left\|\mathcal{L}_{\tau} v\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \gtrsim\|v\|_{L^{2}\left(\mathbb{R}^{n}\right)}$ for $v \in \mathcal{W}_{\tau}$.

Step 1 (pseudodifferential factorization). We have, using the Einstein convention on repeated indices $j \in\{1, \ldots, n-1\}$,

$$
\mathcal{L}_{\tau}=\left(D_{n}+i \tau \varphi^{\prime}\right) c_{n}\left(D_{n}+i \tau \varphi^{\prime}\right)+D_{j} c_{j} D_{j}
$$

and for $v \in \mathcal{W}_{\tau}$, by (1-19), with $m_{ \pm}=m_{ \pm}\left(D^{\prime}\right)=\left(c_{n}^{ \pm}\right)^{-1 / 2}\left(c_{j}^{ \pm} D_{j}^{2}\right)^{1 / 2}$,

$$
\mathcal{L}_{\tau} v=H_{+} c_{n}^{+}\left(\left(D_{n}+i \tau \varphi_{+}^{\prime}\right)^{2}+m_{+}^{2}\right) v_{+}+H_{-} c_{n}^{-}\left(\left(D_{n}+i \tau \varphi_{-}^{\prime}\right)^{2}+m_{-}^{2}\right) v_{-},
$$

[^3]so that
\[

$$
\begin{align*}
\mathcal{L}_{\tau} v=H_{+} c_{n}^{+}(D_{n}+i(\overbrace{\tau \varphi_{+}^{\prime}+m_{+}}^{e_{+}}))( & D_{n}+i(\overbrace{\tau \varphi_{+}^{\prime}-m_{+}}^{f_{+}})) v_{+} \\
& +H_{-} c_{n}^{-}(D_{n}+i(\underbrace{\tau \varphi_{-}^{\prime}-m_{-}}_{f_{-}}))(D_{n}+i(\underbrace{\tau \varphi_{-}^{\prime}+m_{-}}_{e_{-}})) v_{-} . \tag{1-23}
\end{align*}
$$
\]

Note that $e_{ \pm}$are elliptic positive in the sense that $e_{ \pm}=\tau \alpha_{ \pm}+m_{ \pm} \gtrsim \tau+\left|D^{\prime}\right|$. At this point, we want to use certain natural estimates for first-order factors on the half-lines $\mathbb{R}_{ \pm}$. Let us, for instance, check on $t>0$ for $\omega \in \mathscr{C}_{c}^{\infty}(\mathbb{R}), \lambda, \gamma$ positive:

$$
\begin{align*}
\| D_{t} \omega+i(\lambda & +\gamma t) \omega \|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2} \\
& =\left\|D_{t} \omega\right\|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2}+\|(\lambda+\gamma t) \omega\|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2}+2 \operatorname{Re}\left\langle D_{t} \omega, i H(t)(\lambda+\gamma t) \omega\right\rangle \\
& \geq \int_{0}^{+\infty}\left((\lambda+\gamma t)^{2}+\gamma\right)|\omega(t)|^{2} d t+\lambda|\omega(0)|^{2} \geq\left(\lambda^{2}+\gamma\right)\|\omega\|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2}+\lambda|\omega(0)|^{2} \tag{1-24}
\end{align*}
$$

which is in a sense a perfect estimate of elliptic type, suggesting that the first-order factor containing $e_{+}$ should be easy to handle. Changing $\lambda$ in $-\lambda$ gives

$$
\left\|D_{t} \omega+i(-\lambda+\gamma t) \omega\right\|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2} \geq 2 \operatorname{Re}\left\langle D_{t} \omega, i H(t)(-\lambda+\gamma t) \omega\right\rangle=\int_{0}^{+\infty} \gamma|\omega(t)|^{2} d t-\lambda|\omega(0)|^{2}
$$

so that $\left\|D_{t} \omega+i(-\lambda+\gamma t) \omega\right\|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2}+\lambda|\omega(0)|^{2} \geq \gamma\|\omega\|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2}$, an estimate of lesser quality, because we need to secure a control of $\omega(0)$ to handle this type of factor.

Step 2 (case $f_{+} \geq 0$ ). Looking at formula (1-23), since the factor containing $e_{+}$is elliptic in the sense given above, we have to discuss the sign of $f_{+}$. Identifying the operator with its symbol, we have $f_{+}=\tau\left(\alpha_{+}+\beta x_{n}\right)-m_{+}\left(\xi^{\prime}\right)$, and thus $\tau \alpha_{+} \geq m_{+}\left(\xi^{\prime}\right)$, yielding a nonnegative $f_{+}$. Iterating the method outlined above on the half-line $\mathbb{R}_{+}$, we get a nice estimate of the form of (1-24) on $\mathbb{R}_{+}$; in particular, we obtain a control ${ }^{6}$ of $v_{+}(0)$ and $D_{n} v_{+}(0)$. From the transmission condition, we have $v_{+}(0)=v_{-}(0)$, and hence this amounts to also controlling $v_{-}(0)$. That control, along with the natural estimates on $\mathbb{R}_{-}$, is enough to prove an inequality of the form of the Carleman estimate we seek.

Step 3 (case $f_{+}<0$ ). Here we assume that $\tau \alpha_{+}<m_{+}\left(\xi^{\prime}\right)$. On $\mathbb{R}_{+}$we can still use the factor containing $e_{+}$, and by (1-23) and (1-24) we can control the quantity

$$
\begin{equation*}
c_{n}^{+}\left(D_{n}+i f_{+}\right) v_{+}(0)=\overbrace{c_{n}^{+}\left(D_{n} v_{+}+i \tau \alpha_{+}\right) v_{+}(0)}^{=\mathcal{V}_{+}}-c_{n}^{+} i m_{+} v_{+}(0) . \tag{1-25}
\end{equation*}
$$

[^4]Our key assumption is

$$
\begin{equation*}
f_{+}(0)<0 \Longrightarrow f_{-}(0) \leq 0 \tag{1-26}
\end{equation*}
$$

Under that hypothesis, we can use the negative factor $f_{-}$on $\mathbb{R}_{-}$(note that $f_{-}$is increasing with $x_{n}$, so that $f_{-}(0) \leq 0 \Longrightarrow f_{-}\left(x_{n}\right)<0$ for $\left.x_{n}<0\right)$. We then control

$$
\begin{equation*}
c_{n}^{-}\left(D_{n}+i e_{-}\right) v_{-}(0)=\underbrace{c_{n}^{-}\left(D_{n} v_{-}+i \tau \alpha_{-}\right) v_{-}(0)}_{=\mathcal{V}_{-}}+c_{n}^{-} i m_{-} v_{-}(0) \tag{1-27}
\end{equation*}
$$

Nothing more can be achieved with inequalities on each side of the interface. At this point, however, we notice that the second transmission condition in (1-22) implies $\mathcal{V}_{-}=\mathcal{V}_{+}$, yielding the control of the difference of (1-27) and (1-25), that is, of

$$
c_{n}^{-} i m_{-} v_{-}(0)+c_{n}^{+} i m_{+} v_{+}(0)=i\left(c_{n}^{-} m_{-}+c_{n}^{+} m_{+}\right) v(0)
$$

Now, as $c_{n}^{-} m_{-}+c_{n}^{+} m_{+}$is elliptic positive, this gives a control of $v(0)$ in (tangential) $H^{1}$-norm, which is enough to then get an estimate on both sides that leads to the Carleman estimates we seek.

Step 4 (patching estimates together). The analysis we have sketched here relies on a separation into two zones in the ( $\left.\tau, \xi^{\prime}\right)$ space. Patching the estimates of the form of (1-13) in each zone together allows us to conclude the proof of the Carleman estimate.

1F. Explaining the key assumption. Our key assumption, condition (1-26), can be reformulated as

$$
\begin{equation*}
\text { for all } \xi^{\prime} \in \mathbb{S}^{n-2}, \quad \frac{\alpha_{+}}{\alpha_{-}} \geq \frac{m_{+}\left(\xi^{\prime}\right)}{m_{-}\left(\xi^{\prime}\right)} \tag{1-28}
\end{equation*}
$$

In fact, ${ }^{7}$ (1-26) means $\tau \alpha_{+}<m_{+}\left(\xi^{\prime}\right) \Longrightarrow \tau \alpha_{-} \leq m_{-}\left(\xi^{\prime}\right)$, and since $\alpha_{ \pm}, m_{ \pm}$are all positive, this is equivalent to having $m_{+}\left(\xi^{\prime}\right) / \alpha_{+} \leq m_{-}\left(\xi^{\prime}\right) / \alpha_{-}$, which is (1-28). An analogy with an estimate for a first-order factor may shed some light on this condition. With

$$
f(t)=H(t)\left(\tau \alpha_{+}+\beta t-m_{+}\right)+H(-t)\left(\tau \alpha_{-}+\beta t-m_{-}\right), \quad \tau, \alpha_{ \pm}, \beta, m_{ \pm} \text {positive constants, }
$$

we want to prove an injectivity estimate of the type $\left\|D_{t} v+i f(t) v\right\|_{L^{2}(\mathbb{R})} \gtrsim\|v\|_{L^{2}(\mathbb{R})}$, say for $v \in \mathscr{C}_{c}^{\infty}(\mathbb{R})$. It is a classical fact (see, for example, Lemma 3.1.1 in [Lerner 2010]) that such an estimate (for a smooth $f$ ) is equivalent to the condition that $t \mapsto f(t)$ does not change sign from + to - while $t$ increases: it means that the adjoint operator $D_{t}-i f(t)$ satisfies the so-called condition $(\Psi)$. Looking at the function $f$, we see that it increases on each half-line $\mathbb{R}_{ \pm}$, so that the only place to get a "forbidden" change of sign from

[^5]

Figure 1. $f\left(0^{-}\right) \leq 0 ; f\left(0^{+}\right)<0$.

+ to - is at $t=0$ : to get an injectivity estimate, we have to avoid the situation where $f\left(0^{+}\right)<0$ and $f\left(0^{-}\right)>0$, that is, we have to make sure that $f\left(0^{+}\right)<0 \Longrightarrow f\left(0^{-}\right) \leq 0$, which is indeed the condition (1-28). The function $f$ is increasing affine on $\mathbb{R}_{ \pm}$with the same slope $\beta$ on both sides, with a possible discontinuity at 0 ; see Figure 1.

In Figure 1, when $f\left(0^{+}\right)<0$, we should have $f\left(0^{-}\right) \leq 0$, and the line on the left cannot go above the dotted line, in such a way that the discontinuous zigzag curve with the arrows has only a change of sign from - to + .

When $f\left(0^{+}\right) \geq 0$, there is no other constraint on $f\left(0^{-}\right)$: even with a discontinuity, the change of sign can only occur from - to + ; see Figure 2.

We prove below (Section 5) that condition (1-28) is relevant to our problem in the sense that it is indeed necessary to have a Carleman estimate with this weight: if (1-28) is violated, we are able, for this model, to construct a quasimode for $\mathcal{L}_{\tau}$, that is, a $\tau$-family of functions $v$ with $L^{2}$-norm 1 such that $\left\|\mathcal{L}_{\tau} v\right\|_{L^{2}} \ll\|v\|_{L^{2}}$, as $\tau$ goes to $\infty$, ruining any hope of proving a Carleman estimate. As usual for this type of construction, it uses a certain complex geometrical optics method, which is easy in this case to implement directly, due to the simplicity of the expression of the operator.

Remark 1.11. A very particular case of anisotropic medium was tackled in [Le Rousseau and Robbiano 2010] for the purpose of proving a controllability result for linear parabolic equations. The condition


Figure 2. $f\left(0^{-}\right) \gtrless 0 ; f\left(0^{+}\right) \geq 0$.
imposed on the weight function in [Le Rousseau and Robbiano 2010, Assumption 2.1] is much more demanding than what we impose here. In the isotropic case, $c_{j}^{ \pm}=c_{ \pm}$for all $j \in\{1, \ldots, n\}$, we have $m_{+}=m_{-}=\left|\xi^{\prime}\right|$ and our condition (1-29) reads $\alpha_{+}>\alpha_{-}$. Note also that the isotropic case $c_{-} \geq c_{+}$was already considered in [Doubova et al. 2002].

In [Le Rousseau and Robbiano 2010], the controllability result concerns an isotropic parabolic equation. The Carleman estimate we derive here extends this result to an anisotropic parabolic equation.

## 2. Framework

2A. Presentation. Let $\Omega, \Sigma$ be as in (1-3). With

$$
\Xi=\{\text { positive-definite } n \times n \text { matrices }\},
$$

we consider $A_{ \pm} \in \mathscr{C}^{\infty}(\Omega ; \Xi)$ and let $\mathcal{L}, \varphi$ be as in (1-5) and (1-12). We set

$$
\mathcal{L}_{ \pm}=D \cdot A_{ \pm} D=-\operatorname{div}\left(A_{ \pm} \nabla\right)
$$

Here, we generalize our analysis to nonhomogeneous transmission conditions: for $\theta$ and $\Theta$ smooth functions of the interface $\Sigma$, we set

$$
\begin{equation*}
w_{+}-w_{-}=\theta \quad \text { and } \quad\left\langle A_{+} d w_{+}-A_{-} d w_{-}, v\right\rangle=\Theta \quad \text { at } \Sigma \tag{2-1}
\end{equation*}
$$

(compare with (1-8)-(1-9)) and introduce

$$
\begin{equation*}
\mathcal{W}_{0}^{\theta, \Theta}=\left\{H_{-} w_{-}+H_{+} w_{+}\right\}_{w_{ \pm} \in \varphi_{c} \infty(\Omega)}, \quad w_{ \pm} \text {satisfying (2-1). } \tag{2-2}
\end{equation*}
$$

For $\tau \geq 0$, we define the affine space

$$
\begin{equation*}
\mathcal{W}_{\tau}^{\theta, \Theta}=\left\{e^{\tau \varphi} w\right\}_{w \in \mathcal{W}_{0}^{\theta, \Theta}} \tag{2-3}
\end{equation*}
$$

For $v \in \mathcal{W}_{\tau}^{\theta, \Theta}$, we have $v=e^{\tau \varphi} w$ with $w \in \mathcal{W}_{0}^{\theta, \Theta}$, so that using the notation introduced in (1-4), (1-7), with $v_{ \pm}=e^{\tau \varphi_{ \pm}} w_{ \pm}$, we have

$$
\begin{equation*}
v=H_{-} v_{-}+H_{+} v_{+}, \tag{2-4}
\end{equation*}
$$

and we see that the transmission conditions (2-1) on $w$ read for $v$ as

$$
\begin{equation*}
v_{+}-v_{-}=\theta_{\varphi}, \quad\left\langle d v_{+}-\tau v_{+} d \varphi_{+}, A_{+} \nu\right\rangle-\left\langle d v_{-}-\tau v_{-} d \varphi_{-}, A_{-} \nu\right\rangle=\Theta_{\varphi} \quad \text { at } \Sigma, \tag{2-5}
\end{equation*}
$$

with

$$
\begin{equation*}
\theta_{\varphi}=e^{\tau \varphi \varphi_{\mid \Sigma}} \theta, \quad \Theta_{\varphi}=e^{\tau \varphi_{\mid \Sigma}} \Theta . \tag{2-6}
\end{equation*}
$$

Observing that $e^{\tau \varphi_{ \pm}} D e^{-\tau \varphi_{ \pm}}=D+i \tau d \varphi_{ \pm}$for $w \in \mathcal{W}^{\theta, \Theta}$, we obtain

$$
e^{\tau \varphi_{ \pm}} \mathcal{L}_{ \pm} w_{ \pm}=e^{\tau \varphi_{ \pm}} D \cdot A_{ \pm} D e^{-\tau \varphi_{ \pm}} v_{ \pm}=\left(D+i \tau d \varphi_{ \pm}\right) \cdot A_{ \pm}\left(D+i \tau d \varphi_{ \pm}\right) v_{ \pm}
$$

We define

$$
\begin{equation*}
\mathcal{P}_{ \pm}=\left(D+i \tau d \varphi_{ \pm}\right) \cdot A_{ \pm}\left(D+i \tau d \varphi_{ \pm}\right) \tag{2-7}
\end{equation*}
$$

Proposition 2.1. Let $\Omega, \Sigma, \mathcal{L}, \mathcal{W}_{\tau}^{\theta, \Theta}$ be as in (1-3), (1-5), and (2-3). Then for any compact subset $K$ of $\Omega$, there exist a weight function $\varphi$ satisfying (1-12) and positive constants $C, \tau_{1}$ such that for all $\tau \geq \tau_{1}$ and all $v \in \mathcal{W}_{\tau}$ with $\operatorname{supp} v \subset K$,

$$
\begin{aligned}
& C\left(\left\|H_{-} \mathcal{P}_{-} v_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{+} \mathcal{P}_{+} v_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\mathcal{T}_{\theta, \Theta}\right) \\
& \geq \tau^{3 / 2}\left|v_{ \pm}\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|\left(\nabla v_{ \pm}\right)\right|_{L^{2}(\Sigma)}+\tau^{3 / 2}\|v\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{1 / 2}\left\|H_{+} \nabla v_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{1 / 2}\left\|H_{-} \nabla v_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)},
\end{aligned}
$$

where $\mathcal{T}_{\theta, \Theta}=\tau^{3 / 2}\left|\theta_{\varphi}\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|\nabla_{\Sigma} \theta_{\varphi}\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|\Theta_{\varphi}\right|_{L^{2}(\Sigma)}$.
Here, $\nabla_{\Sigma}$ denotes the tangential gradient to $\Sigma$. The proof of this proposition will occupy a large part of the remainder of the article (Sections 3 and 4), as it implies the result of the following theorem, a nonhomogeneous version of Theorem 1.1.

Theorem 2.2. Let $\Omega, \Sigma, \mathcal{L}, \mathcal{W}_{0}^{\theta, \Theta}$ be as in (1-3), (1-5), and (2-2). Then for any compact subset $K$ of $\Omega$, there exist a weight function $\varphi$ satisfying (1-12) and positive constants $C, \tau_{1}$ such that for all $\tau \geq \tau_{1}$ and all $w \in \mathcal{W}$ with $\operatorname{supp} w \subset K$,

$$
\begin{align*}
& C\left(\left\|H_{-} e^{\tau \varphi} \mathcal{L}_{-} w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{+} e^{\tau \varphi_{+}} \mathcal{L}_{+} w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+T_{\theta, \Theta}\right) \\
& \geq \tau^{3 / 2}\left\|e^{\tau \varphi} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{1 / 2}\left(\left\|H_{+} e^{\tau \varphi} \nabla w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{-} e^{\tau \varphi} \nabla w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}\right) \\
&  \tag{2-8}\\
& \quad+\tau^{3 / 2}\left|e^{\tau \varphi} w_{ \pm}\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|e^{\tau \varphi} \nabla w_{ \pm}\right|_{L^{2}(\Sigma)}
\end{align*}
$$

where $T_{\theta, \Theta}=\tau^{3 / 2}\left|e^{\tau \varphi_{\mid \Sigma}} \theta\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|e^{\tau \varphi_{\mid \Sigma}} \nabla_{\Sigma} \theta\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|e^{\tau \varphi_{\mid \Sigma}} \Theta\right|_{L^{2}(\Sigma)}$.
Theorem 1.1 corresponds to the case $\theta=\Theta=0$, since by (1-10), we then have

$$
\left\|e^{\tau \varphi} \mathcal{L} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}=\left\|H_{-} e^{\tau \varphi_{-}} \mathcal{L}_{-} w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{+} e^{\tau \varphi_{+}} \mathcal{L}_{+} w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}
$$

Remark 2.3. It is often useful to have such a Carleman estimate at hand for the case of nonhomogeneous transmission conditions, for example when one tries to patch such local estimates together in the neighborhood of the interface.

Here we derive local Carleman estimates. We can in fact consider a similar geometrical situation on a Riemannian manifold (with or without boundary) with a metric exhibiting jump discontinuities across interfaces. For the associated Laplace-Beltrami operator, the local estimates we derive can be patched together to yield a global estimate. We refer to [Le Rousseau and Robbiano 2011, Section 5] for such questions.

Proof that Proposition 2.1 implies Theorem 2.2. Replacing $v$ by $e^{\tau \varphi} w$, we get

$$
\begin{align*}
& \left\|H_{-} e^{\tau \varphi}-\mathcal{L}_{-} w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{+} e^{\tau \varphi_{+}} \mathcal{L}_{+} w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+T_{\theta, \Theta} \\
& \quad \gtrsim \tau^{3 / 2}\left\|e^{\tau \varphi} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{1 / 2}\left(\left\|H_{+} \nabla e^{\tau \varphi} w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{-} \nabla e^{\tau \varphi} w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}\right) \\
& \quad+\tau^{3 / 2}\left|e^{\tau \varphi} w_{ \pm}\right|_{L^{2}(\Sigma)}+\tau^{1 / 2}\left|\nabla e^{\tau \varphi} w_{ \pm}\right|_{L^{2}(\Sigma)} \tag{2-9}
\end{align*}
$$

Commuting $\nabla$ with $e^{\tau \varphi}$ produces

$$
\begin{aligned}
& C\left(\left\|H_{-} e^{\tau \varphi_{-}} \mathcal{L}_{-} w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{+} e^{\tau \varphi_{+}} \mathcal{L}_{+} w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+T_{\theta, \Theta}\right) \\
& \quad+C_{1} \tau^{3 / 2}\left\|e^{\tau \varphi} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+C_{2} \tau^{3 / 2}\left(\left|e^{\tau \varphi} w_{ \pm \mid \Sigma}\right|_{L^{2}(\Sigma)}\right) \\
& \quad \geq \tau^{1 / 2}\left\|H_{-} e^{\tau \varphi} D w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{1 / 2}\left\|H_{+} e^{\tau \varphi} D w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\tau^{3 / 2}\left\|e^{\tau \varphi} w\right\|_{L^{2}\left(\mathbb{R}^{n}\right)} \\
& \quad+\tau^{1 / 2}\left|e^{\tau \varphi} D w_{ \pm}\right|_{L^{2}(\Sigma)}+\tau^{3 / 2}\left|e^{\tau \varphi} w_{ \pm}\right|_{L^{2}(\Sigma)}
\end{aligned}
$$

but by (2-9), we have

$$
\begin{aligned}
C_{1} \tau^{3 / 2}\left\|e^{\tau \varphi} w\right\|+C_{2} \tau^{3 / 2} & \left|e^{\tau \varphi} w\right| \\
& \leq C \max \left(C_{1}, C_{2}\right)\left(\left\|H_{-} e^{\tau \varphi_{-}} \mathcal{L}_{-} w_{-}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+\left\|H_{+} e^{\tau \varphi_{+}} \mathcal{L}_{+} w_{+}\right\|_{L^{2}\left(\mathbb{R}^{n}\right)}+T_{\theta, \Theta}\right)
\end{aligned}
$$

proving the implication.
2B. Description in local coordinates. Carleman estimates of types (1-13) and (2-8) can be handled locally, as they can be patched together. Assuming, as we may, that the hypersurface $\Sigma$ is given locally by the equation $\left\{x_{n}=0\right\}$, we have, using the Einstein convention on repeated indices $j \in\{1, \ldots, n-1\}$, and noting from the ellipticity condition that $a_{n n}>0$ (the matrix $\left.A(x)=\left(a_{j k}(x)\right)_{1 \leq j, k \leq n}\right)$,

$$
\begin{aligned}
\mathcal{L} & =D_{n} a_{n n} D_{n}+D_{n} a_{n j} D_{j}+D_{j} a_{j n} D_{n}+D_{j} a_{j k} D_{k} \\
& =D_{n} a_{n n}\left(D_{n}+a_{n n}^{-1} a_{n j} D_{j}\right)+D_{j} a_{j n} D_{n}+D_{j} a_{j k} D_{k} .
\end{aligned}
$$

With $T=a_{n n}^{-1} a_{n j} D_{j}$, we have

$$
\mathcal{L}=\left(D_{n}+T^{*}\right) a_{n n}\left(D_{n}+T\right)-T^{*} a_{n n} D_{n}-T^{*} a_{n n} T+D_{j} a_{j n} D_{n}+D_{j} a_{j k} D_{k}
$$

and since $T^{*}=D_{j} a_{n n}^{-1} a_{n j}$, we have $T^{*} a_{n n} D_{n}=D_{j} a_{n j} D_{n}=D_{j} a_{j n} D_{n}$ and

$$
\begin{equation*}
\mathcal{L}=\left(D_{n}+T^{*}\right) a_{n n}\left(D_{n}+T\right)+D_{j} b_{j k} D_{k}, \tag{2-10}
\end{equation*}
$$

where the $(n-1) \times(n-1)$ matrix $\left(b_{j k}\right)$ is positive-definite, since with $\xi^{\prime}=\left(\xi_{1}, \ldots, \xi_{n-1}\right)$ and $\xi=\left(\xi^{\prime}, \xi_{n}\right)$,

$$
\left\langle B \xi^{\prime}, \xi^{\prime}\right\rangle=\sum_{1 \leq j, k \leq n-1} b_{j k} \xi_{j} \xi_{k}=\langle A \xi, \xi\rangle
$$

where $a_{n n} \xi_{n}=-\sum_{1 \leq j \leq n-1} a_{n j} \xi_{j}$. Note also that $b_{j k}=a_{j k}-\left(a_{n j} a_{n k} / a_{n n}\right)$.
Remark 2.4. The positive-definite quadratic form $B$ is the restriction of $\langle A \xi, \xi\rangle$ to the hyperplane $\mathcal{H}$ defined by $\left\{\langle A \xi, \xi\rangle, x_{n}\right\}=\partial_{\xi_{n}}(\langle A \xi, \xi\rangle)=0$, where $\{\cdot, \cdot\}$ stands for the Poisson bracket. In fact, the principal symbol of $\mathcal{L}$ is $\langle A(x) \xi, \xi\rangle$, and if $\Sigma$ is defined by the equation $\psi(x)=0$ with $d \psi \neq 0$ at $\Sigma$, we have

$$
\frac{1}{2}\{\langle A(x) \xi, \xi\rangle, \psi\}=\langle A(x) \xi, d \psi(x)\rangle
$$

so that $\mathcal{H}_{x}=(A(x) d \psi(x))^{\perp}=\left\{\xi \in T_{x}^{*}(\Omega),\langle\xi, A(x) d \psi(x)\rangle_{T_{x}^{*}(\Omega), T_{x}(\Omega)}=0\right\}$. When $x \in \Sigma$, that set does not depend on the choice of the defining function $\psi$ of $\Sigma$, and we simply have

$$
\mathcal{H}_{x}=(A(x) \nu(x))^{\perp}=\left\{\xi \in T_{x}^{*}(\Omega),\langle\xi, A(x) v(x)\rangle_{T_{x}^{*}(\Omega), T_{x}(\Omega)}=0\right\}
$$

where $v(x)$ is the conormal vector to $\Sigma$ at $x$ (recall that from Remark $1.4, v(x)$ is a cotangent vector at $x$, and $A(x) v(x)$ is a tangent vector at $x)$. Now, for $x \in \Sigma$, we can restrict the quadratic form $A(x)$ to $\mathcal{H}_{x}$ : this is the positive-definite quadratic form $B(x)$, providing a coordinate-free definition.

For $w \in \mathcal{W}_{0}^{\theta, \Theta}$, we have

$$
\begin{equation*}
\mathcal{L}_{ \pm} w_{ \pm}=\left(D_{n}+T_{ \pm}^{*}\right) a_{n n}^{ \pm}\left(D_{n}+T_{ \pm}\right) w_{ \pm}+D_{j} b_{j k}^{ \pm} D_{k} w_{ \pm} \tag{2-11}
\end{equation*}
$$

and the nonhomogeneous transmission conditions (2-1) read

$$
\begin{equation*}
w_{+}-w_{-}=\theta, \quad a_{n n}^{+}\left(D_{n}+T_{+}\right) w_{+}-a_{n n}^{-}\left(D_{n}+T_{-}\right) w_{-}=\Theta \quad \text { at } \Sigma . \tag{2-12}
\end{equation*}
$$

2C. Pseudodifferential factorization on each side. At first, we consider the weight function $\varphi=$ $H_{+} \varphi_{+}+H_{-} \varphi_{-}$, with $\varphi_{ \pm}$that solely depend on $x_{n}$. Later on, we shall allow for some dependency upon the tangential variables $x^{\prime}$ (see Section 4E). We define, for $m \in \mathbb{R}$, the class of tangential standard symbols $\mathcal{S}^{m}$ as the smooth functions on $\mathbb{R}^{n} \times \mathbb{R}^{n-1}$ such that for all $(\alpha, \beta) \in \mathbb{N}^{n} \times \mathbb{N}^{n-1}$,

$$
\begin{equation*}
\sup _{\left(x, \xi^{\prime}\right) \in \mathbb{R}^{n} \times \mathbb{R}^{n-1}}\left\langle\xi^{\prime}\right\rangle^{-m+|\beta|}\left|\left(\partial_{x}^{\alpha} \partial_{\xi^{\prime}}^{\beta} a\right)\left(x, \xi^{\prime}\right)\right|<\infty, \tag{2-13}
\end{equation*}
$$

with $\left\langle\xi^{\prime}\right\rangle=\left(1+\left|\xi^{\prime}\right|^{2}\right)^{1 / 2}$. Some basic properties of standard pseudodifferential operators are recalled in Section AA. Section 2B and formulae (2-7), (2-11) give

$$
\begin{equation*}
\mathcal{P}_{ \pm}=\left(D_{n}+i \tau \varphi_{ \pm}^{\prime}+T_{ \pm}^{*}\right) a_{n n}^{ \pm}\left(D_{n}+i \tau \varphi_{ \pm}^{\prime}+T_{ \pm}\right)+D_{j} b_{j k}^{ \pm} D_{k} \tag{2-14}
\end{equation*}
$$

We define $m_{ \pm} \in \mathcal{S}^{1}$ such that

$$
\begin{equation*}
\text { for }\left|\xi^{\prime}\right| \geq 1, \quad m_{ \pm}=\left(\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} \xi_{j} \xi_{k}\right)^{1 / 2}, \quad m_{ \pm} \geq C\left\langle\xi^{\prime}\right\rangle, \quad M_{ \pm}=\mathrm{op}^{w}\left(m_{ \pm}\right) \tag{2-15}
\end{equation*}
$$

We then have $M_{ \pm}^{2} \equiv D_{j} b_{j k}^{ \pm} D_{k} \bmod \operatorname{op}\left(\mathcal{S}^{1}\right)$.
We define

$$
\begin{equation*}
\Psi^{1}=\operatorname{op}\left(\mathcal{S}^{1}\right)+\tau \mathrm{op}\left(\mathcal{S}^{0}\right)+\mathrm{op}\left(\mathcal{S}^{0}\right) D_{n} \tag{2-16}
\end{equation*}
$$

Modulo the operator class $\Psi^{1}$, we may write

$$
\begin{equation*}
\mathcal{P}_{+} \equiv \mathcal{P}_{E+} a_{n n}^{+} \mathcal{P}_{F+}, \quad \mathcal{P}_{-} \equiv \mathcal{P}_{F-} a_{n n}^{-} \mathcal{P}_{E-}, \tag{2-17}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathcal{P}_{E \pm}=D_{n}+S_{ \pm}+i(\underbrace{\tau \varphi_{ \pm}^{\prime}+M_{ \pm}}_{E_{ \pm}}), \quad \mathcal{P}_{F \pm}=D_{n}+S_{ \pm}+i(\underbrace{\tau \varphi_{ \pm}^{\prime}-M_{ \pm}}_{F_{ \pm}}) \tag{2-18}
\end{equation*}
$$

with

$$
\begin{equation*}
S_{ \pm}=s^{w}\left(x, D^{\prime}\right), \quad s_{ \pm}=\sum_{1 \leq j \leq n-1} \frac{a_{n j}^{ \pm}}{a_{n n}^{ \pm}} \xi_{j}, \quad \text { so that } S_{ \pm}^{*}=S_{ \pm}, \quad S_{ \pm}=T_{ \pm}+\frac{1}{2} \operatorname{div} T_{ \pm} \tag{2-19}
\end{equation*}
$$

where

$$
\begin{equation*}
T_{ \pm} \text {is the vector field } \sum_{1 \leq j \leq n-1} \frac{a_{n j}^{ \pm}}{i a_{n n}^{ \pm}} \partial_{j} \tag{2-20}
\end{equation*}
$$

We denote by $f_{ \pm}$and $e_{ \pm}$the homogeneous principal symbols of $F_{ \pm}$and $E_{ \pm}$, respectively, determined modulo the symbol class $\mathcal{S}^{1}+\tau \mathcal{S}^{0}$. The transmission conditions (2-12) with our choice of coordinates read, at $x_{n}=0$,

$$
\left\{\begin{array}{l}
v_{+}-v_{-}=\theta_{\varphi}=e^{\tau \varphi_{\mid x_{n}=0}} \theta  \tag{2-21}\\
a_{n n}^{+}\left(D_{n}+T_{+}+i \tau \varphi_{+}^{\prime}\right) v_{+}-a_{n n}^{-}\left(D_{n}+T_{-}+i \tau \varphi_{-}^{\prime}\right) v_{-}=\Theta_{\varphi}=e^{\tau \varphi_{\mid x_{n}=0}} \Theta
\end{array}\right.
$$

Remark 2.5. The Carleman estimate we shall prove is insensitive to terms in $\Psi^{1}$ in the conjugated operator $\mathcal{P}$. Formulae (2-17) and (2-18) for $\mathcal{P}_{+}$and $\mathcal{P}_{-}$will thus be the base of our analysis.

Remark 2.6. In [Le Rousseau and Robbiano 2010; 2011], the zero crossing of the roots of the symbol of $\mathcal{P}_{ \pm}$, as seen as a polynomial in $\xi_{n}$, is analyzed. Here the factorization into first-order operators isolates each root. In fact, $f_{ \pm}$changes sign, and we shall impose a condition on the weight function at the interface to obtain a certain scheme for this change of sign; see Section 4.

2D. Choice of weight function. The weight function can be taken of the form

$$
\begin{equation*}
\varphi_{ \pm}\left(x_{n}\right)=\alpha_{ \pm} x_{n}+\frac{\beta x_{n}^{2}}{2}, \quad \alpha_{ \pm}>0, \quad \beta>0 \tag{2-22}
\end{equation*}
$$

The choice of the parameters $\alpha_{ \pm}$and $\beta$ will be done below and will take into account the geometric data of our problem: $\alpha_{ \pm}$will be chosen to fulfill a geometric condition at the interface, and $\beta>0$ will be chosen large. Here, we shall require $\varphi^{\prime} \geq 0$, that is, we choose an "observation" region on the right-hand side of $\Sigma$. As we shall need $\beta$ large, this amounts to working in a small neighborhood of the interface, that is, $\left|x_{n}\right|$ small. Also, we shall see below (Section 4E) that this weight can be perturbed by any smooth function with a small gradient.

Other choices for the weight functions are possible. In fact, two sufficient conditions can be put forward. We shall describe them now.

The operators $M_{ \pm}$have a principal symbol $m_{ \pm}\left(x, \xi^{\prime}\right)$ in $\mathcal{S}^{1}$, which is positively homogeneous ${ }^{8}$ of degree 1 and elliptic, that is, there exist $\lambda_{0}^{ \pm}, \lambda_{1}^{ \pm}$positive such that for $\left|\xi^{\prime}\right| \geq 1, x \in \mathbb{R}^{n}$,

$$
\begin{equation*}
\lambda_{0}^{ \pm}\left|\xi^{\prime}\right| \leq m_{ \pm}\left(x, \xi^{\prime}\right) \leq \lambda_{1}^{ \pm}\left|\xi^{\prime}\right| \tag{2-23}
\end{equation*}
$$

We choose $\varphi_{\left.\right|_{n}=0^{ \pm}}^{\prime}=\alpha_{ \pm}$such that

$$
\begin{equation*}
\frac{\alpha_{+}}{\alpha_{-}}>\sup _{\substack{x^{\prime}, \xi^{\prime} \\\left|\xi^{\prime}\right| \geq 1}} \frac{m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{\left.m_{-}\left(x^{\prime}, \xi^{\prime}\right)\right|_{x_{n}=0^{-}}} \tag{2-24}
\end{equation*}
$$

[^6]The consequence of this condition will be made clear in Section 4. We shall also prove that this condition is sharp in Section 5: a strong violation of this condition, namely, $\alpha_{+} / \alpha_{-}<\left.\sup \left(m_{+} / m_{-}\right)\right|_{x_{n}=0}$, ruins any possibility of deriving a Carleman estimate of the form of Theorem 1.1.

Condition (2-24) concerns the behavior of the weight function at the interface. Conditions away from the interface are also needed. These conditions are more classical. From (2-14), the symbols of $\mathcal{P}_{ \pm}$, modulo the symbol class $\mathcal{S}^{1}+\tau \mathcal{S}^{0}+\mathcal{S}^{0} \xi_{n}$, are given by $p_{ \pm}(x, \xi, \tau)=a_{n n}^{ \pm}\left(q_{2}^{ \pm}+2 i q_{1}^{ \pm}\right)$, with

$$
q_{2}^{ \pm}=\left(\xi_{n}+s_{ \pm}\right)^{2}+\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} \xi_{j} \xi_{k}-\tau^{2}\left(\varphi_{ \pm}^{\prime}\right)^{2}, \quad q_{1}^{ \pm}=\tau \varphi_{ \pm}^{\prime}\left(\xi_{n}+s_{ \pm}\right)
$$

for $\varphi$ solely depending on $x_{n}$, and from the construction of $m_{ \pm}$, for $\left|\xi^{\prime}\right| \geq 1$, we have

$$
\begin{equation*}
q_{2}^{ \pm}=\left(\xi_{n}+s_{ \pm}\right)^{2}+m_{ \pm}^{2}-\left(\tau \varphi_{ \pm}^{\prime}\right)^{2}=\left(\xi_{n}+s_{ \pm}\right)^{2}-f_{ \pm} e_{ \pm} \tag{2-25}
\end{equation*}
$$

We can then formulate the usual subellipticity condition, with loss of a half-derivative:

$$
\begin{equation*}
q_{2}^{ \pm}=0 \text { and } q_{1}^{ \pm}=0 \Longrightarrow\left\{q_{2}^{ \pm}, q_{1}^{ \pm}\right\}>0 \tag{2-26}
\end{equation*}
$$

which can be achieved by choosing $\beta$ sufficiently large. It is important to note that this property is coordinate-free. For second-order elliptic operators with real smooth coefficients, this property is necessary and sufficient for a Carleman estimate such as that of Theorem 1.1 to hold (see [Hörmander 1963], or, for example, [Le Rousseau and Lebeau 2012]).

With the weight functions provided in (2-22), we choose $\alpha_{ \pm}$according to condition (2-24) and $\beta>0$ large enough, and we restrict ourselves to a small neighborhood of $\Sigma$, that is, $\left|x_{n}\right|$ small, to have $\varphi^{\prime}>0$ and so that (2-26) is fulfilled.

Remark 2.7. Other "classical" forms for the weight function $\varphi$ are also possible. For instance, one may use $\varphi\left(x_{n}\right)=e^{\beta \phi\left(x_{n}\right)}$ with the function $\phi$ depending solely on $x_{n}$ of the form

$$
\phi=H_{-} \phi_{-}+H_{+} \phi_{+}, \quad \phi_{ \pm} \in \mathscr{C}_{c}^{\infty}(\mathbb{R}),
$$

such that $\phi$ is continuous and $\left|\phi_{ \pm}^{\prime}\right| \geq C>0$. In this case, property (2-24) can be fulfilled by properly choosing $\phi_{\mid x_{n}=0^{ \pm}}^{\prime}$, and (2-26) by choosing $\beta$ sufficiently large.

Property (2-26) concerns the conjugated second-order operator. We show now that this condition concerns, in fact, only one of the first-order terms in the pseudodifferential factorization that we put forward above, namely, $\mathcal{P}_{F \pm}$.

Lemma 2.8. There exist $C>0, \tau_{1}>1$, and $\delta>0$ such that for $\tau \geq \tau_{1}$,

$$
\left|f_{ \pm}\right| \leq \delta \lambda \Longrightarrow C^{-1} \tau \leq\left|\xi^{\prime}\right| \leq C \tau \text { and }\left\{\xi_{n}+s_{ \pm}, f_{ \pm}\right\} \geq C^{\prime} \lambda,
$$

with $\lambda^{2}=\tau^{2}+\left|\xi^{\prime}\right|^{2}$.
See Appendix AB. 1 for a proof. This is the form of the subellipticity condition, with loss of a halfderivative, that we shall use. This will be further highlighted by the estimates we derive in Section 3 and by the proof of the main theorem.

## 3. Estimates for first-order factors

Unless otherwise specified, the notation $\|\cdot\|$ will stand for the $L^{2}\left(\mathbb{R}^{n}\right)$-norm and $|\cdot|$ for the $L^{2}\left(\mathbb{R}^{n-1}\right)$ norm. The $L^{2}\left(\mathbb{R}^{n}\right)$ and $L^{2}\left(\mathbb{R}^{n-1}\right)$ dot-products will be both denoted by $\langle\cdot, \cdot\rangle$.

In this section, we shall use the function space

$$
\mathscr{S}_{\mathrm{c}}\left(\mathbb{R}^{n}\right)=\left\{u \in \mathscr{S}\left(\mathbb{R}^{n}\right): \operatorname{supp}(u) \subset \mathbb{R}^{n-1} \times(-L, L) \text { for some } L>0\right\} .
$$

3A. Preliminary estimates. Most of our pseudodifferential arguments concern a calculus with large parameter $\tau \geq 1$ : with

$$
\begin{equation*}
\lambda^{2}=\tau^{2}+\left|\xi^{\prime}\right|^{2} \tag{3-1}
\end{equation*}
$$

we define for $m \in \mathbb{R}$ the class of tangential symbols $\mathcal{S}_{\tau}^{m}$ as the smooth functions on $\mathbb{R}^{n} \times \mathbb{R}^{n-1}$, depending on the parameter $\tau \geq 1$, such that, for all $(\alpha, \beta) \in \mathbb{N}^{n} \times \mathbb{N}^{n-1}$,

$$
\begin{equation*}
\sup _{\left(x, \xi^{\prime}\right) \in \mathbb{R}^{n} \times \mathbb{R}^{n-1}} \lambda^{-m+|\beta|}\left|\left(\partial_{x}^{\alpha} \partial_{\xi^{\prime}}^{\beta} a\right)\left(x, \xi^{\prime}, \tau\right)\right|<\infty . \tag{3-2}
\end{equation*}
$$

Some basic properties of the calculus of the associated pseudodifferential operators are recalled in Section AA.2. We shall refer to this calculus as the semiclassical calculus (with a large parameter). In particular, we introduce the Sobolev norms

$$
\begin{equation*}
\|u\|_{\mathcal{H}^{s}}:=\left\|\Lambda^{s} u\right\|_{L^{2}\left(\mathbb{R}^{n-1}\right)}, \quad \text { with } \Lambda^{s}:=\operatorname{op}\left(\lambda^{s}\right) \tag{3-3}
\end{equation*}
$$

For $s \geq 0$, note that we have $\|u\|_{\mathcal{H}^{s}} \sim \tau^{s}\|u\|_{L^{2}\left(\mathbb{R}^{n-1}\right)}+\left\|\left\langle D^{\prime}\right\rangle^{s} u\right\|_{L^{2}\left(\mathbb{R}^{n-1}\right)}$. Observe also that we have

$$
\|u\|_{\mathcal{H}^{s}} \leq C \tau^{s-s^{\prime}}\|u\|_{\mathcal{H}^{s^{\prime}}}, \quad s \leq s^{\prime}
$$

In what follows, we shall often refer implicitly to this inequality when invoking a large value for the parameter $\tau$.

The operator $M_{ \pm}$is of pseudodifferential nature in the standard calculus. Observe, however, that in any region where $\tau \gtrsim\left|\xi^{\prime}\right|$ the symbol, $m_{ \pm}$does not satisfy the estimates of $\mathcal{S}_{\tau}^{1}$. We shall circumvent this technical point by introducing a cut-off procedure.

Let $C_{0}, C_{1}>0$ be such that $\varphi^{\prime} \geq C_{0}$ and

$$
\begin{equation*}
\left(M_{ \pm} u, H^{+} u\right) \leq C_{1}\left\|H^{+} u\right\|_{L^{2}\left(\mathbb{R} ; H^{1 / 2}\left(\mathbb{R}^{n-1}\right)\right)}^{2} \tag{3-4}
\end{equation*}
$$

We choose $\psi \in \mathscr{C}^{\infty}\left(\mathbb{R}^{+}\right)$nonnegative such that $\psi=0$ in $[0,1]$ and $\psi=1$ in $[2,+\infty)$. We introduce the Fourier multiplier

$$
\begin{equation*}
\psi_{\epsilon}\left(\tau, \xi^{\prime}\right)=\psi\left(\frac{\epsilon \tau}{\langle\xi\rangle}\right) \in \mathcal{S}_{\tau}^{0}, \quad \text { with } 0<\epsilon \leq \epsilon_{0} \tag{3-5}
\end{equation*}
$$

such that $\tau \gtrsim\left\langle\xi^{\prime}\right\rangle / \epsilon$ in its support. We choose $\epsilon_{0}$ sufficiently small that $\operatorname{supp}\left(\psi_{\epsilon}\right)$ is disjoint from a conic neighborhood (for $\left|\xi^{\prime}\right| \geq 1$ ) of the sets $\left\{f_{ \pm}=0\right\}$ (see Figure 3).

The following lemma states that we can obtain very natural estimates on both sides of the interface in the region $\left|\xi^{\prime}\right| \ll \tau$, that is, for $\epsilon$ small. We refer to Section AB. 2 for a proof.


Figure 3. Relative positions of $\operatorname{supp}\left(\psi_{\epsilon}\right)$ and the sets $\left\{f_{ \pm}=0\right\}$.

Lemma 3.1. Let $\ell \in \mathbb{R}$. There exist $\tau_{1} \geq 1$ and $0<\epsilon_{1} \leq \epsilon_{0}$ and $C>0$ such that

$$
\begin{aligned}
& C\left\|H_{+} \mathcal{A}_{+} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \geq\left|\operatorname{op}\left(\psi_{\epsilon}\right) \omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} \\
& C\left(\left\|H_{-} \mathcal{A}_{-} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left|\operatorname{op}\left(\psi_{\epsilon}\right) \omega_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\ell+1 / 2}}\right) \geq\left\|H_{-} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}
\end{aligned}
$$

for $0<\epsilon \leq \epsilon_{1}$, with $A_{+}=\mathcal{P}_{E+}$ or $\mathcal{P}_{F+}, \mathcal{A}_{-}=\mathcal{P}_{E-}$ or $\mathcal{P}_{F-}$, for $\tau \geq \tau_{1}$ and $\omega \in \mathscr{Y}_{c}\left(\mathbb{R}^{n}\right)$.
3B. Positive imaginary part on a half-line. We have the following estimates for the operators $\mathcal{P}_{E+}$ and $\mathcal{P}_{\text {E- }}$.

Lemma 3.2. Let $\ell \in \mathbb{R}$. There exist $\tau_{1} \geq 1$ and $C>0$ such that

$$
\begin{equation*}
C\left\|H_{+} \mathcal{P}_{E_{+}} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \geq\left|\omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}+\left\|H_{+} D_{n} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \tag{3-6}
\end{equation*}
$$

and

$$
\begin{equation*}
C\left(\left\|H_{-} \mathcal{P}_{E_{-}} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left|\omega_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\ell+1 / 2}}\right) \geq\left\|H_{-} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}+\left\|H_{+} D_{n} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \tag{3-7}
\end{equation*}
$$

for $\tau \geq \tau_{1}$ and $\omega \in \mathscr{S}_{c}\left(\mathbb{R}^{n}\right)$.
The first estimate, in $\mathbb{R}_{+}$, is of very good quality, as both the trace and the volume norms are dominated: we have a perfect elliptic estimate. In $\mathbb{R}_{-}$, we obtain an estimate of lesser quality. Observe also that no assumption on the weight function, apart from the positivity of $\varphi^{\prime}$, is used in the proof below.

Proof. Let $\psi_{\epsilon}$ be defined as in Section 3A. We let $\tilde{\psi} \in \mathscr{C}^{\infty}\left(\mathbb{R}^{+}\right)$be nonnegative and such that $\tilde{\psi}=1$ in $[4,+\infty)$ and $\tilde{\psi}=0$ in $[0,3]$. We then define $\tilde{\psi}_{\epsilon}$ according to (3-5), and we have $\tau \lesssim\left\langle\xi^{\prime}\right\rangle \operatorname{in} \operatorname{supp}\left(1-\tilde{\psi}_{\epsilon}\right)$ and $\operatorname{supp}\left(1-\psi_{\epsilon}\right) \cap \operatorname{supp}\left(\tilde{\psi}_{\epsilon}\right)=\varnothing$. We set $\tilde{m}_{ \pm}=m_{ \pm}\left(1-\tilde{\psi}_{\epsilon}\right)$ and observe that $\tilde{m}_{ \pm} \in \mathcal{S}_{\tau}^{1}$. We define

$$
\tilde{e}_{ \pm}=\tau \varphi^{\prime}+\tilde{m}_{ \pm} \in \mathcal{S}_{\tau}^{1}, \quad \tilde{E}_{ \pm}=\mathrm{op}^{w}\left(\tilde{e}_{ \pm}\right)
$$

From the definition of $\tilde{\psi}_{\epsilon}$, we have

$$
\begin{equation*}
\tilde{e}_{ \pm} \geq C \lambda \tag{3-8}
\end{equation*}
$$

Next,

$$
M_{ \pm} \mathrm{op}\left(1-\psi_{\epsilon}\right) \omega=\mathrm{op}^{w}\left(\tilde{m}_{ \pm}\right) \mathrm{op}\left(1-\psi_{\epsilon}\right) \omega+\mathrm{op}^{w}\left(m_{ \pm} \tilde{\psi}_{\epsilon}\right) \mathrm{op}\left(1-\psi_{\epsilon}\right) \omega
$$

and since $m_{ \pm} \tilde{\psi}_{\epsilon} \in \mathcal{S}^{1}$ and $1-\psi_{\epsilon} \in \mathcal{S}_{\tau}^{0}$, with the latter vanishing in a region $\left\langle\xi^{\prime}\right\rangle \leq C \tau$, Lemma A. 4 yields

$$
\begin{equation*}
M_{ \pm} \mathrm{op}\left(1-\psi_{\epsilon}\right) \omega=\mathrm{op}^{w}\left(\tilde{m}_{ \pm}\right) \mathrm{op}\left(1-\psi_{\epsilon}\right) \omega+R_{1} \omega, \quad \text { with } R_{1} \in \mathrm{op}\left(\mathcal{S}_{\tau}^{-\infty}\right) \tag{3-9}
\end{equation*}
$$

We set $u=\operatorname{op}\left(1-\psi_{\epsilon}\right) \omega$. For $s=2 \ell+1$, we compute

$$
\begin{align*}
2 \operatorname{Re}\left\langle\mathcal{P}_{E_{+}} u, i H_{+} \Lambda^{s} u\right\rangle & =\left\langle i\left[D_{n}, H_{+}\right] u, \Lambda^{s} u\right\rangle+\left\langle i\left[S_{+}, \Lambda^{s}\right] u, H_{+} u\right\rangle+2 \operatorname{Re}\left\langle E_{+} u, H_{+} \Lambda^{s} u\right\rangle \\
& \geq\left|u_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}^{2}+2 \operatorname{Re}\left\langle E_{+} u, H_{+} \Lambda^{s} u\right\rangle-C\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1 / 2}\right)}^{2} . \tag{3-10}
\end{align*}
$$

By (3-9), we have $E_{+} u=\tilde{E}_{+} u+R_{1} \omega$. This yields

$$
\operatorname{Re}\left\langle E_{+} u, H_{+} \Lambda^{s} u\right\rangle+\left\|H_{+} \omega\right\|^{2} \gtrsim \operatorname{Re}\left\langle\tilde{E}_{+} u, H_{+} \Lambda^{s} u\right\rangle \gtrsim\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}^{2}
$$

for $\tau$ sufficiently large, by (3-8) and Lemma A.2. We thus obtain

$$
\operatorname{Re}\left\langle\mathcal{P}_{E_{+}} u, i H_{+} \Lambda^{s} u\right\rangle+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1 / 2}\right)}^{2}+\left\|H_{+} \omega\right\|^{2} \gtrsim\left|u_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}^{2}+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}^{2} .
$$

With the Young inequality and taking $\tau$ sufficiently large, we then find

$$
\left\|H_{+} \mathcal{P}_{E_{+}} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \omega\right\| \gtrsim\left|u_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} .
$$

We now invoke the corresponding estimate provided by Lemma 3.1,

$$
\left\|H_{+} \mathcal{P}_{E+} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \gtrsim\left|\operatorname{op}\left(\psi_{\epsilon}\right) \omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} .
$$

Adding the two estimates, with the triangle inequality we obtain

$$
\begin{aligned}
\left\|H_{+} \mathcal{P}_{E_{+}} \mathrm{op}\left(1-\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \mathcal{P}_{E+} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+ & \left\|H_{+} \omega\right\| \\
& \gtrsim\left|\omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} .
\end{aligned}
$$

Lemma A. 4 gives $\left[\mathcal{P}_{E_{+}}, \operatorname{op}\left(1-\psi_{\epsilon}\right)\right] \in \operatorname{op}\left(\mathcal{S}_{\tau}^{0}\right)$. We thus have

$$
\begin{aligned}
\left\|H_{+} \mathcal{P}_{E_{+}} \mathrm{op}\left(1-\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} & \lesssim\left\|H_{+} \mathrm{op}\left(1-\psi_{\epsilon}\right) \mathcal{P}_{E_{+}} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \\
& \lesssim\left\|H_{+} \mathcal{P}_{E_{+}} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} .
\end{aligned}
$$

By taking $\tau$ sufficiently large, we thus obtain

$$
\begin{equation*}
\left\|H_{+} \mathcal{P}_{E_{+}} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \gtrsim\left|\omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} . \tag{3-11}
\end{equation*}
$$

The term $\left\|H_{+} D_{n} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}$ can simply be introduced on the right-hand side of this estimate to yield (3-6), thanks to the form of the first-order operator $\mathcal{P}_{E_{+}}$. To obtain estimate (3-7), we compute $2 \operatorname{Re}\left\langle\mathcal{P}_{E_{-}} \omega, i H_{-} \omega\right\rangle$. The argument is similar, but the trace term comes out with the opposite sign.

For the operator $\mathcal{P}_{F+}$, we can also obtain a microlocal estimate. We place ourselves in a microlocal region where $f_{+}=\tau \varphi^{+}-m_{+}$is positive. More precisely, let $\chi\left(x, \tau, \xi^{\prime}\right) \in \mathcal{S}_{\tau}^{0}$ be such that $\left|\xi^{\prime}\right| \leq C \tau$ and $f_{+} \geq C_{1} \lambda$ in $\operatorname{supp}(\chi), C_{1}>0$, and $\left|\xi^{\prime}\right| \geq C^{\prime} \tau$ in $\operatorname{supp}(1-\chi)$.

Lemma 3.3. Let $\ell \in \mathbb{R}$. There exist $\tau_{1} \geq 1$ and $C>0$ such that

$$
\begin{aligned}
& C\left(\left\|H_{+} \mathcal{P}_{F_{+}} \mathrm{op}^{w}(\chi) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \omega\right\|\right) \\
& \quad \geq\left|\mathrm{op}^{w}(\chi) \omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \mathrm{op}^{w}(\chi) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}+\left\|H_{+} D_{n} \mathrm{op}^{w}(\chi) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)},
\end{aligned}
$$

for $\tau \geq \tau_{1}$ and $\omega \in \mathscr{S}_{c}\left(\mathbb{R}^{n}\right)$.
As for (3-6) of Lemma 3.2, up to a harmless remainder term, we obtain an elliptic estimate in this microlocal region.
Proof. Let $\psi_{\epsilon}$ be as defined in Section 3A, and let $\tilde{\psi}_{\epsilon}$ be as in the proof of Lemma 3.2. We set

$$
\begin{equation*}
\tilde{f}_{ \pm}=\tau \varphi^{\prime}-\tilde{m}_{ \pm} \in \mathcal{S}_{\tau}^{1}, \quad \tilde{F}_{ \pm}=\mathrm{op}^{w}\left(\tilde{f}_{ \pm}\right) \tag{3-12}
\end{equation*}
$$

We have

$$
\tilde{f}_{ \pm}=\tau \varphi^{\prime}-\tilde{m}_{ \pm}=\tau \varphi^{\prime}-m_{ \pm}\left(1-\tilde{\psi}_{\epsilon}\right)=f_{ \pm}+\tilde{\psi}_{\epsilon} m_{ \pm} \geq f_{ \pm}
$$

This gives $\tilde{f}_{+} \geq C \lambda$ in $\operatorname{supp}(\chi)$.
We set $u=\operatorname{op}\left(1-\psi_{\epsilon}\right) \mathrm{op}^{w}(\chi) \omega$. Following the proof of Lemma 3.2, for $s=2 \ell+1$, we obtain

$$
\operatorname{Re}\left\langle\mathcal{P}_{F+} u, i H_{+} \Lambda^{s} u\right\rangle+\left\|H_{+} \omega\right\|^{2}+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1 / 2}\right)}^{2} \gtrsim\left|u_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}^{2}+\operatorname{Re}\left\langle\tilde{F}_{+} u, H_{+} \Lambda^{s} u\right\rangle .
$$

Let now $\tilde{\chi} \in \mathcal{S}_{\tau}^{0}$ satisfy the same properties as $\chi$, with $\tilde{\chi}=1$ on a neighborhood of $\operatorname{supp}(\chi)$. We then write

$$
\tilde{f}_{+}=\check{f}_{+}+r, \quad \text { with } \check{f}_{+}=\tilde{f}_{+} \tilde{\chi}+\lambda(1-\tilde{\chi}) \in \mathcal{S}_{\tau}^{1}, \quad r=\left(\tilde{f}_{+}-\lambda\right)(1-\tilde{\chi}) \in \mathcal{S}_{\tau}^{1}
$$

As $\operatorname{supp}(1-\tilde{\chi}) \cap \operatorname{supp}(\chi)=\varnothing$, we find $r \sharp\left(1-\psi_{\epsilon}\right) \sharp \chi \in \mathcal{S}_{\tau}^{-\infty}$. Since $\check{f}_{+} \geq C \lambda$ by construction, with Lemma A. 2 we obtain

$$
\operatorname{Re}\left\langle\mathcal{P}_{F+} u, i H_{+} \Lambda^{s} u\right\rangle+\left\|H_{+} \omega\right\|^{2}+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1 / 2}\right)}^{2} \gtrsim\left|u_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}^{2}+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}^{2}
$$

With the Young inequality, taking $\tau$ sufficiently large, we obtain

$$
\left\|H_{+} \mathcal{P}_{F+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \omega\right\| \gtrsim\left|u_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} .
$$

Invoking the corresponding estimate provided by Lemma 3.1 for $\mathrm{op}^{w}(\chi) \omega$,

$$
\begin{aligned}
&\left\|H_{+} \mathcal{P}_{F+} \operatorname{op}\left(\psi_{\epsilon}\right) \mathrm{op}^{w}(\chi) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \\
& \gtrsim\left|\mathrm{op}\left(\psi_{\epsilon}\right) \mathrm{op}^{w}(\chi) \omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \mathrm{op}\left(\psi_{\epsilon}\right) \mathrm{op}^{w}(\chi) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}
\end{aligned}
$$

and arguing as in the end of the proof of Lemma 3.2, we obtain the result.
For the operator $\mathcal{P}_{F-}$ we can also obtain a microlocal estimate. We place ourselves in a microlocal region where $f_{-}=\tau \varphi^{-}-m_{-}$is positive. More precisely, let $\chi\left(x, \tau, \xi^{\prime}\right) \in \mathcal{S}_{\tau}^{0}$ be such that $\left|\xi^{\prime}\right| \leq C \tau$ and $f_{-} \geq C_{1} \lambda$ in $\operatorname{supp}(\chi), C_{1}>0$, and $\left|\xi^{\prime}\right| \geq C^{\prime} \tau$ in $\operatorname{supp}(1-\chi)$.

Lemma 3.4. Let $\ell \in \mathbb{R}$. There exist $\tau_{1} \geq 1$ and $C>0$ such that

$$
\begin{equation*}
C\left(\left\|H_{-} \mathcal{P}_{F_{-}} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{-} \omega\right\|+\left\|H_{-} D_{n} \omega\right\|+\left|u_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\ell+1 / 2}}\right) \geq\left\|H_{-} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} \tag{3-13}
\end{equation*}
$$

for $\tau \geq \tau_{1}$ and $u=a_{n n}^{-} \mathcal{P}_{E-\mathrm{op}^{w}}(\chi) \omega$ with $\omega \in \mathscr{S}_{c}\left(\mathbb{R}^{n}\right)$.
Proof. Let $\psi_{\epsilon}$ be defined as in Section 3A. We define $\tilde{f}_{-}$and $\tilde{F}_{-}$as in (3-12). We have $\tilde{f}_{-} \geq f_{-} \geq C \lambda$ in $\operatorname{supp}(\chi)$. We set $z=\operatorname{op}\left(1-\psi_{\epsilon}\right) u$ and for $s=2 \ell+1$, we compute

$$
\begin{aligned}
2 \operatorname{Re}\left\langle\mathcal{P}_{F_{-}} z, i H_{-} \Lambda^{s} z\right\rangle & =\left\langle i\left[D_{n}, H_{-}\right] z, \Lambda^{s} z\right\rangle+i\left\langle\left[S_{-}, \Lambda^{s}\right] z, H_{-} z\right\rangle+2 \operatorname{Re}\left\langle F_{-} z, H_{-} \Lambda^{s} z\right\rangle \\
& \geq-\left|z_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\ell+1 / 2}}^{2}+2 \operatorname{Re}\left\langle F_{-} z, H_{-} \Lambda^{s} z\right\rangle-C\left\|H_{-} z\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1 / 2}\right)}^{2}
\end{aligned}
$$

Arguing as in the proof of Lemma 3.2 (see (3-9) and (3-10)), we obtain

$$
2 \operatorname{Re}\left\langle\mathcal{P}_{F_{-}} z, i H_{-} \Lambda^{s} z\right\rangle+C\left\|H_{-} u\right\|^{2}+\left|z_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\ell+1 / 2}}^{2}+C\left\|H_{-z}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1 / 2}\right)}^{2} \geq 2 \operatorname{Re}\left\langle\tilde{F}_{-} z, H_{-} \Lambda^{s} z\right\rangle .
$$

Let now $\tilde{\chi} \in \mathcal{S}_{\tau}^{0}$ satisfy the same properties as $\chi$, with $\tilde{\chi}=1$ on a neighborhood of $\operatorname{supp}(\chi)$. We then write

$$
\tilde{f}_{-}=\check{f}_{-}+r, \quad \text { with } \check{f}_{-}=\tilde{f_{-}} \tilde{\chi}+\lambda(1-\tilde{\chi}) \in \mathcal{S}_{\tau}^{1}, \quad r=\left(\tilde{f}_{-}-\lambda\right)(1-\tilde{\chi}) \in \mathcal{S}_{\tau}^{1} .
$$

As $\check{f}_{-} \geq C \lambda$ and $\operatorname{supp}(1-\tilde{\chi}) \cap \operatorname{supp}(\chi)=\varnothing$, with Lemma A. 2 we obtain, for $\tau$ large,

$$
\begin{aligned}
2 \operatorname{Re}\left\langle\mathcal{P}_{F_{-}} z, i H_{-} \Lambda^{s} z\right\rangle+C\left\|H_{-} u\right\|^{2}+|z| x_{n}=\left.0^{-}\right|_{\mathcal{H}^{\ell+1 / 2}} ^{2}+C\left\|H_{-} z\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1 / 2}\right)}^{2} & +\left\|H_{-} \omega\right\|^{2}+\left\|H_{-} D_{n} \omega\right\|^{2} \\
& \geq C^{\prime}\left\|H_{-} z\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}^{2}
\end{aligned}
$$

With the Young inequality and taking $\tau$ sufficiently large, we then find

$$
\left\|H_{-} \mathcal{P}_{F_{-}} z\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{-} u\right\|+\left|z_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{-} \omega\right\|+\left\|H_{-} D_{n} \omega\right\| \gtrsim\left\|H_{-} z\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} .
$$

Invoking the corresponding estimate provided by Lemma 3.1 for $u$ yields

$$
\left\|H_{-} \mathcal{P}_{F_{-}} \mathrm{op}\left(\psi_{\epsilon}\right) u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left|\operatorname{op}\left(\psi_{\epsilon}\right) u_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\ell+1 / 2}} \gtrsim\left\|H_{-} \mathrm{op}\left(\psi_{\epsilon}\right) u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}
$$

and arguing as in the end of Lemma 3.2, we obtain the result.
3C. Negative imaginary part on the negative half-line. Here we place ourselves in a microlocal region where $f_{-}=\tau \varphi^{-}-m_{-}$is negative. More precisely, let $\chi\left(x, \tau, \xi^{\prime}\right) \in \mathcal{S}_{\tau}^{0}$ be such that $\left|\xi^{\prime}\right| \geq C \tau$ and $f_{-} \leq-C_{1} \lambda$ in $\operatorname{supp}(\chi), C_{1}>0$. We have the following lemma, whose form is adapted to our needs in the next section. Up to harmless remainder terms, this can also be considered as a good elliptic estimate.

Lemma 3.5. There exist $\tau_{1} \geq 1$ and $C>0$ such that

$$
\begin{equation*}
C\left(\left\|H_{-} \mathcal{P}_{F_{-}} u\right\|+\left\|H_{-} \omega\right\|+\left\|H_{-} D_{n} \omega\right\|\right) \geq\left|u_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2}}+\left\|H_{-} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)}, \tag{3-14}
\end{equation*}
$$

for $\tau \geq \tau_{1}$ and $u=a_{n n}^{-} \mathcal{P}_{E-\mathrm{op}^{w}}(\chi) \omega$ with $\omega \in \mathscr{S}_{c}\left(\mathbb{R}^{n}\right)$.

Proof. We compute

$$
\begin{aligned}
2 \operatorname{Re}\left\langle\mathcal{P}_{F_{-}} u,-i H_{-} \Lambda^{1} u\right\rangle & =\left\langle i\left[D_{n},-H_{-}\right] u, \Lambda^{1} u\right\rangle-i\left\langle\left[S_{-}, \Lambda^{1}\right] u, H_{-} u\right\rangle+2 \operatorname{Re}\left\langle-F_{-} u, H_{-} \Lambda^{1} u\right\rangle \\
& \geq\left|u_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2}}^{2}+2 \operatorname{Re}\left\langle-F_{-} u, H_{-} \Lambda^{1} u\right\rangle-C\left\|H_{-} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1 / 2}\right)}^{2}
\end{aligned}
$$

Let now $\tilde{\chi} \in \mathcal{S}_{\tau}^{0}$ satisfy the same properties as $\chi$, with $\tilde{\chi}=1$ on a neighborhood of $\operatorname{supp}(\chi)$. We then write

$$
f_{-}=\check{f}_{-}+r, \quad \text { with } \check{f}_{-}=f_{-} \tilde{\chi}-\lambda(1-\tilde{\chi}), \quad r=\left(f_{-}+\lambda\right)(1-\tilde{\chi})
$$

Observe that $f_{-} \tilde{\chi} \in \mathcal{S}_{\tau}^{1}$ because of the support of $\tilde{\chi}$. Hence $\check{f}_{-} \in \mathcal{S}_{\tau}^{1}$. As $-\check{f}_{-} \geq C \lambda$, with Lemma A. 2 we obtain, for $\tau$ large, $\operatorname{Re}\left\langle-\mathrm{op}^{w}\left(\check{f}_{-}\right) u, H_{-} \Lambda^{1} u\right\rangle \gtrsim\left\|H_{-} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)}^{2}$. Note that $r$ does not satisfy the estimates of the semiclassical calculus because of the term $m_{-}(1-\tilde{\chi})$. However, we have

$$
\mathrm{op}^{w}(r) u=\mathrm{op}^{w}(r) a_{n n}^{-} \mathrm{op}^{w}(\chi) D_{n} \omega+\mathrm{op}^{w}(r) a_{n n}^{-} S_{-} \mathrm{op}^{w}(\chi) \omega+i \mathrm{op}^{w}(r) a_{n n}^{-} E_{-} \mathrm{op}^{w}(\chi) \omega .
$$

Applying Lemma A. 4 and using that $1-\tilde{\chi} \in \mathcal{S}_{\tau}^{0} \subset \mathcal{S}^{0}$ yields

$$
\mathrm{op}^{w}(r) u=R \omega \quad \text { with } R \in \operatorname{op}\left(\mathcal{S}_{\tau}^{1}\right) D_{n}+\mathrm{op}\left(\mathcal{S}_{\tau}^{2}\right) .
$$

As $\operatorname{supp}(1-\tilde{\chi}) \cap \operatorname{supp}(\chi)=\varnothing$, the composition formula (A-7) (which is valid in this case - see Lemma A.4) yields $R \in \operatorname{op}\left(\mathcal{S}_{\tau}^{-\infty}\right) D_{n}+\operatorname{op}\left(\mathcal{S}_{\tau}^{-\infty}\right)$. We thus find, for $\tau$ sufficiently large,

$$
\operatorname{Re}\left\langle\mathcal{P}_{F_{-}} u,-i H_{-} \Lambda^{1} u\right\rangle+\left\|H_{-} \omega\right\|^{2}+\left\|H_{-} D_{n} \omega\right\|^{2} \gtrsim\left|u_{\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2}}^{2}+\left\|H_{-} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)}^{2},
$$

and we conclude with the Young inequality.
3D. Increasing imaginary part on a half-line. Here we allow the symbols $f_{ \pm}$to change sign. For the first-order factor $\mathcal{P}_{F_{ \pm}}$, this will lead to an estimate that exhibits a loss of a half-derivative, as can be expected.

Let $\psi_{\epsilon}$ be as defined in Section 3A, and let $\tilde{\psi}_{\epsilon}$ be as in the proof of Lemma 3.2. We define $\tilde{f}_{ \pm}$and $\tilde{F}_{ \pm}$as in (3-12), and set $\tilde{\mathcal{P}}_{F_{ \pm}}=D_{n}+S_{ \pm}+i \tilde{F}_{ \pm}$.

As $\operatorname{supp}\left(\tilde{\psi}_{\epsilon}\right)$ remains away from the sets $\left\{f_{ \pm}=0\right\}$, the subellipticity property of Lemma 2.8 is preserved for $\tilde{f}_{ \pm}$in place of $f_{ \pm}$. We shall use the following inequality.

Lemma 3.6. There exist $C>0$ such that for $\mu>0$ sufficiently large, we have

$$
\rho_{ \pm}=\mu \tilde{f}_{ \pm}^{2}+\tau\left\{\xi_{n}+s_{ \pm}, \tilde{f}_{ \pm}\right\} \geq C \lambda^{2}
$$

with $\lambda^{2}=\tau^{2}+\left|\xi^{\prime}\right|^{2}$.
Proof. If $\left|\tilde{f}_{ \pm}\right| \leq \delta \lambda$, for $\delta$ small, then $\tilde{f}_{ \pm}=f_{ \pm}$and $\tau\left\{\xi_{n}+s_{ \pm}, \tilde{f}_{ \pm}\right\} \geq C \lambda^{2}$, by Lemma 2.8.
If $\left|\tilde{f}_{ \pm}\right| \geq \delta \lambda$, observing that $\tau\left\{\xi_{n}+s_{ \pm}, \tilde{f}_{ \pm}\right\} \in \tau \mathcal{S}_{\tau}^{1} \subset \mathcal{S}_{\tau}^{2}$, we obtain $\rho_{ \pm} \geq C \lambda^{2}$, by choosing $\mu$ sufficiently large.

We now prove the following estimate for $\mathcal{P}_{F_{ \pm}}$.

Lemma 3.7. Let $\ell \in \mathbb{R}$. There exist $\tau_{1} \geq 1$ and $C>0$ such that

$$
C\left(\left\|H_{ \pm} \mathcal{P}_{F_{ \pm}} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left|\omega_{\mid x_{n}=0^{ \pm}}\right|_{\mathcal{H}^{\ell+1 / 2}}\right) \geq \tau^{-1 / 2}\left(\left\|H_{ \pm} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}+\left\|H_{ \pm} D_{n} \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}\right)
$$

for $\tau \geq \tau_{1}$ and $\omega \in \mathscr{S}_{c}\left(\mathbb{R}^{n}\right)$.
Proof. We set $u=\operatorname{op}\left(1-\psi_{\epsilon}\right) \omega$. We start by invoking (3-9), and the fact that $\left[\tilde{\mathcal{P}}_{F+}, \Lambda^{\ell}\right] \in \operatorname{op}\left(\mathcal{S}_{\tau}^{\ell}\right)$, and write

$$
\begin{align*}
\left\|H_{+} \tilde{\mathcal{P}}_{F+} \Lambda^{\ell} u\right\| & \lesssim\left\|H_{+} \Lambda^{\ell} \tilde{\mathcal{P}}_{F+} u\right\|+\left\|H_{+}\left[\tilde{\mathcal{P}}_{F+}, \Lambda^{\ell}\right] u\right\| \\
& \lesssim\left\|H_{+} \tilde{\mathcal{P}}_{F+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}  \tag{3-15}\\
& \lesssim\left\|H_{+} \mathcal{P}_{F+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \omega\right\|+\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} .
\end{align*}
$$

We set $u_{\ell}=\Lambda^{\ell} u$. We then have

$$
\begin{aligned}
\left\|H_{+} \tilde{\mathcal{P}}_{F+} u_{\ell}\right\|^{2} & =\left\|H_{+}\left(D_{n}+S_{+}\right) u_{\ell}\right\|^{2}+\left\|H_{+} \tilde{F}_{+} u_{\ell}\right\|^{2}+2 \operatorname{Re}\left\langle\left(D_{n}+S_{+}\right) u_{\ell}, i H_{+} \tilde{F}_{+} u_{\ell}\right\rangle \\
& \geq \tau^{-1} \operatorname{Re}\left(\left(\mu \tilde{F}_{+}^{2}+i \tau\left[D_{n}+S_{+}, \tilde{F}_{+}\right]\right) u_{\ell}, H_{+} u_{\ell}\right\rangle+\left\langle i\left[D_{n}, H_{+}\right] u_{\ell}, \tilde{F}_{+} u_{\ell}\right\rangle,
\end{aligned}
$$

if $\mu \tau^{-1} \leq 1$. As the principal symbol (in the semiclassical calculus) of $\mu \tilde{F}_{+}^{2}+i \tau\left[D_{n}+S_{+}, \tilde{F}_{+}\right]$is $\rho_{+}=\mu \tilde{f}_{+}^{2}+\tau\left\{\xi_{n}+s_{+}, \tilde{f}_{+}\right\}$, Lemmata 3.6 and A. 2 yield

$$
\left\|H_{+} \tilde{\mathcal{P}}_{F+} u_{\ell}\right\|^{2}+\left|u_{\ell}\right|_{\mathcal{H}^{1 / 2}}^{2} \gtrsim \tau^{-1}\left\|H_{+} u_{\ell}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)}^{2}
$$

for $\mu$ large, that is, $\tau$ large. With (3-15) we obtain, for $\tau$ sufficiently large,

$$
\left\|H_{+} \mathcal{P}_{F+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)}+\left\|H_{+} \omega\right\|+|u|_{\mathcal{H}^{\ell+1 / 2}} \gtrsim \tau^{-1 / 2}\left\|H_{+} u\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)} .
$$

We now invoke the corresponding estimate provided by Lemma 3.1,

$$
\left\|H_{+} \mathcal{P}_{F+} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell}\right)} \gtrsim\left|\operatorname{op}\left(\psi_{\epsilon}\right) \omega_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}+\left\|H_{+} \operatorname{op}\left(\psi_{\epsilon}\right) \omega\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)},
$$

and we proceed as in the end of the proof of Lemma 3.2 to obtain the result for $\mathcal{P}_{F+}$. The same computation and arguments, mutatis mutandis, give the result for $\mathcal{P}_{F-}$.

## 4. Proof of the Carleman estimate

With the estimates for the first-order factors obtained in Section 3, we shall now prove Proposition 2.1, which gives the result of Theorems 1.1 and 2.2 (see the end of Section 2A).

The Carleman estimates we prove are well known away from the interface $\left\{x_{n}=0\right\}$. Since local Carleman estimates can be patched together, we may thus assume that the compact set $K$ in the statements of Theorems 1.1 and 2.2 is such that $\left|x_{n}\right|$ is sufficiently small for the arguments below to be carried out. Hence, we shall assume the functions $w_{ \pm}$in Theorem 2.2 (resp. $v_{ \pm}$in Proposition 2.1) have small supports near 0 in the $x_{n}$-direction.

4A. The geometric hypothesis. In Section 2D, we chose a weight function $\varphi$ that satisfies the condition

$$
\begin{equation*}
\frac{\alpha_{+}}{\alpha_{-}}>\sup _{\substack{x^{\prime}, \xi^{\prime} \\\left|\xi^{\prime}\right| \geq 1}} \frac{m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}}, \quad \alpha_{ \pm}=\partial_{x_{n}} \varphi_{ \pm \mid x_{n}=0^{ \pm}} \tag{4-1}
\end{equation*}
$$

Let us explain the immediate consequences of that assumption. First of all, we can reformulate it by saying that

$$
\begin{equation*}
\frac{\alpha_{+}}{\alpha_{-}}=\sigma^{2} \sup _{\substack{x^{\prime}, \xi^{\prime} \\\left|\xi^{\prime}\right| \geq 1}} \frac{m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}} \quad \text { for some } \sigma>1 \tag{4-2}
\end{equation*}
$$

Let $1<\sigma_{0}<\sigma$.
Consider $\left(x^{\prime}, \xi^{\prime}, \tau\right) \in \mathbb{R}^{n-1} \times \mathbb{R}^{n-1} \times \mathbb{R}^{+, *},\left|\xi^{\prime}\right| \geq 1$, such that

$$
\begin{equation*}
\tau \alpha_{+} \geq \sigma_{0} m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}} \tag{4-3}
\end{equation*}
$$

We then have

$$
\begin{equation*}
\tau \alpha_{+}-m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}} \geq \tau \alpha_{+}\left(1-\sigma_{0}^{-1}\right) \geq \frac{\sigma_{0}-1}{2 \sigma_{0}} \tau \alpha_{+}+\frac{\sigma_{0}-1}{2} m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}} \geq C \lambda \tag{4-4}
\end{equation*}
$$

We choose $\tau$ sufficiently large, say $\tau \geq \tau_{2}>0$, that this inequality remains true for $0 \leq\left|\xi^{\prime}\right| \leq 2$. It also remains true for $x_{n}>0$ small. As $f_{+}=\tau\left(\varphi^{\prime}-\alpha_{+}\right)+\tau \alpha_{+}-m_{+}\left(x, \xi^{\prime}\right)$, for $\left|x_{n}\right|$ small, we obtain $f_{+} \geq C \lambda$, which means that $f_{+}$is elliptic positive in that region.

Second, if we now have $\left|\xi^{\prime}\right| \geq 1$ and

$$
\begin{equation*}
\tau \alpha_{+} \leq \sigma m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}, \tag{4-5}
\end{equation*}
$$

we get that $\tau \alpha_{-} \leq \sigma^{-1} m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}$: otherwise we would have $\tau \alpha_{-}>\sigma^{-1} m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}$and thus

$$
\frac{m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}}{\sigma \alpha_{-}}<\tau \leq \frac{\sigma m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{\alpha_{+}}
$$

implying

$$
\frac{\alpha_{+}}{\alpha_{-}}<\sigma^{2} \frac{m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{m_{-}\left(x^{\prime}, \xi^{\prime}\right) \mid x_{n}=0^{-}} \leq \sigma^{2} \sup _{\substack{x^{\prime}, \xi^{\prime} \\\left|\xi^{\prime}\right| \geq 1}} \frac{m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}}=\frac{\alpha_{+}}{\alpha_{-}}, \quad \text { which is impossible. }
$$

As a consequence, we have

$$
\begin{align*}
\tau \alpha_{-}-m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}} & \leq-m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}} \frac{(\sigma-1)}{\sigma} \\
& \leq-m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}} \frac{(\sigma-1)}{2 \sigma}-\frac{(\sigma-1)}{2} \tau \alpha_{-} \leq-C \lambda \tag{4-6}
\end{align*}
$$

With $f_{-}=\tau\left(\varphi^{\prime}-\alpha_{-}\right)+\tau \alpha_{-} m_{-}\left(x, \xi^{\prime}\right)$, for $\left|x_{n}\right|$ sufficiently small, we obtain $f_{-} \leq-C \lambda$, which means that $f_{-}$is elliptic negative in that region.

We have thus proven the following result.

Lemma 4.1. Let $\sigma>\sigma_{0}>1$ and $\alpha_{ \pm}$be positive numbers such that (4-2) holds. For $s>0$, we define the following "cones" in $\mathbb{R}_{x^{\prime}}^{n-1} \times \mathbb{R}_{\xi^{\prime}}^{n-1} \times \mathbb{R}_{+}^{*}$ :

$$
\begin{aligned}
& \Gamma_{s}=\left\{\left(x^{\prime}, \tau, \xi^{\prime}\right):\left|\xi^{\prime}\right|<2 \text { or } \tau \alpha_{+}>\operatorname{sm} m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}\right\}, \\
& \widetilde{\Gamma}_{s}=\left\{\left(x^{\prime}, \tau, \xi^{\prime}\right):\left|\xi^{\prime}\right|>1 \text { and } \tau \alpha_{+}<\operatorname{sm} m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}\right\} .
\end{aligned}
$$

For $\left|x_{n}\right|$ sufficiently small and $\tau$ sufficiently large, we have $\mathbb{R}^{n-1} \times \mathbb{R}^{n-1} \times \mathbb{R}_{+}^{*}=\Gamma_{\sigma_{0}} \cup \widetilde{\Gamma}_{\sigma}$ and

$$
\begin{aligned}
& \Gamma_{\sigma_{0}} \subset\left\{\left(x^{\prime}, \xi^{\prime}, \tau\right) \in \mathbb{R}^{n-1} \times \mathbb{R}^{n-1} \times \mathbb{R}_{+}^{*}: f_{+}\left(x, \xi^{\prime}\right) \geq C \lambda, \text { if } 0 \leq x_{n} \text { small }\right\}, \\
& \widetilde{\Gamma}_{\sigma} \subset\left\{\left(x^{\prime}, \xi^{\prime}, \tau\right) \in \mathbb{R}^{n-1} \times \mathbb{R}^{n-1} \times \mathbb{R}_{+}^{*}: f_{-}\left(x, \xi^{\prime}\right) \leq-C \lambda, \text { if }\left|x_{n}\right| \text { small, } x_{n} \leq 0\right\} .
\end{aligned}
$$

N.B. The key result for the sequel is that property (4-1) is securing the fact that the overlapping open regions $\Gamma_{\sigma_{0}}$ and $\widetilde{\Gamma}_{\sigma}$ are such that on $\Gamma_{\sigma_{0}}, f_{+}$is elliptic positive and on $\widetilde{\Gamma}_{\sigma}, f_{-}$is elliptic negative. Using a partition of unity and symbolic calculus, we shall be able to assume that either $F_{+}$is elliptic positive, or $F_{-}$is elliptic negative.
N.B. Note that we can keep the preliminary cut-off region of Section 3A away from the overlap of $\Gamma_{\sigma_{0}}$ and $\widetilde{\Gamma}_{\sigma}$ by choosing $\epsilon$ sufficiently small (see (3-5) and Lemma 3.1). This is illustrated in Figure 4.

With the two overlapping "cones", for $\tau \geq \tau_{2}$, we introduce a homogeneous partition of unity

$$
\begin{equation*}
1=\chi_{0}\left(x^{\prime}, \xi^{\prime}, \tau\right)+\chi_{1}\left(x^{\prime}, \xi^{\prime}, \tau\right), \quad \underbrace{\operatorname{supp}\left(\chi_{0}\right) \subset \Gamma_{\sigma_{0}}}_{\left|\xi^{\prime}\right| \lesssim \tau, f_{+} \text {elliptic }>0}, \quad \underbrace{\operatorname{supp}\left(\chi_{1}\right) \subset \widetilde{\Gamma}_{\sigma}}_{\left|\xi^{\prime}\right| \gtrsim \tau, f_{-} \text {elliptic }<0} . \tag{4-7}
\end{equation*}
$$

Note that $\chi_{j}^{\prime}, j=0,1$, are supported at the overlap of the regions $\Gamma_{\sigma_{0}}$ and $\widetilde{\Gamma}_{\sigma}$, where $\tau \lesssim\left|\xi^{\prime}\right|$. Hence, $\chi_{0}$ and $\chi_{1}$ satisfy the estimates of the semiclassical calculus and we have $\chi_{0}, \chi_{1} \in \mathcal{S}_{\tau}^{0}$. With these symbols


Figure 4. The overlapping microlocal regions $\Gamma_{\sigma_{0}}$ and $\widetilde{\Gamma}_{\sigma}$ in the $\tau,\left|\xi^{\prime}\right|$ plane above a point $x^{\prime}$. Dashed is the region used in Section 3A, which is kept away from the overlap of $\Gamma_{\sigma_{0}}$ and $\widetilde{\Gamma}_{\sigma}$.
we associate the operators

$$
\begin{equation*}
\Xi_{j}=\mathrm{op}^{w}\left(\chi_{j}\right), j=0,1, \quad \text { and we have } \Xi_{0}+\Xi_{1}=\mathrm{Id} \tag{4-8}
\end{equation*}
$$

Remark 4.2. Here we have chosen to let $\chi_{0}$ and $\chi_{1}$ (resp. $\Xi_{0}$ and $\Xi_{1}$ ) be independent of $x_{n}$. As the functions $v_{ \pm}$have supports in which $\left|x_{n}\right|$ is small (see the introductory paragraph of this section), we can further introduce a cut-off in the $x_{n}$ direction. The lemmata of Section 3 can then be applied directly.

By the transmission conditions (2-21), we find

$$
\begin{equation*}
\Xi_{j} v_{+\mid x_{n}=0^{+}}-\Xi_{j} v_{-\mid x_{n}=0^{-}}=\Xi_{j} \theta_{\varphi} \tag{4-9}
\end{equation*}
$$

and

$$
\begin{aligned}
a_{n n}^{+}\left(D_{n}+T_{+}+i \tau \varphi_{+}^{\prime}\right) \Xi_{j} v_{+\mid x_{n}=0^{+}}-a_{n n}^{-}\left(D_{n}\right. & \left.+T_{-}+i \tau \varphi_{-}^{\prime}\right) \Xi_{j} v_{-\mid x_{n}=0^{-}} \\
& =\Xi_{j} \Theta_{\varphi}+\mathrm{op}^{w}\left(\kappa_{0}\right) v_{\mid x_{n}=0^{+}}+\mathrm{op}^{w}\left(\tilde{\kappa}_{0}\right) \theta_{\varphi}, \quad j=0,1,
\end{aligned}
$$

with $\kappa_{0}, \tilde{\kappa}_{0} \in \mathcal{S}_{\tau}^{0}$ that originate from commutators and (4-9). Defining

$$
\begin{equation*}
\mathcal{V}_{j, \pm}=a_{n n}^{ \pm}\left(D_{n}+S_{ \pm}+i \tau \varphi_{ \pm}^{\prime}\right) \Xi_{j} v_{ \pm \mid x_{n}=0^{ \pm}} \tag{4-10}
\end{equation*}
$$

and recalling (2-19), we find

$$
\begin{equation*}
\mathcal{V}_{j,+}-\mathcal{V}_{j,-}=\Xi_{j} \Theta_{\varphi}+\mathrm{op}^{w}\left(\kappa_{1}\right) v_{\mid x_{n}=0^{+}}+\mathrm{op}^{w}\left(\tilde{\kappa}_{1}\right) \theta_{\varphi}, \quad \kappa_{1}, \tilde{\kappa}_{1} \in \mathcal{S}_{\tau}^{0} \tag{4-11}
\end{equation*}
$$

We shall now prove microlocal Carleman estimates in the regions $\Gamma_{\sigma_{0}}$ and $\widetilde{\Gamma}_{\sigma}$.
4B. Region $\Gamma_{\sigma_{0}}$ : both roots are positive on the positive half-line. On the one hand, by Lemma 3.2, we have

$$
\begin{equation*}
\left\|H_{+} \mathcal{P}_{+} \Xi_{0} v_{+}\right\| \gtrsim\left|\mathcal{V}_{0,+}-i a_{n n}^{+} M_{+} \Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2}}+\left\|H_{+} \mathcal{P}_{F+} \Xi_{0} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)} \tag{4-12}
\end{equation*}
$$

where the operator $\mathcal{P}_{+}$is defined in (2-7) (see also (2-17)). The positive ellipticity of $F_{+}$on the $\operatorname{supp} \chi_{0} \cap \operatorname{supp}\left(v_{+}\right)$allows us to reiterate the estimate by Lemma 3.3 to obtain

$$
\begin{aligned}
&\left\|H_{+} \mathcal{P}_{+} \Xi_{0} v_{+}\right\|+\left\|H_{+} v_{+}\right\| \gtrsim\left|\mathcal{V}_{0,+}-i a_{n n}^{+} M_{+} \Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2}}+\left|\Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2}} \\
&+\left\|H_{+} \Xi_{0} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2}\right)}+\left\|H_{+} D_{n} \Xi_{0} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)}
\end{aligned}
$$

Since we also have

$$
\begin{equation*}
\left|\mathcal{V}_{0,+}\right|_{\mathcal{H}^{1 / 2}} \lesssim\left|\mathcal{V}_{0,+}-i a_{n n}^{+} M_{+} \Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2}}+\left|\Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2}} \tag{4-13}
\end{equation*}
$$

writing the $\mathcal{H}^{1 / 2}$ norm as $|\cdot|_{\mathcal{H}^{1 / 2}} \sim \tau^{1 / 2}|\cdot|_{L^{2}}+|\cdot|_{H^{1 / 2}}$ and using the regularity of $M_{+} \in \operatorname{op}\left(\mathcal{S}^{1}\right)$ in the standard calculus, we obtain

$$
\begin{align*}
\left\|H_{+} \mathcal{P}_{+} \Xi_{0} v_{+}\right\|+\left\|H_{+} v_{+}\right\| \gtrsim\left|\mathcal{V}_{0,+}\right|_{\mathcal{H}^{1 / 2}} & +\left|\Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2}} \\
& +\left\|H_{+} \Xi_{0} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2}\right)}+\left\|H_{+} \Xi_{0} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)} \tag{4-14}
\end{align*}
$$

On the other hand, with Lemma 3.7, we have, for $k=0$ or $k=\frac{1}{2}$,

$$
\left\|H_{-} \mathcal{P}_{-} \Xi_{0} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{-k}\right)}+\left|\mathcal{V}_{0,-}+i a_{n n}^{-} M_{-} \Xi_{0} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}} \gtrsim \tau^{-1 / 2}\left\|H_{-} \mathcal{P}_{E-} \Xi_{0} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}
$$

This gives

$$
\left\|H_{-} \mathcal{P}_{-} \Xi_{0} v_{-}\right\|+\tau^{k}\left|\mathcal{V}_{0,-}+i a_{n n}^{-} M_{-} \Xi_{0} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}} \gtrsim \tau^{k-1 / 2}\left\|H_{-} \mathcal{P}_{E-} \Xi_{0} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}
$$

which with Lemma 3.2 yields

$$
\begin{aligned}
\left\|H_{-} \mathcal{P}_{-} \Xi_{0} v_{-}\right\|+\tau^{k} \mid \mathcal{V}_{0,-}+i a_{n n}^{-} M_{-} & \left.\Xi_{0} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\tau^{k-1 / 2}\left|\Xi_{0} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}} \\
& \gtrsim \tau^{k-1 / 2}\left(\left\|H_{-} \Xi_{0} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} \Xi_{0} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right)
\end{aligned}
$$

Arguing as for (4-13), we find

$$
\begin{align*}
&\left\|H_{-} \mathcal{P}_{-} \Xi_{0} v_{-}\right\|+\tau^{k}\left|\mathcal{V}_{0,-}\right|_{\mathcal{H}^{1 / 2-k}}+\tau^{k}\left|\Xi_{0} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}} \\
& \gtrsim \tau^{k-1 / 2}\left(\left\|H_{-} \Xi_{0} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} \Xi_{0} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right) . \tag{4-15}
\end{align*}
$$

Now, from the transmission conditions (4-9)-(4-11), by adding $\varepsilon(4-15)+(4-14)$, we obtain

$$
\begin{aligned}
& \left\|H_{-} \mathcal{P}_{-} \Xi_{0} v_{-}\right\|+\left\|H_{+} \mathcal{P}_{+} \Xi_{0} v_{+}\right\|+\tau^{k}\left(\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|v_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}\right)+\left\|H_{+} v_{+}\right\| \\
& \quad \gtrsim \\
& \quad \tau^{k}\left(\left|\mathcal{V}_{0,-}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\mathcal{V}_{0,+}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\Xi_{0} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2-k}}\right) \\
& \quad+\tau^{k-1 / 2}\left(\left\|\Xi_{0} v\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} \Xi_{0} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} \Xi_{0} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right),
\end{aligned}
$$

by choosing $\varepsilon>0$ sufficiently small and $\tau$ sufficiently large. Finally, recalling the form of $\mathcal{V}_{0, \pm}$ and arguing as for (4-13), we obtain

$$
\begin{align*}
& \left\|H_{-} \mathcal{P}_{-} \Xi_{0} v_{-}\right\|+\left\|H_{+} \mathcal{P}_{+} \Xi_{0} v_{+}\right\|+\tau^{k}\left(\left|\theta_{\varphi}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|\Theta_{\varphi}\right|_{\mathcal{H}^{\frac{1}{2}-k}}+\left|v_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}\right)+\left\|H_{+} v_{+}\right\| \\
& \gtrsim \\
& \gtrsim \tau^{k}\left(\left|\Xi_{0} D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}+\left|\Xi_{0} D_{n} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}+\left|\Xi_{0} v_{-}\right| x_{n}=\left.0^{-}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|\Xi_{0} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{3}{2}-k}}\right)  \tag{4-16}\\
& \quad+\tau^{k-\frac{1}{2}}\left(\left\|\Xi_{0} v\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} \Xi_{0} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} \Xi_{0} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right), \quad \text { (4-16) }
\end{align*}
$$

for $k=0$ or $k=\frac{1}{2}$.
Remark 4.3. In the case $k=0$, recalling the form of the second-order operators $\mathcal{P}_{ \pm}$, we can estimate the additional terms $\tau^{-1 / 2}\left\|H_{ \pm} \Xi_{0} D_{n}^{2} v_{ \pm}\right\|$.

4C. Region $\tilde{\Gamma}_{\sigma}$ : only one root is positive on the positive half-line. This case is more difficult a priori, since we cannot expect to control $v_{\mid x_{n}=0^{+}}$directly from the estimates of the first-order factors. Nevertheless, when the positive ellipticity of $F_{+}$is violated, $F_{-}$is elliptic negative: this is the result of our main geometric assumption in Lemma 4.1.

As in (4-12), we have

$$
\left\|H_{+} \mathcal{P}_{+} \Xi_{1} v_{+}\right\| \gtrsim\left|\mathcal{V}_{1,+}-i a_{n n}^{+} M_{+} \Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2}}+\left\|H_{+} \mathcal{P}_{F+} \Xi_{1} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)}
$$

and using Lemma 3.5 for the negative half-line, we have

$$
\begin{aligned}
\left\|H_{-} \mathcal{P}_{-} \Xi_{1} v_{-}\right\|+\left\|H_{-} v_{-}\right\|+\| H_{-} & D_{n} v_{-} \| \\
& \gtrsim\left|\mathcal{V}_{1,-}+i a_{n n}^{-} M_{-} \Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2}}+\left\|H_{-} \mathcal{P}_{E-} \Xi_{1} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)}
\end{aligned}
$$

A quick glance at the above estimates shows that none could be iterated in a favorable manner, since $F_{+}$ could be negative on the positive half-line and $E_{-}$is indeed positive on the negative half-line. We have to use the additional information given by the transmission conditions. From the above inequalities, we control

$$
\tau^{k}\left(\left|\mathcal{V}_{1,-}+i a_{n n}^{-} M_{-} \Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\left|-\mathcal{V}_{1,+}+i a_{n n}^{+} M_{+} \Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}\right)
$$

for $k=0$ or $\frac{1}{2}$, which, by the transmission conditions (4-9)-(4-11), implies the control of

$$
\begin{aligned}
& \tau^{k}\left|\mathcal{V}_{1,-}-\mathcal{V}_{1,+}+i a_{n n}^{-} M_{-} \Xi_{1} v_{-\mid x_{n}=0^{-}}+i a_{n n}^{+} M_{+} \Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}} \\
& \geq \tau^{k}\left|\left(a_{n n}^{-} M_{-}+a_{n n}^{+} M_{+}\right) \Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}-C \tau^{k}\left(\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}+\left|v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}\right)
\end{aligned}
$$

Let now $\tilde{\chi}_{1} \in \mathcal{S}_{\tau}^{0}$ satisfy the same properties as $\chi_{1}$, with $\tilde{\chi}_{1}=1$ on a neighborhood of $\operatorname{supp}\left(\chi_{1}\right)$. We then write

$$
m_{ \pm}=\check{m}_{ \pm}+r, \quad \text { with } \check{m}_{ \pm}=m_{ \pm} \tilde{\chi}_{1}+\lambda\left(1-\tilde{\chi}_{1}\right), \quad r=\left(m_{ \pm}+\lambda\right)\left(1-\tilde{\chi}_{1}\right)
$$

We have $\check{m}_{ \pm} \geq C \lambda$ and $\check{m}_{ \pm} \in \mathcal{S}_{\tau}^{1}$ because of the support of $\tilde{\chi}_{1}$. Because of the supports of $1-\tilde{\chi}_{1}$ and $\chi_{1}$, in particular $\tau \lesssim\left|\xi^{\prime}\right|$ in $\operatorname{supp}\left(\chi_{1}\right)$, Lemma A. 4 yields $r \sharp \chi_{1} \in \mathcal{S}_{\tau}^{-\infty}$. With Lemma A. 2 and (4-9), we thus obtain

$$
\begin{aligned}
& \left|\mathcal{V}_{1,-}+i a_{n n}^{-} M_{-} \Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\left|-\mathcal{V}_{1,+}+i a_{n n}^{+} M_{+} \Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}} \\
& \quad+\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}+\left|v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}} \gtrsim\left|\Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2-k}}
\end{aligned}
$$

From the form of $\mathcal{V}_{1,+}$ we obtain

$$
\begin{aligned}
&\left|\mathcal{V}_{1,-}+i a_{n n}^{-} M_{-} \Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\left|-\mathcal{V}_{1,+}+i a_{n n}^{+} M_{+} \Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}} \\
& \quad+\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}+\left|v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}} \\
& \gtrsim\left|\Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}+ \\
&\left|\Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Xi_{1} D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\Xi_{1} D_{n} v_{+}\right| x_{n}=0^{+}\left.\right|_{\mathcal{H}^{1 / 2-k}}
\end{aligned}
$$

We thus have

$$
\begin{aligned}
& \left\|H_{-} \mathcal{P}_{-} \Xi_{1} v_{-}\right\|+\left\|H_{+} \mathcal{P}_{+} \Xi_{1} v_{+}\right\| \\
& +\tau^{k}\left(\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}+\left|v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}\right)+\left\|H_{-} v_{-}\right\|+\left\|H_{-} D_{n} v_{-}\right\| \\
& \quad \gtrsim \tau^{k}\left(\left|\Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Xi_{1} D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}\right. \\
& \left.\quad \quad+\left|\Xi_{1} D_{n} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}+\left\|H_{-} \mathcal{P}_{E-} \Xi_{1} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} \mathcal{P}_{F+} \Xi_{1} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right),
\end{aligned}
$$

for $k=0$ or $\frac{1}{2}$. The remaining part of the discussion is very similar to the last part of the argument in the previous subsection. By Lemmata 3.2 and 3.7, we have

$$
\begin{aligned}
&\left\|H_{-} \mathcal{P}_{E-} \Xi_{1} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left|\Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}} \\
& \gtrsim\left\|H_{-} \Xi_{1} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} \Xi_{1} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}
\end{aligned}
$$

and

$$
\begin{aligned}
&\left\|H_{+} \mathcal{P}_{F_{+}} \Xi_{1} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left|\Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2-k}} \\
& \gtrsim \tau^{-1 / 2}\left(\left\|H_{+} \Xi_{1} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{+} \Xi_{1} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right) .
\end{aligned}
$$

Since $\left|\Xi_{1} v_{ \pm \mid x_{n}=0^{ \pm}}\right|_{\mathcal{H}^{3 / 2-k}}$ are already controlled, we also control the right-hand side of the above inequalities and have

$$
\begin{align*}
& \left\|H_{-} \mathcal{P}_{-} \Xi_{1} v_{-}\right\|+\left\|H_{+} \mathcal{P}_{+} \Xi_{1} v_{+}\right\|+\tau^{k}\left(\left|\Theta_{\varphi}\right|_{\mathcal{H}^{\frac{1}{2}-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}\right) \\
& +\left\|H_{-} v_{-}\right\|+\left\|H_{-} D_{n} v_{-}\right\| \\
& \gtrsim \\
& \quad \tau^{k}\left(\left|\Xi_{1} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|\Xi_{1} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|\Xi_{1} D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}+\left|\Xi_{1} D_{n} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}\right)  \tag{4-17}\\
& \quad+\tau^{k-\frac{1}{2}}\left(\left\|\Xi_{1} v\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} \Xi_{1} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} \Xi_{1} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right) . \quad \text { (4-17) }
\end{align*}
$$

Remark 4.4. In the case $k=0$, recalling the form of the second-order operators $\mathcal{P}_{ \pm}$, we can estimate the additional terms $\tau^{-1 / 2}\left\|H_{ \pm} \Xi_{1} D_{n}^{2} v_{ \pm}\right\|$.

4D. Patching together microlocal estimates. We now sum estimates (4-16) and (4-17) together. By the triangle inequality, this gives, for $k=0$ or $\frac{1}{2}$,

$$
\begin{aligned}
& \sum_{j=0,1}\left(\left\|H_{-} \mathcal{P}_{-} \Xi_{j} v_{-}\right\|+\left\|H_{+} \mathcal{P}_{+} \Xi_{j} v_{+}\right\|\right)+\tau^{k}\left(\left|\Theta_{\varphi}\right|_{\mathcal{H}^{\frac{1}{2}-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|v_{++}\right| x_{n}=\left.0^{+}\right|_{\mathcal{H}^{\frac{1}{2}-k}}\right) \\
& +\left\|H_{+} v_{+}\right\|+\left\|H_{-} v_{-}\right\|+\left\|H_{-} D_{n} v_{-}\right\| \\
& \gtrsim \\
& \gtrsim \tau^{k}\left(\left|v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{3}{2}-k}}+\left|D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}+\left|D_{n} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\frac{1}{2}-k}}\right) \\
& \\
& \quad+\tau^{k-\frac{1}{2}}\left(\|v\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right) .
\end{aligned}
$$

For $\tau$ sufficiently large, we now obtain

$$
\begin{aligned}
& \sum_{j=0,1}\left(\left\|H_{-} \mathcal{P}_{-} \Xi_{j} v_{-}\right\|+\left\|H_{+} \mathcal{P}_{+} \Xi_{j} v_{+}\right\|\right)+\tau^{k}\left(\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}\right) \\
& \gtrsim \tau^{k}\left(\left|v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\left|D_{n} v_{+}\right| x_{n}=\left.0^{+}\right|_{\mathcal{H}^{1 / 2-k}}\right) \\
& \\
& \quad+\tau^{k-1 / 2}\left(\|v\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right)
\end{aligned}
$$

Arguing with commutators, as in the end of Lemma 3.2, noting here that the second-order operators $\mathcal{P}_{ \pm}$ belong to the semiclassical calculus, that is, $\mathcal{P}_{ \pm} \in \mathcal{S}_{\tau}^{2}$, we obtain, for $\tau$ sufficiently large,

$$
\begin{aligned}
& \left\|H_{-} \mathcal{P}_{-} v_{-}\right\|+\left\|H_{+} \mathcal{P}_{+} v_{+}\right\|+\tau^{k}\left(\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}\right) \\
& \gtrsim \tau^{k}\left(\left|v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|v_{+}\right| x_{n}=\left.0^{+}\right|_{\mathcal{H}^{3 / 2-k}}+\left|D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\left|D_{n} v_{+}\right| x_{n}=\left.0^{+}\right|_{\mathcal{H}^{1 / 2-k}}\right) \\
& \quad+\tau^{k-1 / 2}\left(\|v\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\left\|H_{-} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right) .
\end{aligned}
$$

In particular, this estimate allows us to absorb the perturbation in $\Psi^{1}$ as defined by (2-16) by taking $\tau$ large enough. For $k=\frac{1}{2}$, we obtain the result of Proposition 2.1, which concludes the proof of the Carleman estimate.
N.B. The case $k=0$ gives higher Sobolev norm estimates of the trace terms $v_{ \pm \mid x_{n}=0^{ \pm}}$and $D_{n} v_{ \pm \mid x_{n}=0^{ \pm}}$. It also allows one to estimate $\tau^{-1 / 2}\left\|H_{ \pm} D_{n}^{2} v_{ \pm}\right\|$, as noted in Remarks 4.3 and 4.4. These estimates are obtained at the price of higher requirements (one additional tangential half-derivative) on the nonhomogeneous transmission condition functions $\theta$ and $\Theta$.

4E. Convexification. We want now to slightly modify the weight function $\varphi$, for instance to allow some convexification. We started with $\varphi=H_{+} \varphi_{+}+H_{-} \varphi_{-}$, where $\varphi_{ \pm}$were given by (2-22) and our proof relied heavily on a smooth factorization in first-order factors. We modify $\varphi_{ \pm}$into

$$
\Phi_{ \pm}\left(x^{\prime}, x_{n}\right)=\underbrace{\alpha_{ \pm} x_{n}+\frac{1}{2} \beta x_{n}^{2}}_{\varphi_{ \pm}\left(x_{n}\right)}+\kappa\left(x^{\prime}, x_{n}\right), \quad \kappa \in \mathscr{C}^{\infty}(\Omega ; \mathbb{R}), \quad|d \kappa| \text { bounded on } \Omega .
$$

We shall prove below that the Carleman estimates of Theorems 1.1 and 2.2 also hold in this case if we choose $\left\|\kappa^{\prime}\right\|_{L^{\infty}}$ sufficiently small.

We start by inspecting what survives in our factorization argument. We have from (2-7) $\mathcal{P}_{ \pm}=$ $\left(D+i \tau d \Phi_{ \pm}\right) \cdot A_{ \pm}\left(D+i \tau d \Phi_{ \pm}\right)$, so that, modulo $\Psi^{1}$,

$$
\begin{align*}
\mathcal{P}_{ \pm} \equiv a_{n n}^{ \pm}\left(\left[D_{n}+S_{ \pm}\left(x, D^{\prime}\right)+i \tau\left(\partial_{n} \Phi_{ \pm}+S_{ \pm}(x,\right.\right.\right. & \left.\left.\left.\partial_{x^{\prime}} \Phi_{ \pm}\right)\right)\right]^{2} \\
& \left.+\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}}\left(D_{j}+i \tau \partial_{j} \Phi_{ \pm}\right)\left(D_{k}+i \tau \partial_{k} \Phi_{ \pm}\right)\right) \tag{4-18}
\end{align*}
$$

(See also (2-10).) The new difficulty comes from the fact that the roots in the variable $D_{n}$ are not necessarily smooth: when $\Phi$ does not depend on $x^{\prime}$, the symbol of the term $b_{j k}^{ \pm}\left(D_{j}+i \tau \partial_{j} \Phi_{ \pm}\right)\left(D_{k}+i \tau \partial_{k} \Phi_{ \pm}\right)$ equals $b_{j k}^{ \pm} \xi_{j} \xi_{k}$ and thus is positive elliptic with a smooth positive square root. It is no longer the case when we have an actual dependence of $\Phi$ upon the variable $x^{\prime}$; nevertheless, we have, as $\partial_{x^{\prime}} \Phi_{ \pm}=\partial_{x^{\prime}} \kappa$,

$$
\begin{aligned}
\operatorname{Re}\left(\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}}\left(\xi_{j}+i \tau \partial_{j} \kappa\right)\left(\xi_{k}+i \tau \partial_{k} \kappa\right)\right) & =\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} \xi_{j} \xi_{k}-\tau^{2} \frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} \partial_{j} \kappa \partial_{k} \kappa \geq\left(\lambda_{0}^{ \pm}\right)^{2}\left|\xi^{\prime}\right|^{2}-\tau^{2}\left(\lambda_{1}^{ \pm}\right)^{2}\left|\partial_{x^{\prime} \kappa}\right|^{2} \\
& \geq \frac{3}{4}\left(\lambda_{0}^{ \pm}\right)^{2}\left|\xi^{\prime}\right|^{2} \quad \text { if } \tau\left\|\partial_{x^{\prime}} \kappa\right\|_{L^{\infty}} \leq \frac{\lambda_{0}^{ \pm}}{2 \lambda_{1}^{ \pm}}\left|\xi^{\prime}\right|,
\end{aligned}
$$

where

$$
\lambda_{0}^{ \pm}=\inf _{\substack{x^{\prime}, \xi \\\left|\xi^{\prime}\right| \mid=1}}\left(\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} \xi_{j} \xi_{k}\right)_{\mid x_{n}=0^{ \pm}}^{1 / 2}, \quad \lambda_{1}^{ \pm}=\sup _{\substack{x^{\prime}, \xi \\\left|\xi^{\prime}\right| \mid=1}}\left(\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} \xi_{j} \xi_{k}\right)_{\mid x_{n}=0^{ \pm}}^{1 / 2}
$$

As a result, the roots are smooth when $\tau\left\|\partial_{x^{\prime} \kappa}\right\|_{L^{\infty}} \leq \frac{\lambda_{0}^{ \pm}}{2 \lambda_{1}^{ \pm}}\left|\xi^{\prime}\right|$.
In this case, we define $\mathfrak{m}_{ \pm} \in \mathcal{S}^{1}$ such that

$$
\text { for }\left|\xi^{\prime}\right| \geq 1, \quad \mathfrak{m}_{ \pm}\left(x, \xi^{\prime}\right)=\left(\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}}\left(\xi_{j}+i \tau \partial_{j} \kappa\right)\left(\xi_{k}+i \tau \partial_{k} \kappa\right)\right)^{1 / 2}, \quad \mathfrak{m}_{ \pm}\left(x, \xi^{\prime}\right) \geq C\left\langle\xi^{\prime}\right\rangle
$$

Here we use the principal value of the square root function for complex numbers.
Introducing

$$
\mathfrak{e}_{ \pm}=\tau\left(\partial_{n} \Phi_{ \pm}+S_{ \pm}\left(x, \partial_{x^{\prime}} \kappa\right)\right)+\operatorname{Re} \mathfrak{m}_{ \pm}\left(x, \xi^{\prime}\right), \mathfrak{f}_{ \pm}=\tau\left(\partial_{n} \Phi_{ \pm}+S_{ \pm}\left(x, \partial_{x^{\prime}} \kappa\right)\right)-\operatorname{Re} \mathfrak{m}_{ \pm}\left(x, \xi^{\prime}\right)
$$

we set $\mathfrak{E}_{ \pm}=\mathrm{op}\left(\mathfrak{e}_{ \pm}\right)$and $\mathfrak{F}_{ \pm}=\operatorname{op}\left(\mathfrak{f}_{ \pm}\right)$and

$$
\begin{aligned}
\mathcal{P}_{\mathfrak{E} \pm} & =D_{n}+S_{ \pm}\left(x, D^{\prime}\right)-\mathrm{op}^{w}\left(\operatorname{Im} \mathfrak{m}_{ \pm}\right)+i \mathfrak{E}_{ \pm}, \\
\mathcal{P}_{\mathfrak{F} \pm} & =D_{n}+S_{ \pm}\left(x, D^{\prime}\right)+\mathrm{op}^{w}\left(\operatorname{Im} \mathfrak{m}_{ \pm}\right)+i \mathfrak{F}_{ \pm}
\end{aligned}
$$

Modulo the operator class $\Psi^{1}$, as in Section 2C, we may write

$$
\mathcal{P}_{+} \equiv \mathcal{P}_{\mathfrak{E}+} a_{n n}^{+} \mathcal{P}_{\mathfrak{F}+}, \quad \mathcal{P}_{-} \equiv \mathcal{P}_{\mathfrak{F}-} a_{n n}^{-} \mathcal{P}_{\mathfrak{E}-} .
$$

We keep the notation $m_{ \pm}$for the symbols that correspond to the previous sections, that is, if $\kappa$ vanishes:

$$
m_{ \pm}\left(x, \xi^{\prime}\right)=\left(\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} \xi_{j} \xi_{k}\right)^{1 / 2}, \quad\left|\xi^{\prime}\right| \geq 1
$$

As above, see (4-1), we choose the weight function such that the following property is fulfilled:

$$
\frac{\alpha_{+}}{\alpha_{-}}>\sup _{\substack{x^{\prime}, \xi^{\prime} \\\left|\xi^{\prime}\right| \geq 1}} \frac{m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}}, \quad \alpha_{ \pm}=\partial_{x_{n}} \varphi_{ \pm \mid x_{n}=0^{ \pm}}
$$

and we let $\sigma>1$ be such that

$$
\frac{\alpha_{+}}{\alpha_{-}}=\sigma^{2} \sup _{\substack{x^{\prime}, \xi^{\prime} \\\left|\xi^{\prime}\right| \geq 1}} \frac{m_{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}}{m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}}}
$$

We also introduce $1<\sigma_{0}<\sigma$. As in Section 2C, we set $f_{ \pm}=\tau \varphi_{ \pm}^{\prime}-m_{ \pm}$(compare with $\mathfrak{f}_{ \pm}$above).
We can choose $\alpha_{+} /\left\|\partial_{\chi^{\prime}} \kappa\right\|_{L^{\infty}}$ large enough that

$$
\frac{\sigma m_{\mid x_{n}=0^{+}}^{+}}{\alpha_{+}}<\frac{\lambda_{0}^{+}\left|\xi^{\prime}\right|}{4 \lambda_{1}^{+}\left\|\partial_{x^{\prime}} \kappa\right\|_{L^{\infty}}}
$$

and

$$
\begin{equation*}
f_{ \pm} \geq C \lambda \quad \text { if } \tau \geq\left|\xi^{\prime}\right| \frac{\lambda_{0}^{+}}{4 \lambda_{1}^{+}\left\|\partial_{x^{\prime} \kappa}\right\|_{L^{\infty}}} \text { for }\left|x_{n}\right| \text { sufficiently small. } \tag{4-19}
\end{equation*}
$$

We may then consider the following cases.
(1) When $\tau \alpha_{+} \leq \sigma m^{+}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{+}}$, arguing as in (4-5)-(4-6), we find that

$$
\tau\left(\alpha_{-}+\beta x_{n}\right)-m_{-}\left(x^{\prime}, \xi^{\prime}\right)_{\mid x_{n}=0^{-}} \leq-C \lambda,
$$

if $\left|x_{n}\right|$ is sufficiently small. It follows that $\mathfrak{F}_{-}$is elliptic negative if $\alpha_{+} /\left\|\kappa^{\prime}\right\|_{L^{\infty}}$ is sufficiently large. In this region we may thus argue as we did in Section 4C.
(2) When

$$
\frac{\lambda_{0}^{+}\left|\xi^{\prime}\right|}{2 \lambda_{1}^{+}\left\|\partial_{x^{\prime}} \kappa\right\|_{L^{\infty}}} \geq \tau \geq \frac{\sigma_{0} m_{+}\left(x^{\prime}, \xi^{\prime}\right)}{\alpha_{+}}
$$

the factorization is valid. Arguing as in (4-3)-(4-4), we find that

$$
\tau\left(\alpha_{+}+\beta x_{n}\right)-m_{+}\left(x^{\prime}, \xi^{\prime}\right) \geq C \lambda
$$

if $\left|x_{n}\right|$ is sufficiently small. It follows that $\mathfrak{F}_{+}$is elliptic positive if $\alpha_{+} /\left\|\kappa^{\prime}\right\|_{L^{\infty}}$ is sufficiently large. In this region we may thus argue as we did in Section 4B.

It is important to note that for $\beta$ large and $\left\|\kappa^{\prime}\right\|_{L^{\infty}}$ and $\left\|\kappa^{\prime \prime}\right\|_{L^{\infty}}$ sufficiently small, the weight functions $\Phi_{ \pm}$satisfy the (necessary and sufficient) subellipticity condition (2-26) with a loss of a half-derivative. Then the counterpart of Lemma 2.8 becomes, for $\left\|\kappa^{\prime}\right\|_{L^{\infty}}$ sufficiently small,

$$
\left|\mathfrak{f}_{ \pm}\right| \leq \delta \lambda \Longrightarrow C^{-1} \tau \leq\left|\xi^{\prime}\right| \leq C \tau \text { and }\left\{\xi_{n}+s_{ \pm}+\operatorname{Im}\left(\mathfrak{m}_{ \pm}\right), \mathfrak{f}_{ \pm}\right\} \geq C^{\prime} \lambda
$$

for some $\delta>0$ chosen sufficiently small. This allows us to then obtain the same results as those of Lemma 3.7 for the first-order factors $\mathcal{P}_{\mathfrak{F} \pm}$.
(3) Finally we consider the region

$$
\tau \geq\left|\xi^{\prime}\right| \frac{\lambda_{0}^{+}}{4 \lambda_{1}^{+}\left\|\partial_{\chi^{\prime} \kappa}\right\|_{L^{\infty}}}
$$

There the roots are no longer smooth, but we are well inside an elliptic region; with a perturbation argument, we may in fact disregard the contribution of $\kappa$.

By (4-18), we may write

$$
\begin{equation*}
\mathcal{P}_{ \pm} \equiv \underbrace{a_{n n}^{ \pm}\left(\left[D_{n}+S_{ \pm}\left(x, D^{\prime}\right)+i \tau \partial_{n} \varphi_{ \pm}\right]^{2}+\frac{b_{j k}^{ \pm}}{a_{n n}^{ \pm}} D_{j} D_{k}\right)}_{P_{ \pm}^{0}}+R_{ \pm} \tag{4-20}
\end{equation*}
$$

with $R_{ \pm}=R_{1, \pm}\left(x, D^{\prime}, \tau\right) D_{n}+R_{2, \pm}\left(x, D^{\prime}, \tau\right)$, where $R_{j, \pm} \in \mathrm{op}^{w}\left(\mathcal{S}_{\tau}^{j}\right)$, with $j=1,2$, satisfy

$$
\begin{equation*}
\left\|R_{j, \pm}\left(x, D^{\prime}, \tau\right) u\right\| \leq C\left\|\kappa^{\prime}\right\|_{L^{\infty}}\|u\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{j}\right)} \tag{4-21}
\end{equation*}
$$

The first term $P_{ \pm}^{0}$ in (4-20) corresponds to the conjugated operator in the sections above, where the weight function only depends on the $x_{n}$ variable. This term can be factored into two pseudodifferential first-order terms,

$$
\begin{equation*}
\mathcal{P}_{+}^{0} \equiv \mathcal{P}_{E+} a_{n n}^{+} \mathcal{P}_{F+}, \quad \mathcal{P}_{-}^{0} \equiv \mathcal{P}_{F-} a_{n n}^{-} \mathcal{P}_{E-}, \tag{4-22}
\end{equation*}
$$

with the notation we introduced in Section 2C. In this third region we have $f_{ \pm} \geq C \lambda$, by (4-19). Let $\chi_{2} \in \mathcal{S}_{\tau}^{0}$ be a symbol that localizes in this region and set $\Xi_{2}=\mathrm{op}^{w}\left(\chi_{2}\right)$.

For $\left\|\kappa^{\prime}\right\|_{L^{\infty}}$ bounded with (4-23), we have

$$
\begin{align*}
& \left\|H_{ \pm} R_{1, \pm} D_{n} \Xi_{2} v_{ \pm}\right\| \lesssim \tau^{k}\left\|\kappa^{\prime}\right\|_{L^{\infty}}\left\|H_{ \pm} D_{n} \Xi_{2} v_{ \pm}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right.}+C(\kappa)\left\|H_{ \pm} D_{n} v_{ \pm}\right\|,  \tag{4-23}\\
& \left\|H_{ \pm} R_{2, \pm} D_{n} \Xi_{2} v_{ \pm}\right\| \lesssim \tau^{k}\left\|\kappa^{\prime}\right\|_{L^{\infty} \infty}\left\|H_{ \pm} \Xi_{2} v_{ \pm}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right.}+C(\kappa)\left\|H_{ \pm} v_{ \pm}\right\|, \tag{4-24}
\end{align*}
$$

for $k=0$ or $\frac{1}{2}$.
On the one hand, arguing as in Section 4B, we have (see (4-14))

$$
\begin{align*}
& \left\|H_{+} \mathcal{P}_{+}^{0} \Xi_{2} v_{+}\right\|+\left\|H_{+} v_{+}\right\| \\
& \quad \gtrsim\left|\mathcal{V}_{2,+}\right|_{\mathcal{H}^{1 / 2}}+\left|\Xi_{2} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{3 / 2}}+\left\|H_{+} \Xi_{2} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2}\right)}+\left\|H_{+} \Xi_{2} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1}\right)} \tag{4-25}
\end{align*}
$$

where $\mathcal{V}_{2, \pm}$ is given as in (4-10).
On the other hand, with Lemma 3.4, we have

$$
\begin{aligned}
\left\|H_{-} \mathcal{P}_{-}^{0} \Xi_{2} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{-k}\right)}+\left\|H_{-} v_{-}\right\|+\left\|H_{-} D_{n} v_{-}\right\|+\mid \mathcal{V}_{2,-}+i a_{n n}^{-} M_{-} & \left.\Xi_{2} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}} \\
& \gtrsim\left\|H_{-} \mathcal{P}_{E-} \Xi_{2} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}
\end{aligned}
$$

for $k=0$ or $\frac{1}{2}$, which gives

$$
\begin{aligned}
&\left\|H_{-} \mathcal{P}_{-}^{0} \Xi_{2} v_{-}\right\|+\tau^{k}\left\|H_{-} v_{-}\right\|+\tau^{k}\left\|H_{-} D_{n} v_{-}\right\|+\tau^{k}\left|\mathcal{V}_{2,-}+i a_{n n}^{-} M_{-} \Xi_{2} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}} \\
& \gtrsim \tau^{k}\left\|H_{-} \mathcal{P}_{E-} \Xi_{2} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}
\end{aligned}
$$

Combining this with Lemma 3.2, we obtain

$$
\begin{align*}
\left\|H_{-} \mathcal{P}_{-}^{0} \Xi_{2} v_{-}\right\|+\tau^{k}\left(\left\|H_{-} v_{-}\right\|+\right. & \left.\left\|H_{-} D_{n} v_{-}\right\|+\left|\mathcal{V}_{2,-}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\Xi_{2} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}\right) \\
& \gtrsim \tau^{k}\left\|H_{-} \Xi_{2} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)}+\tau^{k}\left\|H_{+} \Xi_{2} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)} \tag{4-26}
\end{align*}
$$

Now, from the transmission conditions (4-9)-(4-11), by adding $\varepsilon(4-26)+(4-25)$ we obtain, for $\varepsilon$ small,

$$
\begin{align*}
& \left\|H_{+} \mathcal{P}_{+}^{0} \Xi_{2} v_{+}\right\|+\left\|H_{-} \mathcal{P}_{-}^{0} \Xi_{2} v_{-}\right\|+\tau^{k}\left(\left|\theta_{\varphi}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Theta_{\varphi}\right|_{\mathcal{H}^{1 / 2-k}}+\left|v_{\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}\right) \\
& +\tau^{k}\left(\left\|H_{-} v_{-}\right\|+\left\|H_{-} D_{n} v_{-}\right\|\right)+\left\|H_{+} v_{+}\right\|+\left\|H_{+} D_{n} v_{+}\right\| \\
& \quad \gtrsim \tau^{k}\left(\left|\Xi_{2} D_{n} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{1 / 2-k}}+\left|\Xi_{2} D_{n} v_{+\mid x_{n}=0^{+}}\right|_{\mathcal{H}^{1 / 2-k}}\right. \\
& \quad \quad+\left|\Xi_{2} v_{-\mid x_{n}=0^{-}}\right|_{\mathcal{H}^{3 / 2-k}}+\left|\Xi_{2} v_{+}\right| x_{n}=\left.0^{+}\right|_{\mathcal{H}^{3 / 2-k}}+\left\|\Xi_{2} v\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{2-k}\right)} \\
& \left.\quad \quad \quad\left\|H_{-} \Xi_{2} D_{n} v_{-}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}+\left\|H_{+} \Xi_{2} D_{n} v_{+}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{1-k}\right)}\right) . \tag{4-27}
\end{align*}
$$

With (4-23)-(4-24), we see that the same estimate holds for $\mathcal{P}_{ \pm}$in place of $\mathcal{P}_{ \pm}^{0}$ for $\left\|\kappa^{\prime}\right\|_{L^{\infty}}$ chosen sufficiently small. This estimate is of the same quality as those obtained in the two other regions.
Summing up, we have obtained three microlocal overlapping regions and estimates in each of them. The three regions are illustrated in Figure 5. As we did above, we make sure that the preliminary cut-off region of Section 3A does not interact with the overlapping zones by choosing $\epsilon$ sufficiently small (see (3-5) and Lemma 3.1).

The overlap of the regions allows us to use a partition of unity argument, and we can conclude as in Section 4D.

## 5. Necessity of the geometric assumption on the weight function

Considering the operator $\mathcal{L}_{\tau}$ given by (1-23), we may wonder about the relevance of conditions (1-28) to derive a Carleman estimate. In the simple model and weight used here, it turns out that we can show that condition (1-28) is necessary for an estimate to hold. For simplicity, we consider a piecewise constant case $c=H_{+} c_{+}+H_{-} c_{-}$as in Section 1E.

Theorem 5.1. Let us assume that (1-29) is violated, that is,

$$
\begin{equation*}
\frac{\alpha_{+}}{\alpha_{-}}<\frac{m_{+}\left(\xi_{0}^{\prime}\right)}{m_{-}\left(\xi_{0}^{\prime}\right)} \text { for some } \xi_{0}^{\prime} \in \mathbb{R}^{n-1} \backslash 0 . \tag{5-1}
\end{equation*}
$$

Then, for any neighborhood $V$ of the origin, $C>0$, and $\tau_{0}>0$, there exist

$$
v=H_{+} v_{+}+H_{-} v_{-}, \quad v_{ \pm} \in \mathscr{C}_{c}^{\infty}\left(\mathbb{R}^{n}\right)
$$

satisfying the transmission conditions (1-21)-(1-22) at $x_{n}=0$, and $\tau \geq \tau_{0}$ such that

$$
\operatorname{supp}(v) \subset V \quad \text { and } \quad C\left\|\mathcal{L}_{\tau} v\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)} \leq\|v\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}
$$



Figure 5. The overlapping microlocal regions in the case of a convex weight function.

To prove Theorem 5.1, we wish to construct a function $v$, depending on the parameter $\tau$, such that $\left\|\mathcal{L}_{\tau} v\right\|_{L^{2}} \ll\|v\|_{L^{2}}$ as $\tau$ becomes large. The existence of such a quasimode $v$ obviously ruins any hope of obtaining a Carleman estimate for the operator $\mathcal{L}$ with a weight function satisfying (5-1). The remainder of this section is devoted to this construction.

We set

$$
\begin{equation*}
\left(\mathcal{M}_{\tau} u\right)\left(\xi^{\prime}, x_{n}\right)=H_{+}\left(x_{n}\right) c_{n}^{+}\left(D_{n}+i e_{+}\right)\left(D_{n}+i f_{+}\right) u_{+}+H_{-}\left(x_{n}\right) c_{n}^{-}\left(D_{n}+i e_{-}\right)\left(D_{n}+i f_{-}\right) u_{-}, \tag{5-2}
\end{equation*}
$$

that is, the action of the operator $\mathcal{L}_{\tau}$ given in (1-23) in the Fourier domain with respect to $x^{\prime}$. Observe that the terms in each product commute here. We start by constructing a quasimode for $\mathcal{M}_{\tau}$, that is, functions $u_{ \pm}\left(\xi^{\prime}, x_{n}\right)$ compactly supported in the $x_{n}$ variable and in a conic neighborhood of $\xi_{0}^{\prime}$ in the variable $\xi^{\prime}$ with $\left\|\mathcal{M}_{\tau} u\right\|_{L^{2}} \ll\|u\|_{L^{2}}$, so that $u$ is nearly an eigenvector of $\mathcal{M}_{\tau}$ for the eigenvalue 0 .

Condition (5-1) implies that there exists $\tau_{0}>0$ such that

$$
\frac{m_{-}\left(\xi_{0}^{\prime}\right)}{\alpha_{-}}<\tau_{0}<\frac{m_{+}\left(\xi_{0}^{\prime}\right)}{\alpha_{+}} \Longrightarrow \tau_{0} \alpha_{+}-m_{+}\left(\xi_{0}^{\prime}\right)<0<\tau_{0} \alpha_{-}-m_{-}\left(\xi_{0}^{\prime}\right)
$$

By homogeneity, we may in fact choose $\left(\tau_{0}, \xi_{0}^{\prime}\right)$ such that $\tau_{0}^{2}+\left|\xi_{0}^{\prime}\right|^{2}=1$. We thus have, using the notation in (1-23),

$$
f_{+}\left(x_{n}=0\right)=\tau \alpha_{+}-m_{+}\left(\xi^{\prime}\right)<0<f_{-}\left(x_{n}=0\right)=\tau \alpha_{-}-m_{-}\left(\xi^{\prime}\right)
$$

for $\left(\tau, \xi^{\prime}\right)$ in a conic neighborhood $\Gamma$ of $\left(\tau_{0}, \xi_{0}^{\prime}\right)$ in $\mathbb{R} \times \mathbb{R}^{n-1}$. Let $\chi_{1} \in \mathscr{C}_{c}^{\infty}(\mathbb{R}), 0 \leq \chi_{1} \leq 1$, with $\chi_{1} \equiv 1$ in a neighborhood of 0 , such that $\operatorname{supp}(\psi) \subset \Gamma$ with

$$
\psi\left(\tau, \xi^{\prime}\right)=\chi_{1}\left(\frac{\tau}{\left(\tau^{2}+\left|\xi^{\prime}\right|^{2}\right)^{1 / 2}}-\tau_{0}\right) \chi_{1}\left(\left|\frac{\xi^{\prime}}{\left(\tau^{2}+\left|\xi^{\prime}\right|^{2}\right)^{1 / 2}}-\xi_{0}^{\prime}\right|\right)
$$

We thus have

$$
f_{+}\left(x_{n}=0\right) \leq-C \tau, \quad C^{\prime} \tau \leq f_{-}\left(x_{n}=0\right) \quad \text { in } \operatorname{supp}(\psi)
$$

Let $\left(\tau, \xi^{\prime}\right) \in \operatorname{supp}(\psi)$. We can solve the equations

$$
\begin{array}{llll}
\left.\left(D_{n}+i f_{+}\left(x_{n}, \xi^{\prime}\right)\right)\right) q_{+}=0 & \text { on } \mathbb{R}_{+}, & f_{+}\left(x_{n}, \xi^{\prime}\right)=\tau \varphi^{\prime}\left(x_{n}\right)-m_{+}\left(\xi^{\prime}\right)=f_{+}(0)+\tau \beta x_{n}, \\
\left.\left(D_{n}+i f_{-}\left(x_{n}, \xi^{\prime}\right)\right)\right) q_{-}=0 & \text { on } \mathbb{R}_{-}, & f_{-}\left(x_{n}, \xi^{\prime}\right)=\tau \varphi^{\prime}\left(x_{n}\right)-m_{-}\left(\xi^{\prime}\right)=f_{-}(0)+\tau \beta x_{n}, \\
\left.\left(D_{n}+i e_{-}\left(x_{n}, \xi^{\prime}\right)\right)\right) \tilde{q}_{-}=0 & \text { on } \mathbb{R}_{-}, & e_{-}\left(x_{n}, \xi^{\prime}\right)=\tau \varphi^{\prime}\left(x_{n}\right)+m_{-}\left(\xi^{\prime}\right)=e_{-}(0)+\tau \beta x_{n},
\end{array}
$$

that is,

$$
\begin{array}{ll}
q_{+}\left(\xi^{\prime}, x_{n}\right)=Q_{+}\left(\xi^{\prime}, x_{n}\right) q_{+}\left(\xi^{\prime}, 0\right), & Q_{+}\left(\xi^{\prime}, x_{n}\right)=e^{x_{n}\left(f_{+}(0)+\tau \beta x_{n} / 2\right)} \\
q_{-}\left(\xi^{\prime}, x_{n}\right)=Q_{-}\left(\xi^{\prime}, x_{n}\right) q_{-}\left(\xi^{\prime}, 0\right), & Q_{-}\left(\xi^{\prime}, x_{n}\right)=e^{x_{n}\left(f_{-}(0)+\tau \beta x_{n} / 2\right)} \\
\tilde{q}_{-}\left(\xi^{\prime}, x_{n}\right)=\tilde{Q}_{-}\left(\xi^{\prime}, x_{n}\right) \tilde{q}_{-}\left(\xi^{\prime}, 0\right), & \tilde{Q}_{-}\left(\xi^{\prime}, x_{n}\right)=e^{x_{n}\left(e_{-}(0)+\tau \beta x_{n} / 2\right)}
\end{array}
$$

Since $f_{+}(0)<0$, a solution of the form of $q_{+}$is a good idea on $x_{n} \geq 0$ as long as $\tau \beta x_{n}+2 f_{+}(0) \leq 0$, that is, $x_{n} \leq 2\left|f_{+}(0)\right| / \tau \beta$. Similarly, as $f_{-}(0)>0$ (resp. $e_{-}(0)>0$ ), a solution of the form of $q_{-}$(resp.
$\tilde{q}_{-}$) is a good idea on $x_{n} \leq 0$ as long as $\tau \beta x_{n}+2 f_{-}(0) \geq 0$ (resp. $\left.\tau \beta x_{n}+2 e_{-}(0) \geq 0\right)$. To secure this, we introduce a cut-off function $\chi_{0} \in \mathscr{C}_{c}^{\infty}((-1,1) ;[0,1])$, equal to 1 on $\left[-\frac{1}{2}, \frac{1}{2}\right]$, and for $\gamma \geq 1$ we define

$$
\begin{equation*}
u_{+}\left(\xi^{\prime}, x_{n}\right)=Q_{+}\left(\xi^{\prime}, x_{n}\right) \psi\left(\tau, \xi^{\prime}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right) \tag{5-3}
\end{equation*}
$$

and

$$
\begin{equation*}
u_{-}\left(\xi^{\prime}, x_{n}\right)=a Q_{-}\left(\xi^{\prime}, x_{n}\right) \psi\left(\tau, \xi^{\prime}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{f_{-}(0)}\right)+b \tilde{Q}_{-}\left(\xi^{\prime}, x_{n}\right) \psi\left(\tau, \xi^{\prime}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{e_{-}(0)}\right) \tag{5-4}
\end{equation*}
$$

with $a, b \in \mathbb{R}$ and

$$
u\left(\xi^{\prime}, x_{n}\right)=H_{+}\left(x_{n}\right) u_{+}\left(\xi^{\prime}, x_{n}\right)+H_{-}\left(x_{n}\right) u_{-}\left(\xi^{\prime}, x_{n}\right)
$$

The factor $\gamma$ is introduced to control the size of the support in the $x_{n}$ direction. Observe that we can satisfy the transmission condition (1-21)-(1-22) by choosing the coefficients $a$ and $b$. Transmission condition (1-21) implies

$$
\begin{equation*}
a+b=1 \tag{5-5}
\end{equation*}
$$

Transmission condition (1-22) and the equations satisfied by $Q_{+}, Q_{-}$and $\tilde{Q}_{-}$imply

$$
\begin{equation*}
c_{+} m_{+}=c_{-}(a-b) m_{-} . \tag{5-6}
\end{equation*}
$$

In particular, note that $a-b \geq 0$, which gives $a \geq \frac{1}{2}$.
Lemma 5.2. For $\tau$ sufficiently large, we have

$$
\left\|\mathcal{M}_{\tau} u\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}^{2} \leq C\left(\gamma^{2}+\tau^{2}\right) \gamma \tau^{n-1} e^{-C^{\prime} \tau / \gamma}
$$

and

$$
\|u\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}^{2} \geq C \tau^{n-2}\left(1-e^{-C^{\prime} \tau / \gamma}\right)
$$

See Section AB. 3 for a proof.
We now introduce

$$
v_{ \pm}\left(x^{\prime}, x_{n}\right)=(2 \pi)^{-(n-1)} \chi_{0}\left(\left|\tau^{1 / 2} x^{\prime}\right|\right) \check{\hat{u}}_{ \pm}\left(x^{\prime}, x_{n}\right)=(2 \pi)^{-(n-1)} \chi_{0}\left(\left|\tau^{1 / 2} x^{\prime}\right|\right) \hat{u}_{ \pm}\left(-x^{\prime}, x_{n}\right)
$$

that is, a localized version of the inverse Fourier transform (in $x^{\prime}$ ) of $u_{ \pm}$. The functions $v_{ \pm}$are smooth and compactly supported in $\mathbb{R}_{ \pm}^{n-1} \times \mathbb{R}$ and they satisfy transmission conditions (1-21)-(1-22). We set $v\left(x^{\prime}, x_{n}\right)=H_{+}\left(x_{n}\right) v_{+}\left(x^{\prime}, x_{n}\right)+H_{-}\left(x_{n}\right) v_{-}\left(x^{\prime}, x_{n}\right)$. In fact, we have the following estimates.

Lemma 5.3. Let $N \in \mathbb{N}$. For $\tau$ sufficiently large, we have

$$
\left\|\mathcal{L}_{\tau} v\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}^{2} \leq C\left(\gamma^{2}+\tau^{2}\right) \gamma \tau^{n-1} e^{-C^{\prime} \tau / \gamma}+C_{\gamma, N} \tau^{-N}
$$

and

$$
\|v\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}^{2} \geq C \tau^{n-2}\left(1-e^{-C^{\prime} \tau / \gamma}\right)-C_{\gamma, N} \tau^{-N} .
$$

See Section AB. 4 for a proof.
We may now conclude the proof of Theorem 5.1. In fact, if $V$ is an arbitrary neighborhood of the origin, we choose $\tau$ and $\gamma$ sufficiently large that $\operatorname{supp}(v) \subset V$. We then keep $\gamma$ fixed. The estimates of Lemma 5.3 show that

$$
\left\|\mathcal{L}_{\tau} v\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}\|v\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}^{-1} \underset{\tau \rightarrow \infty}{\longrightarrow} 0
$$

Remark 5.4. As opposed to the analogy we give at the beginning of Section 1F, the construction of this quasimode does not simply rely on one of the first-order factors. The transmission conditions are responsible for this fact. The construction relies on the factor $D_{n}+i f_{+}$in $x_{n} \geq 0$, that is, a onedimensional space of solutions (see (5-3)), and on both factors $D_{n}+i f_{-}$and $D_{n}+i e_{-}$in $x_{n} \geq 0$, that is, a two-dimensional space of solutions (see (5-4)). See also (5-5) and (5-6).

## Appendix

## AA. A few facts on pseudodifferential operators.

AA.1. Standard classes and Weyl quantization. We define for $m \in \mathbb{R}$ the class of tangential symbols $\mathcal{S}^{m}$ as the smooth functions on $\mathbb{R}^{n} \times \mathbb{R}^{n-1}$ such that for all $(\alpha, \beta) \in \mathbb{N}^{n} \times \mathbb{N}^{n-1}$,

$$
\begin{equation*}
N_{\alpha \beta}(a)=\sup _{\left(x, \xi^{\prime}\right) \in \mathbb{R}^{n} \times \mathbb{R}^{n-1}}\left\langle\xi^{\prime}\right\rangle^{-m+|\beta|}\left|\left(\partial_{x}^{\alpha} \partial_{\xi^{\prime}}^{\beta} a\right)\left(x, \xi^{\prime}\right)\right|<\infty, \tag{A-1}
\end{equation*}
$$

with $\left\langle\xi^{\prime}\right\rangle^{2}=1+\left|\xi^{\prime}\right|^{2}$. The quantities on the left-hand side are called the seminorms of the symbol $a$. For $a \in \mathcal{S}^{m}$, let $\mathrm{op}(a)$ be the operator defined on $\mathscr{S}\left(\mathbb{R}^{n}\right)$ by

$$
\begin{equation*}
(\operatorname{op}(a) u)\left(x^{\prime}, x_{n}\right)=a\left(x, D^{\prime}\right) u\left(x^{\prime}, x_{n}\right)=\int_{\mathbb{R}^{n-1}} e^{i x^{\prime} \cdot \xi^{\prime}} a\left(x^{\prime}, x_{n}, \xi^{\prime}\right) \hat{u}\left(\xi^{\prime}, x_{n}\right) d \xi^{\prime}(2 \pi)^{1-n} \tag{A-2}
\end{equation*}
$$

with $\left(x^{\prime}, x_{n}\right) \in \mathbb{R}^{n-1} \times \mathbb{R}$, where $\hat{u}$ is the partial Fourier transform of $u$ with respect to the variable $x^{\prime}$. For all $(k, s) \in \mathbb{Z} \times \mathbb{R}$, we have

$$
\begin{equation*}
\operatorname{op}(a): H^{k}\left(\mathbb{R}_{x_{n}} ; H^{s+m}\left(\mathbb{R}_{x^{\prime}}^{n-1}\right)\right) \rightarrow H^{k}\left(\mathbb{R}_{x_{n}} ; H^{s}\left(\mathbb{R}_{x^{\prime}}^{n-1}\right)\right) \quad \text { continuously, } \tag{A-3}
\end{equation*}
$$

and the norm of this mapping depends only on $\left\{N_{\alpha \beta}(a)\right\}_{|\alpha|+|\beta| \leq \mu(k, s, m, n)}$, where $\mu: \mathbb{Z} \times \mathbb{R} \times \mathbb{R} \times \mathbb{N} \rightarrow \mathbb{N}$.
We shall also use the Weyl quantization of $a$, denoted by $\mathrm{op}^{w}(a)$ and given by the formula

$$
\begin{align*}
\left(\mathrm{op}^{w}(a) u\right)\left(x^{\prime}, x_{n}\right) & =a^{w}\left(x, D^{\prime}\right) u\left(x^{\prime}, x_{n}\right) \\
& =\iint_{\mathbb{R}^{2 n-2}} e^{i\left(x^{\prime}-y^{\prime}\right) \cdot \xi^{\prime}} a\left(\frac{x^{\prime}+y^{\prime}}{2}, x_{n}, \xi^{\prime}\right) u\left(y^{\prime}, x_{n}\right) d y^{\prime} d \xi^{\prime}(2 \pi)^{1-n} \tag{A-4}
\end{align*}
$$

Property (A-3) holds as well for $\mathrm{op}^{w}(a)$. A nice feature of the Weyl quantization that we use in this article is the simple relationship with adjoint operators with the formula

$$
\begin{equation*}
\left(\mathrm{op}^{w}(a)\right)^{*}=\mathrm{op}^{w}(\bar{a}), \tag{A-5}
\end{equation*}
$$

so that for a real-valued symbol $a \in \mathcal{S}^{m}$, we have $\left(\mathrm{op}^{w}(a)\right)^{*}=\mathrm{op}^{w}(a)$. We have also, for $a_{j} \in \mathcal{S}^{m_{j}}$, $j=1,2$,

$$
\begin{equation*}
\mathrm{op}^{w}\left(a_{1}\right) \mathrm{op}^{w}\left(a_{2}\right)=\mathrm{op}^{w}\left(a_{1} \sharp a_{2}\right), \quad a_{1} \sharp a_{2} \in \mathcal{S}^{m_{1}+m_{2}}, \tag{A-6}
\end{equation*}
$$

with, for any $N \in \mathbb{N}$,

$$
\begin{equation*}
\left(a_{1} \sharp a_{2}\right)(x, \xi)-\left.\sum_{j<N}\left(\frac{i \sigma\left(D_{x^{\prime}}, D_{\xi^{\prime}} ; D_{y^{\prime}}, D_{\eta^{\prime}}\right)}{2}\right)^{j} \frac{a_{1}(x, \xi) a_{2}(y, \eta)}{j!}\right|_{(y, \eta)=(x, \xi)} \in \mathcal{S}^{m-N}, \tag{A-7}
\end{equation*}
$$

where $\sigma$ is the symplectic two-form, that is, $\sigma(x, \xi ; y, \eta)=y \cdot \xi-x \cdot \eta$. In particular,

$$
\begin{align*}
\mathrm{op}^{w}\left(a_{1}\right) \mathrm{op}^{w}\left(a_{2}\right) & =\mathrm{op}^{w}\left(a_{1} a_{2}\right)+\mathrm{op}^{w}\left(r_{1}\right), & & r_{1} \in \mathcal{S}^{m_{1}+m_{2}-1},  \tag{A-8}\\
\text { with } r_{1} & =\frac{1}{2 i}\left\{a_{1}, a_{2}\right\}+r_{2}, & & r_{2} \in \mathcal{S}^{m_{1}+m_{2}-2},  \tag{A-9}\\
{\left[\mathrm{op}^{w}\left(a_{1}\right), \mathrm{op}^{w}\left(a_{2}\right)\right] } & =\mathrm{op}^{w}\left(\frac{1}{i}\left\{a_{1}, a_{2}\right\}\right)+\mathrm{op}^{w}\left(r_{3}\right), & & r_{3} \in \mathcal{S}^{m_{1}+m_{2}-3}, \tag{A-10}
\end{align*}
$$

where $\left\{a_{1}, a_{2}\right\}$ is the Poisson bracket. Also, for $b_{j} \in \mathcal{S}^{m_{j}}, j=1,2$, both real-valued, we have

$$
\begin{equation*}
\left[\mathrm{op}^{w}\left(b_{1}\right), i \mathrm{op}^{w}\left(b_{2}\right)\right]=\mathrm{op}^{w}\left(\left\{b_{1}, b_{2}\right\}\right)+\mathrm{op}^{w}\left(s_{3}\right), \quad s_{3} \text { real-valued } \in \mathcal{S}^{m_{1}+m_{2}-3} \tag{A-11}
\end{equation*}
$$

Lemma A.1. Let $a \in \mathcal{S}^{1}$ be such that $a\left(x, \xi^{\prime}\right) \geq \mu\left\langle\xi^{\prime}\right\rangle$, with $\mu \geq 0$. Then there exists $C>0$ such that

$$
\mathrm{op}^{w}(a)+C \geq \mu\left\langle D^{\prime}\right\rangle, \quad\left(\mathrm{op}^{w}(a)\right)^{2}+C \geq \mu^{2}\left\langle D^{\prime}\right\rangle^{2} .
$$

Proof. The first statement follows from the sharp Gårding inequality [Hörmander 1985a, Chapters 18.1,18.5] applied to the nonnegative first-order symbol $a\left(x, \xi^{\prime}\right)-\mu\left\langle\xi^{\prime}\right\rangle$; also, $\left(\mathrm{op}^{w}(a)\right)^{2}=\mathrm{op}^{w}\left(a^{2}\right)+\mathrm{op}^{w}(r)$ with $r \in \mathcal{S}^{0}$, so that the Fefferman-Phong inequality [Hörmander 1985a, Chapter 18.5] applied to the second-order $a^{2}-\mu^{2}\left\langle\xi^{\prime}\right\rangle^{2}$ implies the result.

AA.2. Semiclassical pseudodifferential calculus with a large parameter. We let $\tau \in \mathbb{R}$ be such that $\tau \geq \tau_{0} \geq 1$. We set $\lambda^{2}=1+\tau^{2}+\left|\xi^{\prime}\right|^{2}$. We define, for $m \in \mathbb{R}$, the class of symbols $\mathcal{S}_{\tau}^{m}$ as the smooth functions on $\mathbb{R}^{n} \times \mathbb{R}^{n-1}$ depending on the parameter $\tau$ such that for all $(\alpha, \beta) \in \mathbb{N}^{n} \times \mathbb{N}^{n-1}$,

$$
\begin{equation*}
N_{\alpha \beta}(a)=\sup _{\substack{\left(x, \xi^{\prime}\right)\left(\mathbb{R}^{n} \times \mathbb{R}^{n-1} \\ \tau \geq \tau_{0}\right.}} \lambda^{-m+|\beta|}\left|\left(\partial_{x}^{\alpha} \partial_{\xi^{\prime}}^{\beta} a\right)\left(x, \xi^{\prime}, \tau\right)\right|<\infty \tag{A-12}
\end{equation*}
$$

Note that $\mathcal{S}_{\tau}^{0} \subset \mathcal{S}^{0}$. The associated operators are defined by (A-2). We can introduce Sobolev spaces and Sobolev norms which are adapted to the scaling large parameter $\tau$. Let $s \in \mathbb{R}$; we set

$$
\|u\|_{\mathcal{H}^{s}}:=\left\|\Lambda^{s} u\right\|_{L^{2}\left(\mathbb{R}^{n-1}\right)}, \quad \text { with } \Lambda^{s}:=\operatorname{op}\left(\lambda^{s}\right)
$$

and

$$
\mathcal{H}^{s}=\mathcal{H}^{s}\left(\mathbb{R}^{n-1}\right):=\left\{u \in \mathscr{G}^{\prime}\left(\mathbb{R}^{n-1}\right):\|u\|_{\mathcal{H}^{s}}<\infty\right\} .
$$

The space $\mathcal{H}^{s}$ is algebraically equal to the classical Sobolev space $H^{s}\left(\mathbb{R}^{n-1}\right)$, whose norm is denoted by $\|.\|_{H^{s}}$. For $s \geq 0$, we have

$$
\|u\|_{\mathcal{H}^{s}} \sim \tau^{s}\|u\|_{L^{2}\left(\mathbb{R}^{n-1}\right)}+\left\|\left\langle D^{\prime}\right\rangle^{s} u\right\|_{L^{2}\left(\mathbb{R}^{n-1}\right)}
$$

If $a \in \mathcal{S}_{\tau}^{m}$ then, for all $(k, s) \in \mathbb{Z} \times \mathbb{R}$, we have

$$
\begin{equation*}
\mathrm{op}(a): H^{k}\left(\mathbb{R}_{x_{n}} ; \mathcal{H}^{s+m}\right) \rightarrow H^{k}\left(\mathbb{R}_{x_{n}} ; \mathcal{H}^{s}\left(\mathbb{R}_{x^{\prime}}^{n-1}\right)\right) \quad \text { continuously } \tag{A-13}
\end{equation*}
$$

and the norm of this mapping depends only on $\left\{N_{\alpha \beta}(a)\right\}|\alpha|+|\beta| \leq \mu(k, s, m, n)$, where $\mu: \mathbb{Z} \times \mathbb{R} \times \mathbb{R} \times \mathbb{N} \rightarrow \mathbb{N}$.
For the calculus with a large parameter, we shall also use the Weyl quantization of (A-4). The formulae (A-5)-(A-11) hold as well, with $\mathcal{S}^{m}$ everywhere replaced by $\mathcal{S}_{\tau}^{m}$. We shall often use the Gårding inequality as stated in the following lemma.

Lemma A.2. Let $a \in \mathcal{S}_{\tau}^{m}$ such that $\operatorname{Re} a \geq C \lambda^{m}$. Then

$$
\operatorname{Re}\left(\operatorname{op}^{w}(a) u, u\right) \gtrsim\|u\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{m / 2}\right)}^{2},
$$

for $\tau$ sufficiently large.
Proof. The proof follows from the sharp Gårding inequality [Hörmander 1985a, Chapters 18.1 and 18.5] applied to the nonnegative symbol $a-C \lambda^{m}$.
Definition A.3. The essential support of a symbol $a \in \mathcal{S}_{\tau}^{m}$, denoted by esssupp $(a)$, is the complement of the largest open set of $\mathbb{R} \times \mathbb{R}^{n-1} \times\{\tau \geq 1\}$ where the estimates for $\mathcal{S}_{\tau}^{-\infty}=\cap_{m \in \mathbb{R}} \mathcal{S}_{\tau}^{m}$ hold.

For technical reasons we shall often need the following result.
Lemma A.4. Let $m, m^{\prime} \in \mathbb{R}$ and $a_{1}\left(x, \xi^{\prime}\right) \in \mathcal{S}^{m}$ and $a_{2}\left(x, \xi^{\prime}, \tau\right) \in \mathcal{S}_{\tau}^{m^{\prime}}$ such that the essential support of $a_{2}$ is contained in a region where $\left\langle\xi^{\prime}\right\rangle \gtrsim \tau$. Then

$$
\mathrm{op}^{w}\left(a_{1}\right) \mathrm{op}^{w}\left(a_{2}\right)=\mathrm{op}^{w}\left(b_{1}\right), \quad \mathrm{op}^{w}\left(a_{2}\right) \mathrm{op}^{w}\left(a_{1}\right)=\mathrm{op}^{w}\left(b_{2}\right),
$$

with $b_{1}, b_{2} \in \mathcal{S}_{\tau}^{m+m^{\prime}}$. Moreover, the asympotic series of (A-7) is also valid for these cases (with $\mathcal{S}^{m}$ replaced by $\mathcal{S}_{\tau}^{m}$ ).

Proof. As the essential support is invariant when we change quantization, we may simply use the standard quantization in the proof. With $a_{1}$ and $a_{2}$ satisfying the assumption listed above, we thus consider $\operatorname{op}\left(a_{1}\right) \operatorname{op}\left(a_{2}\right)$. For fixed $\tau$, the standard composition formula applies, and we have (see [Hörmander 1985a, Section 18.1] or [Alinhac and Gérard 2007])

$$
\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}, \tau\right)=(2 \pi)^{1-n} \iint e^{-i y^{\prime} \cdot \eta^{\prime}} a_{1}\left(x, \xi^{\prime}-\eta^{\prime}\right) a_{2}\left(x^{\prime}-y^{\prime}, x_{n}, \xi^{\prime}, \tau\right) d y^{\prime} d \eta^{\prime}
$$

Properties of oscillatory integrals (see, for example, [Alinhac and Gérard 2007, Appendices I.8.1 and I.8.2]) give, for some $k \in \mathbb{N}$,

$$
\left|\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}, \tau\right)\right| \leq C \sup _{\substack{|\alpha|+|\beta| \leq k \\\left(y^{\prime}, \eta^{\prime}\right) \in R^{2} n-2}}\left\langle\left(y^{\prime}, \eta^{\prime}\right)\right\rangle^{-|m|}\left|\partial_{y^{\prime}}^{\alpha} \partial_{\eta^{\prime}}^{\beta} a_{1}\left(x, \xi^{\prime}-\eta^{\prime}\right) a_{2}\left(x^{\prime}-y^{\prime}, x_{n}, \xi^{\prime}, \tau\right)\right| .
$$

In a region $\left\langle\xi^{\prime}\right\rangle \gtrsim \tau$ that contains the essential support of $a_{2}$, we have $\left\langle\xi^{\prime}\right\rangle \sim \lambda$. With the Peetre inequality, we thus obtain

$$
\left|\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}, \tau\right)\right| \lesssim\left\langle\eta^{\prime}\right\rangle^{-|m|}\left\langle\xi^{\prime}-\eta^{\prime}\right\rangle^{m} \lambda^{m^{\prime}} \lesssim\left\langle\xi^{\prime}\right\rangle^{m} \lambda^{m^{\prime}} \lesssim \lambda^{m+m^{\prime}}
$$

In a region $\left\langle\xi^{\prime}\right\rangle \lesssim \tau$ outside of the essential support of $a_{2}$, we find, for any $\ell \in \mathbb{N}$,

$$
\left|\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}, \tau\right)\right| \lesssim\left\langle\eta^{\prime}\right\rangle^{-|m|}\left\langle\xi^{\prime}-\eta^{\prime}\right\rangle^{m} \lambda^{-\ell} \lesssim\left\langle\xi^{\prime}\right\rangle^{m} \lambda^{-\ell} \lesssim \lambda^{m-\ell} .
$$

In the whole phase space we thus obtain $\left|\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}\right)\right| \lesssim \lambda^{m+m^{\prime}}$. The estimation of

$$
\left|\partial_{x}^{\alpha} \partial_{\xi^{\prime}}^{\beta}\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}, \tau\right)\right|
$$

can be done similarly to give

$$
\left|\partial_{x}^{\alpha} \partial_{\xi}^{\beta}\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}, \tau\right)\right| \lesssim \lambda^{m+m^{\prime}-|\beta|}
$$

Hence $a_{1} \circ a_{2} \in \mathcal{S}_{\tau}^{m+m^{\prime}}$. We also obtain the asymptotic series (following the references cited above)

$$
\left(a_{1} \circ a_{2}\right)\left(x, \xi^{\prime}, \tau\right)-\left.\sum_{j<N} \frac{\left(i D_{\xi} \cdot D_{y}\right)^{j} a_{1}(x, \xi) a_{2}(y, \eta, \tau)}{j!}\right|_{(y, \eta)=(x, \xi)} \in \mathcal{S}_{\tau}^{m+m^{\prime}-N}
$$

where each term is respectively in $\mathcal{S}_{\tau}^{m+m^{\prime}-j}$ by the arguments given above. From this series, the corresponding Weyl quantization series follows.

For the second result, considering the adjoint operator $\left(\mathrm{op}\left(a_{2}\right) \mathrm{op}\left(a_{1}\right)\right)^{*}$ yields a composition of operators as in the first case. The second result thus follows from the first one.

Remark A.5. The symbol class and calculus we have introduced in this section can be written as $\mathcal{S}_{\tau}^{m}=\mathcal{S}\left(\lambda^{m}, g\right)$ in the sense of the Weyl-Hörmander calculus [Hörmander 1985a, Sections 18.4-18.6] with the phase-space metric $g=|d x|^{2}+|d \xi|^{2} / \lambda^{2}$.

## AB. Proofs of some intermediate results.

AB.1. Proof of Lemma 2.8. For simplicity we remove the $\pm$ notation here. We first prove that there exist $C>0$ and $\eta>0$ such that

$$
\begin{equation*}
\left|q_{2}\right| \leq \eta \tau^{2} \text { and }\left|q_{1}\right| \leq \eta \tau^{2} \Longrightarrow\left\{q_{2}, q_{1}\right\} \geq C \tau^{3} \tag{A-14}
\end{equation*}
$$

We set

$$
\tilde{q}_{2}=\left(\xi_{n}+s\right)^{2}+\frac{b_{j k}}{a_{n n}} \xi_{j} \xi_{k}-\left(\varphi^{\prime}\right)^{2}, \quad \tilde{q}_{1}=\varphi^{\prime}\left(\xi_{n}+s\right)
$$

We have $q_{j}(x, \xi)=\tau^{2} \tilde{q}_{j}(x, \xi / \tau)$. Observe next that we have $\left\{q_{2}, q_{1}\right\}(x, \xi)=\tau^{3}\left\{\tilde{q}_{2}, \tilde{q}_{1}\right\}(x, \xi / \tau)$. We thus have $\tilde{q}_{2}=0$ and $\tilde{q}_{1}=0 \Longrightarrow\left\{\tilde{q}_{2}, \tilde{q}_{1}\right\}>0$. As $\tilde{q}_{2}(x, \xi)=0$ and $\tilde{q}_{1}(x, \xi)=0$ yield a compact set for $(x, \xi)$ (recall that $x$ lies in a compact set $K$ here), for some $C>0$, we have

$$
\tilde{q}_{2}=0 \text { and } \tilde{q}_{1}=0 \Longrightarrow\left\{\tilde{q}_{2}, \tilde{q}_{1}\right\}>C .
$$

This remains true locally, that is, for some $C^{\prime}>0$ and $\eta>0$,

$$
\left|\tilde{q}_{2}\right| \leq \eta \text { and }\left|\tilde{q}_{1}\right| \leq \eta \Longrightarrow\left\{\tilde{q}_{2}, \tilde{q}_{1}\right\}>C^{\prime}
$$

Then (A-14) follows.
We note that $q_{2}^{ \pm}=0$ and $q_{1}^{ \pm}=0$ imply $\tau \sim\left|\xi^{\prime}\right|$. Hence, for $\tau$ sufficiently large, we have (2-25). We thus obtain

$$
q_{2}^{ \pm}=0 \text { and } q_{1}^{ \pm}=0 \Longleftrightarrow \xi_{n}+s_{ \pm}=0 \text { and } \tau \varphi_{ \pm}^{\prime}=m_{ \pm}
$$

Let us assume that $|f| \leq \delta \lambda$ with $\delta$ small and $\lambda^{2}=1+\tau^{2}+\left|\xi^{\prime}\right|^{2}$. Then

$$
\begin{equation*}
\tau \lesssim\left|\xi^{\prime}\right| \lesssim \tau \tag{A-15}
\end{equation*}
$$

We set $\xi_{n}=-s$, that is, we choose $q_{1}=0$. A direct computation yields

$$
\left\{q_{2}, q_{1}\right\}=\tau e \varphi^{\prime}\left\{\xi_{n}+s, f\right\}+\tau f \varphi^{\prime}\left\{\xi_{n}+s, e\right\} \quad \text { if } \xi_{n}+s=0
$$

With (2-25), we have $\left|q_{2}\right| \leq C \delta \tau^{2}$. For $\delta$ small, by (A-14) we have $\left\{q_{2}, q_{1}\right\} \geq C \tau^{3}$. Since $f \tau \varphi^{\prime}\left\{\xi_{n}+s, e\right\} \leq$ $C \delta \tau^{3}$, we obtain $e \tau \varphi^{\prime}\left\{\xi_{n}+s, f\right\} \geq C \tau^{3}$, with $C>0$, for $\delta$ sufficiently small. With (A-15), we have $\tau \lesssim e \lesssim \tau$ and the result follows.

AB.2. Proof of Lemma 3.1. We set $s=2 \ell+1$ and $\omega_{1}=\mathrm{op}\left(\psi_{\epsilon}\right) \omega$. We write

$$
\begin{aligned}
2 \operatorname{Re}\left(\mathcal{P}_{F+} \omega_{1}, i H_{+}\right. & \left.\tau^{s} \omega_{1}\right)=\left(i\left[D_{n}, H_{+}\right] \omega_{1}, \tau^{s} \omega_{1}\right)+2\left(F_{+} \omega_{1}, H_{+} \tau^{s} \omega_{1}\right) \\
& =\tau^{s}\left|\omega_{1 \mid x_{n}=0^{+}}\right|_{L^{2}\left(\mathbb{R}^{n-1}\right)}^{2}+2\left(\tau^{s+1} \varphi^{\prime} \omega_{1}, H_{+} \omega_{1}\right)-2\left(\tau^{s} M_{+} \omega_{1}, H_{+} \omega_{1}\right) \\
& \geq \tau^{s}\left|\omega_{1 \mid x_{n}=0^{+}}\right|_{L^{2}\left(\mathbb{R}^{n-1}\right)}^{2}+2\left(\tau^{s+1} C_{0} \omega_{1}, H_{+} \omega_{1}\right)-2 C_{1} \tau^{s}\left\|H_{+} \omega_{1}\right\|_{L^{2}\left(\mathbb{R} ; H^{1 / 2}\left(\mathbb{R}^{n-1}\right)\right)}^{2},
\end{aligned}
$$

by (3-4). We have

$$
\begin{aligned}
2\left(\tau^{s+1} C_{0} \omega_{1}, H_{+} \omega_{1}\right)-2 C_{1} \tau^{s} \| & H_{+} \omega_{1} \|_{L^{2}\left(\mathbb{R} ; H^{1 / 2}\left(\mathbb{R}^{n-1}\right)\right)}^{2} \\
& =2 \tau^{s}(2 \pi)^{1-n} \int_{0}^{\infty} \int_{\mathbb{R}^{n-1}}\left(C_{0} \tau-C_{1}\left\langle\xi^{\prime}\right\rangle\right)\left|\psi_{\epsilon}\left(\tau, \xi^{\prime}\right) \hat{\omega}\left(\xi^{\prime}, x_{n}\right)\right|^{2} d \xi^{\prime} d x_{n}
\end{aligned}
$$

As $\tau \geq C\langle\xi\rangle / \epsilon$ in $\operatorname{supp}\left(\psi_{\epsilon}\right)$, for $\epsilon$ sufficiently small we have

$$
\begin{aligned}
2\left(\tau^{s+1} C_{0} \omega_{1}, H_{+} \omega_{1}\right)-2 C_{1} \tau^{s} \| & H_{+} \omega_{1} \|_{L^{2}\left(\mathbb{R} ; H^{1 / 2}\left(\mathbb{R}^{n-1}\right)\right)}^{2} \\
& \gtrsim \int_{0}^{\infty} \int_{\mathbb{R}^{n-1}} \lambda^{s+1}\left|\psi_{\epsilon}\left(\tau, \xi^{\prime}\right) \hat{\omega}\left(\xi^{\prime}, x_{n}\right)\right|^{2} d \xi^{\prime} d x_{n} \gtrsim\left\|H_{+} \omega_{1}\right\|_{L^{2}\left(\mathbb{R} ; \mathcal{H}^{\ell+1}\right)}^{2}
\end{aligned}
$$

Similarly, we find $\tau^{s}\left|\omega_{1 \mid x_{n}=0^{+}}\right|_{L^{2}\left(\mathbb{R}^{n-1}\right)}^{2} \gtrsim\left|\omega_{1 \mid x_{n}=0^{+}}\right|_{\mathcal{H}^{\ell+1 / 2}}^{2}$. The result for $\mathcal{P}_{E+}$ follows from the Young inequality. The proof is identical for $\mathcal{P}_{F+}$.

On the other side of the interface we write

$$
\begin{aligned}
2 \operatorname{Re}\left(H_{-} \mathcal{P}_{F-} \omega_{1}, i H_{-} \tau^{s} \omega_{1}\right) & =\left(i\left[D_{n}, H_{-}\right] \omega_{1}, \tau^{s} \omega_{1}\right)+2\left(F_{-} \omega_{1}, H_{-} \tau^{s} \omega_{1}\right) \\
& =-\tau^{s}\left|\omega_{1 \mid x_{n}=0^{-}}\right|_{L^{2}\left(\mathbb{R}^{n-1}\right)}^{2}+2\left(\tau^{s+1} \varphi^{\prime} \omega_{1}, H_{-} \omega_{1}\right)-2\left(\tau^{s} M_{-} \omega_{1}, H_{-} \omega_{1}\right),
\end{aligned}
$$

which yields a boundary contribution with the opposite sign.

AB.3. Proof of Lemma 5.2. Let $\left(\tau, \xi^{\prime}\right) \in \operatorname{supp}(\psi)$. We choose $\tau \operatorname{sufficiently}$ large that, through $\operatorname{supp}(\psi)$, $\left|\xi^{\prime}\right|$ is itself sufficiently large that the symbol $m_{ \pm}$is homogeneous - see (2-15).

We set

$$
\begin{aligned}
& y_{+}\left(\xi^{\prime}, x_{n}\right)=Q_{+}\left(\xi^{\prime}, x_{n}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right) \\
& y_{-}\left(\xi^{\prime}, x_{n}\right)=a Q_{-}\left(\xi^{\prime}, x_{n}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{f_{-}(0)}\right)+b \tilde{Q}_{-}\left(\xi^{\prime}, x_{n}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{e_{-}(0)}\right) .
\end{aligned}
$$

On the one hand, we have $i\left(D_{n}+i f_{+}\right) y_{+}=\frac{\tau \beta \gamma}{\left|f_{+}(0)\right|} Q_{+}\left(\xi^{\prime}, x_{n}\right) \chi_{0}^{\prime}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right)$ and

$$
\left(\mathcal{M}_{\tau} y_{+}\right)\left(\xi^{\prime}, x_{n}\right)=2 \tau \beta \gamma c_{+} m_{+} \frac{Q_{+}\left(\xi^{\prime}, x_{n}\right)}{\left|f_{+}(0)\right|} \chi_{0}^{\prime}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right)-(\tau \beta \gamma)^{2} c_{+} \frac{Q_{+}\left(\xi^{\prime}, x_{n}\right)}{\left|f_{+}(0)\right|^{2}} \chi_{0}^{\prime \prime}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right)
$$

as $D_{n}+i e_{+}=D_{n}+i\left(f_{+}+2 m_{+}\right)$, so that

$$
\begin{aligned}
\int_{0}^{+\infty}\left|\left(\mathcal{M}_{\tau} y_{+}\right)\left(\xi^{\prime}, x_{n}\right)\right|^{2} d x_{n} \leq 8 c_{+}^{2} m_{+}^{2} & \left(\frac{\tau \beta \gamma}{f_{+}(0)}\right)^{2} \int_{0}^{+\infty} \chi_{0}^{\prime}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right)^{2} e^{x_{n}\left(2 f_{+}(0)+\tau \beta x_{n}\right)} d x_{n} \\
& +2 c_{+}^{2}\left(\frac{\tau \beta \gamma}{f_{+}(0)}\right)^{4} \int_{0}^{+\infty} \chi_{0}^{\prime \prime}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right)^{2} e^{x_{n}\left(2 f_{+}(0)+\tau \beta x_{n}\right)} d x_{n}
\end{aligned}
$$

On the support of $\chi_{0}^{(j)}\left(\tau \beta \gamma x_{n} /\left|f_{+}(0)\right|\right), j=1,2$, we have $\left|f_{+}(0)\right| /(2 \tau \beta \gamma) \leq x_{n} \leq\left|f_{+}(0)\right| /(\tau \beta \gamma)$, and in particular $2 f_{+}(0)+\tau \beta \gamma x_{n} \leq-\left|f_{+}(0)\right|$, which gives

$$
\begin{aligned}
& \int_{0}^{+\infty}\left|\left(\mathcal{M}_{\tau} y_{+}\right)\left(\xi^{\prime}, x_{n}\right)\right|^{2} d x_{n} \\
& \quad \leq c_{+}^{2}\left(\frac{\tau \beta \gamma}{f_{+}(0)}\right)^{2}\left(8 m_{+}^{2}\left\|\chi_{0}^{\prime}\right\|_{L^{\infty}}^{2}+2\left(\frac{\tau \beta \gamma}{f_{+}(0)}\right)^{2}\left\|\chi_{0}^{\prime \prime}\right\|_{L^{\infty}}^{2}\right) \int_{\frac{\left|f_{+}(0)\right|}{2 \tau \beta \gamma} \leq x_{n} \leq \frac{\left|f_{+}(0)\right|}{\tau \beta \gamma}} e^{-\left|f_{+}(0)\right| x_{n}} d x_{n} \\
& \quad \leq c_{+}^{2} \frac{\tau \beta \gamma}{\left|f_{+}(0)\right|}\left(4 m_{+}^{2}\left\|\chi_{0}^{\prime}\right\|_{L^{\infty}}^{2}+\left(\frac{\tau \beta \gamma}{f_{+}(0)}\right)^{2}\left\|\chi_{0}^{\prime \prime}\right\|_{L^{\infty}}^{2}\right) e^{-\frac{f_{+}(0)^{2}}{2 \tau \beta \gamma}}
\end{aligned}
$$

Similarly, we have

$$
\begin{aligned}
\left(\mathcal{M}_{\tau} y_{-}\right)\left(\xi^{\prime}, x_{n}\right)=2 \tau \beta \gamma c_{-} m_{-} & \left(\frac{a Q_{-}\left(\xi^{\prime}, x_{n}\right)}{f_{-}(0)} \chi_{0}^{\prime}\left(\frac{\tau \beta \gamma x_{n}}{f_{-}(0)}\right)-b \frac{\tilde{Q}_{-}\left(\xi^{\prime}, x_{n}\right)}{e_{-}(0)} \chi_{0}^{\prime}\left(\frac{\tau \beta \gamma x_{n}}{e_{-}(0)}\right)\right) \\
& -c_{-}(\tau \beta \gamma)^{2}\left(a \frac{Q_{-}\left(\xi^{\prime}, x_{n}\right)}{f_{-}(0)^{2}} \chi_{0}^{\prime \prime}\left(\frac{\tau \beta \gamma x_{n}}{f_{-}(0)}\right)+b \frac{\tilde{Q}_{-}\left(\xi^{\prime}, x_{n}\right)}{e_{-}(0)^{2}} \chi_{0}^{\prime \prime}\left(\frac{\tau \beta \gamma x_{n}}{e_{-}(0)}\right)\right),
\end{aligned}
$$

and because of the support of $\chi_{0}^{(j)}\left(\frac{\tau \beta \gamma x_{n}}{f_{-}(0)}\right)$, resp. $\chi_{0}^{(j)}\left(\frac{\tau \beta \gamma x_{n}}{e_{-}(0)}\right), j=1,2$, for $x_{n} \leq 0$, we obtain

$$
\begin{aligned}
\int_{-\infty}^{0}\left|\left(\mathcal{M}_{\tau} y_{-}\right)\left(\xi^{\prime}, x_{n}\right)\right|^{2} d x_{n} \leq 2 c_{-}^{2} \frac{\tau \beta \gamma a^{2}}{f_{-}(0)} & \left(4 m_{-}^{2}\left\|\chi_{0}^{\prime}\right\|_{L^{\infty}}^{2}+\left\|\chi_{0}^{\prime \prime}\right\|_{L^{\infty}}^{2}\left(\frac{\tau \beta \gamma}{f_{-}(0)}\right)^{2}\right) e^{-\frac{f_{-}(0)^{2}}{2 \tau \beta \gamma}} \\
& +2 c_{-}^{2} \frac{\tau \beta \gamma b^{2}}{e_{-}(0)}\left(4 m_{-}^{2}\left\|\chi_{0}^{\prime}\right\|_{L^{\infty}}^{2}+\left\|\chi_{0}^{\prime \prime}\right\|_{L^{\infty}}^{2}\left(\frac{\tau \beta \gamma}{e_{-}(0)}\right)^{2}\right) e^{-\frac{e_{-}(0)^{2}}{2 \tau \beta \gamma}}
\end{aligned}
$$

Now we have $\left(\mathcal{M}_{\tau} u\right)\left(\xi^{\prime}, x_{n}\right)=\psi\left(\tau, \xi^{\prime}\right)\left(\mathcal{M}_{\tau} y\right)\left(\xi^{\prime}, x_{n}\right)$. As $\left|\xi^{\prime}\right| \sim \tau$ in $\operatorname{supp}(\psi)$, we obtain

$$
\left\|\mathcal{M}_{\tau} u\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}^{2} \leq C\left(\gamma^{2}+\tau^{2}\right) \gamma e^{-C^{\prime} \tau / \gamma} \int_{\mathbb{R}^{n-1}} \psi\left(\tau, \xi^{\prime}\right)^{2} d \xi^{\prime} .
$$

With the change of variable $\xi^{\prime}=\tau \eta$, we find

$$
\begin{equation*}
\int_{\mathbb{R}^{n-1}} \psi\left(\tau, \xi^{\prime}\right)^{2} d \xi^{\prime}=C \tau^{n-1} \tag{A-16}
\end{equation*}
$$

which gives the first result.
On the other hand, observe now that

$$
\begin{aligned}
\left\|y_{+}\right\|_{L^{2}\left(\mathbb{R}_{+}\right)}^{2} & =\int_{0}^{+\infty} Q_{+}\left(\xi^{\prime}, x_{n}\right)^{2} \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|}\right)^{2} d x_{n} \\
& \left.\geq \int_{0 \leq \frac{\tau \beta \gamma x_{n}}{\left|f_{+}(0)\right|} \leq 1 / 2} e^{x_{n}\left(2 f_{+}(0)+\tau \beta x_{n}\right)} d x_{n}=\frac{\left|f_{+}(0)\right|}{\tau \beta \gamma} \int_{0}^{1 / 2} e^{2 t \frac{\left|f_{+}(0)\right|}{\tau \beta \gamma}\left(f_{+}(0)+t \frac{\left|f_{+}(0)\right|}{2 \gamma}\right.}\right) d t \\
& \geq \frac{\left|f_{+}(0)\right|}{\tau \beta \gamma} \int_{0}^{1 / 2} e^{-2 t \frac{\left|f_{+}(0)\right|^{2}}{\tau \beta \gamma}} d t=\frac{1}{2\left|f_{+}(0)\right|}\left(1-e^{-\frac{\left|f_{+}(0)\right|^{2}}{\tau \beta \gamma}}\right) .
\end{aligned}
$$

We also have

$$
\begin{aligned}
\left\|y_{-}\right\|_{L^{2}\left(\mathbb{R}_{-}\right)}^{2} & =\int_{-\infty}^{0}\left(a Q_{-}\left(\xi^{\prime}, x_{n}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{f_{-}(0)}\right)+b \tilde{Q}_{-}\left(\xi^{\prime}, x_{n}\right) \chi_{0}\left(\frac{\tau \beta \gamma x_{n}}{e_{-}(0)}\right)\right)^{2} d x_{n} \\
& \geq \int_{-1 / 2 \leq \frac{\tau \beta \gamma x_{n}}{f-(0)} \leq 0} e^{x_{n}\left(2 f_{-}(0)+\tau \beta x_{n}\right)}\left(a+b e^{x_{n}\left(e_{-}(0)-f_{-}(0)\right)}\right)^{2} d x_{n}
\end{aligned}
$$

and as $e_{-}(0)-f_{-}(0)=2 m_{-} \geq 0$ and $a+b=1$ and $a \geq \frac{1}{2}$, we have $a+b e^{x_{n}\left(e_{-}(0)-f_{-}(0)\right)} \geq \frac{1}{2}$, and thus obtain

$$
\|y-\|_{L^{2}\left(\mathbb{R}_{-}\right)}^{2} \geq \frac{1}{4} \int_{-1 / 2 \leq \frac{\tau \beta \gamma x_{n}}{f_{-}(0)} \leq 0} e^{x_{n}\left(2 f_{-}(0)+\tau \beta x_{n}\right)} d x_{n} \geq \frac{1}{8 f_{-}(0)}\left(1-e^{-\frac{\left|f_{-}(0)\right|^{2}}{\tau \beta \gamma}}\right)
$$

arguing as above. As a result, using (A-16), we have

$$
\|u\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}\right)}^{2} \geq C \tau^{n-2}\left(1-e^{-C^{\prime} \tau / \gamma}\right)
$$

AB.4. Proof of Lemma 5.3. We start with the second result. We set

$$
z_{+}=\left(1-\chi_{0}\left(\left|\tau^{1 / 2} x^{\prime}\right|\right)\right) \check{\hat{u}}_{+}\left(x^{\prime}, x_{n}\right), \quad \text { for } x_{n} \geq 0
$$

We shall prove that for all $N \in \mathbb{N}$, we have $\left\|z_{+}\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}_{+}\right)} \leq C_{\gamma, N} \tau^{-N}$.
From the definition of $\chi_{0}$, we find

$$
\left\|z_{+}\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}_{+}\right)}^{2} \leq \int_{\left|\tau^{1 / 2} x^{\prime}\right| \geq 1 / 2} \int_{\mathbb{R}_{+}}\left|\hat{u}_{+}\left(x^{\prime}, x_{n}\right)\right|^{2} d x^{\prime} d x_{n} .
$$

Recalling the definition of $u_{+}$and performing the change of variable $\xi^{\prime}=\tau \eta$, we obtain

$$
\hat{u}_{+}\left(x^{\prime}, x_{n}\right)=\tau^{n-1} \int_{\mathbb{R}^{n-1}} e^{i \tau \phi} \tilde{\psi}(\eta) \chi_{0}\left(\frac{\beta \gamma x_{n}}{\left|\tilde{f}_{+}(\eta)\right|}\right) d \eta
$$

where the complex phase function is given by

$$
\phi=-x^{\prime} \cdot \eta-i x_{n}\left(\tilde{f}_{+}(\eta)+\frac{\beta x_{n}}{2}\right), \quad \text { with } \tilde{f}_{+}(\eta)=\alpha_{+}-m_{+}(\eta)
$$

and

$$
\tilde{\psi}(\eta)=\chi_{1}\left(\frac{1}{\left(1+|\eta|^{2}\right)^{1 / 2}}-\tau_{0}\right) \chi_{1}\left(\left|\frac{\eta}{\left(1+|\eta|^{2}\right)^{1 / 2}}-\xi_{0}^{\prime}\right|\right)
$$

Here $\tau$ is chosen sufficiently large that $m_{+}$is homogeneous. Observe that $\tilde{\psi}$ has a compact support independent of $\tau$ and that $\tilde{f}_{+}(\eta)+\beta x_{n} / 2 \leq-C<0$ in the support of the integrand.

We place ourselves in the neighborhood of a point $x^{\prime}$ such that $\left|\tau^{1 / 2} x^{\prime}\right| \geq \frac{1}{2}$. Up to a permutation of the variables, we may assume that $\left|\tau^{1 / 2} x_{1}\right| \geq C$. We then introduce the differential operator

$$
L=\tau^{-1} \frac{\partial_{\eta_{1}}}{-i x_{1}-x_{n} \partial_{\eta_{1}} m_{+}(\eta)}
$$

which satisfies $L e^{i \tau \phi}=e^{i \tau \phi}$. We thus have

$$
\hat{u}_{+}\left(x^{\prime}, x_{n}\right)=\tau^{n-1} \int_{\mathbb{R}^{n-1}} e^{i \tau \phi}\left(L^{t}\right)^{N}\left(\tilde{\psi}(\eta) \chi_{0}\left(\frac{\beta \gamma x_{n}}{\left|\tilde{f}_{+}(\eta)\right|}\right)\right) d \eta
$$

and we find

$$
\left|\hat{u}_{+}\left(x^{\prime}, x_{n}\right)\right| \leq C_{N} \frac{\tau^{n-1} \gamma^{N}}{\left|\tau x_{1}\right|^{N}} e^{-C \tau x_{n}}
$$

More generally, for $\left|\tau^{1 / 2} x^{\prime}\right| \geq \frac{1}{2}$ we have

$$
\left|\hat{u}_{+}\left(x^{\prime}, x_{n}\right)\right| \leq C_{N} \frac{\tau^{n-1} \gamma^{N}}{\left|\tau x^{\prime}\right|^{N}} e^{-C \tau x_{n}}
$$

Then we obtain

$$
\begin{aligned}
\int_{\left|\tau^{1 / 2} x^{\prime}\right| \geq 1 / 2} \int_{\mathbb{R}_{+}}\left|\hat{u}_{+}\left(x^{\prime}, x_{n}\right)\right|^{2} d x^{\prime} & d x_{n} \\
& \leq C_{N}^{2} \gamma^{2 N} \tau^{2 n-2}\left(\int_{\left|\tau^{1 / 2} x^{\prime}\right| \geq 1 / 2} \frac{1}{\left|\tau x^{\prime}\right|^{2 N}} d x^{\prime}\right)\left(\int_{\mathbb{R}_{+}} e^{-2 C \tau x_{n}} d x_{n}\right) \\
& \leq C_{N}^{\prime} \gamma^{2 N} \tau^{(3 / 2) n-N-5 / 2} \int_{\left|x^{\prime}\right| \geq 1 / 2} \frac{1}{\left|x^{\prime}\right|^{2 N}} d x^{\prime} .
\end{aligned}
$$

Similarly, setting $z_{-}=\left(1-\chi_{0}\left(\left|\tau^{1 / 2} x^{\prime}\right|\right)\right) \check{\hat{u}}_{-}\left(x^{\prime}, x_{n}\right)$ for $x_{n} \leq 0$, we get $\left\|z_{-}\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}_{-}\right)} \leq C_{\gamma, N} \tau^{-N}$. The second result thus follows from Lemma 5.2.

For the first result we write

$$
\mathcal{L}_{\tau} v_{ \pm}=(2 \pi)^{-(n-1)} \chi_{0}\left(\left|\tau^{1 / 2} x^{\prime}\right|\right) \mathcal{L}_{\tau} \check{\hat{u}}_{ \pm}+(2 \pi)^{-(n-1)}\left[\mathcal{L}_{\tau}, \chi_{0}\left(\left|\tau^{1 / 2} x^{\prime}\right|\right)\right] \check{\hat{u}}_{ \pm} .
$$

The first term is estimated, using Lemma 5.2, as

$$
(2 \pi)^{-(n-1) / 2}\left\|\mathcal{L}_{\tau} \check{\hat{u}}_{ \pm}\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}_{ \pm}\right)}=\left\|\mathcal{M}_{\tau} u_{ \pm}\right\|_{L^{2}\left(\mathbb{R}^{n-1} \times \mathbb{R}_{ \pm}\right)} .
$$

Observe that $\mathcal{L}_{\tau}$ is a differential operator; the commutator is thus a first-order differential operator in $x^{\prime}$ with support in a region $\left|\tau^{1 / 2} x^{\prime}\right| \geq C$, because of the behavior of $\chi_{1}$ near 0 . The coefficients of this operator depend on $\tau$ polynomially. The zero-order terms can be estimated as we did for $z_{+}$above with an additional $\tau^{3 / 2}$ factor.

For the first-order term, observe that we have

$$
\partial_{x_{j}^{\prime}} \check{\hat{u}}_{+}\left(x^{\prime}, \tau\right)=\tau^{n} \int_{\mathbb{R}^{n-1}} \eta_{j} e^{i \tau\left(x^{\prime} \cdot \eta-i x_{n}\left(\tilde{f}_{+}(\eta)+\frac{\beta x_{n}}{2}\right)\right)} \tilde{\psi}(\eta) \chi_{0}\left(\frac{\beta \gamma x_{n}}{\left|\tilde{f}_{+}(\eta)\right|}\right) d \eta .
$$

We thus obtain similar estimates as above with an additional $\tau^{3 / 2}$ factor. This concludes the proof.

## References

[Alinhac 1980] S. Alinhac, "Non-unicité pour des opérateurs différentiels à caractéristiques complexes simples", Ann. Sci. École Norm. Sup. (4) 13:3 (1980), 385-393. MR 83b:35004b Zbl 0456.35002
[Alinhac and Gérard 2007] S. Alinhac and P. Gérard, Pseudo-differential operators and the Nash-Moser theorem, Graduate Studies in Mathematics 82, Amer. Math. Soc., Providence, RI, 2007. MR 2007m:35001 Zbl 1121.47033
[Bahouri 1987] H. Bahouri, "Dépendance non linéaire des données de Cauchy pour les solutions des équations aux dérivées partielles", J. Math. Pures Appl. (9) 66:2 (1987), 127-138. MR 88e:35019 Zbl 0565.35009
[Barbu 2000] V. Barbu, "Exact controllability of the superlinear heat equation", Appl. Math. Optim. 42:1 (2000), 73-89. MR 2001i:93010 Zbl 0964.93046
[Bardos et al. 1992] C. Bardos, G. Lebeau, and J. Rauch, "Sharp sufficient conditions for the observation, control, and stabilization of waves from the boundary", SIAM J. Control Optim. 30:5 (1992), 1024-1065. MR 94b:93067 Zbl 0786.93009
[Benabdallah et al. 2007] A. Benabdallah, Y. Dermenjian, and J. Le Rousseau, "Carleman estimates for the one-dimensional heat equation with a discontinuous coefficient and applications to controllability and an inverse problem", J. Math. Anal. Appl. 336:2 (2007), 865-887. MR 2008k:35205 Zbl 1189.35349
[Benabdallah et al. 2011] A. Benabdallah, Y. Dermenjian, and J. Le Rousseau, "Carleman estimates for stratified media", J. Funct. Anal. 260:12 (2011), 3645-3677. MR 2012c:35050 Zbl 1218.35238
[Bukhgeim and Klibanov 1981] A. L. Bukhgeim and M. V. Klibanov, "Global uniqueness of class of multidimensional inverse problems", Sov. Math. Dokl. 24 (1981), 244-247. Zbl 0497.35082
[Buonocore and Manselli 2000] P. Buonocore and P. Manselli, "Nonunique continuation for plane uniformly elliptic equations in Sobolev spaces", Ann. Scuola Norm. Sup. Pisa Cl. Sci. (4) 29:4 (2000), 731-754. MR 2002d:35038 Zbl 1072.35049
[Burq 1998] N. Burq, "Décroissance de l'énergie locale de l'équation des ondes pour le problème extérieur et absence de résonance au voisinage du réel", Acta Math. 180:1 (1998), 1-29. MR 99j:35119 Zbl 0918.35081
[Calderón 1958] A.-P. Calderón, "Uniqueness in the Cauchy problem for partial differential equations", Amer. J. Math. 80 (1958), 16-36. MR 21 \#3675 Zbl 0080.30302
[Carleman 1939] T. Carleman, "Sur un problème d'unicité pur les systèmes d'équations aux dérivées partielles à deux variables indépendantes", Ark. Mat., Astr. Fys. 26:17 (1939), 9. MR 1,55f Zbl 0022.34201
[Doubova et al. 2002] A. Doubova, A. Osses, and J.-P. Puel, "Exact controllability to trajectories for semilinear heat equations with discontinuous diffusion coefficients", ESAIM Control Optim. Calc. Var. 8 (2002), 621-661. MR 2004c:93011 Zbl 1092.93006
[Fernández-Cara and Zuazua 2000] E. Fernández-Cara and E. Zuazua, "Null and approximate controllability for weakly blowing up semilinear heat equations", Ann. Inst. H. Poincaré Anal. Non Linéaire 17:5 (2000), 583-616. MR 2001j:93009 Zbl 0970.93023
[Filonov 2001] N. Filonov, "Second-order elliptic equation of divergence form having a compactly supported solution", J. Math. Sci. (New York) 106:3 (2001), 3078-3086. MR 2003h:35047 Zbl 0991.35020
[Fursikov and Imanuvilov 1996] A. V. Fursikov and O. Y. Imanuvilov, Controllability of evolution equations, Lecture Notes Series 34, Seoul National University, Seoul, 1996. MR 97g:93002 Zbl 0862.49004
[Hörmander 1958] L. Hörmander, "On the uniqueness of the Cauchy problem", Math. Scand. 6 (1958), 213-225. MR 21 \#3674 Zbl 0088.30201
[Hörmander 1963] L. Hörmander, Linear partial differential operators, Die Grundlehren der mathematischen Wissenschaften 116, Academic, New York, 1963. MR 28 \#4221 Zbl 0108.09301
[Hörmander 1985a] L. Hörmander, The analysis of linear partial differential operators, III: Pseudodifferential operators, Grundlehren der Mathematischen Wissenschaften [Fundamental Principles of Mathematical Sciences] 274, Springer, Berlin, 1985. MR 87d:35002a Zbl 0601.35001
[Hörmander 1985b] L. Hörmander, The analysis of linear partial differential operators, IV: Fourier integral operators, Grundlehren der Mathematischen Wissenschaften 275, Springer, Berlin, 1985. MR 87d:35002b Zbl 0612.35001
[Imanuvilov and Puel 2003] O. Y. Imanuvilov and J.-P. Puel, "Global Carleman estimates for weak solutions of elliptic nonhomogeneous Dirichlet problems", Int. Math. Res. Not. 2003:16 (2003), 883-913. MR 2004c:35081 Zbl 1146.35340
[Imanuvilov et al. 2003] O. Imanuvilov, V. Isakov, and M. Yamamoto, "An inverse problem for the dynamical Lamé system with two sets of boundary data", Comm. Pure Appl. Math. 56:9 (2003), 1366-1382. MR 2004i:35308 Zbl 1044.35105
[Isakov 1998] V. Isakov, Inverse problems for partial differential equations, Applied Mathematical Sciences 127, Springer, New York, 1998. MR 99b:35211 Zbl 0908.35134
[Jerison and Kenig 1985] D. Jerison and C. E. Kenig, "Unique continuation and absence of positive eigenvalues for Schrödinger operators", Ann. of Math. (2) 121:3 (1985), 463-494. MR 87a:35058 Zbl 0593.35119
[Jerison and Lebeau 1999] D. Jerison and G. Lebeau, "Nodal sets of sums of eigenfunctions", pp. 223-239 in Harmonic analysis and partial differential equations (Chicago, 1996), edited by M. Christ et al., University of Chicago Press, Chicago, 1999. MR 2001b:58035 Zbl 0946.35055
[John 1960] F. John, "Continuous dependence on data for solutions of partial differential equations with a presribed bound", Comm. Pure Appl. Math. 13 (1960), 551-585. MR 24 \#A317 Zbl 0097.08101
[Kenig et al. 2007] C. E. Kenig, J. Sjöstrand, and G. Uhlmann, "The Calderón problem with partial data", Ann. of Math. (2) 165:2 (2007), 567-591. MR 2008k:35498 Zbl 1127.35079
[Koch and Tataru 2001] H. Koch and D. Tataru, "Carleman estimates and unique continuation for second-order elliptic equations with nonsmooth coefficients", Comm. Pure Appl. Math. 54:3 (2001), 339-360. MR 2001m:35075 Zbl 1033.32025
[Koch and Tataru 2002] H. Koch and D. Tataru, "Sharp counterexamples in unique continuation for second order elliptic equations", J. Reine Angew. Math. 542 (2002), 133-146. MR 2002m:35020 Zbl 1222.35050
[Le Rousseau 2007] J. Le Rousseau, "Carleman estimates and controllability results for the one-dimensional heat equation with BV coefficients", J. Differential Equations 233:2 (2007), 417-447. MR 2009c:35190 Zbl 1128.35020
[Le Rousseau and Lebeau 2012] J. Le Rousseau and G. Lebeau, "On Carleman estimates for elliptic and parabolic operators: Applications to unique continuation and control of parabolic equations", ESAIM Control Optim. Calc. Var. 18:3 (2012), 712-747. MR 3041662 Zbl 06111871
[Le Rousseau and Robbiano 2010] J. Le Rousseau and L. Robbiano, "Carleman estimate for elliptic operators with coefficients with jumps at an interface in arbitrary dimension and application to the null controllability of linear parabolic equations", Arch. Ration. Mech. Anal. 195:3 (2010), 953-990. MR 2011a:93018 Zbl 1202.35336
[Le Rousseau and Robbiano 2011] J. Le Rousseau and L. Robbiano, "Local and global Carleman estimates for parabolic operators with coefficients with jumps at interfaces", Invent. Math. 183:2 (2011), 245-336. MR 2012k:35208 Zbl 1218.35054
[Lebeau 1996] G. Lebeau, "Équation des ondes amorties", pp. 73-109 in Algebraic and geometric methods in mathematical physics (Kaciveli, 1993), edited by A. Boutet de Monvel and V. Marchenko, Math. Phys. Stud. 19, Kluwer, Dordrecht, 1996. MR 97i:58173 Zbl 0863.58068
[Lebeau and Robbiano 1995] G. Lebeau and L. Robbiano, "Contrôle exact de l'équation de la chaleur", Comm. Partial Differential Equations 20:1-2 (1995), 335-356. MR 95m:93045 Zbl 0819.35071
[Lebeau and Robbiano 1997] G. Lebeau and L. Robbiano, "Stabilisation de l'équation des ondes par le bord", Duke Math. J. 86:3 (1997), 465-491. MR 98c:35104 Zbl 0884.58093
[Lebeau and Zuazua 1998] G. Lebeau and E. Zuazua, "Null-controllability of a system of linear thermoelasticity", Arch. Rational Mech. Anal. 141:4 (1998), 297-329. MR 99f:93013 Zbl 1064.93501
[Lerner 2010] N. Lerner, Metrics on the phase space and non-selfadjoint pseudo-differential operators, Pseudo-Differential Operators: Theory and Applications 3, Birkhäuser, Basel, 2010. MR 2011b:35002 Zbl 1186.47001
[Mandache 1998] N. Mandache, "On a counterexample concerning unique continuation for elliptic equations in divergence form", Math. Phys. Anal. Geom. 1:3 (1998), 273-292. MR 2000c:35033 Zbl 0920.35034
[Miller 1974] K. Miller, "Nonunique continuation for uniformly parabolic and elliptic equations in self-adjoint divergence form with Hölder continuous coefficients", Arch. Rational Mech. Anal. 54 (1974), 105-117. MR 49 \#7566 Zbl 0289.35046
[Pliś 1963] A. Pliś, "On non-uniqueness in Cauchy problem for an elliptic second order differential equation", Bull. Acad. Polon. Sci. Sér. Sci. Math. Astronom. Phys. 11 (1963), 95-100. MR 27 \#3920 Zbl 0107.07901
[Rauch and Taylor 1974] J. Rauch and M. Taylor, "Exponential decay of solutions to hyperbolic equations in bounded domains", Indiana Univ. Math. J. 24 (1974), 79-86. MR 50 \#13906 Zbl 0281.35012
[Schulz 1998] F. Schulz, "On the unique continuation property of elliptic divergence form equations in the plane", Math. $Z$. 228:2 (1998), 201-206. MR 99e:35035 Zbl 0905.35020
[Sogge 1989] C. D. Sogge, "Oscillatory integrals and unique continuation for second order elliptic differential equations", J. Amer. Math. Soc. 2:3 (1989), 491-515. MR 91d:35037 Zbl 0703.35027

Received 31 Jan 2012. Revised 8 Mar 2013. Accepted 13 Apr 2013.
JÉRÔME LE Rousseau: jlr@univ-orleans.fr
Laboratoire de Mathématiques - Analyse, Probabilités, Modélisation - Orléans, Université d'Orléans, Bâtiment de mathématiques - Route de Chartres, B.P. 6759, 45067 Orléans Cedex 2, France
and
Fédération Denis-Poisson, CNRS FR 2964
and
Institut Universitaire de France
NICOLAS LERNER: lerner@math.jussieu.fr
Institut de Mathématiques de Jussieu, Université Pierre et Marie Curie (Paris VI), Boîte 186, 4 Pl. Jussieu, 75252 Paris Cedex 5, France

## Analysis \& PDE

msp.org/apde

## EDITORS

Editor-IN-Chief
Maciej Zworski
zworski@math.berkeley.edu
University of California
Berkeley, USA
BOARD OF EDITORS

| Nicolas Burq | Université Paris-Sud 11, France nicolas.burq@math.u-psud.fr | Yuval Peres | University of California, Berkeley, USA peres@stat.berkeley.edu |
| :---: | :---: | :---: | :---: |
| Sun-Yung Alice Chang | Princeton University, USA chang@math.princeton.edu | Gilles Pisier | Texas A\&M University, and Paris 6 pisier@math.tamu.edu |
| Michael Christ | University of California, Berkeley, USA mchrist@math.berkeley.edu | Tristan Rivière | ETH, Switzerland riviere@math.ethz.ch |
| Charles Fefferman | Princeton University, USA cf@math.princeton.edu | Igor Rodnianski | Princeton University, USA irod@math.princeton.edu |
| Ursula Hamenstaedt | Universität Bonn, Germany ursula@math.uni-bonn.de | Wilhelm Schlag | University of Chicago, USA schlag@math.uchicago.edu |
| Vaughan Jones | U.C. Berkeley \& Vanderbilt University vaughan.f.jones@vanderbilt.edu | Sylvia Serfaty | New York University, USA serfaty@cims.nyu.edu |
| Herbert Koch | Universität Bonn, Germany koch@math.uni-bonn.de | Yum-Tong Siu | Harvard University, USA siu@math.harvard.edu |
| Izabella Laba | University of British Columbia, Canada ilaba@math.ubc.ca | Terence Tao | University of California, Los Angeles, USA tao@math.ucla.edu |
| Gilles Lebeau | Université de Nice Sophia Antipolis, France lebeau@unice.fr | Michael E. Taylor | Univ. of North Carolina, Chapel Hill, USA met@math.unc.edu |
| László Lempert | Purdue University, USA lempert@math.purdue.edu | Gunther Uhlmann | University of Washington, USA gunther@math.washington.edu |
| Richard B. Melrose | Massachussets Institute of Technology, USA rbm@math.mit.edu | András Vasy | Stanford University, USA andras@math.stanford.edu |
| Frank Merle | Université de Cergy-Pontoise, France Dan Frank.Merle@u-cergy.fr | an Virgil Voiculescu | University of California, Berkeley, USA dvv@math.berkeley.edu |
| William Minicozzi II | Johns Hopkins University, USA minicozz@math.jhu.edu | Steven Zelditch | Northwestern University, USA zelditch@math.northwestern.edu |
| Werner Müller | Universität Bonn, Germany mueller@math.uni-bonn.de |  |  |

PRODUCTION
production@msp.org
Silvio Levy, Scientific Editor

See inside back cover or msp.org/apde for submission instructions.
The subscription price for 2013 is US $\$ 160 /$ year for the electronic version, and $\$ 310 / y$ year $(+\$ 35$, if shipping outside the US) for print and electronic. Subscriptions, requests for back issues from the last three years and changes of subscribers address should be sent to MSP.

Analysis \& PDE (ISSN 1948-206X electronic, 2157-5045 printed) at Mathematical Sciences Publishers, 798 Evans Hall \#3840, c/o University of California, Berkeley, CA 94720-3840, is published continuously online. Periodical rate postage paid at Berkeley, CA 94704, and additional mailing offices.

APDE peer review and production are managed by EditFLOW ${ }^{\circledR}$ from Mathematical Sciences Publishers.
PUBLISHED BY
mathematical sciences publishers
nonprofit scientific publishing
http://msp.org/
© 2013 Mathematical Sciences Publishers

## ANalysis \& PDE

## Volume 6 No. 72013

Fractional conformal Laplacians and fractional Yamabe problems ..... 1535
María del Mar González and Jie Qing
$L^{p}$ estimates for the Hilbert transforms along a one-variable vector field ..... 1577
Michael Bateman and Christoph Thiele
Carleman estimates for anisotropic elliptic operators with jumps at an interface ..... 1601
Jérôme Le Rousseau and Nicolas Lerner
The semiclassical limit of the time dependent Hartree-Fock equation: The Weyl symbol of ..... 1649 the solutionLaurent Amour, Mohamed Khodja and Jean Nourrigat
The classification of four-end solutions to the Allen-Cahn equation on the plane ..... 1675
Micha£ Kowalczyk, Yong Liu and Frank Pacard
Pseudoparabolic regularization of forward-backward parabolic equations: A logarithmic non- ..... 1719linearityMichiel Bertsch, Flavia Smarrazzo and Alberto Tesei
The heat kernel on an asymptotically conic manifold ..... 1755
DAVID A. SHER


[^0]:    The authors wish to thank E. Fernández-Cara for bringing to their attention the importance of Carleman estimates for anisotropic elliptic operators towards applications to biological tissues. Le Rousseau was partially supported by l'Agence Nationale de la Recherche under grant ANR-07-JCJC-0139-01.
    MSC2010: 35J15, 35J57, 35J75.
    Keywords: Carleman estimate, elliptic operator, nonsmooth coefficient, quasimode.
    ${ }^{1}$ F. John [1960] showed that, although the Hadamard well-posedness property is a privilege of hyperbolic operators, a weaker type of continuous dependence, which he called Hölder continuous well-behavior, could occur. Strong connections between the well-behavior property and Carleman estimates can be found in an article by H. Bahouri [1987].
    ${ }^{2}$ For analytic operators, Holmgren's theorem provides uniqueness for the noncharacteristic Cauchy problem, but that analytical result falls short of giving a control of the solution from the data.

[^1]:    ${ }^{3}$ S. Alinhac [1980] showed the nonunique continuation property for second-order elliptic operators with nonconjugate roots; of course, if the coefficients of the principal part are real, this is excluded.

[^2]:    ${ }^{4}$ In the sections below, we shall also consider nonhomogeneous boundary conditions.

[^3]:    ${ }^{5}$ In the main text, we shall introduce some minimal requirements on the weight function and suggest other possible choices.

[^4]:    ${ }^{6}$ In the case $f_{+}(0)=0$, one needs to consider the estimation of

    $$
    \left\|\left(D_{n}+i e_{+}\right)\left(D_{n}+i f_{+}\right) v_{+}\right\|_{L^{2}\left(\mathbb{R}^{+}\right)}+\left\|\left(D_{n}+i f_{+}\right)\left(D_{n}+i e_{+}\right) v_{+}\right\|_{L^{2}\left(\mathbb{R}^{+}\right)}
    $$

    from below to obtain a control of $v_{+}(0)$ and $D_{n} v_{+}(0)$ with the previous estimates used in cascade. Indeed, the first term will give an estimate of $D_{n} v_{+}(0)$, and the second term one of $v_{+}(0)$.

[^5]:    ${ }^{7}$ For the main theorem, we shall in fact require the stronger strict inequality

    $$
    \begin{equation*}
    \frac{\alpha_{+}}{\alpha_{-}}>\frac{m_{+}\left(\xi^{\prime}\right)}{m_{-}\left(\xi^{\prime}\right)} \tag{1-29}
    \end{equation*}
    $$

    This condition is then stable under perturbations, whereas (1-28) is not. This gives us the freedom to introduce microlocal cutoff in the analysis below.

    However, we shall see in Section 5 that in the particular case presented here, where the matrix $A$ is piecewise constant and the weight function $\varphi$ depends solely on $x_{n}$, the inequality (1-28) is actually a necessary and sufficient condition to obtain a Carleman estimate with weight $\varphi$.

[^6]:    ${ }^{8}$ The homogeneity property means, as usual, $m_{ \pm}\left(x, \rho \xi^{\prime}\right)=\rho m_{ \pm}\left(x, \xi^{\prime}\right)$ for $\rho \geq 1,\left|\xi^{\prime}\right| \geq 1$.

