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Kashif Bari and Michael E. O’Sullivan

# The Hamiltonian problem and $t$-path traceable graphs 

Kashif Bari and Michael E. O'Sullivan<br>(Communicated by Ronald Gould)


#### Abstract

The problem of characterizing maximal non-Hamiltonian graphs may be naturally extended to characterizing graphs that are maximal with respect to nontraceability and beyond that to $t$-path traceability. We show how $t$-path traceability behaves with respect to disjoint union of graphs and the join with a complete graph. Our main result is a decomposition theorem that reduces the problem of characterizing maximal $t$-path traceable graphs to characterizing those that have no universal vertex. We generalize a construction of maximal nontraceable graphs by Zelinka to $t$-path traceable graphs.


## 1. Introduction

The motivating problem for this article is the characterization of maximal nonHamiltonian (MNH) graphs. The first broad family of MNH graphs was given in [Skupień 1979], and all MNH graphs with ten or fewer vertices were described in [Jamrozik et al. 1982], a paper where Skupien and his coauthors gave three constructions, called types $A 1, A 2$, A3, with a similar structure. Zelinka [1998] gave two constructions of graphs that are maximal nontraceable; that is, they have no Hamiltonian path, but the addition of any edge gives a Hamiltonian path. The join of such a graph with a single vertex gives an MNH graph. Zelinka's first family produces, under the join with $K_{1}$, the original MNH graphs of Skupien. Zelinka's second family is a broad generalization of the type $A 1, A 2$, and $A 3$ graphs of [Jamrozik et al. 1982]. Further examples of infinite families of maximal nontraceable graphs appeared in [Bullock et al. 2008].

In this article, we work with two closely related invariants of a graph $G, \check{\mu}(G)$ and $\mu(G)$. The $\mu$-invariant, introduced by Ore [1961] and also used by Noorvash [1975], is the minimal number of paths in $G$ required to cover the vertex set of $G$. We define $\check{\mu}(G)$ to be the smallest integer $\ell$ such that the join of $K_{\ell}$ with $G$ is Hamiltonian. We show that $\check{\mu}(G)=\mu(G)$ unless $G$ is Hamiltonian, when $\check{\mu}(G)=0$. Maximal

[^0]non-Hamiltonian graphs are maximal with respect to $\check{\mu}(G)=1$, and maximal nontraceable graphs are maximal with respect to $\check{\mu}(G)=2$. It is useful to broaden the perspective to study, for arbitrary $t$, graphs that are maximal with respect to $\check{\mu}(G)=t$, which we call $t$-path traceable graphs.

In Section 2 we show how the $\check{\mu}$ and $\mu$ invariants behave with respect to disjoint union of graphs and the join with a complete graph. Section 3 derives the main result, a decomposition theorem that reduces the problem of characterizing maximal $t$-path traceable graphs to characterizing those that have no universal vertex, which we call trim. Section 4 presents a generalization of the Zelinka construction to $t$-path traceable graphs.

## 2. Traceability and Hamiltonicity

It will be notationally convenient to say that the complete graphs $K_{1}$ and $K_{2}$ are Hamiltonian. As justification for this view, consider an undirected graph as a directed graph with each edge having a conjugate edge in the reverse direction. This perspective does not affect the Hamiltonicity of a graph with more than three vertices, but it does give $K_{2}$ a Hamiltonian cycle. Similarly, adding loops to any graph with more than two vertices does not alter the Hamiltonicity of the graph, but $K_{1}$, with an added loop, has a Hamiltonian cycle.

Let $G$ be a graph. A vertex, $v \in V(G)$, is called a universal vertex if $\operatorname{deg}(v)=$ $|V(G)|-1$. A universal vertex is also known as a dominating vertex. Let $\bar{G}$ denote the graph complement of $G$, having vertex set $V(G)$ and edge set $E\left(K_{n}\right) \backslash E(G)$. We will use the disjoint union of two graphs, $G \sqcup H$ and the join of two graphs $G * H$. The latter is $G \sqcup H$ together with the edges $\{v w \mid v \in V(G)$ and $w \in V(H)\}$.

Definition 1. A set of $s$ disjoint paths in a graph $G$ that includes every vertex in $G$ is an s-path covering of $G$. We define the following invariants:

$$
\begin{aligned}
\mu(G) & :=\min \{s \in \mathbb{N} \mid \text { there exists an } s \text {-path covering of } G\}, \\
\check{\mu}(G) & :=\min \left\{l \in \mathbb{N}_{0} \mid K_{l} * G \text { is Hamiltonian }\right\}, \\
i_{H}(G) & := \begin{cases}1 & \text { if } G \text { is Hamiltonian, } \\
0 & \text { otherwise. }\end{cases}
\end{aligned}
$$

We will say $G$ is $t$-path traceable when $\mu(G)=t$. A set of $t$ disjoint paths that covers a $t$-path traceable graph $G$ is a minimal path covering.

Note that $K_{r} *\left(K_{s} * G\right)=K_{r+s} * G$. If $G$ is Hamiltonian then so is $K_{r} * G$ for $r \geq 0$ (in particular, this is true for $G=K_{1}$ and $G=K_{2}$ ).

We now present a series of lemmas that leads to the main result of this section, which is a formula showing how the $\mu$-invariant and $\check{\mu}$-invariant behave with respect to the disjoint union and the join with a complete graph.

Lemma 2. $\check{\mu}(G)=\min \left\{l \in \mathbb{N}_{0} \mid \bar{K}_{l} * G\right.$ is Hamiltonian $\}$.
Proof. Since $\bar{K}_{l} * G$ is a subgraph of $K_{l} * G$, a Hamiltonian cycle in $\bar{K}_{l} * G$ would also be one in $K_{l} * G$.

Let $\check{\mu}(G)=a$. Suppose $C$ is a Hamiltonian cycle in $K_{a} * G$ and write $C$ as $v \sim P_{1} \sim Q_{1} \sim \cdots \sim P_{s} \sim Q_{s} \sim v$, where $v$ is a vertex in $G$ and the paths $P_{i}$ in $G$ and $Q_{i}$ in $K_{a}$. If any $Q_{i}$ contains two vertices or more, say $u$ and $w_{1}, \ldots, w_{k}$ with $k \geq 1$, then we may simply remove all the vertices, except $u$, and end up with a Hamiltonian graph on $K_{a-k}$. This contradicts the minimality of $a=\check{\mu}(G)$. Therefore, $C$ must not contain any paths of length greater than two in the subgraph $K_{a}$, and any Hamiltonian cycle on $K_{a} * G$ is also a Hamiltonian cycle on $\bar{K}_{a} * G$.

## Lemma 3.

$$
\check{\mu}(G)=\mu(G)-i_{H}(G) .
$$

Proof. If $G$ is Hamiltonian (including $K_{1}$ and $K_{2}$ ) then $\check{\mu}(G)=0, \mu(G)=1$ so the equality holds. Suppose $G$ is non-Hamiltonian with $\mu(G)=t$ and $t$-path covering $P_{1}, \ldots, P_{t}$. Let $K_{t}$ have vertices $u_{1}, \ldots, u_{t}$. In the graph $K_{t} * G$, there is a Hamiltonian cycle: $v_{1} \sim P_{1} \sim v_{2} \sim P_{2} \sim \cdots \sim v_{t} \sim P_{t} \sim v_{1}$. Thus $\check{\mu}(G) \leq t=\mu(G)$.

Let $\check{\mu}(G)=a$, so there is a Hamiltonian cycle in $K_{a} * G$. Removing the vertices of $K_{a}$ breaks the cycle into at most $a$ disjoint paths covering $G$. Thus $\mu(G) \leq \check{\mu}(G)$.

Lemma 4.

$$
\begin{aligned}
& \mu(G \sqcup H)=\mu(G)+\mu(H) \text { and } \\
& \check{\mu}(G \sqcup H)=\check{\mu}(G)+\check{\mu}(H)+i_{H}(G)+i_{H}(H) .
\end{aligned}
$$

Proof. A path covering of $G$ may be combined with a path covering of $H$ to create one for $G \sqcup H$ so $\mu(G \sqcup H) \leq \mu(G)+\mu(H)$. Conversely, paths in a $t$-path covering of $G \sqcup H$ can be partitioned into those contained in $G$ and those contained in $H$, giving a path covering of $G$ and one of $H$. Consequently, $\mu(G \sqcup H) \geq \mu(G)+\mu(H)$.

Since $G \sqcup H$ is not Hamiltonian we have

$$
\begin{aligned}
\check{\mu}(G \sqcup H) & =\mu(G \sqcup H)+i_{H}(G \sqcup H) \\
& =\mu(G)+\mu(H) \\
& =\check{\mu}(G)+i_{H}(G)+\check{\mu}(H)+i_{H}(H) .
\end{aligned}
$$

Lemma 5. For any graph $G$,

$$
\begin{aligned}
& \mu\left(K_{s} * G\right)=\max \{1, \mu(G)-s\}, \\
& \check{\mu}\left(K_{s} * G\right)=\max \{0, \check{\mu}(G)-s\} .
\end{aligned}
$$

In particular, if $K_{s} * G$ is Hamiltonian then $\mu\left(K_{s} * G\right)=1$ and $\check{\mu}\left(K_{s} * G\right)=0$; otherwise, $\mu\left(K_{s} * G\right)=\mu(G)-s$ and $\check{\mu}\left(K_{s} * G\right)=\check{\mu}(G)-s$.

Proof. The formula for $\check{\mu}$ is immediate when $G$ is Hamiltonian since we have observed that this forces $K_{s} * G$ to be Hamiltonian. Otherwise, it follows from
$K_{r} *\left(K_{s} * G\right)=K_{r+s} * G:$ if $\check{\mu}(G)=a$, then $K_{r} *\left(K_{s} * G\right)$ is Hamiltonian if and only if $r+s \geq a$.

The formula for $\mu$ may be derived from the result for $\check{\mu}$ using Lemma 3 .
The main result of this section is the following two formulas for the $\mu$ and $\check{\mu}$ invariants of the disjoint union of graphs, and the join with a complete graph.

Proposition 6. Let $\left\{G_{j}\right\}_{j=1}^{m}$ be graphs. Then

$$
\begin{aligned}
& \mu\left(\bigsqcup_{j=1}^{m} G_{j}\right)=\sum_{j=1}^{m} \mu\left(G_{j}\right), \\
& \check{\mu}\left(\bigsqcup_{j=1}^{m} G_{j}\right)=\sum_{j=1}^{m} \check{\mu}\left(G_{j}\right)+\sum_{j=1}^{m} i_{H}\left(G_{j}\right) .
\end{aligned}
$$

Furthermore,

$$
\check{\mu}\left(\left(\bigsqcup_{j=1}^{m} G_{j}\right) * K_{r}\right)=\max \left\{0, \sum_{j=1}^{m} \check{\mu}\left(G_{j}\right)+\sum_{j=1}^{m} i_{H}\left(G_{j}\right)-r\right\} .
$$

Proof. We proceed by induction. The base case $k=2$ is exactly Lemma 4. Assume the formula holds for $k$ graphs; we will prove it for $k+1$ graphs.

$$
\begin{aligned}
\mu\left(\bigsqcup_{j=1}^{k+1} G_{j}\right) & =\mu\left(\left(\bigsqcup_{j=1}^{k} G_{j}\right) \sqcup G_{k+1}\right)=\mu\left(\bigsqcup_{j=1}^{k} G_{j}\right)+\mu\left(G_{k+1}\right) \\
& =\sum_{j=1}^{k} \mu\left(G_{j}\right)+\mu\left(G_{k+1}\right)=\sum_{j=1}^{k+1} \mu\left(G_{j}\right)
\end{aligned}
$$

By Lemma 3 and the fact that disjoint graphs are not Hamiltonian, we have

$$
\begin{aligned}
\check{\mu}\left(\bigsqcup_{j=1}^{m} G_{j}\right) & =\mu\left(\bigsqcup_{j=1}^{m} G_{j}\right)+i_{H}\left(\bigsqcup_{j=1}^{m} G_{j}\right) \\
& =\sum_{j=1}^{m}\left(\check{\mu}\left(G_{j}\right)+i_{H}\left(G_{j}\right)\right)=\sum_{j=1}^{m} \check{\mu}\left(G_{j}\right)+\sum_{j=1}^{m} i_{H}\left(G_{j}\right) .
\end{aligned}
$$

Therefore, we have by Lemma 5,

$$
\begin{aligned}
\check{\mu}\left(\left(\bigsqcup_{j=1}^{m} G_{j}\right) * K_{r}\right) & =\max \left\{0, \check{\mu}\left(\bigsqcup_{j=1}^{m} G_{j}\right)-r\right\} \\
& =\max \left\{0, \sum_{j=1}^{m} \check{\mu}\left(G_{j}\right)+\sum_{j=1}^{m} i_{H}\left(G_{j}\right)-r\right\} .
\end{aligned}
$$

The following lemma will be useful in the next section. To express it succinctly, we introduce the following Boolean condition. For a graph $G$ and vertex $v \in V(G)$, $T(v, G)$ is true if and only if $v$ is a terminal vertex in some minimal path covering of $G$.

Lemma 7. Let $v \in V(G)$ and $w \in V(H)$. Then we have

$$
\mu((G \sqcup H)+v w)= \begin{cases}\mu(G \sqcup H)-1 & \text { if } T(v, G) \text { and } T(w, H), \\ \mu(G \sqcup H) & \text { otherwise. }\end{cases}
$$

Proof. Let $\mu(G)=c, \mu(H)=d$ and $\mu((G \sqcup H)+v w)=t$. Clearly, $t \leq c+d$.
Let $R_{1}, \ldots, R_{t}$ be a minimal path cover of $(G \sqcup H)+v w$. If no $R_{i}$ contains $v w$ then this is also a minimal path cover of $(G \sqcup H)$ so $t=c+d$. Suppose $R_{1}$ contains $v w$ and note that $R_{1}$ is the only path with vertices in both $G$ and $H$. Removing $v w$ gives two paths $P \subseteq G$ and $Q \subseteq H$. Paths $P$ and $Q$ along with $R_{2}, \ldots, R_{t}$ cover $G \sqcup H$, so $t+1 \geq c+d$. Thus, $t$ can either be $c+d$ or $c+d-1$.

If $t=c+d-1$, then we have the minimal $(t+1)$-path covering $P, Q, R_{2}, \ldots, R_{t}$ of $G \sqcup H$, as above. We note that $v$ must be a terminal point of $P$ and $w$ must be a terminal point of $Q$, by construction. This path covering may be partitioned into a $c$-path covering of $G$ containing $P$ and a $d$-path covering of $H$ containing $Q$. Thus, $T(v, G)$ and $T(w, G)$ hold.

Conversely, suppose $T(u, G)$ and $T(w, H)$ both hold. Let $P_{1}, \ldots, P_{c}$ be a minimal path of $G$ with $v$ a terminal vertex of $P_{1}$ and let $Q_{1}, \ldots, Q_{d}$ be a minimal path cover of $H$ with $w$ a terminal vertex of $Q_{1}$. The edge $v w$ knits $P_{1}$ and $Q_{1}$ into a single path and $P_{1} \sim Q_{1}, P_{1}, \ldots, P_{c}, Q_{1}, \ldots, Q_{d}$ is a $c+d-1$ cover of $(G \sqcup H)+v w$. Consequently, $t \leq c+d-1$.

Thus, $T(u, G)$ and $T(w, H)$ both hold if and only if $t=c+d-1$. Otherwise, $t=c+d$.

Corollary 8. Let $v \in V(G)$ and $w \in V(H)$. Then we have

$$
\check{\mu}((G \sqcup H)+v w)= \begin{cases}\check{\mu}(G \sqcup H)-2 & \text { if } G=H=K_{1}, \\ \check{\mu}(G \sqcup H)-1 & \text { if } T(v, G) \text { and } T(w, H), \\ \check{\mu}(G \sqcup H) & \text { otherwise } .\end{cases}
$$

Proof. Let $\delta=1$ if $T(v, G)$ and $T(w, H)$ are both true and $\delta=0$ otherwise. Then

$$
\begin{aligned}
\check{\mu}((G \sqcup H)+v w) & =\mu((G \sqcup H)+v w)-i_{H}((G \sqcup H)+v w) \\
& =\mu\left((G \sqcup H)-\delta-i_{H}((G \sqcup H)+v w) .\right.
\end{aligned}
$$

The final term is -1 if and only if $G=H=K_{1}$.

## 3. Decomposing maximal $t$-path traceable graphs

In this section we prove our main result, a maximal $t$-path traceable graph may be uniquely written as the join of a complete graph and a disjoint union of graphs that are also maximal with respect to traceability, but which are also either complete or have no universal vertex. We work with the families of graphs $\mathcal{M}_{t}$ for $t \geq 0$ and $\mathcal{N}_{t}$ for $t \geq 1$ :

$$
\begin{aligned}
\mathcal{M}_{t} & :=\{G \mid \check{\mu}(G)=t \text { and } \check{\mu}(G+e)<t, \forall e \in E(\bar{G})\}, \\
\mathcal{N}_{t} & :=\left\{G \in \mathcal{M}_{t} \mid G \text { is connected and has no universal vertex }\right\} .
\end{aligned}
$$

The set $\mathcal{M}_{0}$ is the set of complete graphs. The set $\mathcal{M}_{1}$ is the set of graphs with a Hamiltonian path but no Hamiltonian cycle, that is, maximal non-Hamiltonian graphs. For $t>1, \mathcal{M}_{t}$ is also the set of graphs $G$ such $\mu(G)=t$ and $\mu(G+e)=t-1$ for any $e \in E(\bar{G})$. We will call these maximal $t$-path traceable graphs. A graph in $\mathcal{N}_{t}$ will be called trim.

Proposition 9. For $0 \leq r<t, G \in \mathcal{M}_{t}$ if and only if $K_{r} * G \in \mathcal{M}_{t-r}$.
Proof. We have $\check{\mu}\left(K_{r} * G\right)=\check{\mu}(G)-r$, by Lemma 5 , so we just need to show that $K_{r} * G$ is maximal if and only if $G$ is maximal. The only edges that can be added to $K_{r} * G$ are those between vertices of $G$, that is, $E\left(\overline{K_{r} * G}\right)=E(\bar{G})$. For such an edge $e$,

$$
\begin{equation*}
\check{\mu}\left(\left(K_{r} * G\right)+e\right)=\check{\mu}\left(K_{r} *(G+e)\right)=\check{\mu}(G+e)-r . \tag{1}
\end{equation*}
$$

Thus, $\check{\mu}(G+e)=\check{\mu}(G)-1$ if and only if $\check{\mu}\left(\left(K_{r} * G\right)+e\right)=\check{\mu}\left(K_{r} * G\right)-1$.
Note that the proposition is false for $r=t>0$ since $K_{r} * G$ will not be a complete graph and $\mathcal{M}_{0}$ is the set of complete graphs. The proof breaks down in (1).

As a key step before the main theorem, the next lemma shows that in a maximal graph, each vertex is either universal or it is a terminal vertex in a minimal path covering (but not both).
Lemma 10. Let $c \geq 1$ and $G \in \mathcal{M}_{c}$. For any two nonadjacent vertices $v, w$ in $G$, there is a $c$-path covering of $G$ in which both $v$ and $w$ are terminal points of paths. Moreover, a vertex $v \in V(G)$ is a terminal point in some $c$-path covering if and only if $v$ is not universal.
Proof. Suppose $c>1$ and let $v, w$ be nonadjacent in $G$. Since $G$ is maximal, $G+v w$ has a $(c-1)$-path covering, $P_{1}, \ldots, P_{c-1}$. The edge $v w$ must be contained in some $P_{i}$ because $G$ has no $(c-1)$-path covering. Removing that edge gives a $c$-path covering of $G$ with $v$ and $w$ as terminal vertices. The special case $c=1$ is well known, adding the edge $v w$ gives a Hamiltonian cycle, and removing it leaves a path with endpoints $v$ and $w$. A consequence is that any nonuniversal vertex is the terminal point of some path in a $c$-path covering.

Suppose $P_{1}, \ldots, P_{c}$ is a $c$-path covering of $G \in \mathcal{M}_{c}$ with $v$ a terminal point of $P_{i}$. Then $v$ is not adjacent to any of the terminal points of $P_{j}$ for $j \neq i$, for otherwise two paths could be combined into a single one. In the case $c=1, v$ cannot be adjacent to the other terminal point of $P_{1}$, otherwise $G$ would have a Hamiltonian cycle. Consequently, a universal vertex is not a terminal point in a $c$-path covering of $G$.

Proposition 11. Let $G \in \mathcal{M}_{c}$ and $H \in \mathcal{M}_{d}$. The following are equivalent:
(1) $G \sqcup H \in \mathcal{M}_{c+d+i_{H}(G)+i_{H}(H)}$.
(2) Each of $G$ and $H$ is either complete or has no universal vertex.

Proof. We have already shown that $\check{\mu}(G \sqcup H)=c+d+i_{H}(G)+i_{H}(H)$. We have to consider whether adding an edge to $G \sqcup H$ reduces the $\check{\mu}$-invariant. There are three cases to consider: the extra edge may be in $E(\bar{G})$ or $E(\bar{H})$ or it may join a vertex in $G$ to one in $H$. Since $G$ is maximal, adding an edge to $G$ is either impossible, when $G$ is complete, or it reduces the $\check{\mu}$-invariant of $G$. This edge would also reduce the $\check{\mu}$-invariant of $G \sqcup H$ by Lemma 4 . The case for adding an edge of $H$ is the same. Consider the edge $v w$ for $v \in V(G)$ and $w \in V(H)$. By Corollary 8 the $\check{\mu}$-invariant will drop if and only if $v$ is the terminal point of a path in a minimal path covering of $G$ and similarly for $w$ in $H$, that is, $T(v, G)$ and $T(w, H)$. Clearly this holds for all vertices in a complete graph. Lemma 10 shows that $T(v, G)$ holds for $G \in \mathcal{M}_{c}$ with $c>0$ if and only if $v$ is not a universal vertex in $G$. Thus, in order for $G \sqcup H$ to be maximal, $G$ must either be complete or be maximal itself and have no universal vertex, and similarly for $H$.

Theorem 12. For any $G \in \mathcal{M}_{t}, t>0, G$ may be uniquely decomposed as

$$
K_{r} *\left(G_{1} \sqcup \ldots \sqcup G_{m}\right),
$$

where $r$ is the number of universal vertices of $G$, and each $G_{j}$ is either complete or $G_{j} \in \mathcal{N}_{t_{j}}$ for some $t_{j}>0$. Furthermore $t=\sum_{j=1}^{m} t_{j}+\sum_{j=1}^{m} i_{H}\left(G_{j}\right)-r$.
Proof. Suppose $G \in \mathcal{M}_{t}$ and let $r$ be the number of universal vertices of $G$. Let $m$ be the number of components in the graph obtained by removing the universal vertices from $G$, let $G_{1}, \ldots G_{m}$ be the components and let $\check{\mu}\left(G_{j}\right)=t_{j}$. Then $G=K_{r} *\left(G_{1} \sqcup \ldots \sqcup G_{m}\right)$.

Proposition 6 shows that $t=\sum_{j=1}^{m} t_{j}+\sum_{j=1}^{m} i_{H}\left(G_{j}\right)-r$. By Proposition 9, we have that $G \in \mathcal{M}_{t}$ if and only if $G_{1} \sqcup \ldots \sqcup G_{m} \in \mathcal{M}_{t+r}$. Each $G_{i}$ must be maximal, otherwise the disjoint union would not be maximal (add an appropriate edge to a $G_{i}$ in Proposition 6). Inductively applying Proposition 11 to $G_{1} \sqcup \ldots \sqcup G_{m} \in \mathcal{M}_{t+r}$, where $t+r=\sum_{j=1}^{m} t_{j}+\sum_{j=1}^{m} i_{H}\left(G_{j}\right)$, we have that each $G_{j}$ is complete or is $\operatorname{trim}\left(G_{j} \in \mathcal{N}_{t_{j}}\right.$ for $\left.t_{j}>0\right)$.

## 4. Trim maximal $\boldsymbol{t}$-path traceable graphs

Skupień [1979] discovered the first family of maximal non-Hamiltonian graphs, that is, graphs in $\mathcal{M}_{1}$. These graphs are formed by taking the join of $K_{r}$ with the disjoint union of $r+1$ complete graphs [Marczyk and Skupień 1991]. The smallest graph in $\mathcal{N}_{2}$ is shown in Figure 1. Chvátal [1973] identified its join with $K_{1}$ as the smallest maximal non-Hamiltonian graph that is not 1-tough, that is, not one of the Skupień family. Jamrozik, Kalinowski and Skupień [1982] generalized this example to three different families. Family $A 1$ replaces each edge $u_{i} v_{i}$ in Figure 1 with an arbitrary complete graph containing $u_{i}$ and replaces the $K_{3}$ formed by the $u_{i}$ with an arbitrary complete graph. The result - a type $A 1$ graph - has four cliques, the first three disjoint from each other but each intersecting the fourth clique in a single vertex. An $A 1$ graph is in $\mathcal{N}_{2}$ and its join with $K_{1}$ gives a maximal non-Hamiltonian graph. Family $A 2$ is formed by taking the join with $K_{2}$ of the disjoint union of a complete graph and an $A 1$ graph. Theorem 12 shows that the resulting graph is in $\mathcal{M}_{1}$. Family $A 3$ is a modification of the $A 1$ family based on the graph in Figure 2, which is in $\mathcal{N}_{2}$.

More than two decades later, Bullock, Frick, Singleton and van Aardt [2008] recognized that two constructions of Zelinka [1998] give maximal nontraceable graphs, that is, elements of $M_{2}$. Zelinka's first construction is like the Skupień family: formed from $r+1$ complete graphs followed by the join with $K_{r-1}$. The Zelinka type II family contains graphs in $\mathcal{N}_{2}$ that are a significant generalization of the graphs in Figures 1 and 2. In this section we generalize this family further to get graphs in $\mathcal{N}_{t}$ for arbitrary $t$. Our starting point is the graph in Figure 3, which is in $\mathcal{N}_{3}$.
Example 13. Consider $K_{m}$ with $m=2 t-1$ and vertices $u_{1}, \ldots, u_{m}$. Let $G$ be the graph containing $K_{m}$ along with vertices $v_{1}, \ldots, v_{2 t-1}$ and edges $u_{i} v_{i}$. The case with $t=3$ and $m=5=2 t-1$ is Figure 3 . We claim $G \in \mathcal{N}_{t}$.

One can readily check that this graph is $t$-path covered using $v_{2 i-1} \sim u_{2 i-1} \sim$ $u_{2 i} \sim v_{2 i}$ for $i=1, \ldots, t-1$ and $v_{2 t-1} \sim u_{2 t-1} \sim u_{2 t} \sim \cdots \sim u_{m}$. We check that $G$ is maximal. By the symmetry of the graph, we need only consider the addition


Figure 1. Smallest graph in $\mathcal{N}_{2}$.


Figure 2. The join of this graph with $K_{1}$ is the smallest graph in the $A 3$ family.


Figure 3. Whirligig in $\mathcal{N}_{3}$.
of the edge $v_{1} u_{m}$ or $v_{1} u_{2}$ or $v_{1} v_{2}$. In each case, the last and the first paths listed above may be combined into one, either

$$
\begin{aligned}
& v_{2 t-1} \sim u_{2 t-1} \sim \ldots \sim u_{m} \sim v_{1} \sim u_{1} \sim u_{2} \sim v_{2}, \text { or } \\
& v_{2 t-1} \sim u_{2 t-1} \sim \ldots \sim u_{m} \sim u_{1} \sim v_{1} \sim u_{2} \sim v_{2}, \text { or } \\
& v_{2 t-1} \sim u_{2 t-1} \sim \ldots \sim u_{m} \sim u_{1} \sim v_{1} \sim v_{2} \sim u_{2} .
\end{aligned}
$$

Thus, adding an edge creates a $(t-1)$-path covered graph, proving maximality.
The next proposition shows that the previous example is the only way to have a trim maximal $t$-path covered graph with $2 t-1$ degree-one vertices. We start with a technical lemma.
Lemma 14. Let $G$ be a connected graph and $u_{1}, v_{1}, v_{2}, v_{3} \in V(G)$ with $\operatorname{deg}\left(v_{i}\right)=1$, and $u$ adjacent to $v_{1}$ and $v_{2}$ but not $v_{3}$. Then $\mu(G)=\mu\left(G+u v_{3}\right)$.
Proof. Let $P_{1}, \ldots, P_{r}$ be a minimal path covering of $G+u v_{3}$; it is enough to show that there are $r$-paths covering $G$. If the covering doesn't include $u v_{3}$, then $P_{1}, \ldots, P_{r}$ also give a minimal path covering of $G$, establishing the claim of the lemma. Otherwise, suppose $u v_{3}$ is an edge of $P_{1}$. We consider two cases.

Suppose $P_{1}$ contains the edge $u v_{1}$ (or similarly $u v_{2}$ ). Then $P_{1}$ has $v_{1}$ as a terminal point and one of the other paths, say $P_{2}$, must be a length- 0 path containing simply $v_{2}$. Let $Q$ be obtained by removing $u v_{1}$ and $u v_{3}$ from $P_{1}$. Then $v_{1} \sim u \sim$ $v_{2}, Q, P_{3}, \ldots, P_{r}$, gives an $r$-path covering of $G$.

Suppose $P_{1}$ contains neither $u v_{1}$ nor $u v_{2}$. Then each of $v_{1}$ and $v_{2}$ must be on a length- 0 path in the covering, say $P_{2}$ and $P_{3}$ are these paths. Furthermore $u$ must not be a terminal point of $P_{1}$; if it were, the path could be extended to include $v_{1}$ or $v_{2}$, reducing the number of paths required to cover $G$. Removing $u$ from $P_{1}$ yields two paths, $Q_{1}, Q_{2}$. Then $v_{1} \sim u \sim v_{2}, Q_{1}, Q_{2}, P_{4}, \ldots, P_{r}$ gives an $r$-path cover of $G$. This proves the lemma.

Proposition 15. Let $G \in \mathcal{N}_{t}$. The number of degree-one vertices in $G$ is at most $2 t-1$. This occurs if and only if the $2 t-1$ vertices of degree-one have distinct neighbors and removing the degree-one vertices leaves a complete graph.

Proof. Each degree-one vertex must be a terminal point in a path covering. So any graph $G$ covered by $t$ paths can have at most $2 t$ degree-one vertices. Aside from the case $t=1$ and $G=K_{2}$, we can see that a graph with $2 t$ degree-one vertices cannot be maximal $t$-path traceable as follows. It is easy to check that a $2 t$ star is not $t$-path traceable (it is also not trim). A $t$-path traceable graph with $2 t$ degree-one vertices must therefore have an interior vertex $w$ that is not connected to at least one of the degree-one vertices $v$. Such a graph is not maximal because the edge $v w$ can be added leaving $2 t-1$ degree-one vertices. This resulting graph cannot be ( $t-1$ )-path covered.

Suppose that $G \in \mathcal{N}_{t}$ with $2 t-1$ degree-one vertices, $v_{1}, \ldots, v_{2 t-1}$. Lemma 14 shows that no two of the $v_{i}$ can be adjacent to the same vertex, for that would violate maximality of $G$. So, the $v_{i}$ have distinct neighbors. Furthermore, all the vertices except the $v_{i}$ can be connected to each other and a path covering will still require at least $t$ paths since there remain $2 t-1$ degree-one vertices. This proves the necessity of the structure claimed in the proposition. The previous example showed that the graph is indeed in $\mathcal{N}_{t}$.

We can now generalize the Zelinka family.
Construction 16. Let $U_{0}, U_{1}, \ldots, U_{2 t-1}$ be disjoint sets of vertices and

$$
U=\bigsqcup_{i=0}^{2 t-1} U_{i} .
$$

Let $m_{i}=\left|U_{i}\right|$ and assume that for $i>0$ the $U_{i}$ are nonempty, so $m_{i}>0$. For $i=1, \ldots, 2 t-1$ (but not $i=0$ ) and $j=1, \ldots, m_{i}$, let $V_{i j}$ be nonempty sets of vertices disjoint from each other and from $U$. Form the graph $W$ with vertex set $U \sqcup\left(\bigsqcup_{i=1}^{2 t-1}\left(\bigsqcup_{j=1}^{m_{i}} V_{i j}\right)\right)$ and edges $u u^{\prime}$ for $u, u^{\prime} \in U$ and $u v$ for any $u \in U_{i}$


Figure 4. Generalization of the whirligig, $W$.
and $v \in V_{i j}$ with $i=1, \ldots, 2 t-1$ and $j=1, \ldots, m_{i}$ and all edges within each set $V_{i j}$. The cliques of this graph are $K_{U}$ and $K_{U_{i} \sqcup V_{i j}}$ for each $i=1, \ldots, 2 t-1$ and $j=1, \ldots, m_{i}$.

The graph in Figure 2 has $m_{0}=0, m_{1}=m_{2}=1$ and $m_{3}=2$, and the graph in Figure 4 indicates the general construction.
Theorem 17. The graph $W$ in Construction 16 is a trim, maximal $t$-path traceable graph.

Proof. We must show that $W$ is $t$-path covered and not $(t-1)$-path covered, and that the addition of any edge yields a $(t-1)$-path covered graph. The argument is analogous to the one in Example 13.

Let $R$ be a Hamiltonian path in $U_{0}$. For each $i=1, \ldots, 2 t-1$ and $j=1, \ldots, m_{i}$, let $Q_{i j}$ be a Hamiltonian path in $K_{V_{i j}}$. Let $P_{i}$ be the path

$$
P_{i}: Q_{i 1} \sim u_{i 1} \sim Q_{i 2} \sim u_{i 2} \sim \cdots \sim Q_{i m_{i}} \sim u_{i m_{i}}
$$

and let $\overleftarrow{P_{i}}$ be the reversal of $P_{i}$.
Since there is an edge $u_{i m_{i}} u_{j m_{j}}$ there is a path $P_{i} \sim \overleftarrow{P}_{j}$ for any $i \not \equiv j \in$ $\{1, \ldots, 2 t-1\}$. Therefore the graph $W$ has a $t$-path covering $P_{2 i-1} \sim \overleftarrow{P}_{2 i}$ for $i=1, \ldots,(t-1)$, along with $P_{2 t-1} \sim R$. We leave to the reader the argument that there is no $(t-1)$-path cover.

To show $W$ is maximal we show that after adding an edge $e$, we can join two paths in the $t$-path cover above, with a bit of rearrangement. There are three types of edges to consider, the edge $e$ might join $V_{i j}$ to $U_{i^{\prime}}$ for $i \neq i^{\prime}$; or $V_{i j}$ to $V_{i j^{\prime}}$ for $j \neq j^{\prime}$; or $V_{i j}$ to $V_{i^{\prime} j^{\prime}}$ for $i \neq i^{\prime}$. Because of the symmetry of $W$, we may assume
$i=1$ and $j=1$ and that the vertex chosen from $V_{i j}=V_{1,1}$ is the initial vertex of $Q_{1,1}$. Other simplifications due to symmetry will be evident in what follows.

In the first case there are two subcases - determined by $i^{\prime} \geq 2 t$ or not - and after permutation, we may consider the edge $e$ from the initial vertex of $Q_{1,1}$ to the terminal vertex of $R$, or to the terminal vertex of $P_{2 t-1}$. We can then join two paths in the $t$-path cover: either $P_{2 t-1} \sim R \stackrel{e}{\sim} P_{1} \sim \overleftarrow{P}_{2}$ or $P_{2 t-1} \stackrel{e}{\sim} P_{1} \sim R \sim \overleftarrow{P}_{2}$

Suppose next that we join the initial vertex of $Q_{11}$ with the terminal vertex of $Q_{12}$. We then rearrange $P_{1}$ and join two paths in the $t$-path cover to get

$$
P_{2 t-1} \sim R \sim u_{1,1} \sim Q_{1,1} \stackrel{e}{\sim} Q_{1,2} \sim u_{1,2} \sim \cdots \sim Q_{1 m_{1}} \sim u_{1 m_{1}} \sim \overleftarrow{P}_{2}
$$

Finally, suppose that we join the initial vertex of $Q_{1,1}$ with the initial vertex of $Q_{2 t-1,1}$. Then we rearrange to

$$
\overleftarrow{R} \sim \overleftarrow{P}_{2 t-1} \stackrel{e}{\sim} P_{1} \sim \overleftarrow{P}_{2}
$$

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kashbari@math.tamu.edu
mosullivan@mail.sdsu.edu

Department of Mathematics and Statistics, San Diego
State University, San Diego, CA 92182, United States
Department of Mathematics and Statistics, San Diego State University, San Diego, CA 92182, United States

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