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**CONTINUUM LIMIT AND STOCHASTIC HOMOGENIZATION
OF DISCRETE FERROMAGNETIC THIN FILMS**

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We study the discrete-to-continuum limit of ferromagnetic spin systems when the lattice spacing tends to zero. We assume that the atoms are part of a (maybe) nonperiodic lattice close to a flat set in a lower-dimensional space, typically a plate in three dimensions. Scaling the particle positions by a small parameter $\varepsilon > 0$, we perform a Γ -convergence analysis of properly rescaled interfacial-type energies. We show that, up to subsequences, the energies converge to a surface integral defined on partitions of the flat space. In the second part of the paper we address the issue of stochastic homogenization in the case of random stationary lattices. A finer dependence of the homogenized energy on the average thickness of the random lattice is analyzed for an example of a magnetic thin system obtained by a random deposition mechanism.

1. Introduction	499
2. Modeling discrete disordered thin sets and spin systems	504
3. Integral representation on the flat set	512
4. Convergence of boundary value problems	517
5. Homogenization results for stationary lattices	521
6. Volume constraints in the stationary case	532
7. A model for random deposition	536
Appendix A. Plane-like minimizers for one-periodic dimension-reduction problems	546
Appendix B. Density results for trace-constraints on partitions	550
Acknowledgement	552
References	552

1. Introduction

Polymeric magnets are known to be lighter and more flexible than conventional magnets. They can be easily manufactured to form thin films made of few layers and are currently considered one of the main building blocks of the future generations of electronic devices. Under external magnetic fields they form Weiss domains, whose wall energy is influenced by the thickness and the roughness of the film, which in turn depends on the physical and chemical properties of the specific material at use. A fairly large amount of experimental results reconstruct the relation between film thickness and interfacial domain wall energy for different ferromagnetic materials, see [Klein and Smith 1951], but no rigorous explanation has appeared so far in this direction. Among the reasons for such an unsatisfactory analysis, we single out

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one which has a geometric flavor: depositing magnetic particles on a substrate to obtain a thin film leads to disordered arrangements of particles and rough film surfaces, which makes it very difficult to formulate a suitable ansatz leading to the correct (and simpler) continuum model. In this paper we look at this problem from a different perspective: we single out a simple Ising-type model for a thin film obtained by random deposition of magnetic particles on a flat substrate, for which the geometric part of the problem is still nontrivial, and propose an ansatz-free variational analysis of such a film. Combining Γ -convergence and percolation theory, we finally obtain a rigorous explanation of the relation between film thickness and domain-wall energy in some asymptotic regimes.

A simple way to model thin ferromagnetic polymeric materials at the microscale first requires the definition of a polymeric matrix made of magnetic cells and then that of an interaction energy between those cells; see [Vollath 2013] for further details. The polymeric matrix of such a system can be seen as a random network whose nodes are the cross-linkers molecules of the three-dimensional polymeric magnet, which are supposed to entail the local magnetic properties of the system and to interact as magnetic elementary cells via a ferromagnetic Potts-type coupling. The system is supposed to be thin in the sense that the nodes of the matrix are within a small distance, of the order of the average distance between the nodes themselves, from a two-dimensional plane. In the presence of an external magnetic field or of proper boundary conditions, the ferromagnetic coupling induces the system to form mesoscopic Weiss domains, i.e., regions of constant magnetization.

In this paper we aim at upscaling the system described above from its microscopic description to a mesoscopic one in a variational setting. This consists in performing the limit of its energy as the average distance between the magnetic cells, which we denote by ε , goes to zero with respect to the macroscopic size of the system. Such a limit will have two main effects: it will allow us to describe the original discrete system as a continuum, while at the same time it will reduce its dimension from three to two (or more generally from d to k with $2 \leq k < d$).

The discrete-to-continuum analysis in this paper is also part of a general study of the effects of discreteness in lattice systems on their macroscopic description. It is directly related to a series of papers describing the overall behavior of spin energies [Caffarelli and de la Llave 2005; Alicandro et al. 2006; Braides and Piatnitski 2013; Braides and Cicalese 2017; Alicandro and Gelli 2016]. Moreover, discrete-to-continuum analyses for thin elastic objects in a deterministic setting have also been considered, e.g., in [Alicandro et al. 2008; Schmidt 2008; Lazzaroni et al. 2015], and the behavior of full-dimensional random lattices is dealt with in [Alicandro et al. 2011]; see also [Blanc et al. 2007]. For dimension-reduction problems for continuum elastic objects we also refer to [Le Dret and Raoult 1995; Braides et al. 2000], the latter introducing a dimensionally reduced localization argument similar to the one used in the present paper.

Using the same model as in [Alicandro et al. 2015] we describe the polymeric matrix as a random network whose nodes $\mathcal{L} \subset \mathbb{R}^d$ form a thin *admissible stochastic lattice*, meaning that the matrix is thin; i.e., there exist $k \in \mathbb{N}$ with $2 \leq k < d$ and $M > 0$ such that, identifying \mathbb{R}^k with a linear subspace of \mathbb{R}^d ,

$$\text{dist}(x, \mathbb{R}^k) \leq M \quad \text{for all } x \in \mathcal{L}$$

and it is admissible according to the following standard definition; see [Ruelle 1989] and also [Alicandro et al. 2011; Blanc et al. 2007] in the framework of rubber elasticity. We say that \mathcal{L} is an admissible set of points if the following two requirements are satisfied:

- (i) There exists $r > 0$ such that $|x - y| \geq r$ for all $x \neq y, x, y \in \mathcal{L}$,
- (ii) There exists $R > 0$ such that $\text{dist}(x, \mathcal{L}) \leq R$ for all $x \in \mathbb{R}^k$.

Within this definition we may include “slices” of periodic lattices [Alicandro et al. 2008], and also aperiodic geometries [Braides et al. 2012].

Given a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, a random variable $\mathcal{L} : \Omega \rightarrow (\mathbb{R}^d)^\mathbb{N}$ is called an *admissible stochastic lattice* if $\mathcal{L}(\omega)$ is an admissible set of points uniformly with respect to $\omega \in \Omega$.

We assume that the magnetization takes only finitely many values; that is to say, we consider configurations $u : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$ with a state-space $\mathcal{S} = \{s_1, \dots, s_q\}$ that we embed in the euclidean space \mathbb{R}^d . We have in mind the case of spin systems, where $u_i \in \{1, -1\}$. Note that even in that case it is sometimes necessary to use a larger set of parameters \mathcal{S} if frustration forces the formation of texture; see [Braides and Cicalese 2017]. Note that if we have more than two parameters, we may have concentration phenomena of a third phase on the interfaces between two phases. A finer description of this phenomenon can be found in [Alicandro et al. 2012].

Associating a Voronoi tessellation $\mathcal{V}(\mathcal{L})$ to the lattice \mathcal{L} , one introduces the set of nearest neighbors $\mathcal{NN}(\mathcal{L})$ as the set of those pairs of points in \mathcal{L} whose Voronoi cells share a $(d-1)$ -dimensional edge. This allows us to distinguish between long-range and short-range interactions, introducing the (\mathcal{L} -dependent) interactions

$$f_\varepsilon(x, y, s_i, s_j) = \begin{cases} f_{nn}^\varepsilon(x, y, s_i, s_j) & \text{if } (x, y) \in \mathcal{NN}(\mathcal{L}), \\ f_{lr}^\varepsilon(x, y, s_i, s_j) & \text{otherwise,} \end{cases}$$

which we assume to be nonnegative and to satisfy the following coerciveness and growth assumptions.

Hypothesis 1. *There exist $c > 0$ and a decreasing function $J_{lr} : [0, +\infty) \rightarrow [0, +\infty)$ with*

$$\int_{\mathbb{R}^k} J_{lr}(|x|)|x| \, dx = J < +\infty$$

such that, for all $\varepsilon > 0, x, y \in \mathbb{R}^d$ and $s_i, s_j \in \mathcal{S}$,

$$c|s_i - s_j| \leq f_{nn}^\varepsilon(x, y, s_i, s_j) \leq J_{lr}(|x - y|)|s_i - s_j|, \quad f_{lr}^\varepsilon(x, y, s_i, s_j) \leq J_{lr}(|x - y|)|s_i - s_j|.$$

We remark that the decay of J_{lr} is needed to control the effect of long-range interactions and we use the same bound for short-range interactions only to save notation.

We fix $D \subset \mathbb{R}^k$ and denote by $P_k : \mathbb{R}^d \rightarrow \mathbb{R}^k$ the projection onto \mathbb{R}^k . For a given configuration $u : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$ we consider the energy per unit $((k-1)$ -dimensional) surface of D to have the ferromagnetic Potts form; see also [Alicandro et al. 2006; 2012; 2015; Braides and Cicalese 2017] given by

$$E_\varepsilon(u) = \sum_{\substack{x, y \in \mathcal{L} \\ \varepsilon x, \varepsilon y \in P_k^{-1}D}} \varepsilon^{k-1} f_\varepsilon(x, y, u(\varepsilon x), u(\varepsilon y)).$$

Since the sets $\varepsilon\mathcal{L}$ will eventually shrink to a k -dimensional set, we conveniently describe the system in terms of an *average spin order parameter* $Pu : \varepsilon P_k\mathcal{L} \rightarrow \text{co}(S)$ defined on the k -dimensional set $\varepsilon P_k\mathcal{L}$ by

$$Pu(z) := \frac{1}{\#(P_k^{-1}(z) \cap \varepsilon\mathcal{L})} \sum_{\varepsilon x \in P_k^{-1}(z) \cap \varepsilon\mathcal{L}} u(\varepsilon x).$$

We then embed the energies E_ε in $L^1(D)$ by identifying Pu with a function piecewise constant on the cells of the Voronoi tessellation of $P_k\mathcal{L}$, define the convergence $u_\varepsilon \rightarrow u$ in D in the sense that the piecewise constant functions Pu_ε converge to u strongly in $L^1(D)$ and perform the Γ -convergence analysis with respect to this notion (see Section 2 for further details).

In Theorem 3.2 we prove a compactness and integral representation result for the Γ -limit E of E_ε , stating that, up to subsequences, this is finite only on $\text{BV}(D, S)$, where it takes the integral form

$$E(u) = \int_{S_u} \phi^\omega(x, u^+, u^-, \nu_u) \, d\mathcal{H}^{k-1}.$$

In this formula S_u is the jump set of u , the functions u^+ and u^- represent the traces on both sides of the jump set, $\nu_u \in S^{k-1}$ is the measure-theoretical normal to S_u and \mathcal{H}^{k-1} is the $(k-1)$ -dimensional Hausdorff measure. The function ϕ^ω is interpreted as the domain-wall interaction energy (per unit $(k-1)$ -dimensional area) between Weiss domains.

The dependence of such an energy on the randomness of the lattice is studied in Section 5 in the context of stochastic homogenization, assuming the thin random lattice to be stationary (or ergodic) in the directions of the flat subspace to which it is close and the interaction coefficients to be invariant under translation in these directions. More precisely we assume that there exists a measure-preserving group action $(\tau_z)_{z \in \mathbb{Z}^k}$ on Ω such that, almost surely in Ω , we have $\mathcal{L}(\tau_z\omega) = \mathcal{L}(\omega) + z$ (if in addition $(\tau_z)_{z \in \mathbb{Z}^k}$ is ergodic, then also the lattice \mathcal{L} is said to be ergodic) and the following structural assumption:

Hypothesis 2. *There exist functions $f_{nn}, f_{lr} : \mathbb{R}^k \times \mathbb{R}^{2(d-k)} \times S^2 \rightarrow [0, +\infty)$ such that, setting $\Delta_k(x, y) = (y_1 - x_1, \dots, y_k - x_k, x_{k+1}, y_{k+1}, \dots, x_d, y_d)$, it holds that*

$$f_{nn}^\varepsilon(x, y, s_i, s_j) = f_{nn}(\Delta_k(x, y), s_i, s_j), \quad f_{lr}^\varepsilon(x, y, s_i, s_j) = c_{lr}(\Delta_k(x, y), s_i, s_j).$$

In Theorem 5.8 we prove that under Hypotheses 1 and 2 and assuming the stationarity (or ergodicity) in the sense specified above, the Γ -limit of E_ε as $\varepsilon \rightarrow 0$ exists and is finite only on $\text{BV}(D, S)$ where it takes the form

$$E_{\text{hom}}^\omega(u) = \int_{S_u} \phi_{\text{hom}}^\omega(u^+, u^-, \nu_u) \, d\mathcal{H}^{k-1}.$$

The energy density is given by an asymptotic homogenization formula which is averaged in the probability space under ergodicity assumptions on \mathcal{L} , thus turning the stochastic domain wall energy into a deterministic one.

The result is proved by the abstract methods of Γ -convergence, first showing an abstract compactness result, and then giving an integral representation of the limit, as described in detail for deterministic bulk elastic thin films in [Braides et al. 2000]; for other applications of this method in a discrete-to-continuum

setting see, e.g., [Alicandro and Cicalese 2004; Le Dret and Raoult 2017; Braides and Cicalese 2017]. The proof makes use of two main ingredients: the integral-representation theorem in [Bouchitté et al. 2002] and the subadditive ergodic theorem in [Akcoglu and Krengel 1981]. They are combined following a scheme introduced in [Alicandro et al. 2011] in the context of random discrete systems with limit energy on Sobolev spaces, see also [Dal Maso and Modica 1986], and recently extended to sets of finite perimeter in [Alicandro et al. 2015]. Section 6 is devoted to extending the result above to the case of a volume constraint on the phases.

An interesting issue in the theory of thin magnetic composite polymeric materials is the dependence of the domain wall energy on the random geometry of the polymer matrix. We devote the second part of the paper to this problem. We consider a specific model of a discrete system in which the state-space is $\mathcal{S} = \{\pm 1\}$ and the stochastic lattice is generated by the random deposition of magnetic particles on a two-dimensional flat substrate. For simplicity we limit ourselves to a simple deposition model with vertical order and suppose that the magnetic interactions have finite range. We are interested in the dependence of the domain wall energy on the average thickness of the thin film. Even though a complete picture would need a more extended treatment, thanks to percolation arguments we are able to attack the problem in the asymptotic cases when the thickness of the film is either small or very large.

More specifically, we model the substrate (where the particles are deposited) by taking a two-dimensional deterministic lattice, which we choose for simplicity as $\mathcal{L}^0 = \mathbb{Z}^2 \times \{0\}$. We then consider an independent random field $\{X_i^p\}_{i \in \mathbb{Z}^3}$, where the X_i^p are Bernoulli random variables with $\mathbb{P}(X_i^p = 1) = p \in (0, 1)$. For fixed $M \in \mathbb{N}$ we construct the random point set

$$\mathcal{L}_p^M(\omega) := \{(i_1, i_2, i_3) \in \mathbb{Z}^3 : 0 \leq i_3 \leq \sum_{k=1}^M X_{(i_1, i_2, k)}^p(\omega)\},$$

which means that we successively deposit particles M times independently onto the flat lattice \mathcal{L}^0 and stack them over each other (the point set constructed is stationary with respect to translations in \mathbb{Z}^2 and ergodic). Moreover, given $u : \varepsilon \mathcal{L}_p^M(\omega) \rightarrow \{\pm 1\}$, we consider an energy of the form

$$E_{\varepsilon, M}^p(\omega)(u, A) = \sum_{\substack{x, y \in \mathcal{L}_p^M(\omega) \\ \varepsilon P_2(x), \varepsilon P_2(y) \in A}} \varepsilon c(x - y) |u(\varepsilon x) - u(\varepsilon y)|,$$

where the interaction constant $c : \mathbb{R}^3 \rightarrow [0, +\infty)$ has finite range, is bounded from above and is coercive on nearest neighbors, so that the Hypotheses 1 and 2 above are satisfied. As a result Theorem 5.8 guarantees the existence of a surface tension, say $\phi_{\text{hom}}^p(M; \nu)$, given by an asymptotic cell formula.

The main issue now is the dependence of $\phi_{\text{hom}}^p(M; \nu)$ on p and M .

A first result in this direction is proved in Proposition 7.3, where we show that, for every direction $\nu \in S^1$, the wall energy density is linear in the average thickness pM as $M \rightarrow +\infty$; that is,

$$\lim_{M \rightarrow +\infty} \frac{\phi_{\text{hom}}^p(M; \nu)}{pM} = \phi^1(\nu), \quad (1-1)$$

with $\phi^1(\nu)$ given in Lemma 7.2 being the wall energy per unit thickness of the deterministic problem obtained for $p = 1$.

A second and more delicate result is contained in [Theorem 7.5](#) and concerns a percolation-type phenomenon which can be roughly stated as follows: when the deposition probability p is sufficiently low (below a certain critical percolation threshold) the domain wall energy is zero for M small enough. At this stage it is worth noticing that our energy accounts for the interactions between the deposited particles and the substrate. On one hand this assumption might be questionable from a physical point of view in the case one assumes to grow thin films on neutral media, thus expecting the properties of the film to be independent of the substrate. On the other hand removing such an interaction leads to a dilute model similar to the one considered in [\[Braides and Piatnitski 2012\]](#). An adaption of this analysis would require a lot of additional work like the extension of fine percolation results to the (range-1)-dependent case, which goes far beyond the scope of the present paper (see also [Remark 7.4](#)). We prove the percolation result for nearest-neighbor positive interactions. Setting the interaction with the substrate to be $\eta > 0$, we can prove that if $p < 1 - p_{\text{site}}$ (here p_{site} is the critical site percolation threshold in \mathbb{Z}^2), the limit energy $\phi_{\text{hom}}^{p,\eta}(M; \nu)$ is bounded above (up to a constant) by η for M small enough. This result suggests the absence of a positive domain wall energy in the thin film on a neutral substrate ($\eta = 0$ case). In the limit as M diverges, (1-1) holds with $\phi_{\text{hom}}^{p,\eta}(M; \nu)$, which is independent of η , thus showing that the contribution of the first layer does not affect the asymptotic average domain wall energy as expected. The proof of these results needs the extension to the dimension reduction framework of a result by Caffarelli and de la Llave [\[2005\]](#) about the existence of plane-like minimizers for discrete systems subject to periodic Ising-type interactions at the surface scaling. This is contained in [Appendix A](#).

As a final remark, we mention that we prove all our results in the case when the flat object is at least two-dimensional. Most of the results can be extended to one-dimensional objects (with the proof being much simpler), except the ones contained in [Section 6](#), which fail in dimension one as can be seen by simple examples and the percolation-type phenomenon in [Section 7](#), as no percolation can occur in (essentially) one-dimensional lattices.

2. Modeling discrete disordered thin sets and spin systems

This section is devoted to the precise description of the model we are going to study. We start with the notation we are going to use in the sequel.

As we are concerned with dimension-reduction issues, there will be two geometric dimensions k and d with $2 \leq k < d$. Given a measurable set $A \subset \mathbb{R}^k$, we denote by $|A|$ its k -dimensional Lebesgue measure, while more generally $\mathcal{H}^m(A)$ stands for the m -dimensional Hausdorff measure. We denote by $\mathbb{1}_A$ the characteristic function of A . Given $x \in \mathbb{R}^k$ and $r > 0$, we denote by $B_r(x)$ the open ball around x with radius r . By $|x|$ we denote the usual euclidean norm of x . Moreover, we set $d_{\mathcal{H}}(A, B)$ to be the Hausdorff distance between the sets A and B and $\dim_{\mathcal{H}}(A)$ to be the Hausdorff dimension of A . If it is clear from the context we will use the same notation as above also in \mathbb{R}^d (otherwise we will indicate the dimension by sub/superscript indices). Given an open set $D \subset \mathbb{R}^k$, we denote by $\mathcal{A}(D)$ the family of all bounded open subsets of D and by $\mathcal{A}^R(D)$ the family of those sets in $\mathcal{A}(D)$ with Lipschitz boundary. Given a unit vector $\nu \in S^{k-1}$, let $\nu = \nu_1, \dots, \nu_k$ be an orthonormal basis. We define the open cube in \mathbb{R}^k

$$Q_\nu = \left\{ x \in \mathbb{R}^k : |\langle x, \nu_i \rangle| < \frac{1}{2} \text{ for all } i \right\},$$

and, for $x \in \mathbb{R}^k$, $\rho > 0$, we set $Q_\nu(x, \rho) := x + \rho Q_\nu$. We call $\nu \in S^{k-1}$ a rational direction if $\nu \in \mathbb{Q}^k$. We denote by $P_k : \mathbb{R}^d \rightarrow \mathbb{R}^k$ the projection onto \mathbb{R}^k .

For $q \in \mathbb{N}$ we let $BV(D, \mathbb{R}^q)$ be the space of \mathbb{R}^q -valued functions of bounded variation, that is, those functions $u \in L^1(D, \mathbb{R}^q)$ such that their distributional derivative Du is a matrix-valued Radon measure. Given a set $S \subset \mathbb{R}^q$, we denote by $BV(A, S)$ the space of those functions $u \in BV(A, \mathbb{R}^q)$ such that $u(x) \in S$ almost everywhere. If S is a finite set, then the distributional derivative of u can be represented on any Borel set $B \subset D$ as $Du(B) = \int_{B \cap S_u} (u^+(x) - u^-(x)) \otimes \nu_u(x) d\mathcal{H}^{k-1}(x)$ for a countably \mathcal{H}^{k-1} -rectifiable set S_u in D which coincides \mathcal{H}^{k-1} -almost everywhere with the complement in D of the Lebesgue points of u . Moreover $\nu_u(x)$ is a unit normal to S_u , defined for \mathcal{H}^{k-1} -almost every x and $u^+(x)$, $u^-(x)$ are the traces of u on both sides of S_u . Here the symbol \otimes stands for the tensorial product of vectors; that is, for any $a, b \in \mathbb{R}^k$, we have $(a \otimes b)_{ij} := a_i b_j$. A measurable set B is said to have finite perimeter in D if its characteristic function belongs to $BV(D)$. We refer the reader to [Ambrosio et al. 2000] for an introduction to functions of bounded variation. The letter C stands for a generic positive constant that may change every time it appears.

We want to describe (possibly nonperiodic) particle systems, where the particles themselves are located very close to a lower-dimensional linear subspace. To this end we make the following assumptions: Let $\mathcal{L} \subset \mathbb{R}^d$ be a countable set. We assume that there exists $M > 0$ such that, after identifying $\mathbb{R}^k \sim \mathbb{R}^k \times \{0\}^{d-k}$, we have

$$\text{dist}(x, \mathbb{R}^k) \leq M \quad \text{for all } x \in \mathcal{L}. \tag{2-2}$$

Moreover, adapting ideas from [Alicandro et al. 2011; 2015; Blanc et al. 2007] we assume that the point set is regular in the following sense:

Definition 2.1. A countable set $\mathcal{L} \subset \mathbb{R}^d$ is a *thin admissible lattice* if (2-2) holds and

- (i) there exists $r > 0$ such that $|x - y| \geq r$ for all $x \neq y$, $x, y \in \mathcal{L}$,
- (ii) there exists $R > 0$ such that $\text{dist}(x, \mathcal{L}) \leq R$ for all $x \in \mathbb{R}^k$.

We associate to such a lattice a truncated Voronoi tessellation $\mathcal{V}(\mathcal{L})$, where the corresponding d -dimensional cells $\mathcal{C} \in \mathcal{V}(\mathcal{L})$ are defined by

$$\mathcal{C}(x) := \{z \in \mathbb{R}^k \times [-2M, 2M]^{d-k} : |z - x| \leq |z - x'| \text{ for all } x' \in \mathcal{L}\},$$

and we introduce the set of nearest neighbors accordingly by setting

$$\mathcal{NN}(\mathcal{L}) := \{(x, y) \in \mathcal{L}^2 : \dim_{\mathcal{H}}(\mathcal{C}(x) \cap \mathcal{C}(y)) = d - 1\}.$$

As usual in the passage from atomistic to continuum theories, we scale the point set \mathcal{L} by a small parameter $\varepsilon > 0$. We assume that the magnetization of the particles takes values in a finite set $S = \{s_1, \dots, s_q\} \subset \mathbb{R}^q$. Fix a k -dimensional reference set $D \in \mathcal{A}^R(\mathbb{R}^k)$. Given $A \in \mathcal{A}^R(D)$ and $u : \varepsilon\mathcal{L} \rightarrow S$, we consider a localized (on A) pairwise interaction energy

$$E_\varepsilon(u, A) = \sum_{\substack{x, y \in \mathcal{L} \\ \varepsilon x, \varepsilon y \in P_k^{-1}A}} \varepsilon^{k-1} f_\varepsilon(x, y, u(\varepsilon x), u(\varepsilon y)),$$

where the (\mathcal{L} -dependent) interactions distinguish between long- and short-range interactions and are of the form

$$f_\varepsilon(x, y, s_i, s_j) = \begin{cases} f_{nn}^\varepsilon(x, y, s_i, s_j) & \text{if } (x, y) \in \mathcal{NN}(\mathcal{L}), \\ f_{lr}^\varepsilon(x, y, s_i, s_j) & \text{otherwise.} \end{cases}$$

For our analysis we make the following assumptions on the measurable functions $f_{nn}^\varepsilon, f_{lr}^\varepsilon : \mathbb{R}^d \times \mathbb{R}^d \times \mathcal{S}^2 \rightarrow [0, +\infty)$:

Hypothesis 1. There exist $c > 0$ and a decreasing function $J_{lr} : [0, +\infty) \rightarrow [0, +\infty)$ with

$$\int_{\mathbb{R}^k} J_{lr}(|x|)|x| \, dx = J < +\infty$$

such that, for all $\varepsilon > 0$, $x, y \in \mathbb{R}^d$ and $s_i, s_j \in \mathcal{S}$,

$$c \leq c_{nn}^\varepsilon(x, y) \leq J_{lr}(|x - y|), \quad c_{lr}^\varepsilon(x, y) \leq J_{lr}(|x - y|).$$

Since the sets $\varepsilon\mathcal{L}$ shrink to a k -dimensional set as ε vanishes, we want to define a convergence of discrete variables on shrinking domains. To that end, denoting by $\text{co}(\mathcal{S})$ the convex hull of \mathcal{S} , we define the averaged and projected spin variable $Pu : \varepsilon P_k\mathcal{L} \rightarrow \text{co}(\mathcal{S})$ via

$$Pu(\varepsilon z) := \frac{1}{\#(P_k^{-1}(z) \cap \mathcal{L})} \sum_{x \in P_k^{-1}(z) \cap \mathcal{L}} u(\varepsilon x). \tag{2-3}$$

The projected lattice $P_k\mathcal{L} \subset \mathbb{R}^k$ inherits property (ii) from [Definition 2.1](#), but (i) might fail after projection. Nevertheless, due to [\(2-2\)](#) the projected lattice is still locally finite and the following uniform bound on the number of points holds true: there exists a constant $C = C_{\mathcal{L}} > 0$ such that, given a set $A \in \mathcal{A}(D)$ with $|\partial A| = 0$, we have

$$\varepsilon^k \#\{\varepsilon z \in \varepsilon P_k\mathcal{L} \cap A\} \leq C|A| \tag{2-4}$$

for ε small enough. We now associate the corresponding k -dimensional Voronoi tessellation $\mathcal{V}(P_k\mathcal{L}) = \{\mathcal{C}_k(z)\}$ in \mathbb{R}^k to the lattice $P_k\mathcal{L}$ and we identify Pu with a piecewise-constant function belonging to the class

$$\mathcal{PC}_\varepsilon(\mathcal{L}) := \{v : \mathbb{R}^k \rightarrow (\mathcal{S}) : v|_{\varepsilon\mathcal{C}_k(z)} \text{ is constant for all } z \in P_k\mathcal{L}\}$$

Note that we can embed $\mathcal{PC}_\varepsilon(\mathcal{L})$ in $L^1(D)$ since the intersection of two Voronoi cells always has zero k -dimensional Lebesgue measure.

For the sake of illustration, in [Figure 1](#) we picture the construction in the simple case $d = 2$, $k = 1$ and $\mathcal{S} = \{\pm 1\}$. In the picture above, we draw a portion of the truncated Voronoi diagram of the lattice \mathcal{L} represented by the dots, black for $u = -1$ and white for $u = +1$. At the bottom of the Voronoi diagram we include the projected points $P_1\mathcal{L}$ and the values of the variable $Pu \in [-1, 1]$ (range reflected by the gray scale in the figure). The dashed lines indicate the exceptional set of projection points where $|Pu| \neq 1$. The picture below represents the piecewise-constant function on the Voronoi intervals subordinated to $P_1\mathcal{L}$.

To deal with convergence of sequences $u_\varepsilon : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$, we adopt the idea of [\[Braides et al. 2012\]](#). We will see in [Section 6](#) that this notion of convergence is indeed meaningful for variational problems in a random environment.

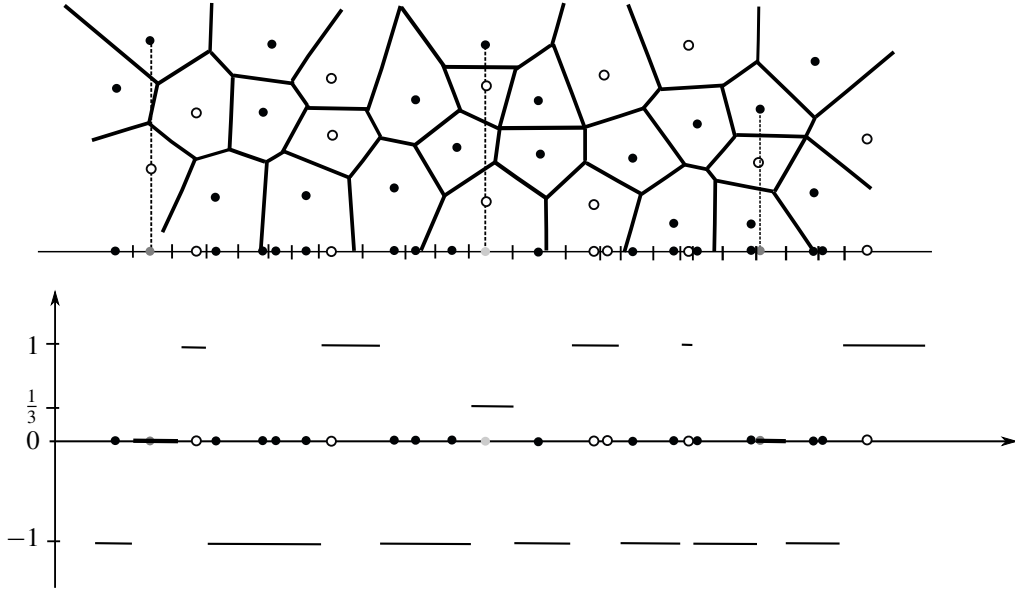


Figure 1. Construction of the piecewise-constant interpolation for $d = 2$, $k = 1$ and $S = \{\pm 1\}$.

Definition 2.2. Let $A \in \mathcal{A}(D)$. We say that a sequence $u_\varepsilon : \varepsilon\mathcal{L} \rightarrow S$ converges in A to $u : A \rightarrow \mathbb{R}^q$ if the piecewise-constant functions Pu_ε converge to u strongly in $L^1(A)$.

For our variational analysis we introduce the lower and upper Γ -limits $E', E'' : L^1(D, \mathbb{R}^q) \times \mathcal{A}^R(D) \rightarrow [0, +\infty]$ setting

$$\begin{aligned} E'(u, A) &:= \inf \left\{ \liminf_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon, A) : u_\varepsilon \rightarrow u \text{ in } D \right\}, \\ E''(u, A) &:= \inf \left\{ \limsup_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon, A) : u_\varepsilon \rightarrow u \text{ in } D \right\}. \end{aligned} \tag{2-5}$$

Remark 2.3. The functionals E', E'' are not Γ -lower/upper limits in the usual sense since they are not defined on the same space as E_ε . However, if we define the functionals $\tilde{E}_\varepsilon : L^1(D, \mathbb{R}^q) \times \mathcal{A}^R(D) \rightarrow [0, +\infty]$ as

$$\tilde{E}_\varepsilon(u, A) := \begin{cases} \inf_v E_\varepsilon(v, A) & \text{if } u = Pv \text{ for some } v : \varepsilon\mathcal{L} \rightarrow S, \\ +\infty & \text{otherwise,} \end{cases}$$

then E', E'' agree with the Γ -lower/upper limit of \tilde{E}_ε in the strong $L^1(D)$ -topology. Therefore we will refer to the equality of E' and E'' as Γ -convergence. Moreover, one can show that

$$\begin{aligned} E'(u, A) &= \inf \left\{ \liminf_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon, A) : u_\varepsilon \rightarrow u \text{ in } A \right\}, \\ E''(u, A) &= \inf \left\{ \limsup_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon, A) : u_\varepsilon \rightarrow u \text{ in } A \right\}. \end{aligned}$$

By the properties of Γ -convergence, this implies that both functionals $u \mapsto E'(u, A)$ and $u \mapsto E''(u, A)$ are $L^1(A)$ -lower semicontinuous and hence local in the sense of [Theorem 3.1\(ii\)](#).

We now prove several properties of the convergence introduced in [Definition 2.2](#). We start with an equicoercivity property.

Lemma 2.4. *Assume [Hypothesis 1](#) holds. Let $A \in \mathcal{A}(D)$ and let $u_\varepsilon : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$ be such that*

$$\sup_\varepsilon E_\varepsilon(u_\varepsilon, A) < +\infty.$$

Then, up to subsequences, the functions Pu_ε defined as in [\(2-3\)](#) converge strongly in $L^1(A)$ to some $u \in \text{BV}(A, \mathcal{S})$.

Proof. Fix $A' \Subset A$ such that $A' \in \mathcal{A}^R(D)$. We start by estimating the measure of the set $\{Pu_\varepsilon \notin \mathcal{S}\} \cap A'$. Note that if $Pu_\varepsilon(\varepsilon z) \notin \mathcal{S}$ for some $z \in P_k\mathcal{L}$ such that $\varepsilon\mathcal{C}_k(z) \cap A' \neq \emptyset$, then there exist $x_1, x_2 \in P_k^{-1}(z) \cap \mathcal{L}$ such that $u_\varepsilon(\varepsilon x_1) \neq u_\varepsilon(\varepsilon x_2)$. As a preliminary step we show that we can find a path of nearest neighbors in \mathcal{L} joining x_1 and x_2 , that is, a finite collection of points $\{x^1, \dots, x^m\} \subset \mathcal{L}$ such that $x^1 = x_1$ and $x^m = x_2$ and $(x^i, x^{i+1}) \in \mathcal{NN}(\mathcal{L})$ for all $i = 1, \dots, m - 1$. Moreover this path will be chosen such that it does not vary too much from the segment between x_1 and x_2 . To this end, fix $0 < \delta \ll 1$ and consider the collection of segments

$$\mathcal{G}_\delta(x_1, x_2) = \{x + \lambda(x_2 - x_1) : x \in B_\delta(x_1), 0 \leq \lambda \leq 1\}. \tag{2-6}$$

We argue that there exists a segment $g^* = \{x^* + \lambda(x_2 - x_1) : 0 \leq \lambda \leq 1\} \subset \mathcal{G}_\delta$ satisfying the implication

$$g^* \cap \mathcal{C}(x) \cap \mathcal{C}(x') \neq \emptyset \implies (x, x') \in \mathcal{NN}(\mathcal{L}). \tag{2-7}$$

Indeed, assume by contradiction that the implication is false for all $x^* \in B_\delta(x_1)$. Since the number of d -dimensional Voronoi cells $\mathcal{C}(x) \in \mathcal{V}(\mathcal{L})$ such that $\mathcal{C}(x) \cap \mathcal{G}_\delta \neq \emptyset$ is uniformly bounded, we can then find finitely many Voronoi facets of dimension less than $d - 1$ whose projection onto the hyperplane containing x_1 and orthogonal to $x_2 - x_1$ covers a $(d - 1)$ -dimensional set. Since projections onto hyperplanes are Lipschitz continuous, we obtain a contradiction.

The path connecting x_1 and x_2 is then given by the set $G(x_1, x_2) := \{x \in \mathcal{L} : g^* \cap \mathcal{C}(x) \neq \emptyset\}$, provided that δ is small enough. Observe that there exist $x, y \in G(x_1, x_2)$ such that $(x, y) \in \mathcal{NN}(\mathcal{L})$ and $u_\varepsilon(\varepsilon x) \neq u_\varepsilon(\varepsilon y)$. From the coercivity assumption in [Hypothesis 1](#), we thus deduce that each path contributes to the energy. Moreover, by [\(2-2\)](#) and the local construction of the paths, for any pair $(x, y) \in \mathcal{NN}(\mathcal{L})$ it holds that

$$\#\{z \in P_k\mathcal{L} : G(x_1, x_2) \cap \{x, y\} \neq \emptyset\} \leq C.$$

From these two facts we infer that

$$\varepsilon^{k-1} \#\{\varepsilon z : \varepsilon\mathcal{C}_k(z) \cap A' \neq \emptyset, Pu_\varepsilon(\varepsilon z) \notin \mathcal{S}\} \leq CE_\varepsilon(u_\varepsilon, A) \leq C, \tag{2-8}$$

where we have used that $\varepsilon G(x_1, x_2) \subset (P_k^{-1}A) \cap \varepsilon\mathcal{L}$ for ε small enough. Since the measure of a Voronoi cell in $P_k\mathcal{L}$ can be bounded uniformly by a constant, by rescaling we deduce that

$$|\{Pu_\varepsilon \notin \mathcal{S}\} \cap A'| \leq C\varepsilon. \tag{2-9}$$

We continue bounding the total variation $|DPu_\varepsilon|(A')$. Since Pu_ε is equibounded and piecewise constant, it is enough to provide a bound for $\mathcal{H}^{k-1}(S_{Pu_\varepsilon} \cap A')$. Note that the jump set S_{Pu_ε} is contained in the

facets of the Voronoi cells of the lattice $\varepsilon P_k \mathcal{L}$. Since \mathcal{L} is thin admissible in the sense of [Definition 2.1](#) and property (ii) is preserved by projection, for each such facet F it holds that

$$\mathcal{H}^{k-1}(F) \leq C\varepsilon^{k-1}.$$

For ε small enough, we conclude that

$$\mathcal{H}^{k-1}(S_{Pu_\varepsilon} \cap A') \leq C\varepsilon^{k-1} \#\{(z, z') \in \mathcal{NN}(P_k \mathcal{L}) : Pu_\varepsilon(\varepsilon z) \neq Pu_\varepsilon(\varepsilon z'), \varepsilon z, \varepsilon z' \in A' + B_{R\varepsilon}(0)\}.$$

Given $\varepsilon z, \varepsilon z' \in A' + B_{R\varepsilon}(0)$ such that $(z, z') \in \mathcal{NN}(P_k \mathcal{L})$ and $Pu_\varepsilon(\varepsilon z) \neq Pu_\varepsilon(\varepsilon z')$, again we may find a path of nearest neighbors

$$G(z, z') = \{x^0 \in P_k^{-1}(z), x^1, \dots, x^m \in P_k^{-1}(z')\}$$

with $u_\varepsilon(\varepsilon x^0) \neq u_\varepsilon(\varepsilon x^m)$ and the paths are local in the sense that

$$\#\{(z, z') \in \mathcal{NN}(P_k \mathcal{L}) : G(z, z') \cap \{x, y\} \neq \emptyset\} \leq C$$

for all $(x, y) \in \mathcal{NN}(\mathcal{L})$. Reasoning as in the first part of the proof we find that

$$\varepsilon^{k-1} \#\{(z, z') \in \mathcal{NN}(P_k \mathcal{L}) : Pu_\varepsilon(\varepsilon z) \neq Pu_\varepsilon(\varepsilon z'), \varepsilon z, \varepsilon z' \in A' + B_{R\varepsilon}(0)\} \leq CE_\varepsilon(u_\varepsilon, A) \leq C.$$

By well-known compactness properties of BV-functions (see, for example, [\[Ambrosio et al. 2000, Corollary 3.49\]](#)) and [\(2-9\)](#), there exists a subsequence (not relabeled) such that $Pu_\varepsilon \rightarrow u$ in $L^1(A')$ for some $u \in \text{BV}(A', S)$. Since A' was arbitrary, the claim follows by a diagonal argument combined with equiboundedness, which rules out concentrations close to the boundary. \square

We will also use the following auxiliary result about the convergence introduced in [Definition 2.2](#).

Lemma 2.5. *Let $A \in \mathcal{A}(D)$ be such that $|\partial A| = 0$ and let $u_\varepsilon, v_\varepsilon : \varepsilon \mathcal{L} \rightarrow S$ both converge in A to u in the sense of [Definition 2.2](#) and assume both have equibounded energy on A . Then*

$$\lim_{\varepsilon \rightarrow 0} \sum_{\substack{\varepsilon x \in \varepsilon \mathcal{L} \\ \varepsilon P_k(x) \in A}} \varepsilon^k |u_\varepsilon(\varepsilon x) - v_\varepsilon(\varepsilon x)| = 0.$$

Proof. Fix a set $A' \Subset A$ such that $A' \in \mathcal{A}^R(D)$. By [\(2-4\)](#) and equiboundedness of u_ε and v_ε it is enough to show that

$$\lim_{\varepsilon \rightarrow 0} \sum_{\substack{\varepsilon x \in \varepsilon \mathcal{L} \\ \varepsilon P_k(x) \in A'}} \varepsilon^k |u_\varepsilon(\varepsilon x) - v_\varepsilon(\varepsilon x)| = 0.$$

Using the fact that $u_\varepsilon, v_\varepsilon$ both have finite energy in A , we can argue as in the derivation of [\(2-8\)](#) to show

$$\#\{\varepsilon x \in \varepsilon \mathcal{L} : \varepsilon P_k(x) \in A', Pu_\varepsilon(\varepsilon P_k(x)) \neq u_\varepsilon(\varepsilon x) \text{ or } Pv_\varepsilon(\varepsilon P_k(x)) \neq v_\varepsilon(\varepsilon x)\} \leq C\varepsilon^{1-k}.$$

Inserting this estimate and using that \mathcal{L} satisfies [\(2-2\)](#) we obtain

$$\sum_{\substack{\varepsilon x \in \varepsilon \mathcal{L} \\ \varepsilon P_k(x) \in A'}} \varepsilon^k |u_\varepsilon(\varepsilon x) - v_\varepsilon(\varepsilon x)| \leq C \sum_{\substack{\varepsilon z \in \varepsilon P_k \mathcal{L} \\ \varepsilon z \in A'}} \varepsilon^k |Pu_\varepsilon(\varepsilon z) - Pv_\varepsilon(\varepsilon z)| + C\varepsilon.$$

Thus it is enough to control the last sum. Since the Voronoi cells in the projected lattice may become degenerate, we can only use bounds on the number of cells. To this end fix $L > 1$ large enough such that, for all $z_L \in L\mathbb{Z}^k$, we have

$$1 \leq \#(\varepsilon P_k \mathcal{L} \cap (\varepsilon z_L + [0, L\varepsilon)^k)) \leq C. \quad (2-10)$$

Define $I_\varepsilon := \{z_L \in L\mathbb{Z}^k : (\varepsilon z_L + [0, L\varepsilon)^k) \cap A' \neq \emptyset\}$ and subdivide this set again as

$$\begin{aligned} I_\varepsilon^1 &:= \{z_L \in I_\varepsilon : Pu_\varepsilon \text{ is not constant on } \varepsilon z_L + [0, L\varepsilon)^k\}, \\ I_\varepsilon^2 &:= \{z_L \in I_\varepsilon : Pv_\varepsilon \text{ is not constant on } \varepsilon z_L + [0, L\varepsilon)^k\}, \\ I_\varepsilon^3 &:= I_\varepsilon \setminus (I_\varepsilon^1 \cup I_\varepsilon^2). \end{aligned}$$

Since every scaled k -dimensional Voronoi cell $\varepsilon C_k(z)$ can only intersect finitely many cubic cells $\varepsilon z_L + [0, L\varepsilon)^k$ with a uniform bound on the cardinality, we can again use the energy bound in A and argue as for (2-8) to conclude

$$\#(I_\varepsilon^1 \cup I_\varepsilon^2) \leq C\varepsilon^{1-k}. \quad (2-11)$$

Combining (2-10) and (2-11) we infer from the definition of the set I_ε^3 that

$$\begin{aligned} \sum_{\substack{\varepsilon z \in \varepsilon P_k \mathcal{L} \\ \varepsilon z \in A'}} \varepsilon^k |Pu_\varepsilon(\varepsilon z) - Pv_\varepsilon(\varepsilon z)| &\leq C\varepsilon + \sum_{z_L \in I_\varepsilon^3} \sum_{\substack{\varepsilon z \in \varepsilon P_k \mathcal{L} \\ \varepsilon z \in \varepsilon z_L + [0, L\varepsilon)^k}} \varepsilon^k |Pu_\varepsilon(\varepsilon z) - Pv_\varepsilon(\varepsilon z)| \\ &\leq C\varepsilon + C \sum_{z_L \in I_\varepsilon^3} \int_{\varepsilon z_L + [0, L\varepsilon)^k} |Pu_\varepsilon(s) - Pv_\varepsilon(s)| ds \\ &\leq C\varepsilon + C \|Pu_\varepsilon - Pv_\varepsilon\|_{L^1(A)}. \end{aligned}$$

This concludes the proof, since the last term tends to 0 by assumption. \square

Following some ideas in [Alicandro et al. 2011] we introduce an auxiliary deterministic square lattice on which we will rewrite the energies E_ε . This lattice, shown in Figure 2, will turn out to be a convenient way to control the long-range interactions.

On setting $r' = r/\sqrt{d}$ it follows that $\#\{\mathcal{L} \cap \{\alpha + [0, r')^d\}\} \leq 1$ for all $\alpha \in r'\mathbb{Z}^d$. We now set

$$\begin{aligned} \mathcal{Z}_{r'}(\mathcal{L}) &:= \{\alpha \in r'\mathbb{Z}^d : \#\{\mathcal{L} \cap \{\alpha + [0, r')^d\}\} = 1\}, \\ x_\alpha &:= \mathcal{L} \cap \{\alpha + [0, r')^d\}, \quad \alpha \in \mathcal{Z}_{r'}(\mathcal{L}), \end{aligned}$$

and, for $\xi \in r'\mathbb{Z}^d$, $U \subset \mathbb{R}^k$ and $\varepsilon > 0$,

$$R_\varepsilon^\xi(U) := \{\alpha : \alpha, \alpha + \xi \in \mathcal{Z}_{r'}(\mathcal{L}), \varepsilon x_\alpha, \varepsilon x_{\alpha+\xi} \in P_k^{-1}U\}.$$

Note that by (2-2), enlarging M if necessary, it is enough to consider

$$\xi \in r'\mathbb{Z}_M^d := r'\mathbb{Z}^d \cap (\mathbb{R}^k \times [-2M, 2M]^{d-k}).$$

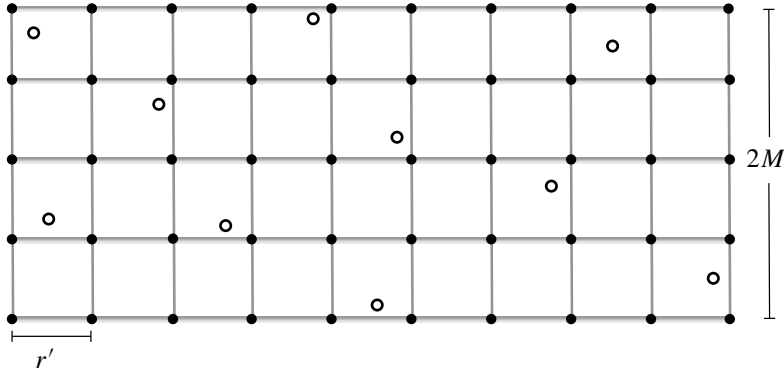


Figure 2. The particles in \mathcal{L} (circles) and the auxiliary lattice $r'\mathbb{Z}^d$ (black dots).

We can then rewrite the localized energy as

$$E_\varepsilon(u, A) = \sum_{\xi \in r'\mathbb{Z}_M^d} \sum_{\alpha \in R_\varepsilon^\xi(A)} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u(\varepsilon x_\alpha), u(\varepsilon x_{\alpha+\xi})).$$

Remark 2.6. Observe that we can write

$$\{\xi \in r'\mathbb{Z}_M^d\} = \bigcup_{\substack{z \in r'\mathbb{Z}^{d-k} \\ |z|_\infty \leq 2M}} \{\xi = (\xi_k, z_1, \dots, z_{d-k}) : \xi_k \in r'\mathbb{Z}^k\}.$$

Hence the monotonicity assumption from [Hypothesis 1](#) allows to transfer the decay of long-range interactions to the discrete environment as follows: given $\delta > 0$, there exists $L_\delta > 0$ such that

$$\sum_{\substack{\xi \in r'\mathbb{Z}_M^d \\ |\hat{\xi}| > L_\delta}} J_{lr}(|\hat{\xi}|) |\xi| \leq \delta, \tag{2-12}$$

where $\hat{\xi} \in \xi + [-r', r']^d$ is such that $|\hat{\xi}| = \text{dist}([0, r']^d, [0, r']^d + \xi)$. This decay property along with [Lemma 2.7](#) below will be crucial to control the long-range interactions. However note that L_δ in general depends on M .

The following lemma asserts that on convex domains we can essentially control the long-range interactions by considering only nearest neighbors.

Lemma 2.7. *Let $B \subset \mathcal{A}(\mathbb{R}^k)$ be convex and $B^\varepsilon = \{x \in \mathbb{R}^k : \text{dist}(x, B) < 3(R + M)\varepsilon\}$. Then there exists a constant C depending only on r, R, M in [Definition 2.1](#) such that for every $\xi \in r'\mathbb{Z}_M^d$ and every $u : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$ it holds that*

$$\sum_{\alpha \in R_\varepsilon^\xi(B)} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u(\varepsilon x_\alpha), u(\varepsilon x_{\alpha+\xi})) \leq C J_{lr}(|\hat{\xi}|) |\xi| \sum_{\substack{(x,y) \in \mathcal{NN}(\mathcal{L}) \\ \varepsilon x, \varepsilon y \in P_k^{-1} B^\varepsilon}} f_\varepsilon(x, y, u(\varepsilon x), u(\varepsilon y)).$$

Proof. Let $\alpha \in R_\varepsilon^\xi(B)$. As in the proof of [Lemma 2.4](#) we consider the collection of segments $\mathcal{G}_\delta(x_\alpha, x_{\alpha+\xi})$ defined as in (2-6). By the same argument, there exists a segment $g^* \subset \mathcal{G}_\delta(x_\alpha, x_{\alpha+\xi})$ satisfying (2-7).

Consider then the set $G(\alpha, \xi) = \{x \in \mathcal{L} : g^* \cap \mathcal{C}(x) \neq \emptyset\}$. By construction we can number $G(\alpha, \xi) = \{x_\alpha = x^0, \dots, x^N = x_{\alpha+\xi}\}$ such that $(x^i, x^{i+1}) \in \mathcal{NN}(\mathcal{L})$. By the bounds of [Hypothesis 1](#) it holds that

$$\begin{aligned} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u(\varepsilon x_\alpha), u(\varepsilon x_{\alpha+\xi})) &\leq J_{lr}(|\hat{\xi}|) |u(\varepsilon x_\alpha) - u(\varepsilon x_{\alpha+\xi})| \leq J_{lr}(|\hat{\xi}|) \sum_{\substack{(x,y) \in \mathcal{NN}(\mathcal{L}) \\ x,y \in G(\alpha,\xi)}} |u(\varepsilon x) - u(\varepsilon y)| \\ &\leq C J_{lr}(|\hat{\xi}|) \sum_{\substack{(x,y) \in \mathcal{NN}(\mathcal{L}) \\ x,y \in (1/\varepsilon)P_k^{-1}B^\varepsilon \cap G(\alpha,\xi)}} f_\varepsilon(x, y, u(\varepsilon x), u(\varepsilon y)), \end{aligned} \tag{2-13}$$

where we used that by convexity we have $G(\alpha, \xi) \subset \frac{1}{\varepsilon}P_k^{-1}B^\varepsilon$ provided δ is small enough. Now given $(x, y) \in \mathcal{NN}(\mathcal{L}) \cap \frac{1}{\varepsilon}P_k^{-1}B^\varepsilon$ we set

$$T_\varepsilon^\xi(x, y) := \{\alpha \in R_\varepsilon^\xi(B) : \{x, y\} \cap G(\alpha, \xi) \neq \emptyset\}.$$

Note that if $\alpha \in T_\varepsilon^\xi(x, y)$, then

$$x_\alpha \in \{z + t\xi : |z - x| \leq C, |t| \leq C\}$$

for some $C > 0$, and hence $\#T_\varepsilon^\xi(x, y) \leq C|\xi|$ by [Definition 2.1](#). The claim now follows by summing [\(2-13\)](#) over all $\alpha \in R_\varepsilon^\xi(B)$. □

3. Integral representation on the flat set

Our first aim is to characterize all possible variational limits of energies E_ε that satisfy [Hypothesis 1](#). As for the case $k = d$ and $\mathcal{S} = \{\pm 1\}$ treated in [\[Alicandro et al. 2015\]](#), the following version of Theorem 3 in [\[Bouchitté et al. 2002\]](#) will be the key ingredient:

Theorem 3.1. *Let $\mathcal{F} : \text{BV}(D, \mathcal{S}) \times \mathcal{A}(D) \rightarrow [0, +\infty)$ satisfy the following hypotheses:*

- (i) $\mathcal{F}(u, \cdot)$ is the restriction to $\mathcal{A}(D)$ of a Radon measure.
- (ii) $\mathcal{F}(u, A) = \mathcal{F}(v, A)$ whenever $u = v$ a.e. on $A \in \mathcal{A}(D)$.
- (iii) $\mathcal{F}(\cdot, A)$ is $L^1(D)$ lower semicontinuous for every $A \in \mathcal{A}(D)$.
- (iv) There exists $c > 0$ such that

$$\frac{1}{c} \mathcal{H}^{k-1}(S_u \cap A) \leq \mathcal{F}(u, A) \leq c \mathcal{H}^{k-1}(S_u \cap A)$$

for every $(u, A) \in \text{BV}(D, \mathcal{S}) \times \mathcal{A}(D)$.

Then for every $u \in \text{BV}(D, \mathcal{S})$ and $A \in \mathcal{A}(D)$,

$$\mathcal{F}(u, A) = \int_{S_u \cap A} g(x, u^+, u^-, \nu_u) d\mathcal{H}^{k-1},$$

with

$$g(x_0, s_i, s_j, \nu) = \limsup_{\rho \rightarrow 0} \frac{m(u_{x_0, \nu}^{ij}, Q_\nu(x_0, \rho))}{\rho^{k-1}},$$

where, for all $s_i, s_j \in \mathcal{S}$,

$$u_{x_0, v}^{ij} := \begin{cases} s_i & \text{if } \langle x - x_0, v \rangle \geq 0, \\ s_j & \text{otherwise,} \end{cases}$$

and for any $(v, A) \in \text{BV}(D, \mathcal{S}) \times \mathcal{A}(D)$ we set

$$m(v, A) = \inf \{ \mathcal{F}(u, A) : u \in \text{BV}(A, \mathcal{S}), u = v \text{ in a neighborhood of } \partial A \}.$$

The following theorem is the main result of this section.

Theorem 3.2. *Let \mathcal{L} be a thin admissible lattice and let f_{nn}^ε and f_{lr}^ε satisfy [Hypothesis 1](#). For every sequence of $\varepsilon \rightarrow 0^+$ there exists a subsequence ε_n such that the functionals E_{ε_n} Γ -converge with respect to the convergence of [Definition 2.2](#) with $A = D$ to a functional $E : L^1(D, \mathbb{R}^q) \rightarrow [0, +\infty]$ of the form*

$$E(u) = \begin{cases} \int_{S_u} \phi(x, u^+, u^-, \nu_u) \, d\mathcal{H}^{k-1} & \text{if } u \in \text{BV}(D, \mathcal{S}), \\ +\infty & \text{otherwise.} \end{cases}$$

Moreover, a local version of the statement above holds: for all $u \in \text{BV}(D, \mathcal{S})$ and all $A \in \mathcal{A}^R(D)$,

$$\Gamma\text{-}\lim_n E_{\varepsilon_n}(u, A) = \int_{S_u \cap A} \phi(x, u^+, u^-, \nu_u) \, d\mathcal{H}^{k-1},$$

with respect to the same convergence as above.

Remark 3.3. If $k = 1$, then a similar result holds. In this case we obtain a limit energy finite for $u \in \text{BV}(D, \mathcal{S})$ and of the form

$$E(u) = \sum_{x \in S_u} \phi(x, u^+, u^-).$$

The proof of [Theorem 3.2](#) will be given later and it is based on [Theorem 3.1](#). We now start proving several propositions that allow us to apply [Theorem 3.1](#).

We start with the growth condition (iv) of [Theorem 3.1](#). Using the lower semicontinuity of the perimeter of level sets in $\text{BV}(D, \mathcal{S})$, one can use the same argument as for [Lemma 2.4](#) to prove the following lower bound for $E'(u, A)$ defined in (2-5):

Proposition 3.4. *Assume that [Hypothesis 1](#) holds. Then $E'(u, A) < +\infty$ only if $u \in \text{BV}(A, \mathcal{S})$ and there exists a constant $c > 0$ independent of A such that*

$$\frac{1}{c} \mathcal{H}^{k-1}(S_u \cap A) \leq E'(u, A).$$

In the next step we provide a suitable upper bound for $E''(u, A)$ defined in (2-5).

Proposition 3.5. *Assume [Hypothesis 1](#) holds. Then there exists a constant $c > 0$ such that, for all $A \in \mathcal{A}^R(D)$ and all $u \in \text{BV}(D, \mathcal{S})$,*

$$E''(u, A) \leq c \mathcal{H}^{k-1}(S_u \cap A).$$

Proof. First, assume that u is a polyhedral function on \mathbb{R}^k , which means that all level sets have boundaries that coincide (up to \mathcal{H}^{k-1} -null sets) with a finite union of $(k-1)$ -dimensional simplexes. We define a sequence $u_\varepsilon : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$ by setting

$$u_\varepsilon(\varepsilon x) := u(\varepsilon P_k(x)).$$

Note that $u_\varepsilon \rightarrow u$ in the sense of [Definition 2.2](#). Given $\delta > 0$, we choose $L_\delta > 0$ such that [\(2-12\)](#) holds. We further set $A^\delta = A + B_\delta(0)$. For $|\xi| \leq L_\delta$, we can argue as in the proof of [Lemma 2.7](#) to show that, for ε small enough, it holds that

$$\begin{aligned} \sum_{\alpha \in R_\varepsilon^\xi(A)} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u_\varepsilon(\varepsilon x_\alpha), u_\varepsilon(\varepsilon x_{\alpha+\xi})) &\leq C J_{lr}(|\hat{\xi}|) |\xi| \sum_{\substack{(x,y) \in \mathcal{NN}(\mathcal{L}) \\ \varepsilon x, \varepsilon y \in P_k^{-1} A^\delta}} \varepsilon^{k-1} |u_\varepsilon(\varepsilon x) - u_\varepsilon(\varepsilon y)| \\ &\leq C J_{lr}(|\hat{\xi}|) |\xi| \mathcal{H}^{k-1}(S_u \cap A^\delta), \end{aligned} \quad (3-14)$$

where the last estimate follows from the regularity of S_u . Next we consider the interactions where $|\xi| > L_\delta$. Let u be a polyhedral function; applying [Lemma 2.7](#) we deduce for any $\varepsilon > 0$ the weaker bound

$$\begin{aligned} \sum_{\alpha \in R_\varepsilon^\xi(A)} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u_\varepsilon(\varepsilon x_\alpha), u_\varepsilon(\varepsilon x_{\alpha+\xi})) &\leq \sum_{\alpha \in R_\varepsilon^\xi(\mathbb{R}^k)} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u_\varepsilon(\varepsilon x_\alpha), u_\varepsilon(\varepsilon x_{\alpha+\xi})) \\ &\leq C J_{lr}(|\hat{\xi}|) |\xi| \mathcal{H}^{k-1}(S_u). \end{aligned} \quad (3-15)$$

Combining [\(3-14\)](#), [\(3-15\)](#) and [\(2-12\)](#) and the integrability assumption from [Hypothesis 1](#), we deduce that

$$E''(u, A) \leq \limsup_\varepsilon E_\varepsilon(u_\varepsilon, A) \leq C \mathcal{H}^{k-1}(S_u \cap A^\delta) + C \delta \mathcal{H}^{k-1}(S_u).$$

As $\delta > 0$ was arbitrary we obtain

$$E''(u, A) \leq C \mathcal{H}^{k-1}(S_u \cap \bar{A}). \quad (3-16)$$

Now we use locality and a density argument. Indeed, for every $u \in \text{BV}(D, S)$ we can find a function $\tilde{u} \in \text{BV}_{\text{loc}}(\mathbb{R}^k, S)$ such that $u = \tilde{u}$ on A and $\mathcal{H}^{k-1}(S_{\tilde{u}} \cap \partial A) = 0$; see [Lemma 2.7](#) in [\[Braides et al. 2017\]](#). From [Remark 2.3](#) it follows that $E''(u, A) = E''(\tilde{u}, A)$. Then, by [\[Braides et al. 2017, Corollary 2.4\]](#) there exists a sequence $u_n \in \text{BV}_{\text{loc}}(\mathbb{R}^k, S)$ of polyhedral functions such that $u_n \rightarrow \tilde{u}$ in $L^1(D)$ and $\mathcal{H}^{k-1}(S_{u_n} \cap D) \rightarrow \mathcal{H}^{k-1}(S_{\tilde{u}} \cap D)$. By the $L^1(D)$ -lower semicontinuity of $E''(\cdot, A)$ stated in [Remark 2.3](#) and [\(3-16\)](#), we obtain

$$E''(u, A) \leq \liminf_n E''(u_n, A) \leq C \limsup_n \mathcal{H}^{k-1}(S_{u_n} \cap \bar{A}) \leq C \mathcal{H}^{k-1}(S_{\tilde{u}} \cap \bar{A}) = C \mathcal{H}^{k-1}(S_u \cap A),$$

where the last inequality is a consequence of the $L^1(D)$ -lower semicontinuity of $u \mapsto \mathcal{H}^{k-1}(S_u \cap D \setminus \bar{A})$ for $u \in \text{BV}(D, S)$. \square

As is usual for applying integral-representation theorems, we next establish a weak subadditivity property of $A \mapsto E''(u, A)$.

Proposition 3.6. *Let f_{nn}^ε and f_{lr}^ε satisfy [Hypothesis 1](#). Then, for every $A, B \in \mathcal{A}^R(D)$, every $A' \subset \mathcal{A}^R(D)$ such that $A' \Subset A$ and every $u \in \text{BV}(D, S)$,*

$$E''(u, A' \cup B) \leq E''(u, A) + E''(u, B).$$

Proof. We may assume that $E''(u, A)$ and $E''(u, B)$ are both finite. Let $u_\varepsilon, v_\varepsilon : \varepsilon \mathcal{L} \rightarrow S$ both converge to u in the sense of [Definition 2.2](#) such that

$$\limsup_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon, A) = E''(u, A), \quad \limsup_{\varepsilon \rightarrow 0} E_\varepsilon(v_\varepsilon, B) = E''(u, B). \quad (3-17)$$

Step 1: extensions to convex domains. Let Q_D be a cube containing \bar{D} . Since $D \in \mathcal{A}^R(D)$, we can extend u (without relabeling) to a function $u \in \text{BV}_{\text{loc}}(\mathbb{R}^k, \mathcal{S})$. We first show that we can modify u_ε and v_ε on $\varepsilon\mathcal{L} \setminus A$ and $\varepsilon\mathcal{L} \setminus B$ respectively, such that they converge to u on $L^1(Q_D)$ and such that they have equibounded energy on the larger set Q_D . We will show the argument for u_ε . Take another cube Q' such that $Q_D \Subset Q'$. Arguing as in the proof of [Proposition 3.5](#), we find a sequence $\tilde{u}_\varepsilon : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$ such that $\tilde{u}_\varepsilon \rightarrow u$ on Q' and $\limsup_{\varepsilon \rightarrow 0} E_\varepsilon(\tilde{u}_\varepsilon, Q') \leq C\mathcal{H}^{k-1}(S_u \cap Q')$. We then set $\bar{u} \in \mathcal{PC}_\varepsilon(\mathcal{L})$ as

$$\bar{u}(\varepsilon x) = \mathbb{1}_A(P_k(\varepsilon x))u_\varepsilon(\varepsilon x) + (1 - \mathbb{1}_A(P_k(\varepsilon x)))\tilde{u}_\varepsilon(\varepsilon x).$$

Then $\bar{u}_\varepsilon \rightarrow u$ on Q_D and applying [Lemma 2.7](#) combined with [Hypothesis 1](#) and (2-2) yields

$$\begin{aligned} E_\varepsilon(\bar{u}_\varepsilon, Q_D) &\leq C \sum_{\xi \in r'\mathbb{Z}_M^d} J_{lr}(|\hat{\xi}|)|\xi| \sum_{\substack{(x,y) \in \mathcal{NN}(\mathcal{L}) \\ \varepsilon x, \varepsilon y \in Q'}} \varepsilon^{k-1} f_\varepsilon(x, y, \bar{u}_\varepsilon(\varepsilon x), \bar{u}_\varepsilon(\varepsilon y)) \\ &\leq C \left(E_\varepsilon(u_\varepsilon, A) + E_\varepsilon(\tilde{u}_\varepsilon, Q' \setminus A) + \frac{1}{\varepsilon} |\partial A + B_{4R\varepsilon}(0)| \right). \end{aligned}$$

The first and second terms remain bounded by construction, while the third term converges to a multiple of the Minkowski content of ∂A which agrees with $\mathcal{H}^{k-1}(\partial A)$ as $A \in \mathcal{A}^R(D)$.

Step 2: energy estimates. Again, given $\delta > 0$ we choose L_δ such that (2-12) holds. Fix $d' \leq \frac{1}{2} \text{dist}(A', \partial A)$ and let

$$N_\varepsilon := \left\lfloor \frac{d'}{\varepsilon(L_\delta + 2r)} \right\rfloor,$$

where $\lfloor \cdot \rfloor$ denotes the integer part. For $j \in \mathbb{N}$ we define

$$A_{\varepsilon,j} := \{x \in A : \text{dist}(x, A') < j\varepsilon(L_\delta + 2r)\}.$$

We let $w_\varepsilon^j \in \mathcal{PC}_\varepsilon(\mathcal{L})$ be the interpolation defined by

$$w_\varepsilon^j(\varepsilon x) = \mathbb{1}_{A_{\varepsilon,j}}(P_k(\varepsilon x))u_\varepsilon(\varepsilon x) + (1 - \mathbb{1}_{A_{\varepsilon,j}}(P_k(\varepsilon x)))v_\varepsilon(\varepsilon x).$$

Note that for each fixed $j \in \mathbb{N}$, we have $w_\varepsilon^j \rightarrow u$ on D in the sense of [Definition 2.2](#). We set

$$S_j^{\xi, \varepsilon} := \{x = y + tP_k(\xi') : y \in \partial A_{\varepsilon,j}, |t| \leq \varepsilon, \xi' \in \xi + [-r', r']^d\} \cap (A \cup B).$$

For $j \leq N_\varepsilon$ we have

$$\begin{aligned} E_\varepsilon(w_\varepsilon^j, A' \cup B) &\leq E_\varepsilon(u_\varepsilon, A_{\varepsilon,j}) + E_\varepsilon(v_\varepsilon, B \setminus A_{\varepsilon,j}) + \sum_{\xi \in r'\mathbb{Z}_M^d} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi, \varepsilon})} \underbrace{\varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, w_\varepsilon^j(\varepsilon x_\alpha), w_\varepsilon^j(\varepsilon x_{\alpha+\xi}))}_{=: \rho_j^{\xi, \varepsilon}(\alpha)} \\ &\leq E_\varepsilon(u_\varepsilon, A) + E_\varepsilon(v_\varepsilon, B) + \sum_{\xi \in r'\mathbb{Z}_M^d} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi, \varepsilon})} \rho_j^{\xi, \varepsilon}(\alpha). \end{aligned} \quad (3-18)$$

We now distinguish between two types of interactions depending on L_δ . If $|\xi| > L_\delta$, we use [Lemma 2.7](#).

Since $A \cup B \Subset Q_D$, we deduce that

$$\sum_{|\xi| > L_\delta} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi, \varepsilon})} \rho_j^{\xi, \varepsilon}(\alpha) \leq C \sum_{|\xi| > L_\delta} J_{lr}(|\hat{\xi}|)|\xi| \sum_{\substack{(x,y) \in \mathcal{NN}(\mathcal{L}) \\ \varepsilon x, \varepsilon y \in P_k^{-1}Q_D}} \varepsilon^{k-1} f_\varepsilon(x, y, w_\varepsilon^j(\varepsilon x), w_\varepsilon^j(\varepsilon y)).$$

We have $P_k^{-1}Q_D \subset P_k^{-1}A_{\varepsilon,j} \cup P_k^{-1}(Q_D \setminus A_{\varepsilon,j})$. Nearest-neighbor interactions between those two sets are contained in $P_k^{-1}S_k^{\xi,\varepsilon}$ for some $\xi \in r'\mathbb{Z}_M^d$ with $|\xi| \leq 4R$. Therefore, we can further estimate the last inequality via

$$\sum_{|\xi| > L_\delta} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi,\varepsilon})} \rho_j^{\xi,\varepsilon}(\alpha) \leq C\delta \left(E_\varepsilon(u_\varepsilon, A) + E_\varepsilon(v_\varepsilon, Q_D) \right) + \sum_{|\xi| \leq L_\delta} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi,\varepsilon})} \rho_j^{\xi,\varepsilon}(\alpha). \quad (3-19)$$

Now we treat the interactions when $|\xi| \leq L_\delta$. Consider any points $\varepsilon x, \varepsilon y \in \varepsilon\mathcal{L}$. If $w_\varepsilon^j(\varepsilon x) \neq w_\varepsilon^j(\varepsilon y)$ then $\varepsilon x, \varepsilon y \in A_{\varepsilon,j}$, $\varepsilon x, \varepsilon y \notin A_{\varepsilon,j}$ or $\varepsilon x \in A_{\varepsilon,j}$ but $\varepsilon y \notin A_{\varepsilon,j}$ (the reverse case can be treated similarly). In the last case we have a contribution only if $u_\varepsilon(\varepsilon x) \neq v_\varepsilon(\varepsilon y)$. Then either $u_\varepsilon(\varepsilon y) = v_\varepsilon(\varepsilon y)$ or $f_\varepsilon(x, y, u_\varepsilon(\varepsilon x), v_\varepsilon(\varepsilon y)) \leq C|u_\varepsilon(\varepsilon y) - v_\varepsilon(\varepsilon y)|$. Summarizing all cases we obtain the inequality

$$\rho_j^{\xi,\varepsilon}(\alpha) \leq \varepsilon^{k-1} f_\varepsilon(x, y, u_\varepsilon(\varepsilon x), u_\varepsilon(\varepsilon y)) + \varepsilon^{k-1} f_\varepsilon(x, y, v_\varepsilon(\varepsilon x), v_\varepsilon(\varepsilon y)) + C\varepsilon^{k-1} |u_\varepsilon(\varepsilon y) - v_\varepsilon(\varepsilon y)|.$$

By our construction we have $S_j^{\varepsilon,\xi} \subset (A_{\varepsilon,j+1} \setminus A_{\varepsilon,j-1}) =: S_j^\varepsilon$. We deduce that

$$\sum_{|\xi| \leq L_\delta} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi,\varepsilon})} \rho_j^{\xi,\varepsilon}(\alpha) \leq E_\varepsilon(u_\varepsilon, S_j^\varepsilon) + E_\varepsilon(v_\varepsilon, S_j^\varepsilon) + C_\delta \sum_{\substack{y \in \mathcal{L} \\ \varepsilon P_k(y) \in S_j^\varepsilon}} \varepsilon^{k-1} |u_\varepsilon(\varepsilon y) - v_\varepsilon(\varepsilon y)|,$$

where C_δ depends only on L_δ . Observe that by definition every point can only lie in at most two sets $S_{j_1}^\varepsilon, S_{j_2}^\varepsilon$. Thus averaging combined with (3-19), Step 1 and the last inequality yields

$$\begin{aligned} I_\varepsilon &:= \frac{1}{N_\varepsilon} \sum_{j=1}^{N_\varepsilon} \sum_{\xi \in r'\mathbb{Z}_M^d} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi,\varepsilon})} \rho_j^{\xi,\varepsilon}(\alpha) \leq \frac{2}{N_\varepsilon} \sum_{j=1}^{N_\varepsilon} \sum_{|\xi| \leq L_\delta} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi,\varepsilon})} \rho_j^{\xi,\varepsilon}(\alpha) + C\delta \\ &\leq \frac{4}{N_\varepsilon} (E_\varepsilon(u_\varepsilon, Q_D) + E_\varepsilon(v_\varepsilon, Q_D)) + C_\delta \sum_{\substack{y \in \mathcal{L} \\ \varepsilon P_k(y) \in D}} \varepsilon^d |u_\varepsilon(\varepsilon y) - v_\varepsilon(\varepsilon y)| + C\delta \\ &\leq \frac{C}{N_\varepsilon} + C_\delta \sum_{\substack{y \in \mathcal{L} \\ \varepsilon P_k(y) \in D}} \varepsilon^d |u_\varepsilon(\varepsilon y) - v_\varepsilon(\varepsilon y)| + C\delta. \end{aligned}$$

Due to Step 1 we can apply Lemma 2.5 to deduce that $\limsup_{\varepsilon \rightarrow 0} I_\varepsilon \leq C\delta$. For every $\varepsilon > 0$, let $j_\varepsilon \in \{1, \dots, N_\varepsilon\}$ be such that

$$\sum_{\xi \in r'\mathbb{Z}_M^d} \sum_{\alpha \in R_\varepsilon^\xi(S_{j_\varepsilon}^{\xi,\varepsilon})} \rho_{j_\varepsilon}^{\xi,\varepsilon}(\alpha) \leq I_\varepsilon \quad (3-20)$$

and set $w_\varepsilon := w_\varepsilon^{j_\varepsilon}$. Note that, as a convex combination, w_ε still converges to u on D . Hence, using (3-18) and (3-20), we conclude that

$$E''(u, A' \cup B) \leq \limsup_{\varepsilon \rightarrow 0} E_\varepsilon(w_\varepsilon, A' \cup B) \leq E''(u, A) + E''(u, B) + C\delta.$$

The arbitrariness of δ proves the claim. □

Proof of Theorem 3.2. From Propositions 3.5 and 3.6 it follows by standard arguments that $E''(u, \cdot)$ is inner regular on $\mathcal{A}^R(D)$; see, for example, Proposition 11.6 in [Braides and Defranceschi 1998]. Therefore, given a sequence $\varepsilon_n \rightarrow 0^+$ we can use Remark 2.3 and the compactness property of Γ -convergence, see [Braides 2002, Section 1.8.2], to construct a subsequence ε_n (not relabeled) such that

$$\Gamma\text{-}\lim_n E_{\varepsilon_n}(u, A) =: \tilde{E}(u, A)$$

exists for every $(u, A) \in L^1(D) \times \mathcal{A}^R(D)$. By Proposition 3.4 we know that $\tilde{E}(u, A)$ is finite only if $u \in \text{BV}(A, \mathcal{S})$. We extend $\tilde{E}(u, \cdot)$ to $\mathcal{A}(D)$ setting

$$E(u, A) := \sup\{\tilde{E}(u, A') : A' \Subset A, A' \in \mathcal{A}^R(D)\}.$$

To complete the proof, it is enough to show that E satisfies the assumptions of Theorem 3.1. Again by standard arguments $E(u, \cdot)$ fulfills the assumptions of the De Giorgi–Letta criterion [Braides 2002, Section 16] so that $E(u, \cdot)$ is the trace of a Borel measure. By Proposition 3.5, it is indeed a Radon measure. The locality property follows from Remark 2.3. By the properties of Γ -limits and again Remark 2.3 we know that $\tilde{E}(\cdot, A)$ is $L^1(D)$ -lower semicontinuous and so is $E(\cdot, A)$ as the supremum of lower semicontinuous functions. The growth conditions (iv) in Theorem 3.1 follow from Propositions 3.4 and 3.5, which still hold for E in place of \tilde{E} . The local version of the theorem is a direct consequence of our construction. \square

4. Convergence of boundary value problems

In this section we consider the convergence of minimum problems with Dirichlet-type boundary data. In order to model boundary conditions in our discrete setting we need to introduce a suitable notion of trace, taking into account possible long-range interactions; see also [Alicandro et al. 2015]. In what follows we will further assume a continuous spatial dependence of the integrand of the limit continuum energy. Without such a condition we can still obtain a weaker result stated in Lemma 4.3. On the other hand continuity assumptions are always fulfilled in the case of the homogenization problem that we are going to treat in Section 5.

Consider $A \in \mathcal{A}^R(D)$ and fix boundary data $u_0 \in \text{BV}(\mathbb{R}_{\text{loc}}^k, \mathcal{S})$. We assume the boundary data are well-prepared in the sense that, setting $u_{\varepsilon,0} \in \mathcal{PC}_\varepsilon(\mathcal{L})$ as $u_{\varepsilon,0}(\varepsilon x) = u_0(P_k(\varepsilon x))$, we have $u_{\varepsilon,0} \rightarrow u_0$ on D and

$$\limsup_{\varepsilon \rightarrow 0} E_\varepsilon(u_{\varepsilon,0}, B) \leq C \mathcal{H}^{k-1}(S_{u_0} \cap \bar{B}), \quad \mathcal{H}^{k-1}(S_{u_0} \cap \partial A) = 0, \quad (4-21)$$

with C independent of $B \in \mathcal{A}^R(\mathbb{R}^k)$. Observe that as in the proof of Proposition 3.5 we may allow for any polyhedral function such that $\mathcal{H}^{k-1}(S_{u_0} \cap \partial A) = 0$, but more generally it suffices that all level sets are Lipschitz sets.

We define a *discrete trace constraint* as follows: let $l_\varepsilon > 0$ be such that

$$\lim_{\varepsilon \rightarrow 0} l_\varepsilon = +\infty, \quad \lim_{\varepsilon \rightarrow 0} l_\varepsilon \varepsilon = 0. \quad (4-22)$$

We set $\mathcal{P}C_{\varepsilon, u_0}^{l_\varepsilon \varepsilon}(\mathcal{L}, A)$ as the space of those u that agree with u_0 at the discrete boundary of A , by setting

$$\mathcal{P}C_{\varepsilon, u_0}^{l_\varepsilon \varepsilon}(\mathcal{L}, A) := \left\{ u : \varepsilon\mathcal{L} \rightarrow \mathcal{S} : u(\varepsilon x) = u_0(P_k(\varepsilon x)) \text{ if } \text{dist}(P_k(\varepsilon x), \partial A) \leq l_\varepsilon \varepsilon \right\}.$$

For $\varepsilon > 0$ and $l_\varepsilon > 0$ we consider the restricted functional $E_{\varepsilon, u_0}^{l_\varepsilon}(\cdot, A) : \mathcal{P}C_{\varepsilon, u_0}^{l_\varepsilon \varepsilon}(\mathcal{L}, A) \rightarrow [0, +\infty]$ defined as

$$E_{\varepsilon, u_0}^{l_\varepsilon}(u, A) := E_\varepsilon(u, A). \tag{4-23}$$

We need some further notation. Given $u \in \text{BV}(D, \mathcal{S})$, we set $u_{A,0} : \mathbb{R}^k \rightarrow \mathcal{S}$ as

$$u_{A,0}(x) := \begin{cases} u(x) & \text{if } x \in A, \\ u_0(x) & \text{otherwise.} \end{cases}$$

Since A is regular we have $u_{A,0} \in \text{BV}_{\text{loc}}(\mathbb{R}^k, \mathcal{S})$. The following convergence result holds:

Theorem 4.1. *Let \mathcal{L} be a thin admissible lattice and let f_{nn}^ε and f_{lr}^ε satisfy [Hypothesis 1](#). For every sequence converging to 0, let ε_n and ϕ be as in [Theorem 3.2](#). Assume that the limit integrand ϕ is continuous on $D \times \mathcal{S}^2 \times \mathcal{S}^{k-1}$. Then, for every set $A \in \mathcal{A}^R(D)$, $A \Subset D$, the functionals $E_{\varepsilon_n, u_0}^{l_{\varepsilon_n}}(\cdot, A)$ defined in [\(4-23\)](#) Γ -converge with respect to the convergence on A in [Definition 2.2](#) to the functional*

$$E_{u_0}(\cdot, A) : L^1(D, \mathbb{R}^q) \rightarrow [0, +\infty]$$

that is finite only for $u \in \text{BV}(A, \mathcal{S})$, where it takes the form

$$E_{u_0}(u, A) = \int_{S_{u_{A,0}} \cap \bar{A}} \phi(x, u_{A,0}^+, u_{A,0}^-, \nu_{u_{A,0}}) d\mathcal{H}^{k-1}.$$

Proof. By [Proposition 3.4](#) we know that the limit energy is finite only for $u \in \text{BV}(A, \mathcal{S})$. To save notation, we replace the subsequence ε_n again by ε .

Lower bound: Without loss of generality let $u_\varepsilon \rightarrow u$ on A in the sense of [Definition 2.2](#) be such that

$$\liminf_\varepsilon E_{\varepsilon, u_0}^{l_\varepsilon}(u_\varepsilon, A) \leq C. \tag{4-24}$$

Passing to a subsequence, we may assume $u_\varepsilon \in \mathcal{P}C_{\varepsilon, u_0}^{l_\varepsilon \varepsilon}(\mathcal{L}, A)$. We define a new sequence $v_\varepsilon : \varepsilon\mathcal{L} \rightarrow \mathcal{S}$ by

$$v_\varepsilon(\varepsilon x) = \mathbb{1}_A(P_k(\varepsilon x))u_\varepsilon(\varepsilon x) + (1 - \mathbb{1}_A(P_k(\varepsilon x)))u_0(\varepsilon P_k(x)).$$

Note that by our assumptions on u_0 we have $v_\varepsilon \rightarrow u_{A,0}$ on D in the sense of [Definition 2.2](#). Now fix $A_1 \Subset A \Subset A_2$ such that $A_1, A_2 \in \mathcal{A}^R(D)$. Setting

$$S^{\xi, \varepsilon} := \{\alpha \in R_\varepsilon^\xi(A_2) : \varepsilon x_\alpha \in P_k^{-1}A, \varepsilon x_{\alpha+\xi} \notin P_k^{-1}A \text{ or vice versa}\},$$

it holds that

$$E_\varepsilon(v_\varepsilon, A_2) \leq E_{\varepsilon, u_0}^{l_\varepsilon}(u_\varepsilon, A) + E_\varepsilon(u_{\varepsilon,0}, A_2 \setminus \bar{A}_1) + \sum_{\xi \in r'\mathbb{Z}_M^d} \sum_{\alpha \in S^{\xi, \varepsilon}} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, v_\varepsilon(\varepsilon x_\alpha), v_\varepsilon(\varepsilon x_{\alpha+\xi})), \tag{4-25}$$

Given $\delta > 0$, let $L_\delta > 0$ be such that (2-12) holds. To bound the long-range interactions, we fix again a large cube Q_D containing \bar{D} . Then Lemma 2.7 and the coercivity assumption in Hypothesis 1 yield

$$\begin{aligned} & \sum_{|\xi| > L_\delta} \sum_{\alpha \in S^{\xi, \varepsilon}} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, v_\varepsilon(\varepsilon x_\alpha), v_\varepsilon(\varepsilon x_{\alpha+\xi})) \\ & \leq C \sum_{|\xi| > L_\delta} J_{lr}(|\hat{\xi}|) |\xi| \sum_{\substack{(x, y) \in \mathcal{NN}(\mathcal{L}) \\ \varepsilon x, \varepsilon y \in P_k^{-1} Q_D}} \varepsilon^{k-1} f_\varepsilon(x, y, v_\varepsilon(\varepsilon x), v_\varepsilon(\varepsilon y)) \\ & \leq C \delta \left(E_\varepsilon(u_\varepsilon, A) + E_\varepsilon(u_{\varepsilon, 0}, Q_D) + \sum_{|\xi| \leq L_\delta} \sum_{\alpha \in S^{\xi, \varepsilon}} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, v_\varepsilon(\varepsilon x_\alpha), v_\varepsilon(\varepsilon x_{\alpha+\xi})) \right). \end{aligned} \quad (4-26)$$

For interactions with $|\xi| \leq L_\delta$ and ε small enough, we have $S^{\xi, \varepsilon} \subset A_2 \setminus \bar{A}_1$. Moreover, if $l_\varepsilon > L_\delta + 2r$, then by the boundary conditions on u_ε we get

$$\sum_{|\xi| \leq L_\delta} \sum_{\alpha \in S^{\xi, \varepsilon}} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, v_\varepsilon(\varepsilon x_\alpha), v_\varepsilon(\varepsilon x_{\alpha+\xi})) \leq E_\varepsilon(u_{\varepsilon, 0}, A_2 \setminus \bar{A}_1).$$

From the local version of Theorem 3.2, (4-21), (4-24), (4-25) and (4-26) we infer

$$E(u_{A, 0}, A_2) \leq \liminf_{\varepsilon} E_{\varepsilon, u_0}^{l_\varepsilon}(u_\varepsilon, A) + C \delta (1 + \mathcal{H}^{d-1}(S_{u_0} \cap \bar{Q}_D)) + C \mathcal{H}^{d-1}(S_{u_0} \cap \bar{A}_2 \setminus A_1).$$

The lower bound follows by letting $A_2 \downarrow \bar{A}$ and $A_1 \uparrow A$ combined with (4-21) and the arbitrariness of δ .

Upper bound: We first provide a recovery sequence in the case when $u = u_0$ in a neighborhood of ∂A . Let $u_\varepsilon : \varepsilon \mathcal{L} \rightarrow \mathcal{S}$ converge to u on D in the sense of Definition 2.2 and be such that

$$\lim_{\varepsilon \rightarrow 0} E_\varepsilon(u_\varepsilon, A) = E(u, A). \quad (4-27)$$

Again, given $\delta > 0$ we let $L_\delta > 0$ be such that (2-12) holds. Now choose regular sets $A_1 \Subset A_2 \Subset A$ such that

$$u = u_0 \quad \text{on } A \setminus \bar{A}_1. \quad (4-28)$$

The remaining argument is similar to the proof of Proposition 3.6 and therefore we only sketch it. Fix $d' \leq \frac{1}{2} \text{dist}(A_1, \partial A_2)$ and set $N_\varepsilon = \lfloor d' / (\varepsilon(L_\delta + 2r)) \rfloor$. For $j \in \mathbb{N}$ we define the sets

$$A_{\varepsilon, j} := \{x \in A : \text{dist}(x, A_1) < j\varepsilon(L_\delta + 2r)\}.$$

We further define $u_\varepsilon^j : \varepsilon \mathcal{L} \rightarrow \mathcal{S}$ setting

$$u_\varepsilon^j(\varepsilon x) = \begin{cases} u_0(\varepsilon x) & \text{if } P_k(\varepsilon x) \notin A_{\varepsilon, j}, \\ u_\varepsilon(\varepsilon x) & \text{otherwise.} \end{cases}$$

It holds that

$$E_\varepsilon(u_\varepsilon^j, A) \leq E_\varepsilon(u_\varepsilon, A) + E_\varepsilon(u_{\varepsilon, 0}, A \setminus \bar{A}_1) + \sum_{\xi \in r' \mathbb{Z}_M^d} \varepsilon^{k-1} \sum_{\alpha \in R_\varepsilon^{\xi, \varepsilon}(S_j^{\xi, \varepsilon})} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u_\varepsilon^j(\varepsilon x_\alpha), u_\varepsilon^j(\varepsilon x_{\alpha+\xi})),$$

where the set $S_j^{\xi, \varepsilon}$ is defined as

$$S_j^{\xi, \varepsilon} := \{x = y + tP_k(\xi') : y \in \partial A_{\varepsilon, j}, |t| \leq \varepsilon, \xi' \in \xi + [-r', r']^d\} \cap A.$$

As for (4-26), using (4-21) and (4-27) we can show that

$$\begin{aligned} \sum_{\xi \in r' \mathbb{Z}_M^d} \varepsilon^{k-1} \sum_{\alpha \in R_\varepsilon^\xi(S_j^{\xi, \varepsilon})} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u_\varepsilon^j(\varepsilon x_\alpha), u_\varepsilon^j(\varepsilon x_{\alpha+\xi})) \\ \leq C\delta + C \sum_{|\xi| \leq L_\delta} \sum_{\alpha \in \mathbb{K}_\varepsilon(S_j^{\xi, \varepsilon})} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, u_\varepsilon^j(\varepsilon x_\alpha), u_\varepsilon^j(\varepsilon x_{\alpha+\xi})). \end{aligned}$$

To estimate the interactions where $|\xi| \leq L_\delta$, note that due to (4-28) we can use the averaging technique like in Step 2 of Proposition 3.6 to obtain $j_\varepsilon \in \{1, \dots, N_\varepsilon\}$ and the corresponding sequence $u_\varepsilon^{j_\varepsilon}$ satisfying the boundary conditions, at least for small ε because of (4-22), such that

$$\limsup_n E_{\varepsilon, u_0}^{l_\varepsilon}(u_\varepsilon^{j_\varepsilon}, A) \leq E(u, A) + C\mathcal{H}^{k-1}(S_{u_0} \cap (\bar{A} \setminus A_1)) + C\delta,$$

where we used (4-21). Moreover, due to the assumptions on u_0 and (4-28) we know that $u_\varepsilon^{j_\varepsilon} \rightarrow u$ on A . Letting first $\delta \rightarrow 0$ and then $A_1 \uparrow A$ we finally get

$$\Gamma\text{-}\limsup_\varepsilon E_{\varepsilon, u_0}^{l_\varepsilon}(u, A) \leq E(u, A) = E_{u_0}(u, A).$$

For a general function $u \in \text{BV}(A, \mathcal{S})$ we argue by approximation. To this end we take any $B \in \mathcal{A}^R(D)$ such that $A \Subset B$. By Lemma B.1 we obtain a sequence $u_n \in \text{BV}(D, \mathcal{S})$ such that $u_n = u_0$ in a neighborhood of ∂A and moreover $u_n \rightarrow u_{A,0}$ in $L^1(B)$ and $\mathcal{H}^{k-1}(S_{u_n} \cap B) \rightarrow \mathcal{H}^{k-1}(S_u \cap B)$. By $L^1(A)$ -lower semicontinuity and the previous argument we obtain

$$\Gamma\text{-}\limsup_\varepsilon E_{\varepsilon, u_0}^{l_\varepsilon}(u, A) \leq \liminf_n E(u_n, A) \leq \liminf_n E(u_n, B) = E(u_{A,0}, B).$$

In the last step we used the continuity assumption on the integrand and a Reshetnyak-type continuity result for functionals defined on partitions that is proven in [Ruf 2017]. Letting $B \downarrow \bar{A}$ we obtain the claim. \square

Remark 4.2. (i) It is a direct consequence of our proof, that if we have only finite range of interactions, that is $f_{lr}^\varepsilon(x, y) = 0$ for $|x - y| \geq L$, then it is enough to take $l_\varepsilon \geq L$.

(ii) By Remark 2.3 the above Theorem 4.1 implies the usual convergence of minimizers in the spirit of Γ -convergence.

Finally we prove an auxiliary result about convergence of boundary value problems that holds without any continuity assumptions. This result will be useful to treat homogenization problems as in Section 5. To this end we replace the discrete width l_ε by a macroscopic value η and then take first the limit when $\varepsilon \rightarrow 0$ and let $\eta \rightarrow 0$ in a second step. Given $\eta > 0$ and $A \in \mathcal{A}^R(D)$, we set

$$\partial A_\eta = \{x \in A : \text{dist}(x, \partial A) \leq \eta\}.$$

We let u_0 be as before. Using a similar notation to that in Theorem 3.1 we define the quantities

$$\begin{aligned} m_\varepsilon^\eta(u_0, A) &= \inf\{E_\varepsilon(v, A) : v \in \mathcal{PC}_{\varepsilon, u_0}^\eta(\mathcal{L}, A)\}, \\ m(u_0, A) &= \inf\{E(v, A) : v = u_0 \text{ in a neighborhood of } \partial A\}, \end{aligned}$$

where the limit functional E is given (up to subsequences) by Theorem 3.2. Note that the mapping $\eta \mapsto m_\varepsilon^\eta(u_0, A)$ is nondecreasing. Then we have the following weak version of Theorem 4.1.

Lemma 4.3. *Let ε_n and E be as in Theorem 3.2. Then it holds that*

$$\lim_{\eta \rightarrow 0} \liminf_n m_{\varepsilon_n}^\eta(u_0, A) = \lim_{\eta \rightarrow 0} \limsup_n m_{\varepsilon_n}^\eta(u_0, A) = m(u_0, A).$$

Proof. First note that by monotonicity the limits for $\eta \rightarrow 0$ are well-defined. Moreover, by the first assumption in (4-21) we have that $m_\varepsilon^\eta(u_0, A)$ is equibounded. Now for any $n \in \mathbb{N}$ let $u_n \in \mathcal{PC}_{\varepsilon_n, u_0}^\eta(\mathcal{L}, A)$ be such that $m_{\varepsilon_n}^\eta(u_0, A) = E_{\varepsilon_n}(u_n, A)$. By Lemma 2.4 we know that, up to a subsequence (not relabeled), $u_n \rightarrow u$ on A and by the assumptions on u_0 it follows that $u = u_0$ on ∂A_η . Extending u we can assume that u is admissible in the infimum problem defining $m(u_0, A)$ and using Theorem 3.2 we obtain

$$m(u_0, A) \leq E(u, A) \leq \liminf_n E_{\varepsilon_n}(u_n, A) \leq \liminf_n m_{\varepsilon_n}^\eta(u_0, A).$$

Since η is arbitrary, we conclude that $m(u_0, A) \leq \lim_{\eta \rightarrow 0} \liminf_n m_{\varepsilon_n}^\eta(u_0, A)$.

In order to prove the remaining inequality, given $\gamma > 0$ we let $u \in \text{BV}(A, \mathcal{S})$ be such that $u = u_0$ in a neighborhood of ∂A and $E(u, A) \leq m(u_0, A) + \gamma$. Now let $u_n : \mathcal{E}\mathcal{L} \rightarrow \mathcal{S}$ be a recovery sequence for u . Repeating the argument for the upper bound in Theorem 4.1, given $\delta > 0$ we can modify u_n to a function $\bar{u}_n \in \mathcal{PC}_{\varepsilon_n, u_0}^\eta(\mathcal{L}, A)$ for some $\eta = \eta(\delta) > 0$ such that

$$\limsup_n E_{\varepsilon_n}(\bar{u}_n, A) \leq E(u, A) + \delta.$$

By the choice of u we obtain

$$\lim_{\eta \rightarrow 0} \limsup_n m_{\varepsilon_n}^\eta(u_0, A) \leq \limsup_n E_{\varepsilon_n}(\bar{u}_n, A) + \delta \leq m(u_0, A) + \gamma + \delta.$$

The claim now follows letting first $\delta \rightarrow 0$ and then $\gamma \rightarrow 0$. □

5. Homogenization results for stationary lattices

We now replace the deterministic lattice \mathcal{L} by a random point set. In what follows we introduce the probabilistic framework. To this end let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space with a complete σ -algebra \mathcal{F} .

Definition 5.1. We say that a family $(\tau_z)_{z \in \mathbb{Z}^k}$, $\tau_z : \Omega \rightarrow \Omega$, is an *additive group action* on Ω if

$$\tau_{z_1+z_2} = \tau_{z_2} \circ \tau_{z_1} \quad \text{for all } z_1, z_2 \in \mathbb{Z}^k.$$

Such an additive group action is called *measure preserving* if

$$\mathbb{P}(\tau_z B) = \mathbb{P}(B) \quad \text{for all } B \in \mathcal{F}, z \in \mathbb{Z}^k.$$

Moreover $(\tau_z)_{z \in \mathbb{Z}^k}$ is called *ergodic* if, in addition, for all $B \in \mathcal{F}$ we have the implication

$$(\tau_z(B) = B \text{ for all } z \in \mathbb{Z}^k) \implies \mathbb{P}(B) \in \{0, 1\}.$$

For general $m \in \mathbb{N}$ we denote by $[a, b) := \{x \in \mathbb{R}^m : a_i \leq x_i < b_i \text{ for all } i\}$ the m -dimensional coordinate parallelepiped with opposite vertices a and b , and we set $\mathcal{I}_m = \{[a, b) : a, b \in \mathbb{Z}^m, a \neq b\}$. Next, we introduce the notion of regular families and discrete subadditive stochastic processes:

Definition 5.2. Let $\{I_n\} \subset \mathcal{I}_m$ be a family of sets. Then $\{I_n\}$ is called *regular* if there exists another family $\{I'_n\} \subset \mathcal{I}_m$ and a constant $C > 0$ such that

- (i) $I_n \subset I'_n$ for all n ,
- (ii) $I'_{n_1} \subset I'_{n_2}$ whenever $n_1 < n_2$,
- (iii) $0 < \mathcal{H}^m(I'_n) \leq C \mathcal{H}^m(I_n)$ for all n .

Moreover, if $\{I'_n\}$ can be chosen such that $\mathbb{R}^m = \bigcup_n I'_n$, then we write $\lim_{n \rightarrow \infty} I_n = \mathbb{R}^m$.

Definition 5.3. A function $\mu : \mathcal{I}_m \rightarrow L^1(\Omega)$ is said to be a *discrete subadditive stochastic process* if the following properties hold \mathbb{P} -almost surely:

- (i) For every $I \in \mathcal{I}_m$ and for every finite partition $(I_j)_{j \in J} \subset \mathcal{I}_m$ of I we have

$$\mu(I, \omega) \leq \sum_{j \in J} \mu(I_j, \omega).$$

- (ii) $\inf\{(\mathcal{H}^m(I))^{-1} \int_{\Omega} \mu(I, \omega) d\mathbb{P}(\omega) : I \in \mathcal{I}_m\} > -\infty$.

One of the key ingredients for our stochastic homogenization result will be the following pointwise ergodic theorem; see Theorem 2.7 in [Akcoğlu and Krengel 1981].

Theorem 5.4. Let $\mu : \mathcal{I}_m \rightarrow L^1(\Omega)$ be a discrete subadditive stochastic process and let I_n be a regular family in \mathcal{I}_m . If μ is stationary with respect to a measure-preserving group action $(\tau_z)_{z \in \mathbb{Z}^m}$, that is,

$$\text{for all } I \in \mathcal{I}_m, z \in \mathbb{Z}^m, \quad \mu(I + z, \omega) = \mu(I, \tau_z \omega) \text{ almost surely,}$$

then there exists $\mu^\infty : \Omega \rightarrow \mathbb{R}$ such that, for \mathbb{P} -almost every ω ,

$$\lim_{n \rightarrow +\infty} \frac{\mu(I_n, \omega)}{\mathcal{H}^m(I_n)} = \mu^\infty(\omega).$$

The statement is written for a generic m since in this section we will use Theorem 5.4 for $m = k - 1$, while in the next one we use it for $m = k$. We require some geometric and probabilistic properties of the random point set.

Definition 5.5. A random variable $\mathcal{L} : \Omega \rightarrow (\mathbb{R}^d)^\mathbb{N}$, $\omega \mapsto \mathcal{L}(\omega) = \{\mathcal{L}(\omega)_i\}_{i \in \mathbb{N}}$, is called a *stochastic lattice*. We say that \mathcal{L} is a *thin admissible lattice* if $\mathcal{L}(\omega)$ is a thin admissible lattice in the sense of Definition 2.1 and the constants M, r, R can be chosen independent of ω \mathbb{P} -almost surely. The stochastic lattice \mathcal{L} is said to be *stationary* if there exists a measure-preserving group action $(\tau_z)_{z \in \mathbb{Z}^k}$ on Ω such that, for \mathbb{P} -almost every $\omega \in \Omega$,

$$\mathcal{L}(\tau_z \omega) = \mathcal{L}(\omega) + z.$$

If in addition $(\tau_z)_{z \in \mathbb{Z}^k}$ is ergodic, then \mathcal{L} is called *ergodic*, too.

In order to prove a homogenization result we make the following *structural assumption*:

Hypothesis 2. There exist functions $f_{nn}, f_{lr} : \mathbb{R}^k \times \mathbb{R}^{2(d-k)} \rightarrow [0, +\infty)$ such that, setting $\Delta_k(x, y) = (y_1 - x_1, \dots, y_k - x_k, x_{k+1}, y_{k+1}, \dots, x_d, y_d)$, it holds that

$$f_{nn}^\varepsilon(x, y) = f_{nn}(\Delta_k(x, y)), \quad f_{lr}^\varepsilon(x, y) = f_{lr}(\Delta_k(x, y)).$$

Note that nearest-neighbor and long-range interaction coefficients are deterministic, but the set of nearest neighbors becomes now random. In the following we let $E_\varepsilon(\omega)$ be the discrete energy defined in the previous section, with the stochastic lattice $\mathcal{L}(\omega)$ in place of \mathcal{L} . As a general rule we will replace \mathcal{L} by ω to indicate the dependence on the stochastic lattice $\mathcal{L}(\omega)$.

In view of [Theorem 3.1](#) and [Lemma 4.3](#) we can further characterize the Γ -limits of the family $E_\varepsilon(\omega)$ by investigating the quantities $m_\varepsilon^\eta(u_0, Q)$ for suitable oriented cubes and $u_0 = u_{x,v}^{ij}$. Due to the decay assumptions of [Hypothesis 1](#) it will be enough to consider truncated interactions. To this end, for fixed $L \in \mathbb{N}$ we will replace the long-range coefficients by

$$f_{lr}^L(x, y) := f_{lr}(\Delta_k(x, y)) \mathbb{1}_{|x-y| \leq L}$$

and denote the corresponding energy by $E_\varepsilon^L(\omega)(u, A)$. By [Remark 4.2](#) the Γ -limit of the truncated energies is characterized by the minimum problem defined below: for $s_i, s_j \in \mathcal{S}$, $v \in S^{k-1}$ and a cube $Q_v(x, \rho)$ we set

$$m_1^{\eta,L}(\omega)(u_{x,v}^{ij}, Q_v(x, \rho)) := \inf \{ E_1^L(\omega)(u, Q_v(x, \rho)) : u \in \mathcal{PC}_{1,u_{x,v}^{ij}}^\eta(\omega, Q_v(x, \rho)) \}. \quad (5-29)$$

The following technical auxiliary result will be used several times.

Lemma 5.6. *Let $Q = Q_v(z, \rho) \subset \mathbb{R}^k$ be a cube and let $\{Q_n = Q_v(z_n, \rho_n)\}_n$ be a finite family of disjoint cubes with the following properties:*

- (i) $\min_n \rho_n \geq 4L$.
- (ii) $z_n - z_1 \in \{v\}^\perp$.
- (iii) $\text{dist}(z_1, \{v\}^\perp + z) \leq \frac{1}{4} \min_n \rho_n$.
- (iv) $\bigcup_n Q_n \subset Q$.
- (v) *Either $\text{dist}(\partial \bigcup_n Q_n, \partial Q) > \eta$ or $z_1 - z \in \{v\}^\perp$.*

Then there exists $C = C_L > 0$ such that for all $\eta \geq L$,

$$m_1^{\eta,L}(\omega)(u_{z,v}^{ij}, Q) \leq \sum_n m_1^{\eta,L}(\omega)(u_{z_n,v}^{ij}, Q_n) + C \mathcal{H}^{k-1} \left(\left(Q \setminus \bigcup_n \bar{Q}_n \right) \cap (\{v\}^\perp + z) \right) \\ + C \sum_n \left(\mathcal{H}^{k-2} \left((\partial Q_n \setminus \partial Q) \cap (\{v\}^\perp + z_1) \right) + \mathcal{H}^{k-1}(\partial Q_n \cap S_v(z, z_1)) \right),$$

where $S_v(z, z_1)$ is the infinite (possibly, flat) stripe enclosed by the two hyperplanes $\{v\}^\perp + z$ and $\{v\}^\perp + z_1$.

Proof. During this proof, given $y \in \mathbb{R}^k$, we denote by $P_{v,y}$ the projection onto the affine space $\{v\}^\perp + y$. For each n let u_n be a minimizer for the problem in [\(5-29\)](#) with $Q_v(x, \rho) = Q_n$. By assumptions (ii)

and (v), the function $v : \mathcal{L}(\omega) \rightarrow \mathcal{S}$ defined as

$$v(x) = \begin{cases} u_n(x) & \text{if } P_k(x) \in \bar{Q}_n \text{ for some } n, \\ u_{z,v}^{ij}(P_k(x)) & \text{otherwise} \end{cases}$$

is well-defined and belongs to $\mathcal{PC}_{1,u_{z,v}^{ij}}^\eta(\omega, Q)$. For $x, y \in \mathcal{L}(\omega) \cap Q$ with $|x - y| \leq L$, we say that

- (I) holds if $P_k(x) \in \bar{Q}_n$ and $P_k(y) \in \bar{Q}_m$ for $n \neq m$ or if $P_k(x), P_k(y) \in \partial Q_n$,
- (II) holds if $P_k(x) \in Q \setminus \bigcup_n \bar{Q}_n$ and $P_k(y) \in \bar{Q}_n$ for some n .

By (iv) and [Hypothesis 1](#) we can estimate

$$\begin{aligned} m_1^{\eta,L}(\omega)(u_{z,v}^{ij}, Q) &\leq E_1^L(\omega)(v, Q) \\ &\leq \sum_n m_1^{\eta,L}(\omega)(u_{z_n,v}^{ij}, Q_n) + E_1^L(\omega)\left(v, Q \setminus \bigcup_n \bar{Q}_n\right) + C \sum_{\substack{|x-y| \leq L \\ \text{(I) or (II) hold}}} |v(x) - v(y)|. \end{aligned} \quad (5-30)$$

We start with estimating the contribution of $x, y \in Q \setminus \bigcup_n \bar{Q}_n$. Suppose $v(x) \neq v(y)$. Then $P_k(x)$ and $P_k(y)$ lie on different sides of the hyperplane $\{v\}^\perp + z$. Then it holds true that $P_{v,z}(P_k(x)) \in Q \setminus \bigcup_n \bar{Q}_n$; otherwise assumptions (i) and (iii) would imply

$$L \geq |P_k(x) - P_k(y)| \geq |P_k(x) - P_{v,z}(P_k(x))| \geq \frac{1}{2}\rho_n - \frac{1}{4}\rho_n \geq 2L.$$

Thus $\text{dist}(P_k(x), (Q \setminus \bigcup_n \bar{Q}_n) \cap (\{v\}^\perp + z)) \leq L$ and, using the properties of [Definition 2.1](#), it follows that

$$E_1^L(\omega)\left(v, Q \setminus \bigcup_n \bar{Q}_n\right) \leq C \mathcal{H}^{k-1}\left(\left(Q \setminus \bigcup_n \bar{Q}_n\right) \cap (\{v\}^\perp + z)\right). \quad (5-31)$$

Next we have to control the interactions in Case (I). Given such x, y with $|x - y| \leq L$, we know that by the definition of v , the boundary conditions on the smaller cubes and (ii) that $v(x) = u_{z_1,v}^{ij}(P_k(x))$ and $v(y) = u_{z_1,v}^{ij}(P_k(y))$, so that if they contribute to the energy we conclude from assumption (ii) that $P_k(x)$ and $P_k(y)$ must lie on different sides of the hyperplane $\{v\}^\perp + z_1$. We deduce that $|P_{v,z_1}(P_k(x)) - P_k(x)| \leq L$. Since by (iv) the segment $[P_{v,z_1}(P_k(x)), P_{v,z_1}(P_k(y))]$ intersects the $(k-2)$ -dimensional set $(\partial Q_n \setminus \partial Q) \cap (\{v\}^\perp + z_1)$, it follows that

$$\text{dist}(P_k(x), (\partial Q_n \setminus \partial Q) \cap (\{v\}^\perp + z_1)) \leq 2L.$$

Again, by [Definition 2.1](#) and the above inequality we derive the estimate

$$\sum_{\substack{|x-y| \leq L \\ \text{(I) holds}}} |v(x) - v(y)| \leq C \sum_n \mathcal{H}^{k-2}\left((\partial Q_n \setminus \partial Q) \cap (\{v\}^\perp + z_1)\right). \quad (5-32)$$

It remains to estimate the contributions coming from Case (II). For such x, y with $|x - y| \leq L$, due to the boundary conditions on the smaller cubes, a positive energy contribution implies $u_{z,v}^{ij}(P_k(x)) \neq u_{z,v}^{ij}(P_k(y))$. Thus the segment $[P_k(x), P_k(y)]$ intersects ∂Q_n in (at least) one point x_n and also $S_v(z, z_1)$ in (at least) one point x_S . Denote by $x_{n,S}$ the projection of x_S onto the facet of the cube Q_n containing x_n . Since this facet cannot be parallel to $\{v\}^\perp$ by (i) and (iii), it holds that $x_{n,S} \in \partial Q_n \cap S_v(z, z_1)$ and

$$|P_k(x) - x_{n,S}| \leq |P_k(x) - x_S| + |x_S - x_{n,S}| \leq L + |x_S - x_n| \leq 2L,$$

which yields the estimate

$$\text{dist}(P_k(x), \partial Q_n \cap S_\nu(z, z_1)) \leq 2L. \quad (5-33)$$

This set may not be $(k-1)$ -dimensional in the second possibility of (v). In this case one can bound the interactions by the right-hand side of (5-31). Otherwise, using (5-33) we obtain the estimate

$$\sum_{\substack{|x-y| \leq L \\ \text{(II) holds}}} |v(x) - v(y)| \leq C \sum_n \mathcal{H}^{k-1}(\partial Q_n \cap S_\nu(z, z_1)). \quad (5-34)$$

In any case the claim now follows from (5-30), (5-31), (5-32) and (5-34). \square

Remark 5.7. Lemma 5.6 still holds if we replace cubes by k -parallelepipeds of the type $I_\nu(z, \{\rho_m\}_m) = z + \{x \in \mathbb{R}^k : |\langle x, \nu_m \rangle| < \frac{1}{2}\rho_m\}$. Then the cubes Q_n are replaced by the collection $I_n = I_\nu(z_n, \{\rho_m^n\}_m)$ and in the assumptions (i) and (iii) we have to replace ρ_n by $\min_m \rho_m^n$.

The next theorem is the main result of this section.

Theorem 5.8. *Let \mathcal{L} be a stationary, thin admissible stochastic lattice and let f_{nm} and f_{lr} satisfy Hypotheses 1 and 2. For \mathbb{P} -almost every ω and for all $s_i, s_j \in \mathcal{S}$ and $\nu \in S^{k-1}$ there exists*

$$\phi_{\text{hom}}(\omega; s_i, s_j, \nu) := \lim_{\eta \rightarrow 0} \limsup_{t \rightarrow +\infty} \frac{1}{t^{k-1}} \inf\{E_1(\omega)(u, Q_\nu(0, t)) : u \in \mathcal{PC}_{1, u_{0, \nu}^{ij}}^{\eta t}(\omega, Q_\nu(0, t))\}.$$

The functionals $E_\varepsilon(\omega)$ Γ -converge with respect to the convergence of Definition 2.2 to the functional $E_{\text{hom}}(\omega) : L^1(D, \mathbb{R}^q) \rightarrow [0, +\infty]$ defined by

$$E_{\text{hom}}(\omega)(u) = \begin{cases} \int_{S_u} \phi_{\text{hom}}(\omega; u^+, u^-, \nu_u) d\mathcal{H}^{k-1} & \text{if } u \in \text{BV}(D, S), \\ +\infty & \text{otherwise.} \end{cases}$$

If \mathcal{L} is ergodic, then $\omega \mapsto \phi_{\text{hom}}(\omega, s_i, s_j, \nu)$ is almost-surely constant.

Proof. Fix any sequence $\varepsilon \rightarrow 0$. According to Theorem 3.2, for all $\omega \in \Omega$ such that $\mathcal{L}(\omega)$ is admissible, there exists a (ω -dependent) subsequence ε_n such that

$$\Gamma\text{-}\lim_n E_{\varepsilon_n}(\omega)(u, A) = \int_{S_u \cap A} \phi(\omega; x, u^+, u^-, \nu) d\mathcal{H}^{k-1}$$

for all $u \in \text{BV}(D, S)$ and every $A \in \mathcal{A}^R(D)$. According to Theorem 3.1 and Lemma 4.3, for any $x \in D$, $s_i, s_j \in \mathcal{S}$ and $\nu \in S^{k-1}$ it holds that

$$\begin{aligned} \phi(\omega; x, s_i, s_j, \nu) &= \limsup_{\rho \rightarrow 0} \frac{1}{\rho^{k-1}} m(\omega)(u_{x, \nu}^{ij}, Q_\nu(x, \rho)) \\ &= \limsup_{\rho \rightarrow 0} \frac{1}{\rho^{k-1}} \lim_{\eta \rightarrow 0} \limsup_n m_{\varepsilon_n}^\eta(\omega)(u_{x, \nu}^{ij}, Q_\nu(x, \rho)). \end{aligned}$$

If we change the variables via $t_n = \varepsilon_n^{-1}$ and $v(x) = u(t_n^{-1}x)$, the above characterization reads as

$$\phi(\omega; x, s_i, s_j, \nu) = \limsup_{\rho \rightarrow 0} \lim_{\eta \rightarrow 0} \limsup_n \frac{1}{(\eta t_n)^{k-1}} m_1^{\eta t_n}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho)).$$

Except for the claim on ergodicity, due to the Urysohn property of Γ -convergence (recall [Remark 2.3](#)) it is enough to show that for a set of full probability the limit in ρ can be neglected and the remaining limits do not depend on x or the subsequence t_n . We divide the proof into several steps.

Step 1: truncating the range of interactions. First we show that it is enough to consider the case of finite range interactions. We argue that it is enough to prove that there exists $\phi_{\text{hom}}^L(\omega; \nu)$ and a set Ω_L of full probability such that for all $\omega \in \Omega_L$, $x \in D$, every cube $Q_\nu(x, \rho)$ and every sequence $t_n \rightarrow +\infty$ it holds that

$$\phi_{\text{hom}}^L(\omega; s_i, s_j, \nu) = \lim_{\eta \rightarrow 0} \limsup_n \frac{1}{(\rho t_n)^{k-1}} m_1^{\eta t_n, L}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho)), \tag{5-35}$$

where $m_1^{\eta t_n, L}(\omega)$ is defined in [\(5-29\)](#). Indeed, if [\(5-35\)](#) is proven, then for all $\omega \in \bigcap_L \Omega_L$ we find a configuration $v_n^L : \mathcal{L}(\omega) \rightarrow \mathcal{S}$ with the correct boundary conditions (extended to the whole space) that minimizes $E_1^L(\omega)(\cdot, t_n Q_\nu(x, \rho))$ in [\(5-29\)](#). Using [Lemma 2.7](#) we obtain the estimate

$$\begin{aligned} 0 &\leq \frac{m_1^{\eta t_n}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho)) - m_1^{\eta t_n, L}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho))}{(\rho t_n)^{k-1}} \\ &\leq \frac{E_1(\omega)(v_n^L, t_n Q_\nu(x, \rho)) - E_1^L(\omega)(v_n^L, t_n Q_\nu(x, \rho))}{(\rho t_n)^{k-1}} \\ &\leq \frac{C}{(\rho t_n)^{k-1}} \sum_{2|\hat{\xi}| > L} J_{lr}(|\hat{\xi}|) |\hat{\xi}| \sum_{\substack{(x, y) \in \mathcal{NN}(\omega) \\ x, y \in (t_n Q_\nu(x, \rho))^{3(R+M)}}} f_{nn}(x, y, v_n^L(x), v_n^L(y)). \end{aligned}$$

The inner sum can be bounded by the energy plus interactions close to $\partial t_n Q_\nu(x, \rho)$. Due to the boundary conditions, these are of order $(\rho t_n)^{k-2}$. Using the trivial a priori bound $m_1^\eta(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho)) \leq C(\rho t_n)^{k-1}$ we deduce that

$$0 \leq \frac{m_1^{\eta t_n}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho)) - m_1^{\eta t_n, L}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho))}{(\rho t_n)^{k-1}} \leq C \sum_{2|\hat{\xi}| > L} J_{lr}(|\hat{\xi}|) |\hat{\xi}|.$$

Due to the integrability assumption of [Hypothesis 1](#), we infer that $\phi_{\text{hom}}^L(\omega; s_i, s_j, \nu)$ is a Cauchy sequence with respect to L and moreover, in combination with [\(5-35\)](#), we deduce that

$$\lim_L \phi_{\text{hom}}^L(\omega; s_i, s_j, \nu) = \lim_{\eta \rightarrow 0} \limsup_n \frac{1}{(\rho t_n)^{k-1}} m_1^{\eta t_n}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho))$$

exists and is independent of x, ρ and the sequence t_n . Therefore it remains to show [\(5-35\)](#). For clarity of the argument we first consider an auxiliary problem where we replace the varying boundary width ηt_n by L . As an intermediate result we show that there exists

$$\phi_{ij}^L(\omega; \nu) = \lim_n \frac{1}{(\rho t_n)^{k-1}} m_1^{L, L}(\omega)(u_{t_n x, \nu}^{ij}, t_n Q_\nu(x, \rho)) \tag{5-36}$$

and this limit does not depend on x, ρ or the sequence t_n .

Step 2: existence of ϕ_{ij}^L for $x = 0$ and rational directions. Fix $L \in \mathbb{N}$. We have to show that, for \mathbb{P} -almost every $\omega \in \Omega$ and every $s_i, s_j \in \mathcal{S}$ and $v \in S^{k-1}$, there exists the limit in (5-36). We start with the case $x = 0$ and $v \in S^{k-1} \cap \mathbb{Q}^k$. For this choice we can use the subadditive ergodic theorem in $(k-1)$ -dimensions.

Substep 2.1: defining a stochastic process. We need a few preliminaries: given $v \in S^{k-1}$ there exists an orthogonal matrix $A_v \in \mathbb{R}^{k \times k}$ such that $A_v e_k = v$, the mapping $v \mapsto A_v e_i$ is continuous on $S^{k-1} \setminus \{-e_k\}$ and if $v \in \mathbb{Q}^k$ then $A_v \in \mathbb{Q}^{k \times k}$ (it suffices to consider the orthogonal transformation that keeps the vector $v + e_k$ fixed and reverses the orthogonal complement). We now fix a rational direction $v \in S^{k-1} \cap \mathbb{Q}^k$. Then there exists an integer $N = N(v) > 4L$ such that $NA_v(z, 0) \in \mathbb{Z}^k$ for all $z \in \mathbb{Z}^{k-1}$. We now define a discrete stochastic process (see Definition 5.3). To $I = [a_1, b_1) \times \cdots \times [a_{k-1}, b_{k-1}) \in \mathcal{I}_{k-1}$ we associate the set $Q_I \subset \mathbb{R}^k$ defined by

$$Q_I := NA_v(\text{int } I \times (-\frac{1}{2}s_{\max}, \frac{1}{2}s_{\max})),$$

where $s_{\max} = \max_i |b_i - a_i|$ is the maximal side length. Then we define the process $\mu : \mathcal{I}_{k-1} \rightarrow L^1(\Omega)$ as

$$\mu(I, \omega) := \inf\{E_1^L(\omega)(v, Q_I) : v \in \mathcal{P}C_{1, u_{0,v}}^L(\omega, Q_I)\} + C_\mu \mathcal{H}^{k-2}(\partial I), \quad (5-37)$$

where C_μ is a constant to be chosen later. We first have to show that $\mu(I, \cdot)$ is an $L^1(\Omega)$ -function. Testing the $\mathcal{L}(\omega)$ -interpolation of $u_{0,v}$ as a candidate in the infimum problem, one can use the growth assumptions from Hypothesis 1 and Definition 2.1 to show that there exists a constant $C > 0$ such that

$$\mu(I, \omega) \leq CN^{k-1} \mathcal{H}^{k-1}(I) \quad (5-38)$$

for all $I \in \mathcal{I}_{k-1}$ and almost every $\omega \in \Omega$ so that $\mu(I, \cdot)$ is essentially bounded. \mathcal{F} -measurability can be proven similar to [Alicandro et al. 2015, Lemma A.2].

We continue with proving lower-dimensional stationarity of the process. Let $z \in \mathbb{Z}^{d-1}$. Note that $Q_{I-z} = Q_I - z_v^N$, where $z_v^N := NA_v(z, 0) \in \{v\}^\perp \cap \mathbb{Z}^k$. By the stationarity of \mathcal{L} it holds that $v \in \mathcal{P}C_{1, u_{0,v}}^L(\omega, Q_{I-z})$ if and only if $u(\cdot) = v(\cdot - z_v^N) \in \mathcal{P}C_{1, u_{0,v}}^L(\tau_{z_v^N} \omega, Q_I)$. Moreover, by the definition of nearest neighbors, Hypothesis 2 and again the stationarity of \mathcal{L} , we obtain $E_1^L(\omega)(v, Q_{I-z}) = E_1^L(\tau_{z_v^N} \omega)(u, Q_I)$. By the shift invariance of the Hausdorff measure we conclude that $\mu(I - z, \omega) = \mu(I, \tau_{z_v^N} \omega)$. Setting $\tilde{\tau}_z = \tau_{-z_v^N}$ we obtain a measure-preserving group action on \mathbb{Z}^{k-1} such that $\mu(I, \tilde{\tau}_z \omega) = \mu(I + z)(\omega)$, which yields stationarity.

To show subadditivity, let $I \in \mathcal{I}_{k-1}$ and let $\{I_n\}_n \subset \mathcal{I}_{k-1}$ be a finite disjoint family such that $I = \bigcup_n I_n$. Note that Q_I and the family $\{Q_{I_n}\}_n$ fulfill the assumptions of Lemma 5.6 (in the sense of Remark 5.7). We conclude

$$m_1^{L,L}(\omega)(u_{0,v}^{ij}, Q_I) \leq \sum_n m_1^{L,L}(\omega)(u_{0,v}^{ij}, Q_{I_n}) + C \sum_n \mathcal{H}^{k-2}((\partial Q_{I_n} \setminus \partial Q_I) \cap \{v\}^\perp).$$

Applying the definition of $\mu(I, \omega)$ yields

$$\begin{aligned} \mu(I, \omega) &= m_1^{L,L}(\omega)(u_{0,v}^{ij}, Q_I) + C_\mu \mathcal{H}^{k-2}(\partial Q_I \cap \{v\}^\perp) \\ &\leq \sum_n \mu(I_n, \omega) + (C - C_\mu) \sum_n \mathcal{H}^{k-2}((\partial Q_{I_n} \setminus \partial Q_I) \cap \{v\}^\perp), \end{aligned}$$

which yields subadditivity if we choose $C_\mu > C$. Property (ii) in [Definition 5.3](#) is trivial since $\mu(I, \omega)$ is always nonnegative. By [Theorem 5.4](#) there exists $\phi_{ij}^L(\omega; \nu)$ such that almost surely, for rational directions $\nu \in S^{k-1}$, it holds that

$$\phi_{ij}^L(\omega; \nu) = \lim_{n \rightarrow +\infty} \frac{1}{(2Nn)^{k-1}} m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, 2Nn)),$$

where we used that the term $C_\mu \mathcal{H}^{k-2}(\partial I)$ is negligible for the limit.

Substep 2.2: from integer sequences to all sequences. Next we consider an arbitrary sequence $t_n \rightarrow +\infty$. From the previous step we know that

$$\phi_{ij}^L(\omega; \nu) = \lim_{n \rightarrow +\infty} \frac{1}{(2N \lfloor t_n \rfloor)^{k-1}} m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, 2N \lfloor t_n \rfloor))$$

exists almost surely. To shorten notation we set $\Lambda_n = 2Nt_n$ and $\lambda_n = 2N \lfloor t_n \rfloor$. For n large enough, we can apply [Lemma 5.6](#) to the cube $Q_\nu(0, \Lambda_n)$ and singleton family $\{Q_\nu(0, \lambda_n)\}$ and obtain

$$\begin{aligned} & m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, \Lambda_n)) \\ & \leq m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, \lambda_n)) + \mathcal{H}^{k-2}(\partial(Q_\nu(0, \lambda_n)) \cap \{v\}^\perp) + C \mathcal{H}^{k-1}((Q_\nu(0, \Lambda_n) \setminus \overline{Q_\nu(0, \lambda_n)}) \cap \{v\}^\perp) \\ & \leq m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, \lambda_n)) + C \Lambda_n^{k-2}, \end{aligned}$$

which yields

$$\limsup_{j \rightarrow +\infty} \frac{1}{\Lambda_n^{k-1}} m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, \Lambda_n)) \leq \phi_{ij}^L(\omega; \nu). \quad (5-39)$$

Similarly, one can prove that

$$\phi_{ij}^L(\omega; \nu) \leq \liminf_{n \rightarrow +\infty} \frac{1}{\Lambda_n^{k-1}} m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, \Lambda_n)). \quad (5-40)$$

Combining (5-39) and (5-40) yields almost surely the existence of the limit for arbitrary sequences.

Substep 2.3: shift invariance in the probability space. Up to neglecting a countable union of null sets, we may assume that the limit defining $\phi_{ij}^L(\omega; \nu)$ exists for all rational directions ν . We next prove that the function $\omega \mapsto \phi_{ij}^L(\omega; \nu)$ is invariant under the entire group action $\{\tau_z\}_{z \in \mathbb{Z}^k}$. This will be important to treat the ergodic case but also for the shift invariance in the physical space. Given $z \in \mathbb{Z}^k$ there exists $R = R(L, z) > 0$ such that for all $t > 0$

$$Q_\nu(0, t) \subset Q_\nu(-z, R+t), \quad 2L \leq \text{dist}(\partial Q_\nu(0, t), \partial Q_\nu(-z, R+t)). \quad (5-41)$$

Similar to the stationarity of the stochastic process we have

$$\begin{aligned} \phi_{ij}^L(\tau_z \omega; \nu) & \leq \limsup_{t \rightarrow +\infty} \frac{1}{(R+t)^{k-1}} m_1^{L,L}(\omega)(u_{-z,\nu}^{ij}, Q_\nu(-z, R+t)) \\ & = \limsup_{t \rightarrow +\infty} \frac{1}{t^{k-1}} m_1^{L,L}(\omega)(u_{-z,\nu}^{ij}, Q_\nu(-z, R+t)). \end{aligned}$$

Due to (5-41) we can apply Lemma 5.6 to the cube $Q_\nu(-z, R+t)$ and the singleton family $\{Q_\nu(0, t)\}$ and deduce that there exists a constant $C = C(R, z)$ such that

$$m_1^{L,L}(\omega)(u_{-z,\nu}^{ij}, Q_\nu(-z, R+t)) \leq m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, t)) + Ct^{k-2}.$$

Hence we get $\phi_{ij}^L(\tau_z\omega; \nu) \leq \phi_{ij}^L(\omega; \nu)$. The other inequality can be proven similarly so that the limit indeed exists (which we implicitly assumed with our notation) and, for \mathbb{P} -almost every $\omega \in \Omega$,

$$\phi_{ij}^L(\tau_z\omega; \nu) = \phi_{ij}^L(\omega; \nu). \quad (5-42)$$

Step 3: shift invariance in the physical space. In this step we prove the existence of the limit defining $\phi_{ij}^L(\omega; \nu)$ when we blow up a cube not centered in the origin. We further show that it agrees with the one already considered. We start with considering a cube $Q_\nu(x, \rho)$ with rational direction ν , $x \in \mathbb{Z}^k \setminus \{0\}$ and $\rho \in \mathbb{Q}$. Given $\varepsilon > 0$ and $N \in \mathbb{N}$ (not the same one of Step 2.1) we define the events

$$\mathcal{Q}_N := \left\{ \omega \in \Omega : \sup_{t \geq N/2} |(t\rho)^{1-k} m_1^{L,L}(\omega)(u_{0,\nu}^{ij}, Q_\nu(0, t\rho)) - \phi_{ij}^L(\omega; \nu)| \leq \varepsilon \right\}.$$

By Step 2 we know that the function $\mathbb{1}_{\mathcal{Q}_N}$ converges almost surely to $\mathbb{1}_\Omega$ when $N \rightarrow +\infty$. Denote by \mathcal{J}_x the σ -algebra of invariant sets for the measure-preserving map τ_x . Fatou's lemma for the conditional expectation yields

$$\mathbb{1}_\Omega = \mathbb{E}[\mathbb{1}_\Omega | \mathcal{J}_x] \leq \liminf_{N \rightarrow +\infty} \mathbb{E}[\mathbb{1}_{\mathcal{Q}_N} | \mathcal{J}_x]. \quad (5-43)$$

By (5-43), given $\delta > 0$, almost surely we find $N_0 = N_0(\omega, \delta)$ such that

$$1 \geq \mathbb{E}[\mathbb{1}_{\mathcal{Q}_{N_0}} | \mathcal{J}_x](\omega) \geq 1 - \delta.$$

Now due to Birkhoff's ergodic theorem, almost surely, there exists $n_0 = n_0(\omega, \delta)$ such that, for any $n \geq \frac{1}{2}n_0$,

$$\left| \frac{1}{n} \sum_{l=1}^n \mathbb{1}_{\mathcal{Q}_{N_0}}(\tau_{lx}\omega) - \mathbb{E}[\mathbb{1}_{\mathcal{Q}_{N_0}} | \mathcal{J}_x](\omega) \right| \leq \delta.$$

Note that the set we exclude will be a countable union of null sets provided $\varepsilon \in \mathbb{Q}$.

For fixed $n \geq \max\{n_0, N_0\}$ we denote by R the maximal integer such that for all $l = n+1, \dots, n+R$ we have $\tau_{lx}(\omega) \notin \mathcal{Q}_{N_0}$. In order to bound R , let \tilde{n} be the number of ones in the sequence $\{\mathbb{1}_{\mathcal{Q}_{N_0}}(\tau_{lx}(\omega))\}_{l=1}^n$. By the definition of R we have

$$\delta \geq \left| \frac{\tilde{n}}{n+R} - \mathbb{E}[\mathbb{1}_{\mathcal{Q}_{N_0}} | \mathcal{J}_x](\omega) \right| = \left| 1 - \mathbb{E}[\mathbb{1}_{\mathcal{Q}_{N_0}} | \mathcal{J}_x](\omega) + \frac{\tilde{n} - n - R}{n+R} \right| \geq \frac{R + n - \tilde{n}}{n+R} - \delta.$$

Since $n - \tilde{n} \geq 0$ and without loss of generality $\delta \leq \frac{1}{4}$, this provides an upper bound by $R \leq 4n\delta$.

So for any $n \geq \max\{n_0, N_0\}$ and $\tilde{R} = 6n\delta$, we find $l_n \in [n+1, n+\tilde{R}]$ such that $\tau_{l_n x}(\omega) \in \mathcal{Q}_{N_0}$. Then by (5-42) and stationarity we have for all $t \geq \frac{1}{2}N_0$ that

$$|(t\rho)^{1-k} m_1^{L,L}(\omega)(u_{-l_n x, \nu}^{ij}, Q_\nu(-l_n x, t\rho)) - \phi_{ij}^L(\omega; \nu)| \leq \varepsilon. \quad (5-44)$$

Define $\beta_n = n + c_L \rho^{-1}|x|(l_n - n)$, where $c_L \in \mathbb{N}$ is chosen such that $Q_v(-nx, n\rho) \subset Q_v(-l_n x, \beta_n \rho)$ and $\text{dist}(\partial Q_v(-nx, n\rho), \partial Q_v(-l_n x, \beta_n \rho)) > L$. Observe that such c_L exists as $l_n - n \geq 1$. Then each face of the cube $Q_v(-nx, n\rho)$ has at most distance $(\beta_n - n)\rho = c_L|x|(l_n - n)$ to the corresponding face in $Q_v(-l_n x, \beta_n \rho)$. Then, for n large enough, we can apply [Lemma 5.6](#) to the cube $Q(-l_n x, \beta_n \rho)$ and the singleton family $\{Q_v(-nx, n\rho)\}$ to obtain

$$\begin{aligned} \frac{m_1^{L,L}(\omega)(u_{-l_n x, v}^{ij}, Q_v(-l_n x, \beta_n \rho))}{(\beta_n \rho)^{k-1}} &\leq \frac{m_1^{L,L}(\omega)(u_{-nx, v}^{ij}, Q_v(-nx, n\rho))}{(\beta_n \rho)^{k-1}} + C\tilde{R}(\beta_n \rho)^{-1} \\ &\leq \frac{m_1^{L,L}(\omega)(u_{-nx, v}^{ij}, Q_v(-nx, n\rho))}{(n\rho)^{k-1}} + 6C\delta. \end{aligned} \tag{5-45}$$

On the other hand we can define $\theta_n = n - c'_L \rho^{-1}|x|(l_n - n)$ for a suitable $c'_L \in \mathbb{N}$ and deduce from a similar reasoning that

$$\frac{m_1^{L,L}(\omega)(u_{-nx, v}^{ij}, Q_v(-nx, n\rho))}{(n\rho)^{k-1}} \leq \frac{m_1^{L,L}(\omega)(u_{-l_n x, v}^{ij}, Q_v(-l_n x, \theta_n \rho))}{(\theta_n \rho)^{k-1}} + 6C\delta. \tag{5-46}$$

Now if δ is small enough (depending only on x, L and ρ) we have $\beta_n \geq \theta_n \geq \frac{1}{2}n \geq \frac{1}{2}N_0$. Combining [\(5-45\)](#), [\(5-46\)](#) and [\(5-44\)](#) we infer

$$\limsup_{n \rightarrow +\infty} \left| \frac{m_1^{L,L}(\omega)(u_{-nx, v}^{ij}, Q_v(-nx, n))}{n^{k-1}} - \phi_{ij}^L(\omega; v) \right| \leq 6C\delta + \varepsilon,$$

which yields the claim in [\(5-36\)](#) for $Q_v(x, \rho)$ with $x \in \mathbb{Z}^k$ and rational v and ρ . The extension to arbitrary sequences $t_n \rightarrow +\infty$ (and thus to rational centers x) can be achieved again by [Lemma 5.6](#), comparing first the minimal energy on the two cubes $Q_v(\lfloor t_n \rfloor x, \lfloor t_n \rfloor \rho)$ and $Q_v(\lfloor t_n \rfloor x, t_n \rho)$, similar to Substep 2.2, and then the energy on the latter cube with the one on $Q_v(t_n x, t_n \rho)$, as in Substep 2.3. Eventually the convergence of irrational ρ follows from the estimate

$$m_1^{L,L}(\omega)(u_{t_n x, v}^{ij}, Q_v(t_n x, t_n \rho)) \leq m_1^{L,L}(\omega)(u_{t_n x, v}^{ij}, Q_v(t_n x, t_n(\rho - \delta))) + Ct_n \delta (t_n \rho)^{k-2},$$

which is a consequence of [Lemma 5.6](#) applied to the cube $Q_v(t_n x, t_n \rho)$ and $\{Q_v(t_n x, t_n(\rho - \delta))\}$, when one neglects lower-order terms. Choosing $0 < \delta_l \rightarrow 0$ such that $\rho - \delta_l \in \mathbb{Q}$ then yields

$$\limsup_n \frac{m_1^{L,L}(\omega)(u_{t_n x, v}^{ij}, Q_v(t_n x, t_n \rho))}{(t_n \rho)^{k-1}} \leq \phi_{ij}^L(\omega; v).$$

Using the same argument for the cube $Q_v(t_n x, t_n(\rho + \delta))$ and the family $\{Q_v(t_n x, t_n \rho)\}$, we find that the limit exists and agrees with $\phi_{ij}^L(\omega; v)$. Finally, for irrational centers we can again use a perturbation argument based on [Lemma 5.6](#) as we did for proving [\(5-45\)](#) and [\(5-46\)](#). We omit the details.

Step 4: from rational to irrational directions. Now we extend the convergence from rational directions to all $v \in S^{k-1}$. As the argument is purely geometric similar to [Lemma 5.6](#), we assume without loss of generality that $x = 0$. First note that the set of rational directions is dense in S^{k-1} (as the inverse of the stereographic

projection maps rational points to rational directions). Given $v \in S^{k-1}$ and a sequence $t_n \rightarrow +\infty$ we define

$$\begin{aligned}\bar{\phi}_{ij}^L(\omega; v) &= \limsup_{n \rightarrow +\infty} \frac{1}{t_n^{k-1}} m_1^{L,L}(\omega)(u_{0,v}^{ij}, Q_v(0, t_n)), \\ \underline{\phi}_{ij}^L(\omega; v) &= \liminf_{n \rightarrow +\infty} \frac{1}{t_n^{k-1}} m_1^{L,L}(\omega)(u_{0,v}^{ij}, Q_v(0, t_n)).\end{aligned}$$

Let $v \in S^{k-1} \setminus \mathbb{Q}^k$. By the construction of the matrix A_v in Substep 2.1 we can assume that there exists a sequence of rational directions v_l such that $A_{v_l} \rightarrow A_v$. Therefore, given $\delta > 0$ we find $l_0 \in \mathbb{N}$ such that for all $l \geq l_0$ the following properties hold:

- (i) $Q_v(0, (1-2\delta)) \Subset Q_{v_l}(0, 1-\delta) \Subset Q_v(0, 1)$.
- (ii) $0 < d_{\mathcal{H}}(\{v\}^\perp \cap B_2(0), \{v_l\}^\perp \cap B_2(0)) \leq \delta$.

For a fixed $l \geq l_0$ and $n \in \mathbb{N}$, we let $u_{n,l} : \mathcal{L}(\omega) \rightarrow \mathcal{S}$ be an admissible minimizer for the problem $m_1^{L,L}(\omega)(u_{0,v_l}^{ij}, Q_{v_l}(0, (1-\delta)t_n))$. We define a test function $v_n : \mathcal{L}(\omega) \rightarrow \mathcal{S}$ setting

$$v_n(x) := \begin{cases} u_{n,l}(x) & \text{if } x \in Q_{v_l}(0, (1-\delta)t_n), \\ u_{0,v}(x) & \text{otherwise.} \end{cases}$$

Note that if $P_k(x), P_k(y) \in Q_v(0, t_n) \setminus Q_{v_l}(0, (1-\delta)t_n)$ are such that $|x-y| \leq L$ and $v_n(x) \neq v_n(y)$, then by the choice of l_0 and (i), for l large enough we have

$$\text{dist}(P_k(x), (Q_v(0, t_n) \setminus Q_v(0, (1-2\delta)t_n)) \cap \{v\}^\perp) \leq L. \quad (5-47)$$

If $P_k(x) \in Q_v(0, t_n) \setminus Q_{v_l}(0, (1-\delta)t_n)$ and $P_k(y) \in Q_{v_l}(0, (1-\delta)t_n)$ with $|x-y| \leq L$ and $v_n(x) \neq v_n(y)$, then, for l large enough one can show that by (ii) either $P_k(x)$ or $P_k(y)$ must lie in the cone

$$\mathcal{K}(v, v_l) = \{x \in \mathbb{R}^k : \langle x, v \rangle \cdot \langle x, v_l \rangle \leq 0\}.$$

As the segment $[P_k(x), P_k(y)]$ intersects $\partial Q_{v_l}(0, (1-\delta)t_n)$, we conclude that

$$\text{dist}(P_k(x), (\mathcal{K}(v, v_l) + B_L(0)) \cap \partial Q_{v_l}(0, (1-\delta)t_n)) \leq L. \quad (5-48)$$

By (i) it holds that $v_n \in \mathcal{PC}_{1, u_{0,v}^{ij}}^L(\omega, Q_v(0, t_n))$ for n large enough. From (5-47), (5-48) and the choice of l_0 we deduce that for l large enough

$$m_1^{L,L}(\omega)(u_{0,v}^{ij}, Q_v(0, t_n)) \leq m_1^{L,L}(\omega)(u_{0,v_l}^{ij}, Q_{v_l}(0, (1-\delta)t_n)) + C\delta t_n^{k-1}.$$

Dividing the last inequality by t_n^{k-1} and taking the lim sup as $n \rightarrow +\infty$, we deduce

$$\bar{\phi}_{ij}^L(\omega; v) \leq \phi_{ij}^L(\omega; v_l) + C\delta.$$

Letting first $l \rightarrow +\infty$ and then $\delta \rightarrow 0$ yields $\bar{\phi}_{ij}^L(\omega; v) \leq \liminf_l \phi_{ij}^L(\omega; v_l)$. By a similar argument we can also prove that $\limsup_l \phi_{ij}^L(\omega; v_l) \leq \underline{\phi}_{ij}^L(\omega; v)$. Hence, we get almost surely the existence of the limit in (5-36) for all directions v and the limit does not depend on x, ρ or the sequence t_n .

Step 5: proof of (5-35). We claim that $\phi_{ij}^L(\omega; \nu) = \phi_{\text{hom}}^L(\omega; s_i, s_j, \nu)$. By the preceding steps this concludes the proof. First observe that by monotonicity it is enough to show that $\phi_{\text{hom}}^L(\omega; s_i, s_j, \nu) \leq \phi_{ij}^L(\omega; \nu)$. Let $t_n \rightarrow +\infty$ and fix a cube $Q_\nu(x, \rho)$. By a trivial extension argument, for η small enough (depending on ρ) it holds that

$$m_1^{\eta t_n, L}(\omega)(u_{t_n x, \nu}^{ij}, Q(t_n x, t_n \rho)) \leq m_1^{L, L}(\omega)(u_{t_n x, \nu}^{ij}, Q(t_n x, t_n \rho - \eta t_n)) + C\eta t_n^{k-1}.$$

Dividing by $(t_n \rho)^{k-1}$ and letting first $n \rightarrow +\infty$ and then $\eta \rightarrow 0$ we obtain the claim.

When the group action is ergodic, the additional statement in Theorem 5.8 follows from (5-42) since in this case all the functions $\omega \mapsto \phi_{ij}^L(\omega; \nu)$ are constant and so is the pointwise limit when $L \rightarrow +\infty$. \square

Remark 5.9. One can show that the surface tension can be obtained by one single limit procedure. Indeed, referring to (4-22) and repeating Steps 1 and 5 of the proof of Theorem 5.8, it follows that

$$\phi_{\text{hom}}(\omega; s_i, s_j, \nu) = \lim_{t \rightarrow +\infty} \frac{1}{t^{k-1}} \inf \left\{ E_1(\omega)(u, Q_\nu(0, t)) : u \in \mathcal{PC}_{1, u_{0, \nu}^{ij}}^{l_1/t}(\omega, Q_\nu(0, t)) \right\}.$$

6. Volume constraints in the stationary case

In this section we will discuss the variational limit of the energies $E_\varepsilon(\omega)$ when, for all $i = 1, \dots, q$, we fix the number of lattice points where the configuration takes the value s_i . For general thin admissible lattices this energy might not converge without passing to a further subsequence, so we treat only the case of stationary lattices in the sense of Definition 5.5. In order to formulate the result, given $A \in \mathcal{A}^R(D)$ and a family $V_\varepsilon = \{V_{i, \varepsilon}\}_{i=1}^q \in \mathbb{N}^q$, we introduce the class

$$\mathcal{PC}_\varepsilon^{V_\varepsilon}(\omega) := \{u : \varepsilon \mathcal{L}(\omega) \rightarrow \mathcal{S} : \#\{\varepsilon x \in \varepsilon \mathcal{L}(\omega) \cap P_k^{-1} D : u(\varepsilon x) = s_i\} = V_{i, \varepsilon}\}.$$

Beside the natural compatibility condition $\sum_i V_{i, \varepsilon} = \#\{\varepsilon \mathcal{L}(\omega) \cap P_k^{-1} D\}$, we assume that for all $i = 1, \dots, q$ there exists $V_i > 0$ such that

$$\lim_{\varepsilon \rightarrow 0} \frac{V_{i, \varepsilon}}{\#\{\varepsilon \mathcal{L} \cap P_k^{-1} D\}} = V_i.$$

Note that we exclude the case $V_i = 0$ for some i . This case contains some nontrivial aspects which are related to the concept of (B)-convexity studied in [Ambrosio and Braides 1990b]. Such conditions are not necessarily satisfied by our discrete energies. Of course the extreme case $V_{i, \varepsilon} = 0$ for all $\varepsilon > 0$ can be treated by changing the set \mathcal{S} and thus the whole model.

The following lemma describes how the volume constraint behaves for sequences with finite energy.

Lemma 6.1. *For \mathbb{P} -almost all $\omega \in \Omega$ the following statement holds true: for all $u \in \text{BV}(D, \mathcal{S})$ such that there exists a sequence $u_\varepsilon : \varepsilon \mathcal{L}(\omega) \rightarrow \mathcal{S}$ with $u_\varepsilon \rightarrow u$ in the sense of Definition 2.2 and*

$$\sup_{\varepsilon > 0} E_\varepsilon(\omega)(u_\varepsilon) \leq C, \quad \lim_{\varepsilon \rightarrow 0} \frac{\#\{\varepsilon x \in \varepsilon \mathcal{L}(\omega) \cap P_k^{-1} D : u_\varepsilon(\varepsilon x) = s_i\}}{\#\{\varepsilon x \in \varepsilon \mathcal{L}(\omega) \cap P_k^{-1} D\}} = V'_i,$$

we have

$$|\{u = s_i\}| = V'_i |D|.$$

Proof. Up to the transformation $T(s_i) = e_i$ we may assume that the vectors s_i form a basis. For $\omega \in \Omega$ we consider the sequence of nonnegative Borel measures $\gamma_\varepsilon(\omega)$ on D defined as

$$\gamma_\varepsilon(\omega) = \sum_{z \in P_k(\mathcal{L}(\omega)) \cap D/\varepsilon} \varepsilon^k \#(P_k^{-1}(z) \cap \mathcal{L}(\omega)) \delta_{\varepsilon z}.$$

As $\gamma_\varepsilon(\omega)(D) \leq C|D|$, up to subsequences we know that $\gamma_\varepsilon(\omega) \xrightarrow{*} \gamma(\omega)$ in the sense of measures. We now identify the limit measure. To this end we define a discrete stochastic process $\gamma : \mathcal{I}_k \rightarrow L^1(\Omega)$ as

$$\gamma(I)(\omega) := \sum_{y \in P_k(\mathcal{L}(\omega)) \cap I} \#(P_k^{-1}(y) \cap \mathcal{L}(\omega)) = \#(x \in \mathcal{L}(\omega) : P_k(x) \in I). \quad (6-49)$$

It follows from (2-4) that $\gamma(I)$ is essentially bounded for every $I \in \mathcal{I}_k$. In addition it can be checked that $\gamma(I)$ is \mathcal{F} -measurable; thus we infer that $\gamma(I) \in L^\infty(\Omega)$. Upon redefining the group action as $\tilde{\tau}_z = \tau_{-z}$, the process γ is stationary and (sub)additive. By Theorem 5.4 there exists $\gamma_0(\omega)$ such that for almost every $\omega \in \Omega$ and all $I \in \mathcal{I}_k$ we have

$$\lim_{n \rightarrow +\infty} \frac{\gamma(nI)(\omega)}{n^k |I|} = \gamma_0(\omega).$$

It is straightforward to extend this result to all sequences $t_n \rightarrow +\infty$ and then to all cubes in \mathbb{R}^k by a continuity argument. Now let $a, b \in \mathbb{R}^k$ and let $Q = [a, b)$. Then by definition

$$\lim_{\varepsilon \rightarrow 0} \gamma_\varepsilon(\omega)(Q) = \lim_{\varepsilon \rightarrow 0} \sum_{z \in P_k(\mathcal{L}(\omega)) \cap (1/\varepsilon)Q} \varepsilon^k \#(P_k^{-1}(z) \cap \mathcal{L}(\omega)) = \gamma_0(\omega)|Q|. \quad (6-50)$$

Given any open set $A \in \mathcal{A}(D)$, for $\delta > 0$ we consider the following interior approximation:

$$A_{\text{int}}(\delta) = \bigcup_{z \in \delta \mathbb{Z}^k : z + [0, \delta)^k \subset A} z + [0, \delta)^k.$$

It can be checked by monotone convergence that $\lim_{\delta \rightarrow 0} |A(\delta)| = |A|$. By (6-50) and additivity we obtain

$$\liminf_{\varepsilon \rightarrow 0} \gamma_\varepsilon(\omega)(A) \geq \liminf_{\varepsilon \rightarrow 0} \gamma_\varepsilon(\omega)(A(\delta)) = \gamma_0(\omega)|A(\delta)|.$$

Letting $\delta \rightarrow 0$ we obtain $\liminf_{\varepsilon} \gamma_\varepsilon(\omega)(A) \geq \gamma_0(\omega)|A|$. By the portmanteau theorem we conclude that $\gamma(\omega)(B) = \gamma_0(\omega)|B|$ for all Borel sets $B \subset D$. In particular the whole sequence converges in the sense of measures. On the other hand, if $A \in \mathcal{A}(D)$ is such that $|\partial A| = 0$, then the outer approximation

$$A_{\text{out}}(\delta) = \bigcup_{z \in \delta \mathbb{Z}^k : z + [0, \delta)^k \cap A \neq \emptyset} z + [0, \delta)^k$$

also fulfills $\lim_{\delta \rightarrow 0} |A(\delta)| = |A|$; hence

$$\lim_{\varepsilon \rightarrow 0} \gamma_\varepsilon(\omega)(A) = \gamma_0(\omega)|A| \quad (6-51)$$

for all $A \in \mathcal{A}(D)$ such that $|\partial A| = 0$. Given now $\delta > 0$, we take any polyhedral function $u_\delta \in \text{BV}_{\text{loc}}(\mathbb{R}^k, \mathcal{S})$ such that $\|u - u_\delta\|_{L^1(D)} \leq \delta$. As u_δ is Borel-measurable, we have

$$\int_D P u_\varepsilon \, d\gamma_\varepsilon(\omega) = \int_D (P u_\varepsilon - u_\delta) \, d\gamma_\varepsilon(\omega) + \int_D u_\delta \, d\gamma_\varepsilon(\omega).$$

Since u_δ is a polyhedral function, we can use (6-51) to obtain

$$\lim_{\varepsilon \rightarrow 0} \int_D u_\delta \, d\gamma_\varepsilon(\omega) = \gamma_0(\omega) \int_D u_\delta \, dx. \tag{6-52}$$

Concerning the first term, by (2-2) and the regularity of S_{u_δ} and ∂D we have

$$\left| \int_D (Pu_\varepsilon - u_\delta) \, d\gamma_\varepsilon(\omega) \right| \leq C \sum_{z \in P_k(\mathcal{L}(\omega)) \cap D/\varepsilon} \varepsilon^k |Pu_\varepsilon(\varepsilon z) - u_\delta(\varepsilon z)|. \tag{6-53}$$

Now using the fact that u_ε has equibounded energy, one can reason as in the proof of Lemma 2.5 to show that

$$\limsup_{\varepsilon \rightarrow 0} \sum_{z \in P_k(\mathcal{L}(\omega)) \cap D/\varepsilon} \varepsilon^k |Pu_\varepsilon(\varepsilon z) - u_\delta(\varepsilon z)| \leq C \|u - u_\delta\|_{L^1(D)} \leq C\delta.$$

Combining the above inequality with (6-52) and (6-53) we finally obtain by the arbitrariness of δ that

$$\lim_{\varepsilon \rightarrow 0} \int_D Pu_\varepsilon \, d\gamma_\varepsilon(\omega) = \gamma_0(\omega) \int_D u \, dx = \gamma_0(\omega) \sum_{i=1}^q s_i |\{u = s_i\}|$$

On the other hand, plugging in the definition and using again (6-51), it holds

$$\lim_{\varepsilon \rightarrow 0} \int_D Pu_\varepsilon \, d\gamma_\varepsilon(\omega) = \lim_{\varepsilon \rightarrow 0} \sum_{i=1}^q s_i \#\{\varepsilon x \in \varepsilon \mathcal{L}(\omega) \cap D : u_\varepsilon(\varepsilon x) = s_i\} \varepsilon^k = \sum_{i=1}^q s_i V'_i |D| \gamma_0(\omega).$$

Since we assumed the s_i form a basis, we conclude the proof. □

In order to include the volume constraint in the functional, for almost every $\omega \in \Omega$ we introduce $E_\varepsilon^{V_\varepsilon}(\omega) : \mathcal{PC}_\varepsilon(\omega) \rightarrow [0, +\infty]$ as

$$E_\varepsilon^{V_\varepsilon}(\omega)(u) = \begin{cases} E_\varepsilon(\omega)(u) & \text{if } u \in \mathcal{PC}_\varepsilon^{V_\varepsilon}(\omega), \\ +\infty & \text{otherwise.} \end{cases}$$

With the help of Lemma 6.1 we can now prove the following theorem.

Theorem 6.2. *Let \mathcal{L} be a stationary stochastic lattice and let f_{nn} and f_{lr} satisfy Hypotheses 1 and 2. For \mathbb{P} -almost every ω the functionals $E_\varepsilon^{V_\varepsilon}(\omega)$ Γ -converge with respect to the convergence of Definition 2.2 to the functional $E_{\text{hom}}^V(\omega) : L^1(D, \mathbb{R}^q) \rightarrow [0, +\infty]$ defined by*

$$E_{\text{hom}}^V(\omega)(u) = \begin{cases} \int_{S_u} \phi_{\text{hom}}(\omega; u^+, u^-, \nu_u) \, d\mathcal{H}^{k-1} & \text{if } u \in \text{BV}(D, S) \text{ and } |\{u = s_i\}| = V_i |D| \text{ for all } i, \\ +\infty & \text{otherwise.} \end{cases}$$

Proof. The lower bound follows from Theorem 5.8 and Lemma 6.1. In order to prove the upper bound, for the moment assume that $u \in \text{BV}(D, S)$ satisfies the volume constraint and that each level set $\{u = s_i\}$ contains an interior point. In particular, in each level set we find q disjoint open balls $B_\eta(x_i^l) \Subset \{u = s_i\}$ with $\eta \ll 1$. By Theorem 5.8 we can find a sequence $u_\varepsilon : \varepsilon \mathcal{L}(\omega) \rightarrow S$ such that u_ε converges to u in the sense of Definition 2.2 and

$$\lim_{\varepsilon \rightarrow 0} E_\varepsilon(\omega)(u_\varepsilon) = E_{\text{hom}}(\omega)(u). \tag{6-54}$$

Repeating the argument used for proving [Proposition 3.6](#), one can show that without loss of generality we may assume that $u_\varepsilon(\varepsilon x) = s_i$ for all $\varepsilon x \in \varepsilon\mathcal{L}(\omega) \cap B_\eta(x_i^1)$ and that u_ε has equibounded energy on a large cube Q_D containing \bar{D} . For each i set $\tilde{V}_{i,\varepsilon} = \#\{\varepsilon x \in \varepsilon\mathcal{L}(\omega) \cap P_k^{-1}D : u_\varepsilon(\varepsilon x) = s_i\}$. Applying [Lemma 6.1](#) we deduce that

$$\lim_{\varepsilon \rightarrow 0} \frac{\tilde{V}_{i,\varepsilon} - V_{i,\varepsilon}}{\#\{\varepsilon x \in \varepsilon\mathcal{L}(\omega) \cap P_k^{-1}D\}} = 0. \quad (6-55)$$

We now adjust the sequence u_ε so that it belongs to $\mathcal{PC}_\varepsilon^{V_\varepsilon}(\omega)$. This will be done locally on the balls $B_\eta(x_i^1)$. First we change the values on $B_\eta(x_1^1)$ and $B_\eta(x_2^1)$ so that the sequence satisfies the constraint for $i = 1$. In general, for $i < q$ we change the sequence on $B_\eta(x_i^1)$ and $B_\eta(x_{i+1}^1)$ so that it satisfies the constraints for all $j \leq i$. At the end the constraint for $i = q$ follows by the compatibility assumption. Each modification will be such that L^1 -convergence and convergence of the energies is conserved. We will provide the construction only for the first step. In what follows we consider the case $\tilde{V}_{1,\varepsilon} > V_{1,\varepsilon}$. We set $h_\varepsilon = (\tilde{V}_{1,\varepsilon} - V_{1,\varepsilon})^{1/k}$. Up to modifying u_ε on a set of lattice points contained in the complement of the union of the balls $B_\eta(x_i^1)$ and with diverging cardinality much less than ε^{1-k} , we may assume that $h_\varepsilon \rightarrow +\infty$. Note that such a modification still yields a recovery sequence.

Observe that [\(6-55\)](#) and the properties of a thin admissible lattice imply

$$\lim_{\varepsilon \rightarrow 0} h_\varepsilon \varepsilon = 0. \quad (6-56)$$

We already know from the proof of [Lemma 6.1](#) that, almost surely, we can write

$$q^\omega(x_1^1, h_\varepsilon) := \#\{x \in \mathcal{L}(\omega) : P_k(x) \in Q_{e_1}(x_1^1, \gamma_0(\omega)^{-1}h_\varepsilon)\} = h_\varepsilon^k + h_\varepsilon^{k-1}\gamma_\varepsilon$$

for some sequence $\gamma_\varepsilon = \gamma_\varepsilon(\omega, x_1^1)$ such that $\lim_{\varepsilon \rightarrow 0}(\gamma_\varepsilon/h_\varepsilon) = 0$. In the following we assume that $\gamma_\varepsilon \leq 0$, but with a similar argument we can also treat the case $\gamma_\varepsilon > 0$. As $\mathcal{L}(\omega)$ is thin admissible in the sense of [Definition 2.1](#), one can show that for some appropriate $c = c(R) > 0$ it holds true that

$$\frac{1}{C}h_\varepsilon^{k-1} \leq q^\omega(x_0, h_\varepsilon + n + c) - q^\omega(x_0, h_\varepsilon + n) \leq Ch_\varepsilon^{k-1}$$

for any $0 \leq n \leq h_\varepsilon$. In particular, there exist $n_\varepsilon = \mathcal{O}(\gamma_\varepsilon)$ and nonnegative equibounded c_ε such that

$$q^\omega(x_0, h_\varepsilon + n_\varepsilon) = h_\varepsilon^k + c_\varepsilon h_\varepsilon^{k-1}. \quad (6-57)$$

Now choose any set $G_\varepsilon \subset \mathbb{R}^d$ such that $P_k G_\varepsilon \subset B_\eta(x_2^1)$ and $\#(G_\varepsilon \cap \mathcal{L}(\omega)) = c_\varepsilon h_\varepsilon^{k-1}$. To reduce notation, set $Q_\varepsilon := Q_{e_1}(x_1^1, \gamma_0(\omega)^{-1}\varepsilon(h_\varepsilon + n_\varepsilon))$. We define

$$\bar{u}_\varepsilon(\varepsilon x) = \begin{cases} s_2 & \text{if } \varepsilon P_k(x) \in Q_\varepsilon, \\ s_1 & \text{if } \varepsilon x \in G_\varepsilon, \\ u_\varepsilon(\varepsilon x) & \text{otherwise.} \end{cases}$$

Note that by [\(6-56\)](#) we have $Q_\varepsilon \Subset B_\eta(x_1^1)$ for ε small enough and therefore

$$\#\{\varepsilon x \in \varepsilon\mathcal{L}(\omega) \cap P_k^{-1}D : \bar{u}_\varepsilon(\varepsilon x) = s_1\} = V_{1,\varepsilon}.$$

Again by (6-56) we still have $\bar{u}_\varepsilon \rightarrow u$ in the sense of Definition 2.2. From Hypothesis 1 we deduce

$$E_\varepsilon(\omega)(\bar{u}_\varepsilon) \leq E_\varepsilon(\omega)(u_\varepsilon) + C \sum_{\xi \in r'\mathbb{Z}_M^d} J_{I_r}(|\hat{\xi}|) \#(G_\varepsilon \cap \varepsilon\mathcal{L}(\omega)) \varepsilon^{k-1} + \sum_{\xi \in r'\mathbb{Z}_M^d} \sum_{\substack{\alpha \in R_\varepsilon^\xi(D) \\ \varepsilon P_k([x_\alpha, x_{\alpha+\xi}]) \cap \partial Q_\varepsilon \neq \emptyset}} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, \bar{u}_\varepsilon(\varepsilon x_\alpha), \bar{u}_\varepsilon(\varepsilon x_{\alpha+\xi})).$$

It remains to bound the last term since the second one vanishes by (6-56) and the integrability of J_{I_r} . We split the interactions according to (2-12). By Lemma 2.7 and Hypothesis 1, for ε small enough we have by construction

$$\sum_{|\hat{\xi}| \leq L_\delta} \sum_{\substack{\alpha \in R_\varepsilon^\xi(D) \\ \varepsilon P_k([x_\alpha, x_{\alpha+\xi}]) \cap \partial Q_\varepsilon \neq \emptyset}} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, \bar{u}_\varepsilon(\varepsilon x_\alpha), \bar{u}_\varepsilon(\varepsilon x_{\alpha+\xi})) \leq C \sum_{|\hat{\xi}| \leq L_\delta} J_{I_r}(|\hat{\xi}|) |\xi| \sum_{\substack{(x,y) \in \mathcal{NN}(\omega) \\ \varepsilon x, \varepsilon y \in B_\eta(x_1^+)}} \varepsilon^{k-1} f_\varepsilon(x, y, \bar{u}_\varepsilon(\varepsilon x), \bar{u}_\varepsilon(\varepsilon y)) \leq C \mathcal{H}^{k-1}(\partial Q_\varepsilon) \leq C(\varepsilon h_\varepsilon)^{k-1}, \tag{6-58}$$

so that the left-hand side vanishes when $\varepsilon \rightarrow 0$. To control the remaining interactions, recall that u_ε has finite energy on the larger cube Q_D . Hence Lemma 2.7 and Hypothesis 1 yield

$$\sum_{|\hat{\xi}| > L_\delta} \sum_{\substack{\alpha \in R_\varepsilon^\xi(D) \\ \varepsilon P_k([x_\alpha, x_{\alpha+\xi}]) \cap \partial Q_\varepsilon \neq \emptyset}} \varepsilon^{k-1} f_\varepsilon(x_\alpha, x_{\alpha+\xi}, \bar{u}_\varepsilon(\varepsilon x_\alpha), \bar{u}_\varepsilon(\varepsilon x_{\alpha+\xi})) \leq C\delta \sum_{\substack{(x,y) \in \mathcal{NN}(\omega) \\ \varepsilon x, \varepsilon y \in Q_D}} \varepsilon^{k-1} f_\varepsilon(x, y, \bar{u}_\varepsilon(\varepsilon x), \bar{u}_\varepsilon(\varepsilon y)) \leq C\delta(E_\varepsilon(\omega)(u_\varepsilon, Q_D) + \mathcal{H}^{k-1}(\partial Q_\varepsilon) + \#(G_\varepsilon \cap \varepsilon\mathcal{L}(\omega))\varepsilon^{k-1}) \leq C\delta.$$

As $\delta > 0$ was arbitrary, we infer from (6-54), (6-58) and (6-58) that

$$\limsup_{\varepsilon \rightarrow 0} E_\varepsilon(\omega)(\bar{u}_\varepsilon) = \limsup_{\varepsilon \rightarrow 0} E_\varepsilon(\omega)(u_\varepsilon) = E_{\text{hom}}(\omega)(u).$$

The case when $V'_\varepsilon \leq V_\varepsilon$ can be treated by an almost symmetric argument. Repeating this construction for the remaining phases as described at the beginning of this proof, we obtain

$$\Gamma\text{-}\limsup_{\varepsilon \rightarrow 0} E_\varepsilon^{V_\varepsilon}(\omega)(u) = E_{\text{hom}}(\omega)(u).$$

Now for a general $u \in \text{BV}(D, \mathcal{S})$ such that $|\{u = s_i\}| = V_i|D|$, the statement follows by density. This procedure is classical, see [Ambrosio and Braides 1990a], and therefore we omit the details. \square

7. A model for random deposition

The general homogenization result proved in Section 5 describes only the qualitative phenomenon that interfaces may form on the flat subspace. In this final section we investigate the asymptotic behavior of the

limit energy as a function of the average thickness. To simplify matters, we consider a three-dimensional to two-dimensional dimension-reduction problem in which magnetic particles are deposited with vertical order on a two-dimensional flat substrate and interact via finite-range ferromagnetic interactions of Ising-type, which means in particular that $\mathcal{S} = \{\pm 1\}$. We obtain information on the dependence of the limit energy on the average thickness when the latter is very small or very large.

In order to model the substrate where the particles are deposited, we take a two-dimensional deterministic lattice, which we choose for simplicity to be $\mathcal{L}^0 = \mathbb{Z}^2 \times \{0\}$. We then consider an independent random field $\{X_i^p\}_{i \in \mathbb{Z}^3}$, where the X_i^p are Bernoulli random variables with $\mathbb{P}(X_i^p = 1) = p \in (0, 1)$ and, for fixed $M \in \mathbb{N}$, we define the random point set

$$\mathcal{L}_p^M(\omega) := \{(i_1, i_2, i_3) \in \mathbb{Z}^3 : 0 \leq i_3 \leq \sum_{k=1}^M X_{(i_1, i_2, k)}^p(\omega)\}, \tag{7-59}$$

which means that we successively deposit particles M times independently on the flat lattice \mathcal{L}^0 and stack them over each other (see [Figure 3](#)). Note that the point set constructed in (7-59) is stationary with respect to integer translations in \mathbb{Z}^2 and ergodic by the independence assumption. Given $u : \varepsilon \mathcal{L}_p^M(\omega) \rightarrow \{\pm 1\}$, we consider an energy of the form

$$E_{\varepsilon, M}^p(\omega)(u, A) = \sum_{\substack{x, y \in \mathcal{L}_p^M(\omega) \\ P_2(x), P_2(y) \in A/\varepsilon}} \varepsilon c(x - y) |u(\varepsilon x) - u(\varepsilon y)|, \tag{7-60}$$

where the interaction $c : \mathbb{R}^3 \rightarrow [0, +\infty)$ fulfills

- (i) $c(z) \leq C$ for all $z \in \mathbb{R}^3$,
- (ii) $c(z) = 0$ if $|z| \geq L$,
- (iii) $c(z) \geq c_0 > 0$ if $|z| = 1$.

Remark 7.1. The coefficients above satisfy [Hypothesis 2](#), but in general are not coercive, as required in [Hypothesis 1](#). However, the results obtained in the first part of this paper still hold true. This is due to the vertical order of the deposition model, which makes the proof of coercivity much simpler. However, note that, for instance, the constant in [Lemma 2.7](#) now depends strongly on M .

Due to [Remark 7.1](#) we can apply [Theorem 5.8](#) and thus we know that there exists the effective (deterministic) surface tension

$$\phi_{\text{hom}}^p(M; \nu) := \lim_{t \rightarrow +\infty} \frac{1}{t} \inf \{ E_{1, M}^p(\omega)(v, Q_\nu(0, t)) : v(x) = u_{0, \nu}(P_2(x)) \text{ if } \text{dist}(P_2(x), \partial Q_\nu(0, t)) \leq 2L \},$$

where we used the alternative formula in [Remark 5.9](#) and [Remark 4.2](#). Note that, due to symmetry reasons, the surface tension does not depend on the traces; see also [\[Alicandro et al. 2015\]](#).

We are interested in the asymptotic behavior of $\phi_{\text{hom}}^p(M; \nu)$ when $M \rightarrow +\infty$. First, we define some auxiliary quantities. Given $p \in (0, 1]$, $0 \leq N < M$ and $u : \mathbb{Z}^3 \rightarrow \{\pm 1\}$, we set

$$E_{[N, M]}^p(\omega)(u, O) := \sum_{\substack{x, y \in \mathcal{L}_p^M(\omega) \\ x, y \in O \times [N, M]}} c(x - y) |u(x) - u(y)|$$

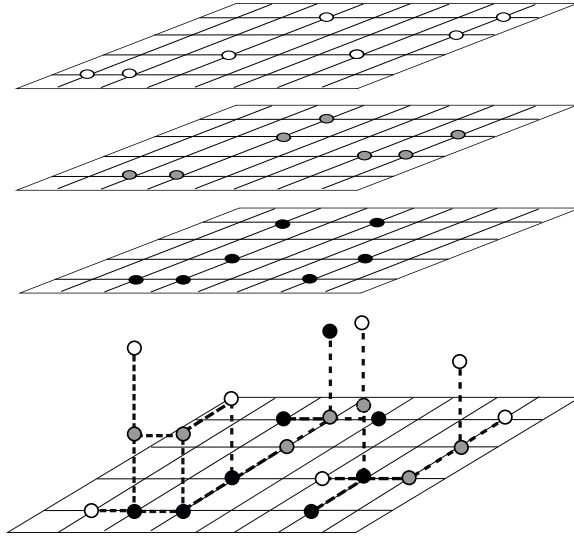


Figure 3. Three successive deposition steps (black, gray and white) in the construction of $\mathcal{L}_p^M(\omega)$. The dashed bonds connect nearest neighboring particles.

and omit the dependence on ω of $E_{[N,M]}^p$ when $p = 1$. In that case, given $v \in S^1$ we further introduce the corresponding surface tension

$$\phi^{1,M}(v) = \lim_{t \rightarrow +\infty} \frac{1}{t} \inf \{ E_{[0,M]}^1(u, Q_v(0, t)) : v(x) = u_{0,v}(P_2(x)) \text{ if } \text{dist}(P_2(x), \partial Q_v(0, t)) \leq 2L \}.$$

Note that the existence of this limit follows by standard subadditivity arguments. The next lemma shows that the auxiliary surface tensions converge when $M \rightarrow +\infty$.

Lemma 7.2. *For any $v \in S^1$ there exists the limit*

$$\phi^1(v) := \lim_{M \rightarrow +\infty} \frac{1}{M} \phi^{1,M}(v).$$

Proof. We define a sequence $a_k = \phi^{1,k-1}(v)$. It is enough to show that a_k is superadditive. To reduce notation, similar to (5-29) we introduce

$$m_{[N,M]}(u_{0,v}, Q_v(x, \rho)) := \inf \{ E_{[N,M]}^1(u, Q_v(x, \rho)) : u \in \mathcal{PC}_{1,u_{0,v}}^{2L}(Q_v(x, \rho)) \}.$$

Note that by periodicity, $m_{[N,M]}(u_{0,v}, Q_v(x, \rho)) = m_{[N+k,M+k]}(u_{0,v}, Q_v(x, \rho))$ for every $k \in \mathbb{N}$. For fixed $t \gg 1$ one can take any admissible configuration for $m_{[0,M+M'-1]}(u_{0,v}, Q_v(0, t))$ and restrict it to the sets $Q_v(0, t) \times [0, M - 1]$ and $Q_v(0, t) \times [M, M + M' - 1]$ to obtain the inequality

$$\begin{aligned} \frac{1}{t} m_{[0,M+M'-1]}(u_{0,v}, Q_v(0, t)) &\geq \frac{1}{t} m_{[0,M-1]}(u_{0,v}, Q_v(0, t)) + \frac{1}{t} m_{[M,M+M'-1]}(u_{0,v}, Q_v(0, t)) \\ &= \frac{1}{t} m_{[0,M-1]}(u_{0,v}, Q_v(0, t)) + \frac{1}{t} m_{[0,M'-1]}(u_{0,v}, Q_v(0, t)), \end{aligned}$$

where we neglected the interactions between the two cubes and used periodicity in the last equality. Letting $t \rightarrow +\infty$, we obtain superadditivity of the sequence a_k . □

The next result shows the asymptotic behavior of the surface tension when the average number of layers pM diverges.

Proposition 7.3. *Let ϕ^1 be defined as in the previous lemma. For $v \in S^1$ it holds that*

$$\lim_{M \rightarrow +\infty} \frac{\phi_{\text{hom}}^p(M; v)}{pM} = \phi^1(v).$$

Proof. Throughout this proof we assume without loss of generality that $L \in \mathbb{N}$ and we set $\mathbb{Z}_M^2 = \mathbb{Z}^2 \times \{0, \dots, M\}$. Fix $v \in S^1$ (we will drop the dependence on v for several quantities). We separately show two inequalities. For the moment we also fix M . Consider a sequence of minimizing configurations u_N such that $\lim_N (1/N) E_{[0, M]}^1(u_N, Q_v(0, N)) = \phi^{1, M}(v)$. As we show now, we can assume that u_N is a plane-like configuration, as given by [Theorem A.3](#). Indeed, applying that theorem we find a plane-like ground state u_v for the energy

$$E_M(u, Q_v(0, N)) := \sum_{\substack{x \in \mathbb{Z}_M^2 \\ P_2(x) \in Q_v(0, N)}} \sum_{y \in \mathbb{Z}_M^2} c(x - y) |u(x) - u(y)|.$$

To reduce notation, we set

$$S_v(N, \lambda) = \{x \in \mathbb{R}^2 : x \in Q_v(0, N), \text{dist}(x, \{v\}^\perp) \leq 4(\lambda + L)\}$$

so that the energy of u_v is concentrated on $S_v(N, \lambda) \times [0, M]$ with $\lambda \leq CM$ (see [Theorem A.3](#)). For any $N \in \mathbb{N}$ we define two configurations $\bar{u}_N, \tilde{u}_N : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ via

$$\begin{aligned} \bar{u}_N(x) &= \begin{cases} u_{0,v}(P_2(x)) & \text{if } \text{dist}(P_2(x), \mathbb{R}^2 \setminus Q_v(0, N)) \leq 2L, \\ u_v(x) & \text{otherwise,} \end{cases} \\ \tilde{u}_N(x) &= \begin{cases} u_v(x) & \text{if } \text{dist}(P_2(x), \mathbb{R}^2 \setminus (Q_v(0, N))) \leq L, \\ u_N(x) & \text{otherwise.} \end{cases} \end{aligned}$$

Then \bar{u}_N is a plane-like configuration whose energy is again concentrated on $S_v(N, \lambda) \times [0, M]$. Using the boundary conditions and the finite-range assumptions one can prove that

$$\begin{aligned} E_{[0, M]}^1(u_N, Q_v(0, N)) &\leq E_{[0, M]}^1(\bar{u}_N, Q_v(0, N)) \leq E_M(u_v, Q_v(0, N)) + CM^2 \\ &\leq E_M(\tilde{u}_N, Q_v(0, N)) + CM^2 \leq E_{[0, M]}^1(u_N, Q_v(0, N)) + 2CM^2. \end{aligned}$$

Dividing by N and letting $N \rightarrow +\infty$ we see that asymptotically we can replace u_N by the plane-like configuration \bar{u}_N . From now on we denote by $u_{N, M}$ a plane-like minimizer whose energy is concentrated on $S_v(N, \lambda) \times [0, M]$ with $\lambda \leq CM$ and such that

$$\phi^{1, M}(v) = \lim_N \frac{1}{N} E_{[0, M]}^1(u_{N, M}, Q_v(0, N)).$$

We extend $u_{N, M}$ to \mathbb{Z}^3 setting $u_{N, M}(x) = u_{0,v}(P_2(x))$ for $x_3 \notin \{0, \dots, M\}$. For $\delta > 0$ small enough, we separate the contribution of the bottom and the first $M_\delta^p := \lceil (p + \delta)M \rceil$ random layers and estimate the

remaining interactions. This leads to

$$\begin{aligned} \frac{1}{M} \phi_{\text{hom}}^p(M; \nu) &\leq \frac{1}{M} \liminf_{N \rightarrow +\infty} \frac{1}{N} \mathbb{E}[E_{1,M}^p(\omega)(u_{N, M_\delta^p}, Q_\nu(0, N))] \\ &\leq \frac{1}{M} \liminf_{N \rightarrow +\infty} \frac{1}{N} \mathbb{E}[E_{[0, M_\delta^p]}^1(u_{N, M_\delta^p}, Q_\nu(0, N))] \\ &\quad + \frac{C}{M} \limsup_{N \rightarrow +\infty} \frac{1}{N} \mathbb{E}[\#\{x \in \mathcal{L}_p^M(\omega) : x \in S_\nu(N, \lambda) \times (M_\delta^p - L, M)\}] \\ &\leq \frac{1}{M} \phi^{1, M_\delta^p}(\nu) + C \mathbb{E}[\#\{x \in \mathcal{L}_p^M(\omega) : x \in \{(0, 0)\} \times (M_\delta^p - L, M)\}] \\ &\leq \frac{1}{M} \phi^{1, M_\delta^p}(\nu) + C \sum_{k=M_\delta^p-L}^M (k - M_\delta^p + L) \binom{M}{k} p^k (1-p)^{M-k}, \end{aligned}$$

where in the last step we have used that the probability of having k points in $\{(0, 0)\} \times (M_\delta^p - L, M]$ is the same as having $k + M_\delta^p - L$ successes out of M trials in a Bernoulli experiment. In order to bound the last sum, we use Hoeffding's inequality, which yields, for M large enough depending on L, δ ,

$$\mathbb{P}\left(\sum_{i=1}^M X_{(0,0,i)}^p \geq k + M_\delta^p - L\right) \leq \mathbb{P}\left(\sum_{i=1}^M X_{(0,0,i)}^p \geq k + \left(p + \frac{\delta}{2}\right)M\right) \leq \exp\left(-2M\left(\frac{\delta}{2} + \frac{k}{M}\right)^2\right).$$

From this bound we infer the estimate

$$\sum_{k=M_\delta^p-L}^M (k - M_\delta^p + L) \binom{M}{k} p^k (1-p)^{M-k} \leq \sum_{k=1}^M k \exp\left(-\frac{1}{2}M\delta^2\right) \exp(-2\delta k).$$

Since the right-hand side vanishes when $M \rightarrow +\infty$, by [Lemma 7.2](#) we deduce $\limsup_M (1/M) \phi_{\text{hom}}^p(M; \nu) \leq (p+\delta) \phi^1(\nu)$. Since δ was arbitrary, the first inequality is proven.

It remains to show the reverse inequality. Given any admissible function $v_N : \mathcal{L}_p^M(\omega) \rightarrow \{\pm 1\}$, we can neglect the interactions coming from $Q_\nu(0, N) \times [M_{-\delta}^p + 1, M]$, which yields the estimate

$$E_{1,M}^p(\omega)(v_N, Q_\nu(0, N)) \geq E_{[0, M_{-\delta}^p]}^p(\omega)(v_N, Q_\nu(0, N)).$$

Minimizing on both sides and dividing by N , we obtain in the limit that

$$\frac{1}{M} \phi_{\text{hom}}^p(M; \nu) \geq \frac{1}{M} \phi^{p, M_{-\delta}^p}(\nu). \tag{7-61}$$

Now the idea is to estimate the error when we replace $\phi^{p, M_{-\delta}^p}(\nu)$ by $\phi^{1, M_{-\delta}^p}(\nu)$. Let u_N be a sequence of plane-like configurations as in the first part of the proof. We also consider an optimal sequence $u_N^{p, \delta} = u_N^{p, \delta}(\omega)$ such that

$$\phi^{p, M_{-\delta}^p}(\nu) = \lim_{N \rightarrow +\infty} \frac{1}{N} \mathbb{E}[E_{[0, M_{-\delta}^p]}^p(\omega)(u_N^{p, \delta}, Q_\nu(0, N))].$$

Since the deterministic surface tension dominates the random one, we have

$$\begin{aligned} 0 \leq \phi^{1, M_{-\delta}^p}(v) - \phi^{p, M_{-\delta}^p}(v) &= \lim_N \frac{1}{N} \mathbb{E} \left[E_{[0, M_{-\delta}^p]}^1(u_N, S_v(N, \lambda)) - E_{[0, M_{-\delta}^p]}^p(\omega)(u_N^{p, \delta}(\omega), Q_v(0, N)) \right] \\ &\leq \limsup_N \frac{1}{N} \mathbb{E} \left[E_{[0, M_{-\delta}^p]}^1(u_N^{p, \delta}, S_v(N, \lambda)) - E_{[0, M_{-\delta}^p]}^p(\omega)(u_N^{p, \delta}(\omega), S_v(N, \lambda)) \right] \\ &\leq C \limsup_N \frac{1}{N} \mathbb{E} \left[\#\{x \in (S_v(\lambda, N) \times [1, M_{-\delta}^p]) \cap \mathbb{Z}^3 : x \notin \mathcal{L}_p^M(\omega)\} \right] \\ &\leq CM \mathbb{E} \left[\max \left\{ M_{-\delta}^p - \sum_{i=1}^M X_{(0,0,i)}^p, 0 \right\} \right] \leq CM \sum_{k=1}^{M_{-\delta}^p} k \mathbb{P} \left(M_{-\delta}^p - \sum_{i=1}^M X_{(0,0,i)}^p \geq k \right). \end{aligned}$$

Here we used that the number of missing interactions can be estimated by the number of missing lattice points since each point can only interact with finitely many others. Now we apply again Hoeffding’s inequality, which yields

$$\mathbb{P} \left(M_{-\delta}^p - \sum_{i=1}^M X_{(0,0,i)}^p \geq k \right) \leq \mathbb{P} \left(M \left(p - \frac{\delta}{2} \right) - k \geq \sum_{i=1}^M X_{(0,0,i)}^p \right) \leq \exp \left(-2M \left(\frac{\delta}{2} + \frac{k}{M} \right)^2 \right).$$

We conclude the bound

$$\sum_{k=1}^{M_{-\delta}^p} k \mathbb{P} \left(M_{-\delta}^p - \sum_{i=1}^M X_{(0,0,i)}^p \geq k \right) \leq \sum_{k=1}^{M_{-\delta}^p} k \exp \left(-\frac{1}{2} M \delta^2 \right) \exp \left(-2\delta k \right).$$

Again the right-hand side vanishes when $M \rightarrow +\infty$ and thus $\lim_M (1/M) |\phi^{1, M_{-\delta}^p}(v) - \phi^{p, M_{-\delta}^p}(v)| = 0$, so that [Lemma 7.2](#) and (7-61) imply the estimate

$$\liminf_{M \rightarrow +\infty} \frac{1}{M} \phi_{\text{hom}}^p(M; v) \geq \lim_{M \rightarrow +\infty} \frac{1}{M} \phi^{1, M_{-\delta}^p}(v) = (p - \delta) \phi^1(v).$$

Again the desired estimate follows by the arbitrariness of $\delta > 0$. □

Remark 7.4. If we had not included the initial layer \mathcal{L}^0 , then [Proposition 7.3](#) would still hold. However, then the surface tension may not be related to an appropriate Γ -limit since the compactness of sequences with bounded energy becomes a nontrivial issue. We refer to [\[Braides and Piatnitski 2012\]](#) for a possible approach to this problem in the case of nearest-neighbor interactions and bond-percolation models.

A percolation-type phenomenon. We close this final section with a result on the growth of the averaged surface tension when the number of layers increases. We let $\mathcal{L}_p^M(\omega)$ be defined as in (7-59) but restrict the analysis to nearest-neighbor interactions and make them nonperiodic in the sense that their magnitude is very small when one of the particles belongs to the initial layer \mathcal{L}^0 . More precisely, given $0 < \eta \ll 1$ we consider functions of the form

$$c_\eta(\Delta_2(x, y)) = \begin{cases} 0 & \text{if } |x - y| > 1, \\ \eta & \text{if } |x - y| = 1 \text{ and } x_3 \cdot y_3 = 0, \\ c(x - y) & \text{otherwise,} \end{cases}$$

where Δ_2 is defined in [Hypothesis 2](#) and $x \mapsto c(x)$ is strictly positive on the unit circle. Then the coefficients satisfy [Hypothesis 2](#) and fulfill (a slightly weaker version of) [Hypothesis 1](#). We define $E_{\varepsilon, M}^{p, \eta}$ as in [\(7-60\)](#) with c replaced by c_η . According to [Theorem 5.8](#), again there exists the limit

$$\phi_{\text{hom}}^{p, \eta}(M; \nu) := \lim_{t \rightarrow +\infty} \frac{1}{t} \inf \{ E_{1, M}^{p, \eta}(\omega)(\nu, Q_\nu(0, t)) : \nu(x) = u_{0, \nu}(P_2(x)) \text{ if } \text{dist}(P_2(x), \partial Q_\nu(0, t)) \leq 2 \}.$$

In contrast to [Proposition 7.3](#), for this model we also consider the case of small M . We will show that if $p < 1 - p_{\text{site}}$, where p_{site} is the critical site percolation probability on \mathbb{Z}^2 , then it holds that

$$\phi_{\text{hom}}^{p, \eta}(1; \nu) \leq C_p \eta,$$

where C_p may blow up only for $p \rightarrow 1 - p_{\text{site}}$. Note that we do not claim here that p_{site} is the optimal bound. We can actually improve the result in the sense that for all $M \in \mathbb{N}$ such that $(1 - p)^M > p_{\text{site}}$, we have

$$\phi_{\text{hom}}^{p, \eta}(M; \nu) \leq C_p \eta.$$

This shows that when the probability is very small but finite, the surface tension can be arbitrary small depending on the strength of the interaction in the substrate layer, on the other hand we will establish an analogue of [Proposition 7.3](#) asserting that if the average number of layers increases further, even the normalized surface tension approaches a value independent of η . This result can be interpreted as the equivalent to the percolation phenomenon described in the introduction of the paper for the model without initial layer ($\eta = 0$). Before proving this result, we introduce the typical energy of one slice. Given $q \in (0, 1]$ and $u : \mathbb{Z}^2 \rightarrow \{\pm 1\}$, we set

$$E_{sl}^q(\omega)(u, A) := \sum_{\substack{x, y \in \mathcal{L}_q^1(\omega) \setminus \mathcal{L}^0 \\ P_2(x), P_2(y) \in A}} c(x - y) |u(x) - u(y)|$$

and omit the dependence on ω if $q = 1$. We further introduce the corresponding surface tension

$$\phi_{sl}^q(\nu) = \lim_{t \rightarrow +\infty} \frac{1}{t} \inf \{ E_{sl}^q(\omega)(\nu, Q_\nu(0, t)) : \nu(x) = u_{0, \nu}(x) \text{ if } \text{dist}(x, \partial Q_\nu(0, t)) \leq 2 \}.$$

Note that the existence of this deterministic limit follows again from the subadditive ergodic theorem as in the proof of [Theorem 5.8](#), since we used the coercivity only for passing from finite range to decaying interactions in Step 4. In general the random variables $\omega \mapsto E_{sl}^q(\omega)(u, A)$ are not defined on the same probability space but we will use them only for slices of the large set $\mathcal{L}_p^M(\omega)$.

Theorem 7.5. *Let $p \in (0, 1)$ and $M \in \mathbb{N}$ be such that $(1 - p)^M > p_{\text{site}}$. There exists a constant $C_{p, M}$ locally bounded for $(1 - p)^M \in (p_{\text{site}}, 1)$ such that*

$$\phi_{\text{hom}}^{p, \eta}(M; \nu) \leq C_{p, M} \eta.$$

On the other hand, for any $p \in (0, 1)$ it holds that

$$\lim_{M \rightarrow +\infty} \frac{1}{M} \phi_{\text{hom}}^{p, \eta}(M; \nu) = 2p \left((c(e_1) + c(-e_1)) |v_1| + (c(e_2) + c(-e_2)) |v_2| \right).$$

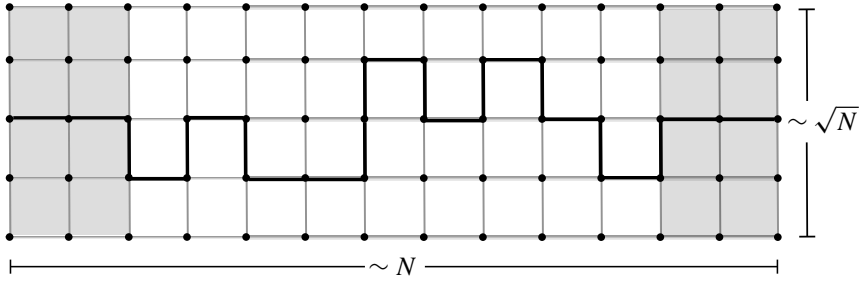


Figure 4. The different sets in the construction of u_N . R_N^+ and R_N^- correspond to the white regions above and below the bold line, respectively. In the light gray region, $u_N(x)$ agrees with $u_{0,e_2}(P_2(x))$.

Proof. In order to prove the first statement, we start with the case $\nu = e_2$ and use results from percolation theory which show that the contribution from the random layers is negligible: for $q := (1 - p)^M > p_{\text{site}}$, we consider the so-called Bernoulli site percolation on \mathbb{Z}^2 ; that is, we assign independently a weight $X_i(\omega) \in \{\pm 1\}$ to all the vertices $i \in \mathbb{Z}^2$ such that $\mathbb{P}(X_i = 1) = q$. We say that i_0, \dots, i_k is an occupied path if $|i_n - i_{n+1}| = 1$ and $X_{i_n}(\omega) = 1$ for all $n = 0, \dots, k$. Theorem 11.1 in [Kesten 1982] yields that there exist universal constants c_j, d_j such that

$$\mathbb{P}(\text{at least } c_1(q - p_{\text{site}})^{d_1}n \text{ disjoint occupied paths from } \{0\} \times [0, n] \text{ to } \{m\} \times [0, n] \text{ and contained in } [0, m] \times [0, n] \text{ exist}) \geq 1 - c_2(m+1) \exp(-c_3(q - p_{\text{site}})^{d_2}n).$$

Given $N \in \mathbb{N}$, we first combine this estimate with the Borel–Cantelli lemma and, using stationarity, we obtain that for almost every $\omega \in \Omega$ there exists $N_0 = N_0(\omega)$ such that for all $N \geq N_0$ we find at least $c_1(q - p_{\text{site}})^{d_1}2\sqrt{N}$ disjoint occupied paths connecting the vertical boundary segments of the rectangle

$$R_N := \left[-\left\lfloor \frac{1}{2}N \right\rfloor + 2, \left\lfloor \frac{1}{2}N \right\rfloor - 2\right] \times \left[-\lceil \sqrt{N} \rceil, \lceil \sqrt{N} \rceil\right].$$

As the paths are disjoint and are contained in R_N , at least one of them uses at most $(2/c_1)(q - p_{\text{site}})^{-d_1}N$ vertices. Now we come back to the actual proof. By the definition of the random lattice in (7-59), using the above considerations in the layer $\mathbb{Z}^2 \times \{1\}$, for $N \geq N_0$ we can find a path connecting the vertical boundary segments of the rectangle $R_N \times \{1\}$, contained in $R_N \times \{1\}$, using at most $c_{p,M}N$ vertices with none of them belonging to $\mathcal{L}_p^M(\omega)$. This path separates $R_N \times \{1\}$ into two subregions $R_N^- \times \{1\}$ and $R_N^+ \times \{1\}$. As depicted in Figure 4, for $N \geq N_0$ we define a (random) configuration $u_N : \mathcal{L}_p^M(\omega) \rightarrow \{\pm 1\}$ as

$$u_N(x) = \begin{cases} u_{0,e_2}(P_2(x)) & \text{if } P_2(x) \notin R_N, \\ +1 & \text{if } P_2(x) \in R_N^+, \\ -1 & \text{otherwise.} \end{cases}$$

Up to possibly exchanging the roles of R_N^\pm , we can assume that $u_N \in \mathcal{PC}_{1,u_0,e_2}^2(\omega, Q_{e_2}(0, N))$. Hence by the definition of $\phi_{\text{hom}}^{p,\eta}(e_2)$ and the fact that u_N does not depend on the z -direction, it holds that

$$\begin{aligned}
 \phi_{\text{hom}}^{p,\eta}(e_2) &\leq \liminf_{N \rightarrow +\infty} \frac{1}{N} E_{1,M}^{p,\eta}(\omega)(u_N, \mathcal{Q}_{e_2}(0, N)) \\
 &\leq \limsup_{N \rightarrow +\infty} \frac{1}{N} \sum_{\substack{x,y \in \mathcal{Q}_{e_2}(0,N) \cap \mathbb{Z}^2 \\ |x-y|=1}} \eta |u_N(x) - u_N(y)| \\
 &\quad + \limsup_{N \rightarrow +\infty} \frac{1}{N} \sum_{k=1}^M \sum_{\substack{x,y \in \mathcal{L}_p^M(\omega) \\ x,y \in \mathcal{Q}_{e_2}(0,N) \times \{k\}}} c(x-y) |u_N(x) - u_N(y)|. \tag{7-62}
 \end{aligned}$$

We now estimate each of the two terms on the right-hand side. Concerning the second one, we observe that if $x, y \in (\mathcal{Q}_{e_2}(0, N) \times \{k\}) \cap \mathcal{L}_p^M(\omega)$ are such that $|x - y| = 1$ and $u_N(x) \neq u_N(y)$, then either $P_2(x), P_2(y) \in \pm \frac{1}{2} N e_1 + ([-4, 4] \times [-2\sqrt{N}, 2\sqrt{N}])$ or, without loss of generality, $P_2(x) \in R_N^-$ and $P_2(y) \in R_N^+$. In the second case, we note that either $(P_2(x), 1)$ or $(P_2(y), 1)$ has to be a vertex of the path constructed above; hence either $x \notin \mathcal{L}_p^M(\omega)$ or $y \notin \mathcal{L}_p^M(\omega)$. We then rule out the existence of such interactions and we may bound the second term via

$$\limsup_{N \rightarrow +\infty} \frac{1}{N} \sum_{k=1}^M \sum_{\substack{x,y \in \mathcal{L}_p^M(\omega) \\ x,y \in \mathcal{Q}_{e_2}(0,N) \times \{k\}}} c(x-y) |u_N(x) - u_N(y)| \leq \limsup_{N \rightarrow +\infty} \frac{CM}{\sqrt{N}} = 0. \tag{7-63}$$

Applying the same arguments for the first term, we may use the fact that the separating path uses at most $c_{p,M}N$ vertices and we deduce that

$$\limsup_{N \rightarrow +\infty} \frac{1}{N} \sum_{\substack{x,y \in \mathcal{Q}_{e_2}(0,N) \cap \mathbb{Z}^2 \\ |x-y|=1}} \eta |u_N(x) - u_N(y)| \leq 4c_{p,M}\eta.$$

From this estimate, the first claim in the case $v = e_2$ follows by (7-62) and (7-63). The above argument can be adapted to the cases $v = -e_2$ and $v = \pm e_1$. By L^1 -lower semicontinuity, the one-homogeneous extension of $\phi_{\text{hom}}^{p,\eta}$ must be convex; see [Ambrosio and Braides 1990b]. For general $v \in S^1$ the claim then follows upon multiplying the constant by a factor $\sqrt{2}$.

In order to prove the second claim, we need to show two inequalities. Given a sequence of admissible configurations u_N such that

$$\lim_N \frac{1}{N} E_{sl}^1(u_N, \mathcal{Q}_v(0, N)) = \phi_{sl}^1(v),$$

we define an admissible configuration $\bar{u}_N : \mathcal{L}_p^M(\omega) \rightarrow \{\pm 1\}$ via

$$\bar{u}_N(x) = u_N(P_2(x)).$$

Arguing as in the proof of Proposition 7.3, we may assume that u_N is a plane-like configuration and its energy is concentrated in a stripe

$$S_v(N, \lambda) = \{x \in \mathbb{R}^2 : x \in \mathcal{Q}_v(0, N), \text{dist}(x, \{v\}^\perp) \leq 4(\lambda + 1)\},$$

where now λ is independent of N, M . By definition and the fact that \bar{u}_N gives no interaction in the z -direction, we obtain that for any $\delta > 0$ small enough

$$\begin{aligned} \frac{\phi_{\text{hom}}^{p,\eta}(M; \nu)}{M} &\leq \frac{1}{M} \liminf_{N \rightarrow +\infty} \frac{1}{N} \mathbb{E}[E_{1,M}^{p,\eta}(\omega)(\bar{u}_N, Q_\nu(0, N))] \\ &\leq \left(\liminf_{N \rightarrow +\infty} \frac{1}{M} \sum_{k=1}^M \frac{1}{N} \mathbb{E}[E_{sl}^{pk}(\omega)(u_N, Q_\nu(0, N))] \right) + \frac{C}{M} \limsup_{N \rightarrow +\infty} \frac{1}{N} \#\{z \in \mathbb{Z}^2 \cap S_\nu(N, \lambda)\} \\ &\leq \liminf_{N \rightarrow +\infty} \frac{1}{N} \left((p+\delta) E_{sl}^1(u_N, Q_\nu(0, N)) + \frac{1}{M} \sum_{k > \lfloor (p+\delta)M \rfloor}^M \mathbb{E}[E_{sl}^{pk}(\omega)(u_N, Q_\nu(0, N))] \right) + \frac{C\lambda}{M} \\ &= (p+\delta)\phi_{sl}^1(\nu) + \sup_{k > \lfloor (p+\delta)M \rfloor} \liminf_{N \rightarrow +\infty} \frac{1}{N} \mathbb{E}[E_{sl}^{pk}(\omega)(u_N, Q_\nu(0, N))] + \frac{C\lambda}{M}, \end{aligned}$$

where $p_k = \sum_{l=k}^M \binom{M}{l} p^l (1-p)^{M-l}$ is the probability of having at least k successes out of M trials in a Bernoulli experiment. Note that here the new random variables are indeed defined on the same probability space and are coupled to the variables generating the stochastic lattice $\mathcal{L}_p^M(\omega)$. As λ is independent of M , the third term vanishes when $M \rightarrow +\infty$, so that we are left to show that also the second one converges to zero. In order to estimate the second term we use the fact that u_N is a plane-like configuration, so that

$$\frac{1}{N} \mathbb{E}[E_{sl}^{pk}(\omega)(u_N, Q_\nu(0, N))] = \frac{1}{N} \mathbb{E}[E_{sl}^{pk}(\omega)(u_N, S_\nu(N, \lambda))] \leq p_k C\lambda.$$

For any $k > \lfloor (p+\delta)M \rfloor$, by the law of large numbers it holds that $p_k \rightarrow 0$ when $M \rightarrow +\infty$. Hence we deduce $\limsup_M (1/M)\phi_{\text{hom}}^{p,\eta}(M; \nu) \leq (p+\delta)\phi_{sl}^1(\nu)$. As $\delta > 0$ was arbitrary, we finally obtain

$$\limsup_M \frac{1}{M} \phi_{\text{hom}}^{p,\eta}(M; \nu) \leq p \phi_{sl}^1(\nu).$$

We next show the reverse inequality. Given any admissible function $\bar{u}_N : \mathcal{L}_p^M(\omega) \rightarrow \{\pm 1\}$ we can neglect the interactions in the z -direction and the lowest layer \mathcal{L}^0 and obtain the estimate

$$E_{1,M}^{p,\eta}(\omega)(\bar{u}_N, Q_\nu(0, N)) \geq \sum_{k=1}^M E_{sl}^{pk}(\omega)(\bar{u}_N(\cdot, k), Q_\nu(0, N)) \geq \sum_{k=1}^{\lceil (p-\delta)M \rceil} E_{sl}^{pk}(\omega)(\bar{u}_N(\cdot, k), Q_\nu(0, N)).$$

Since $\bar{u}_N(\cdot, k)$ fulfills the correct boundary condition in every layer, we deduce that

$$\frac{1}{M} \phi_{\text{hom}}^{p,\eta}(M; \nu) \geq (p-\delta) \inf_{k \leq \lceil (p-\delta)M \rceil} \phi_{sl}^{pk}(\nu).$$

Again by the law of large numbers for an independent Bernoulli experiment it remains to show that the function $q \mapsto \phi_{sl}^q(\nu)$ is continuous in $q = 1$, which means we can pass from a random to a deterministic lattice. This will be the last step.

In order to prove continuity let u_N be a plane-like sequence of configurations as in the first part of the proof and consider an optimal sequence $u_N^q(\omega)$ such that

$$\phi_{sl}^q(\nu) = \lim_{N \rightarrow +\infty} \frac{1}{N} \mathbb{E}[E_{sl}^q(\omega)(u_N^q(\omega), Q_\nu(0, N))].$$

Similar to the proof of [Proposition 7.3](#) we obtain

$$\begin{aligned} 0 &\leq \phi_{\text{sl}}^1(v) - \phi_{\text{sl}}^q(v) = \lim_N \frac{1}{N} \mathbb{E} [E_{\text{sl}}^1(u_N, S_v(\lambda, N)) - E_{\text{sl}}^q(\omega)(u_N^q(\omega), Q_v(0, N))] \\ &\leq \limsup_N \frac{1}{N} \mathbb{E} [E_{\text{sl}}^1(u_N^q(\omega), S_v(\lambda, N)) - E_{\text{sl}}^q(\omega)(v_N^q(\omega), S_v(\lambda, N))] \\ &\leq C \lim_N \frac{1}{N} \mathbb{E} [\#\{z \in (S_v(\lambda, N) \cap \mathbb{Z}^2) \times \{1\} : z \notin \mathcal{L}_q^1(\cdot)\}] = C(1 - q)\lambda. \end{aligned}$$

The estimate above clearly implies convergence of the surface tensions when $q \rightarrow 1$, which shows that $\limsup_M (1/M) \phi_{\text{hom}}^{p,\eta}(M; v) \geq p \phi_{\text{sl}}^1(v)$.

It remains to identify $\phi_{\text{sl}}^1(v)$. We just sketch the argument. Any admissible configuration asymptotically has an interface containing at least $|v_1|$ interactions along the two directions $\pm e_1$ and $|v_2|$ interactions along the directions $\pm e_2$. Since any pair of interacting points is counted twice with reversing direction and $|u(x) - u(y)| \in \{0, 2\}$, we find that $\phi_{\text{sl}}^1(v) \geq 2(c(e_1) + c(-e_1))|v_1| + 2(c(e_2) + c(-e_2))|v_2|$. On the other hand, a suitable discretization of a plane attains this value; hence

$$\phi_{\text{sl}}^1(v) = 2(c(e_1) + c(-e_1))|v_1| + 2(c(e_2) + c(-e_2))|v_2|. \quad \square$$

Appendix A: Plane-like minimizers for one-periodic dimension-reduction problems

We prove that the results about plane-like minimizers for periodic interactions in [\[Caffarelli and de la Llave 2005\]](#) can be extended to dimension-reduction problems. We restrict the analysis to one-periodic interactions, which is the case when the coefficients depend only on the difference, as in [Hypothesis 2](#). Moreover, we focus on the physical case of reducing from three dimensions to two dimensions. To fix notation, for any set $\Gamma \subset \mathbb{Z}^2$, we write $\Gamma_M = \Gamma \times (\mathbb{Z} \cap [0, M])$. In contrast to the main part of this paper, here we consider an interaction energy that takes into account also interactions outside the domain. To be more precise, given $u : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ we investigate finite-range energies of the form

$$E_M(u, \Gamma) = \sum_{x \in \Gamma_M} \sum_{y \in \mathbb{Z}_M^2} c(x - y) |u(x) - u(y)|,$$

where the coefficients fulfill the following assumptions:

- (i) $0 \leq c(z) \leq C$ for all $z \in \mathbb{R}^3$ and $\min_i c(\pm e_i) \geq c_0 > 0$.
- (ii) There exists $L > 0$ such that $c(z) = 0$ for all $|z| \geq L$.

Before stating and proving the main theorem we need some definitions.

Definition A.1. We say that $u : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ is a ground state for the energy E_M whenever $E_M(u, \Gamma) \leq E_M(v, \Gamma)$ for all finite sets $\Gamma \subset \mathbb{Z}^2$ and all $v : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ such that $u = v$ on $\{z \in \mathbb{Z}_M^2 : \exists z' \in (\mathbb{Z}^2 \setminus \Gamma)_M \text{ with } |z - z'| \leq L\}$.

Remark A.2. When u and Γ are such that $E_M(u, \Gamma) \leq E_M(v, \Gamma)$ for all v such that $u = v$ on $\{z \in \mathbb{Z}_M^2 : \exists z' \in (\mathbb{Z}^2 \setminus \Gamma)_M \text{ with } |z - z'| \leq L\}$, the same conclusion holds for every subset $\Gamma' \subset \Gamma$. Indeed, take any v

such that $u = v$ on $\{z \in \mathbb{Z}_M^2 : \exists z' \in (\mathbb{Z}^2 \setminus \Gamma')_M \text{ with } |z - z'| \leq L\}$. Then for any two points x, y with $x \in (\Gamma \setminus \Gamma')_M$ and $y \in \mathbb{Z}_M^2$ with $|x - y| \leq L$, it holds that $u(x) = v(x)$ and $u(y) = v(y)$. Hence it follows that

$$E_M(u, \Gamma') - E_M(v, \Gamma') = E_M(u, \Gamma) - E_M(v, \Gamma) \leq 0.$$

Using the same notation as for the stochastic group action, for $k \in \mathbb{Z}^2$ we denote by τ_k the shift operator acting on sets Γ and configurations $u : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ via

$$\tau_k \Gamma = \Gamma + k, \quad \tau_k u(x) = u(x - (k, 0)).$$

Then the following formula holds true:

$$E_M(\tau_k u, \tau_k \Gamma) = E_M(u, \Gamma). \quad (\text{A-64})$$

The remaining part of this appendix will be devoted to the proof of the next theorem.

Theorem A.3. *There exists $\lambda > 0$ such that for all $v \in S^1$ there exists a ground state u_v of E_M such that $u(x) \neq u(y)$ implies $\text{dist}(x, \{v\}^\perp) \leq \lambda$. Such a ground state is called plane-like. Moreover we can choose $\lambda \leq CM$ for some constant C independent of v, M .*

The proof of this theorem is very similar to [Caffarelli and de la Llave 2005; Cozzi et al. 2017]. We first construct a particular minimizer among periodic configurations that enjoys several geometric properties. To this end, we need further notation; see [Caffarelli and de la Llave 2005] for more details. Fix a rational direction $v \in S^1 \cap \mathbb{Q}^2$. We define the \mathbb{Z} -module $\mathbb{Z}_v = \{z \in \mathbb{Z}^2 : \langle z, v \rangle = 0\}$ and, given $m \in \mathbb{N}$, we let $\mathcal{F}_{m,v}$ be any fundamental domain of the quotient $\mathbb{Z}_v^2 / m\mathbb{Z}_v$; that is, for every $z \in \mathbb{Z}^2$ there exist unique $z_1 \in m\mathbb{Z}_v$ and $z_2 \in \mathcal{F}_{m,v}$ such that $z = z_1 + z_2$. Given real numbers θ and λ , with $\theta < \lambda$, we further introduce

$$\mathcal{F}_{m,v}^{\theta,\lambda} = \{z \in \mathcal{F}_{m,v} : \langle v, z \rangle \in [\theta, \lambda]\}.$$

Now we define an admissible class of periodic configurations: A function $u : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ is called (m, v) -periodic if $u(x) = u(x + m(z, 0))$ for every $x \in \mathbb{Z}_M^2$ and every $z \in \mathbb{Z}_v$. We set

$$\mathcal{A}_{m,v}^{\theta,\lambda} = \{u : u \text{ is } (m, v)\text{-periodic, } u = +1 \text{ if } \langle P_2(z), v \rangle < \theta, u(z) = -1 \text{ if } \langle P_2(z), v \rangle > \lambda\}.$$

We start with a very elementary lemma that shows how for periodic functions any translation gives the same energy.

Lemma A.4. *Let u be (m, v) -periodic and $k \in \mathbb{Z}^2$. Then it holds that*

$$E_M(\tau_k u, \mathcal{F}_{m,v}) = E_M(u, \mathcal{F}_{m,v}).$$

Proof. Given $x \in (\tau_{-k}\mathcal{F}_{m,v})_M$, we find $z_1(x) \in m\mathbb{Z}_v$ and $z_2(x) \in \mathcal{F}_{m,v}$ such that $P_2(x) = z_1(x) + z_2(x)$. By (m, v) -periodicity, for any $y \in \mathbb{Z}_M^2$ it holds that

$$\begin{aligned} |u(x) - u(y)| &= |u(x - (z_1(x), 0)) - u(y - (z_1(x), 0))|, \\ c(x - y) &= c(x - (z_1(x), 0) - y + (z_1(x), 0)). \end{aligned}$$

Now assume that there exist another $x' \in (\tau_{-k}\mathcal{F}_{m,v})_M \setminus \{x\}$ with $\langle x - x', e_3 \rangle = 0$ and $z_2(x) = z_2(x')$. Then $\tau_k P_2(x) - \tau_k P_2(x') = z_1(x) - z_1(x') \in m\mathbb{Z}_v \setminus \{(0, 0)\}$. As $\tau_k P_2(x), \tau_k P_2(x') \in \mathcal{F}_{m,v}$, this contradicts the fact that $\mathcal{F}_{m,v}$ is a fundamental domain. Using (A-64) we conclude by comparison that

$$E_M(\tau_k u, \mathcal{F}_{m,v}) = E_M(u, \tau_{-k}\mathcal{F}_{m,v}) \leq E_M(u, \mathcal{F}_{m,v}).$$

Applying the above inequality to τ_{-k} and $\tilde{u} := \tau_k u$, which is also (m, v) -periodic, we obtain the claim. \square

We define the class of minimizers for the energy $E_M(\cdot, \mathcal{F}_{m,v})$ on $\mathcal{A}_{m,v}^{\theta,\lambda}$ via

$$\mathcal{M}_{m,v}^{\theta,\lambda} = \{u \in \mathcal{A}_{m,v}^{\theta,\lambda} : E_M(u, \mathcal{F}_{m,v}) \leq E_M(v, \mathcal{F}_{m,v}) \text{ for all } v \in \mathcal{A}_{m,v}^{\theta,\lambda}\}.$$

As the set $\mathcal{A}_{m,v}^{\theta,\lambda}$ is finite, the class of minimizers is nonempty. Next we define the so-called infimal minimizer, which has several useful properties:

$$u_{m,v}^{\theta,\lambda} = \min\{u \in \mathcal{M}_{m,v}^{\theta,\lambda}\} \in \mathcal{A}_{m,v}^{\theta,\lambda}.$$

We next show that the infimal minimizer also belongs to the class of minimizers. This follows from the following elementary observation; see Lemma 2.1 and also Lemma 2.3 in [Cozzi et al. 2017].

Lemma A.5. *Given any $u : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ and $\Gamma \in \mathbb{Z}^2$ finite, it holds that*

$$E_M(\min\{u, v\}, \Gamma) + E_M(\max\{u, v\}, \Gamma) \leq E_M(u, \Gamma) + E_M(v, \Gamma).$$

Iterating the above lemma finitely many times we find that $u_{m,v}^{\theta,\lambda} \in \mathcal{M}_{m,v}^{\theta,\lambda}$.

We now turn to the first property of the infimal minimizer. This is the so-called absence of symmetry breaking, which says that the infimal minimizer does not depend on the length m of the period.

Lemma A.6. *For any $m \in \mathbb{N}$ it holds that $u_{m,v}^{\theta,\lambda} = u_{1,v}^{\theta,\lambda}$.*

Proof. We define an auxiliary configuration via $u = \min\{\tau_k u_{m,v}^{\theta,\lambda} : k \in \mathbb{Z}_v\}$. By elementary arguments it follows that $u \in \mathcal{A}_{1,v}^{\theta,\lambda}$, while Lemma A.4 implies that $\tau_k u_{m,v}^{\theta,\lambda} \in \mathcal{M}_{m,v}^{\theta,\lambda}$ and by iterating Lemma A.5 we obtain $u \in \mathcal{M}_{m,v}^{\theta,\lambda}$. Since $u \leq u_{m,v}^{\theta,\lambda}$, by the definition of infimal minimizer we obtain $u = u_{m,v}^{\theta,\lambda}$. Moreover, as u and $u_{1,v}^{\theta,\lambda}$ are both $(1, v)$ -periodic it follows that

$$E_M(u, \mathcal{F}_{1,v}) = \frac{1}{m} E_M(u, \mathcal{F}_{m,v}) \leq \frac{1}{m} E_M(u_{1,v}^{\theta,\lambda}, \mathcal{F}_{m,v}) = E_M(u_{1,v}^{\theta,\lambda}, \mathcal{F}_{1,v}). \tag{A-65}$$

In particular we deduce that $u \in \mathcal{M}_{1,v}^{\theta,\lambda}$ and thus $u \geq u_{1,v}^{\theta,\lambda}$. On the other hand, (A-65) must be an equality, so that $u_{1,v}^{\theta,\lambda} \in \mathcal{M}_{m,v}^{\theta,\lambda}$ and therefore $u_{1,v}^{\theta,\lambda} \geq u$. This proves the claim. \square

We next establish the so-called Birkhoff property of the infimal minimizer, which will be the main ingredient for the proof of Theorem A.3.

Lemma A.7. *Let $k \in \mathbb{Z}^2$. Then $\tau_k u_{1,v}^{\theta,\lambda} \leq u_{1,v}^{\theta,\lambda}$ if $\langle k, v \rangle \leq 0$ and $\tau_k u_{1,v}^{\theta,\lambda} \geq u_{1,v}^{\theta,\lambda}$ if $\langle k, v \rangle \geq 0$.*

Proof. We start with the case $\langle k, v \rangle \leq 0$ and define the two configurations $m = \min\{u_{1,v}^{\theta,\lambda}, \tau_k u_{1,v}^{\theta,\lambda}\}$ and $M = \max\{u_{1,v}^{\theta,\lambda}, \tau_k u_{1,v}^{\theta,\lambda}\}$. By elementary considerations one can prove $m \in \mathcal{A}_{1,v}^{\theta+\langle k,v \rangle, \lambda+\langle k,v \rangle}$ and $M \in \mathcal{A}_{1,v}^{\theta,\lambda}$. Using Lemma A.5 we obtain

$$E_M(m, \mathcal{F}_{1,v}) + E_M(u_{1,v}^{\theta,\lambda}, \mathcal{F}_{1,v}) \leq E_M(m, \mathcal{F}_{1,v}) + E_M(M, \mathcal{F}_{1,v}) \leq E_M(\tau_k u_{1,v}^{\theta,\lambda}, \mathcal{F}_{1,v}) + E_M(u_{1,v}^{\theta,\lambda}, \mathcal{F}_{1,v}),$$

which yields

$$E_M(m, \mathcal{F}_{1,v}) \leq E_M(\tau_k u_{1,v}^{\theta,\lambda}, \mathcal{F}_{1,v}).$$

We claim that $\tau_k u_{1,v}^{\theta,\lambda} = u_{1,v}^{\theta+\langle k,v \rangle, \lambda+\langle k,v \rangle}$. Indeed, as $\tau_k u_{1,v}^{\theta,\lambda} \in \mathcal{A}_{1,v}^{\theta+\langle k,v \rangle, \lambda+\langle k,v \rangle}$, this configuration is admissible and minimality follows by [Lemma A.4](#). Now assume it is not the infimal minimizer; then also $u_{1,v}^{\theta,\lambda}$ is not the infimal minimizer, as we could construct a smaller one by translation of the other infimal minimizer.

By definition of the infimal minimizer we infer that $m \geq \tau_k u_{1,v}^{\theta,\lambda}$, which proves the claim by definition of m . The case $\langle k, v \rangle \geq 0$ follows upon applying the translation τ_k to the inequality $\tau_{-k} u_{1,v}^{\theta,\lambda} \leq u_{1,v}^{\theta,\lambda}$, which holds by the first part of the proof. \square

In the next lemma we deduce a powerful property of configurations fulfilling the Birkhoff property.

Lemma A.8. *Let $u : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ satisfy the Birkhoff property with respect to $v \in S^1 \cap \mathbb{Q}^2$; that is, $\tau_k u \leq u$ if $\langle k, v \rangle \leq 0$, and $\tau_k u \geq u$ if $\langle k, v \rangle \geq 0$. Assume further that $u(x_0) = -1$ for some $x_0 \in \mathbb{Z}_M^2$. Then $u(x) = -1$ for all $x \in \mathbb{Z}_M^2$ such that $\langle x - x_0, e_3 \rangle = 0$ and $\langle P_2(x - x_0), v \rangle \geq 0$.*

Proof. Every such x can be written as $x = x_0 - (k, 0)$ with $k \in \mathbb{Z}^2$ such that $\langle k, v \rangle \leq 0$. Hence [Lemma A.7](#) implies that $u(x) = \tau_k u(x_0) \leq u(x_0) = -1$, so that $u(x) = -1$. \square

We are now in a position to prove that the infimal minimizer becomes unconstrained when we take $\theta = 0$ and λ large enough. To reduce notation, from now on we set $u_v^\lambda := u_{1,v}^{0,\lambda}$.

Lemma A.9. *There exists $\lambda_0 > 0$ (depending on M in such a way that $\lambda_0 \leq CM$) such that for all $\lambda \geq \lambda_0$ it holds that $u_v^\lambda(x) = -1$ for all $x \in \mathbb{Z}_M^2$ such that $\langle P_2(x), v \rangle \geq \lambda - \sqrt{2}$.*

Proof. By [Lemma A.8](#) it is enough to show that for large enough λ , in every layer $\mathbb{Z}^2 \times \{l\}$ with $l \in \{0, \dots, M\}$ there exists some x_l such that $\langle P_2(x_l), v \rangle \leq \lambda - \sqrt{2}$ and $u_v^\lambda(x_l) = -1$. We will show that this is always the case provided λ is large enough.

Assume that there exists a layer $\mathbb{Z}^2 \times \{l\}$ such that $u_v^\lambda(x) = 1$ for all $x \in \mathbb{Z}^2 \times \{l\}$ with $\langle P_2(x), v \rangle \leq \lambda - \sqrt{2}$. We argue that in this case there must exist a second layer $\mathbb{Z}^2 \times \{l'\}$ and a point $x_{l'} \in \mathbb{Z}^2 \times \{l'\}$ with $\langle P_2(x_{l'}), v \rangle \leq \sqrt{2}$ and $u_v^\lambda(x_{l'}) = -1$. Indeed, if this would be false, then the function $\tau_k u_v^\lambda$ with any $k \in \{0, \pm 1\}^2$ such that $\langle k, v \rangle < 0$ fulfills $\tau_k u_v^\lambda \in \mathcal{A}_{1,v}^{0,\lambda}$. By [Lemma A.7](#) we further know that $\tau_k u_v^\lambda \leq u_v^\lambda$. On the other hand, by [Lemma A.4](#) we have $\tau_k u_v^\lambda \in \mathcal{M}_{1,v}^{0,\lambda}$; hence by the definition of infimal minimizer we obtain $\tau_k u_v^\lambda = u_v^\lambda$. This contradicts the boundary conditions by the choice of k . Now applying [Lemma A.8](#) in the second layer $\mathbb{Z}^2 \times \{l'\}$, we obtain $u_v^\lambda(x) = -1$ for all $x \in \mathbb{Z}^2 \times \{l'\}$ such that $\langle P_2(x), v \rangle \geq \sqrt{2}$. As we will see now, for fixed M this will cost too much energy.

Without loss of generality we assume that $l > l'$, the other case can be treated almost the same way. For every $r \in \{1, \dots, M\}$ there exists $x \in \mathbb{Z}^2 \times \{r\}$ such that $u_v^\lambda(x_r) = -1$. Let x_r be one of such points that minimizes $\langle P_2(x), v \rangle$ among all such points. According to [Lemma A.8](#) we obtain $u_v^\lambda(x) = -1$ for all $x \in \mathbb{Z}^2 \times \{r\}$ with $\langle P_2(x), v \rangle \geq \langle P_2(x_r), v \rangle =: p_r$. Note that

$$\left| \sum_{r=l'}^{l-1} (p_{r+1} - p_r) \right| \geq \lambda - 2\sqrt{2}. \quad (\text{A-66})$$

On the other hand, just counting the interactions between neighboring layers, we obtain by the coercivity of the interactions and (A-66) that

$$E_M(u_v^\lambda, \mathcal{F}_{1,v}) \geq c \sum_{r=1}^M |p_r - p_{r-1}| \geq c(\lambda - 2\sqrt{2}).$$

Testing a discretized plane as a possible minimizer, by the finite-range assumption we know an a priori bound of the form $E_M(u_v^\lambda, \mathcal{F}_{1,v}) \leq CM$. Hence our assumption can only hold as long as $\lambda \leq CM$ for some constant C depending neither on v nor on M and the claim follows upon setting $\lambda_0 = 2CM$. \square

The next (and last) lemma bounds the oscillation of the jump set of the infimal minimizer $u_v^{\lambda_0}$.

Lemma A.10. *Let λ_0 be as in Lemma A.9. Then $u_v^{\lambda_0} \in \mathcal{M}_{m,v}^{-n, \lambda_0+n}$ for any $n, m \in \mathbb{N}$.*

Proof. We first claim that $u_v^{\lambda_0} = u_v^{\lambda_0+l}$ for any $l \in \mathbb{N}$. This will be done iteratively. First note that for any $\lambda \geq \lambda_0$ it holds that $u_v^\lambda \in \mathcal{A}_{1,v}^{0, \lambda+1}$ and by Lemma A.9 it also holds that $u_v^{\lambda+1} \in \mathcal{A}_{1,v}^{0, \lambda}$. Then

$$E_M(u_v^{\lambda+1}, \mathcal{F}_{1,v}) = E_M(u_v^\lambda, \mathcal{F}_{1,v})$$

and both are infimal minimizers. Hence they must agree. This proves the first claim.

Give an arbitrary configuration $v \in \mathcal{A}_{m,v}^{-n, \lambda_0+n}$, we choose a vector $k \in \mathbb{Z}^2$ such that $\langle k, v \rangle \geq n$ and $\langle k, v \rangle \in \mathbb{N}$. Then

$$\tau_k v \in \mathcal{A}_{m,v}^{-n+\langle k, v \rangle, \lambda_0+n+\langle k, v \rangle} \subset \mathcal{A}_{m,v}^{0, \lambda_0+n'}$$

with $n' \in \mathbb{N}$. Using the first claim and Lemmata A.4 and A.6 we obtain

$$E_M(u_v^{\lambda_0}, \mathcal{F}_{m,v}) \leq E_M(\tau_k v, \mathcal{F}_{m,v}) = E_M(v, \mathcal{F}_{m,v}).$$

As $u_v^{\lambda_0} \in \mathcal{A}_{m,v}^{-n, \lambda_0+n}$ we proved the claim. \square

Proof of Theorem A.3. First assume that $v \in S^1 \cap \mathbb{Q}^2$. We show that $u_v^{\lambda_0}$ is a ground state. To this end let $\Gamma \subset \mathbb{Z}^2$ be finite and let $v : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$ be such that $v = u_v^{\lambda_0}$ on $\{z \in \mathbb{Z}_M^2 : \exists z' \in (\mathbb{Z}^2 \setminus \Gamma)_M \text{ with } |z - z'| \leq L\}$. Then we find $m \in \mathbb{N}$ such that, for a suitable fundamental domain, $\Gamma \subset \mathcal{F}_{m,v}$. By Lemma A.10 we have $E_M(u_v^{\lambda_0}, \mathcal{F}_{m,v}) \leq E_M(v, \mathcal{F}_{m,v})$ and the claim then follows by Remark A.2.

For general directions $v \in S^1$ we argue by approximation. Take a sequence $v_j \rightarrow v$ of rational directions and consider the sequence $u_j := u_{v_j}^{\lambda_j}$, where λ_j is uniformly bounded in j . By Tychonoff's theorem we can assume that $u_j \rightarrow u$ for some $u : \mathbb{Z}_M^2 \rightarrow \{\pm 1\}$. It holds that u is a plane-like configuration. By the definition of the topology, given any finite set $\Gamma \subset \mathbb{Z}^2$ we can find an index j_0 such that $u_j(x) = u(x)$ for all $x \in \Gamma_M$ and all $j \geq j_0$. Since we assume a finite range of interaction, the previous convergence property implies that u is also a ground state. \square

Appendix B: Density results for trace-constraints on partitions

In this second appendix we show the density result needed in the proof of Theorem 4.1.

Lemma B.1. *Let $A \Subset B$ both be bounded open sets with Lipschitz boundary. Given $v, w \in \text{BV}(B, S)$ such that $\mathcal{H}^{k-1}(S_w \cap \partial A) = 0$, we set $u = \mathbb{1}_A v + (1 - \mathbb{1}_A)w$. Then there exists a sequence $A_n \Subset A$ of*

sets of finite perimeter such that $u_n := \mathbb{1}_{A_n}v + (1 - \mathbb{1}_{A_n})w$ converges to u in $L^1(B)$ and additionally $\mathcal{H}^{k-1}(S_{u_n} \cap B) \rightarrow \mathcal{H}^{k-1}(S_u \cap B)$.

Proof. We define the mapping $T : \mathcal{S} \rightarrow \mathbb{R}^q$ by $T(s_i) = e_i$. As a special case of Proposition 4.1 in [Schmidt 2015], applied to the bounded BV-function $\alpha := T(w) - T(v)$, for every $\varepsilon > 0$ we find an open set A_ε of finite perimeter such that $A_\varepsilon \Subset A$, $|A \setminus A_\varepsilon| \leq \varepsilon$ and

$$\int_{\partial A_\varepsilon} |\alpha^+_{|\partial A_\varepsilon}| \, d\mathcal{H}^{k-1} \leq \int_{\partial A} |\alpha^+_{|\partial A}| \, d\mathcal{H}^{k-1} + \varepsilon. \quad (\text{B-67})$$

With the same arguments as in [Schmidt 2015], the sets A_ε can be constructed in such a way that for all $\delta > 0$ there exists $\varepsilon_0 > 0$ such that for all $\varepsilon < \varepsilon_0$

$$\{x \in A : \text{dist}(x, \partial A) > \delta\} \subset A_\varepsilon. \quad (\text{B-68})$$

We show that the sets A_ε fulfill the required properties. As a first step we claim that $T(u_\varepsilon)$ converges strictly to $T(u)$. We have that $T(u_\varepsilon)$ converges to $T(u)$ in $L^1(B)$. By lower semicontinuity of the total variation it is enough to show that

$$\limsup_{\varepsilon \rightarrow 0} |DT(u_\varepsilon)|(B) \leq |DT(u)|(B). \quad (\text{B-69})$$

By definition we have $|DT(u_\varepsilon)|(B \setminus \bar{A}) = |DT(u)|(B \setminus \bar{A})$, so that we can reduce the analysis to \bar{A} . By Theorem 3.84 in [Ambrosio et al. 2000] it holds that

$$DT(u_\varepsilon) = DT(v) \llcorner A_\varepsilon^{(1)} + DT(w) \llcorner A_\varepsilon^{(0)} + (T(v)^+_{|\partial A_\varepsilon} - T(w)^-_{|\partial A_\varepsilon}) \otimes v \mathcal{H}^{k-1} \llcorner \partial A_\varepsilon,$$

where in general $A_\varepsilon^{(t)}$ is defined for $t \in [0, 1]$ via

$$A_\varepsilon^{(t)} = \left\{ x \in \mathbb{R}^k : \lim_{\rho \rightarrow 0} \frac{|A_\varepsilon \cap B_\rho(x)|}{|B_\rho(x)|} = t \right\}.$$

Since $A_\varepsilon \Subset A$ and A_ε is open we infer $A_\varepsilon^{(1)} \subset A$ and $A_\varepsilon^{(0)} \subset \mathbb{R}^k \setminus A_\varepsilon$, so that

$$\begin{aligned} |DT(u_\varepsilon)|(\bar{A}) &\leq |DT(v)|(A) + |DT(w)|(\bar{A} \setminus A_\varepsilon) + \int_{\partial A_\varepsilon} |T(v)^+_{|\partial A_\varepsilon} - T(w)^-_{|\partial A_\varepsilon}| \, d\mathcal{H}^{k-1} \\ &\leq |DT(v)|(A) + |DT(w)|(\bar{A} \setminus A_\varepsilon) + \int_{\partial A_\varepsilon} |T(w)^+_{|\partial A_\varepsilon} - T(w)^-_{|\partial A_\varepsilon}| \, d\mathcal{H}^{k-1} \\ &\quad + \int_{\partial A_\varepsilon} |T(v)^+_{|\partial A_\varepsilon} - T(w)^+_{|\partial A_\varepsilon}| \, d\mathcal{H}^{k-1}. \end{aligned}$$

By the assumption on w we have $|DT(w)|(\partial A) = 0$, so that by (B-68) the second and the third terms vanish when $\varepsilon \rightarrow 0$. For the fourth one we use (B-67) and infer

$$\begin{aligned} \limsup_{\varepsilon \rightarrow 0} |DT(u_\varepsilon)|(\bar{A}) &\leq |DT(v)|(A) + \int_{\partial A} |T(v)^+_{|\partial A} - T(w)^+_{|\partial A}| \, d\mathcal{H}^{k-1} \\ &= |DT(v)|(A) + \int_{\partial A} |T(v)^+_{|\partial A} - T(w)^-_{|\partial A}| \, d\mathcal{H}^{k-1} = |DT(u)|(\bar{A}), \end{aligned}$$

where we used that inner and outer trace of $T(u)$ agree for \mathcal{H}^{k-1} -almost every $x \in \partial A$. By the structure of the set $T(S)$, strict convergence implies that

$$\mathcal{H}^{k-1}(S_{T(u_\varepsilon)} \cap B) = \frac{1}{\sqrt{2}} |DT(u_\varepsilon)| \rightarrow \frac{1}{\sqrt{2}} |DT(u)| = \mathcal{H}^{k-1}(S_{T(u)} \cap B).$$

As for every $u \in \text{BV}(B, S)$ it holds that $\mathcal{H}^{k-1}(S_u \cap B) = \mathcal{H}^{k-1}(S_{T(u)} \cap B)$ and also L^1 -convergence is conserved, we conclude the proof. \square

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Concentration et randomisation universelle de sous-espaces propres RAFIK IMEKRAZ	263
Asymptotic limits and stabilization for the 2D nonlinear Mindlin–Timoshenko system FÁGNER DIAS ARARUNA, PABLO BRAZ E SILVA and PAMMELLA QUEIROZ-SOUZA	351
Finite time blowup for a supercritical defocusing nonlinear Schrödinger system TERENCE TAO	383
A sublinear version of Schur’s lemma and elliptic PDE STEPHEN QUINN and IGOR E. VERBITSKY	439
Radial Fourier multipliers in \mathbb{R}^3 and \mathbb{R}^4 LAURA CLADEK	467
Continuum limit and stochastic homogenization of discrete ferromagnetic thin films ANDREA BRAIDES, MARCO CICALESE and MATTHIAS RUF	499