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# FUSION RULES ON A PARAMETRIZED SERIES OF GRAPHS 

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#### Abstract

A series of pairs of graphs $\left(\Gamma_{k}, \Gamma_{k}^{\prime}\right), k=0,1,2, \ldots$, has been considered as candidates for dual pairs of principal graphs of subfactors of small Jones index above 4 and it has recently been proved that the pair ( $\Gamma_{k}, \Gamma_{k}^{\prime}$ ) comes from a subfactor if and only if $k=0$ or $k=1$. We show that nevertheless there exists a unique fusion system compatible with this pair of graphs for all nonnegative integers $k$.


## 1. Introduction

A subfactor $N \subset M$ with finite index and finite depth generates finitely many isomorphism classes of bimodules with four different combinations of left and right coefficients. They form a bigraded fusion category. Its Grothendieck ring forms a fusion ring or a fusion hypergroup, namely a bigraded $\mathbb{Z}$-algebra $\mathscr{A}$ satisfying:

- $A$ has a basis given by finitely many irreducible bimodules of four different kinds: $\mathscr{X}={ }_{N} \mathscr{X}_{N} \sqcup_{N} \mathscr{X}_{M} \sqcup_{M} \mathscr{X}_{N} \sqcup_{M} \mathscr{X}_{M}$ (we call the labels $N$ and $M$ right or left coefficients, depending on the position).
- An involution $X \in{ }_{P} \mathscr{X}_{Q} \rightarrow \bar{X} \in \mathscr{X}_{P}$ is defined, where $P, Q \in\{N, M\}$.
- A product is defined for a pair of bimodules with "matching" coefficients, namely, for a pair $(X, Y) \in \mathscr{X} \times \mathscr{X}$ such that the right coefficient of $X$ and the left coefficient of $Y$ match, $X Y$ is defined. It decomposes as

$$
X Y=\sum N_{X, Y}^{Z} Z
$$

where the sum is taken over those $Z \in \mathscr{X}$ that have the same left (respectively, right) coefficient as $X$ (respectively, $Y$ ), and $N_{X, Y}^{Z} \in \mathbb{N}_{0}$. Moreover, Frobenius reciprocity holds:

$$
N_{X, Y}^{Z}=N_{Z, \bar{Y}}^{X}=N_{\bar{X}, Z}^{Y}=N_{\bar{Y}, \bar{X}}^{\bar{Z}}=N_{\bar{Z}, X}^{\bar{Y}}=N_{Y, \bar{Z}}^{\bar{X}}
$$

- There are identity objects $\mathbf{1}_{N} \in{ }_{N} \mathscr{X}_{N}, \mathbf{1}_{M} \in{ }_{M} \mathscr{X}_{M}$ that act as identity with respect to the product, whenever it is defined.

[^0]The involution extends linearly to define an involution on $\mathscr{A}$. For a fusion ring $\mathscr{A}$, there is a unique weight function $\mu: \mathscr{A} \rightarrow \mathbb{R}_{\geq}$satisfying

$$
\begin{aligned}
\mu\left(\mathbf{1}_{N}\right) & =\mu\left(\mathbf{1}_{M}\right)=1 \\
\mu(X Y) & =\mu(X) \mu(Y) \\
\mu(X+Z) & =\mu(X)+\mu(Z),
\end{aligned}
$$

where $X, Y, Z \in \mathscr{X}$ are with suitable coefficients for each equality, so that $X Y$ and $X+Z$ are defined. The (dual) principal graph of the subfactor encodes partial information of the fusion algebra: namely, the (dual) principal graph has the vertices corresponding to ${ }_{N} \mathscr{X}_{N} \sqcup_{N} \mathscr{X}_{M}$ (respectively, $M_{M} \mathscr{X}_{N} \sqcup_{M} \mathscr{X}_{M}$ ), with the number of the edges between vertices ${ }_{N} X_{N}$ and ${ }_{N} Y_{M}$ (respectively, ${ }_{M} X_{M}$ and ${ }_{M} Y_{N}$ ) given by $N_{X,{ }_{N} M_{M}}^{Y}$ (respectively, $N_{X,{ }_{M} M_{N}}^{Y}$.)

On the other hand, one may start with a pair of graphs and may consider if there is a fusion algebra compatible with the fusion constraints determined by the graphs. Such investigation may be used to exclude graphs as (dual) principal graphs of subfactors. For example, type $E_{7}$ and $D_{2 n+1}$ Dynkin diagrams are proved not to be (dual) principal graphs of subfactors, by showing that the fusion constraints given by the graphs give rise to inconsistency in fusion rules [Izumi 1991; Sunder and Vijayarajan 1993]. Note that the existence of a fusion algebra compatible with a given pair of graphs does not imply the existence of a subfactor with given graphs as (dual) principal graphs.

In this paper, we deal with the series of pairs of graphs shown in Figure 1.


Figure 1. $n=4 k+3, k=0,1, \ldots$

These graphs are a part of the list of the graphs that were candidates for (dual) principal graphs of a subfactor with indices between 4 and $3+\sqrt{3}$ given by [Haagerup 1994]. The notation used here is somewhat different from the one used in [Haagerup 1994]. It has been already proved that, for $k=0,1$, the graphs $\Gamma_{k}$ (respectively, $\Gamma_{k}^{\prime}$ ) are (dual) principal graphs of a subfactors [Asaeda and Haagerup 1999; Bigelow et al. 2009], and for $k>1$, they are not realized as (dual) principal graphs [Asaeda and Yasuda 2009]. In this paper, we prove that, despite that the $\Gamma_{k}$ (respectively, $\Gamma_{k}^{\prime}$ ) are not principal graphs for $k>1$, there are still fusion algebras consistent with the graphs, and moreover such fusion algebras are unique for each $k$.

Theorem 1.1. Let $V_{11}:=\left\{\right.$ even vertices of $\left.\Gamma_{k}\right\}, V_{12}:=\left\{\right.$ odd vertices of $\left.\Gamma_{k}\right\}, V_{21}:=$ $\left\{\right.$ odd vertices of $\left.\Gamma_{k}^{\prime}\right\}, V_{22}:=\left\{\right.$ even vertices of $\left.\Gamma_{k}^{\prime}\right\}$, and $V:=V_{11} \sqcup V_{12} \sqcup V_{21} \sqcup V_{22}$. For each $k$, there is a unique fusion algebra $\mathscr{A}=\mathbb{Z} \mathscr{X}$, where

$$
\mathscr{X}={ }_{N} \mathscr{X}_{N} \sqcup_{N} \mathscr{X}_{M} \sqcup_{M} \mathscr{X}_{N} \sqcup_{M} \mathscr{X}_{M}
$$

is compatible with the graphs $\Gamma_{k}, \Gamma_{k}^{\prime}$. Namely,

$$
\begin{aligned}
& { }_{N} \mathscr{X}_{N}=V_{11}, \\
& { }_{N} \mathscr{X}_{M}=V_{12}, \\
& { }_{M} \mathscr{X}_{N}=V_{21}, \\
& { }_{\mathscr{X}_{M}}=V_{22}
\end{aligned}
$$

as sets, and

$$
\begin{aligned}
N_{X, \alpha_{1}}^{Y}\left(\text { respectively, } N_{X, \bar{\alpha}_{1}}^{Y}\right) & = \begin{cases}1 & \text { if } X \text { and } Y \text { are connected by an edge }, \\
0 & \text { else, }\end{cases} \\
N_{X, 1}^{Y} & =\delta_{X, Y},
\end{aligned}
$$

where $X, Y \in \mathscr{X}$, and 1 denotes identity objects $1_{N}=\alpha_{0} \in_{N} \mathscr{X}_{N}$ or $1_{M}=\alpha_{0}^{\prime} \in{ }_{M} \mathscr{X}_{M}$.
In Section 2 we show that if there is a fusion system compatible with the graphs $\Gamma_{k}, \Gamma_{k}^{\prime}$, it must be unique. In Section 3 we show the existence of such a fusion system.

## 2. Uniqueness, positivity, and integrality of the fusion rules

In this section we prove that if there is a fusion algebra compatible with the graphs, it is unique. Positivity and integrality of fusion coefficients is derived: we do not impose them in showing uniqueness of the fusion rules.

2A. Fusion rules for the even vertices. In this subsection we show that there is a unique fusion algebra structure on $\mathscr{A}_{1}=\mathbb{Z}_{N} \mathscr{X}_{N}$ compatible with the graph $\Gamma_{k}$.

The main issue is to determine the fusion rule among $\beta_{1}, \beta_{3}, \gamma_{1}, \gamma_{3}$. The rest will follow easily from this.

In the following we assume there is a fusion algebra compatible with $\left(\Gamma_{k}, \Gamma_{k}^{\prime}\right)$. The involution $\gamma \in V \rightarrow \bar{\gamma} \in V$ extends linear to a map on $\mathbb{R} V$. For simplicity, we refer to the objects in $\mathscr{X}$ by corresponding vertices in $V$. For $X:=\sum N_{X}^{Z} Z \in \mathbb{R} V$ and $Y \in V$, denote

$$
\langle X, Y\rangle=\langle Y, X\rangle:=N_{X}^{Y}
$$

Observe that $\langle\cdot, \cdot\rangle$ expends linearly to define a bilinear form on $\mathbb{R} V$, and

$$
\langle X Y, Z\rangle=\langle X, Z \bar{Y}\rangle=\langle Y, \bar{X} Z\rangle
$$

holds by Frobenius reciprocity. The graph $\Gamma_{k}$ encodes the decomposition of $X \alpha_{1}$ for $X$ in $V_{11}$ as a direct sum of vertices from $V_{12}$ and the decomposition of $Y \bar{\alpha}_{1}$ as a direct sum of vertices from $V_{11}$. Let $G$ be the adjacency matrix for $\left(V_{11}, V_{12}\right)$, that is,

$$
G=\left(G_{X, Y}\right)_{X \in V_{11}, Y \in V_{12}},
$$

where $G_{X, Y}$ is the number of the edges connecting $X$ and $Y$, namely

$$
G_{X, Y}=\left\langle X \alpha_{1}, Y\right\rangle=\left\langle Y \bar{\alpha}_{1}, X\right\rangle
$$

$G$ has dimensions $\left(\frac{n+1}{2}+4\right) \times\left(\frac{n+1}{2}+2\right)$ and can be written as
(1)

Letting

$$
\Delta:=\left(\begin{array}{cc}
0 & G \\
G^{t} & 0
\end{array}\right)
$$

we have

$$
\Delta^{2}=\left(\begin{array}{cc}
G G^{t} & 0 \\
0 & G^{t} G
\end{array}\right)
$$

Put $\mathbb{D}:=G G^{t}$, which acts on $\overline{\mathscr{A}}_{1}:=\mathbb{R} V_{11}$. We utilize certain eigenvectors of $\mathbb{D}$ to determine the fusion structure of $\mathscr{A}_{1}$.

Observe from the graph that

$$
\begin{array}{ll}
\Delta \beta_{1}=\alpha_{n}+\beta_{2}, & \Delta \gamma_{1}=\alpha_{n}+\gamma_{2} \\
\Delta \beta_{2}=\beta_{1}+\beta_{3}, & \Delta \gamma_{2}=\gamma_{1}+\gamma_{2} \\
\Delta \beta_{3}=\beta_{2}, & \Delta \gamma_{3}=\gamma_{2} .
\end{array}
$$

Put

$$
\begin{aligned}
& \xi=\left(\beta_{1}-\gamma_{1}\right)+\left(\beta_{3}-\gamma_{3}\right), \\
& \eta=\left(\beta_{1}-\gamma_{1}\right)-\left(\beta_{3}-\gamma_{3}\right) .
\end{aligned}
$$

Then

$$
\begin{aligned}
\mathbb{D} \xi & =\Delta^{2} \xi=\Delta\left(2 \beta_{2}-2 \gamma_{2}\right)=2 \xi \\
\mathbb{D} \eta & =\Delta^{2} \eta=0 .
\end{aligned}
$$

Let $E(\mathbb{D}, c), c \in \mathbb{R}$, be the eigenspace of the eigenvalue $c$ for $\mathbb{D}$ in $\mathbb{R}\left(V_{11}\right)$.
Lemma 2.1. $\operatorname{dim} E(\mathbb{D}, 2)=E(\mathbb{D}, 0)=2$.
Proof. The matrix $\mathbb{D}$ is

Recall that $n=4 k+3$. Let $\rho_{k}(x):=\operatorname{det}(t I-\mathbb{D})$ be the characteristic polynomial of $\mathbb{D}=G G^{t}$. It was proved in [Asaeda 2007] that the characteristic polynomial of $G^{t} G$ is equal to $(t-2)^{2} q_{k}(t)$, where the polynomials $q_{k}(t), k \geq 0$, can be defined recursively by

$$
\begin{aligned}
& q_{0}(t)=t^{2}-5 t+3 \\
& q_{1}(t)=(t-1)\left(t^{3}-8 t^{2}+17 t-5\right) \\
& q_{k}(t)=\left(t^{2}-4 t+2\right) q_{k-1}(t)-q_{k-2}(t), \quad k \geq 2
\end{aligned}
$$

Since the matrix $G$ has $2 k+6$ rows and $2 k+4$ columns, $G G^{t}$ is a unitary conjugate of $G^{t} G \oplus 0_{2}$, where $0_{2}$ is the zero $2 \times 2$ matrix. Hence

$$
\begin{aligned}
\rho_{k}(t) & =t^{2} \operatorname{det}\left(t I-G^{t} G\right) \\
& =t^{2}(t-2)^{2} q_{k}(t)
\end{aligned}
$$

The recursion formula for $q_{k}(t)$ gives $q_{k}(0)=2 k+3$ and $q_{k}(2)=(-1)^{(k+1)}(2 k+3)$ In particular neither 0 nor 2 is a root of $q_{k}$. Hence 0 and 2 are roots of multiplicity 2 in $\rho_{k}$. Since $\mathbb{D}=G G^{t}$ is a symmetric matrix, the dimensions of the eigenspaces for $\mathbb{D}$ for the eigenvalues 0 and 2 are both equal to 2 .

Bases of $E(\mathbb{D}, 2), E(\mathbb{D}, 0)$ may be taken as

$$
\begin{aligned}
& E(\mathbb{D}, 2):=\operatorname{span}\left\{x_{1}, x_{2}\right\}, \\
& E(\mathbb{D}, 0):=\operatorname{span}\left\{y_{1}, y_{2}\right\},
\end{aligned}
$$

where

$$
\begin{aligned}
& x_{1}:=2\left(\alpha_{0}+\alpha_{2}\right)-2\left(\alpha_{4}+\alpha_{6}\right)+\cdots+(-1)^{k} 2\left(\alpha_{4 k}+\alpha_{4 k+2}\right) \\
&+(-1)^{k+1}\left(\beta_{1}+\gamma_{1}+\beta_{3}+\gamma_{3}\right), \\
& x_{2}:=\xi=\left(\beta_{1}-\gamma_{1}\right)+\left(\beta_{3}-\gamma_{3}\right), \\
& y_{1}:=2 \alpha_{0}-2 \alpha_{2}+\cdots+2 \alpha_{4 k}-2 \alpha_{4 k+2}+\left(\beta_{1}+\gamma_{1}\right)-\left(\beta_{3}+\gamma_{3}\right), \\
& y_{2}:=\eta=\left(\beta_{1}-\gamma_{1}\right)-\left(\beta_{3}-\gamma_{3}\right) .
\end{aligned}
$$

Assume that we have a fusion algebra compatible with the pair of the graphs ( $\Gamma_{k}, \Gamma_{k}^{\prime}$ ), and let $\pi$ and $\pi^{\prime}$ be the conjugate maps $\gamma \mapsto \bar{\gamma}$ on $V_{11}$ and $V_{22}$. By the argument used in [Haagerup 1994, pp 28-31], the map $\pi^{\prime}$ fixes every element of $V_{22}$. For $\pi$, there are only two possibilities:

Case 1 [Haagerup 1994, Case (b), p 31].

$$
\bar{\beta}_{1}=\beta_{1}, \quad \bar{\gamma}_{1}=\gamma_{1}, \quad \bar{\beta}_{3}=\gamma_{3}\left(\Leftrightarrow \bar{\gamma}_{3}=\beta_{3}\right)
$$

Case 2 [Haagerup 1994, Case (a), p 31]. (This case will be eliminated.)

$$
\bar{\beta}_{1}=\gamma_{1}\left(\Leftrightarrow \bar{\gamma}_{1}=\beta_{1}\right), \quad \bar{\beta}_{3}=\beta_{3}, \quad \bar{\gamma}_{3}=\gamma_{3} .
$$

In both cases, $\bar{\alpha}_{2 j}=\alpha_{2 j}$ for $j=0,1, \ldots, 2 k+1$. Note that $\pi$ extends linearly to $\mathscr{A}_{1}$ and $\bar{A}_{1}=\mathbb{R} V_{11}$. Let $E(\mathbb{D}, c)_{s c}:=E(\mathbb{D}, c)^{\pi}$. Observe that

$$
c_{1} \bar{x}_{1}+c_{2} \bar{x}_{2}=c_{1} x_{1}+c_{2} x_{2}, \quad c_{1}, c_{2} \in \mathbb{R}
$$

holds if and only if $c_{2}=0$ in both Cases 1 and 2, and similarly

$$
c_{1} c_{1} \bar{y}_{1}+c_{2} \bar{y}_{2}=c_{1} y_{1}+c_{2} y_{2}, \quad c_{1}, c_{2} \in \mathbb{R}
$$

if and only if $c_{2}=0$ in both cases. Therefore

$$
\begin{aligned}
& E(\mathbb{D}, 2)_{\mathrm{s} c}=\mathbb{R} x_{1}, \\
& E(\mathbb{D}, 0)_{\mathrm{s} c}=\mathbb{R} y_{1} .
\end{aligned}
$$

By the definition of principal graphs, the matrix $\mathbb{D}: \mathbb{R} V_{11} \rightarrow \mathbb{R} V_{11}$ corresponds to the fusion rule of the right tensor product by $\alpha \bar{\alpha}$, where $\alpha=\alpha_{1}$. Therefore

$$
\begin{aligned}
& \mathbb{D}(\bar{\xi} \xi)=\bar{\xi} \mathbb{D}(\xi)=2 \bar{\xi} \xi \\
& \mathbb{D}(\bar{\eta} \eta)=\bar{\eta} \mathbb{D}(\eta)=0
\end{aligned}
$$

Hence

$$
\begin{aligned}
& \bar{\xi} \xi \in E(\mathbb{D}, 2)_{s c}=\mathbb{R} x_{1}, \\
& \bar{\eta} \eta \in E(\mathbb{D}, 0)_{s c}=\mathbb{R} y_{1} .
\end{aligned}
$$

Thus

$$
\left\langle\bar{\xi} \xi, \alpha_{0}\right\rangle=\left\langle\xi, \xi \alpha_{0}\right\rangle=\langle\xi, \xi\rangle=4
$$

Hence the coefficient of $\bar{\xi} \xi$ at $\alpha_{0}$ is 4 . Since $\bar{\xi} \xi \in \mathbb{R} x_{1}$, we have $\bar{\xi} \xi=2 x_{1}$. Likewise we obtain $\bar{\eta} \eta=2 y_{1}$. Noting that

$$
\bar{\xi}=\left\{\begin{aligned}
\eta & \text { in Case } 1 \\
-\eta & \text { in Case } 2
\end{aligned}\right.
$$

we have

$$
\begin{cases}\xi \eta=2 y_{1}, & \eta \xi=2 x_{1} \\ \xi \eta=-2 y_{1}, & \eta \xi=-2 x_{1} \\ \text { in Case } 1 \\ \xi \eta\end{cases}
$$

which completes the proof.
Lemma 2.2. $\xi^{2}=0$ and $\eta^{2}=0$.
Proof. The equality $\mathbb{D}\left(\xi^{2}\right)=\xi \mathbb{D}(\xi)=2 \xi^{2}$ implies $\xi^{2}=c_{1} x_{1}+c_{2} x_{2}$ for some $c_{1}, c_{2} \in \mathbb{R}$. Moreover, since $\langle\xi, \eta\rangle=0$, we have

$$
\left\langle\xi^{2}, \alpha_{0}\right\rangle=\left\langle\xi, \bar{\xi} \alpha_{0}\right\rangle= \pm\langle\xi, \eta\rangle=0
$$

Together with $\left\langle c_{1} x_{1}+c_{2} x_{2}, \alpha_{0}\right\rangle=2 c_{1}, c_{1}, c_{2} \in \mathbb{R}$, we obtain

$$
\xi^{2}=c_{2} x_{2}=c_{2} \xi
$$

We show that $c_{2}=0$, using that $\bar{\xi} \xi=2 x_{1}$ and $\xi \bar{\xi}=2 y_{1}$ in Cases 1 and 2 :

$$
\begin{aligned}
4 c_{2} & =\left\langle c_{2} \xi, c_{2} \xi\right\rangle=\left\langle\xi^{2}, \xi^{2}\right\rangle=\langle\bar{\xi} \xi, \xi \bar{\xi}\rangle=4\left\langle x_{1}, y_{1}\right\rangle \\
& =(2-2)-(2-2)+\cdots+(-1)^{k}(2-2)+(1+1-1-1)=0
\end{aligned}
$$

Thus $\xi^{2}=0$. Then $\bar{\xi}^{2}=\eta^{2}=0$ for both cases.

Since $\beta_{3}-\gamma_{3}=\frac{1}{2}(\xi-\eta)$, we get

$$
\begin{aligned}
\left(\beta_{3}-\gamma_{3}\right)^{2} & =\frac{1}{4}(\xi-\eta)^{2} \\
& =\frac{1}{4}\left(\xi^{2}+\eta^{2}-\xi \eta-\eta \xi\right) \\
& =-\frac{1}{4}(\xi \eta+\eta \xi) \\
& =\left\{\begin{aligned}
-\frac{1}{2}\left(x_{1}+y_{1}\right) & \text { in Case } 1 \\
\frac{1}{2}\left(x_{1}+y_{1}\right) & \text { in Case } 2
\end{aligned}\right.
\end{aligned}
$$

Remark 2.3. For $k$ even, that is, $n=3(\bmod 8)$ and $k=2 l$,

$$
\frac{1}{2}\left(x_{1}+y_{1}\right)=2\left(\alpha_{0}-\alpha_{6}+\alpha_{8}-\alpha_{14}+\alpha_{16}-\cdots+\alpha_{8 l}\right)-\left(\beta_{3}+\gamma_{3}\right)
$$

and for $k$ odd, that is, $n=7(\bmod 8)$ and $k=2 l+1$,

$$
\frac{1}{2}\left(x_{1}+y_{1}\right)=2\left(\alpha_{0}-\alpha_{6}+\alpha_{8}-\alpha_{14}+\alpha_{16}-\cdots+\alpha_{8 l}-\alpha_{8 l+6}\right)+\left(\beta_{1}+\gamma_{1}\right) .
$$

Consider next the sequence of polynomials $R_{n}$ given recursively by

$$
R_{0}(t)=1, R_{1}(t)=t, R_{m}(t)=t R_{m-1}(t)-R_{m-2}(t), \quad n \geq 2
$$

as in [Haagerup 1994, pp 33-34]. Note that $R_{m}(t)=U_{m}\left(\frac{t}{2}\right)$, where $U_{m}$ is the $m$-th Chebyshev polynomial of second kind [Erdélyi et al. 1981, Section 10.11]. Moreover,

$$
R_{m}(2 \cos \theta)=\frac{\sin (m+1) \theta}{\sin \theta}, \quad 0<\theta<\pi
$$

By the recursion formula for $R_{n}$,

$$
\begin{aligned}
R_{j}(\Delta) \alpha_{0} & =\alpha_{j}, \quad 0 \leq j \leq n \\
R_{n+1}(\Delta) \alpha_{0} & =\beta_{1}+\gamma_{1} \\
R_{n+2}(\Delta) \alpha_{0} & =\alpha_{n}+\beta_{2}+\gamma_{2} \\
R_{n+3}(\Delta) \alpha_{0} & =\alpha_{n-1}+\beta_{1}+\gamma_{1}+\beta_{3}+\gamma_{3}
\end{aligned}
$$

Hence

$$
\begin{aligned}
\beta_{3}+\gamma_{3} & =\left(R_{n+3}(\Delta)-R_{n+1}(\Delta)-R_{n-1}(\Delta)\right) \alpha_{0} \\
& =\left(R_{4 k+6}(\Delta)-R_{4 k+4}(\Delta)-R_{4 k+2}(\Delta)\right) \alpha_{0}
\end{aligned}
$$

For $m$ even, $R_{m}(t)$ is an even polynomial in $t$, thus there is are unique polynomials $\left(Q_{j}\right)_{j=0,1,2, \ldots}$ with $\operatorname{deg}\left(Q_{l}\right)=l$, such that

$$
Q_{j}\left(t^{2}\right)=R_{2 j}(t), \quad t \in \mathbb{R}, \quad j=0,1,2, \ldots
$$

With this notation, we have

$$
\begin{aligned}
\beta_{3}+\gamma_{3} & =\left(Q_{2 k+3}(\mathbb{D})-Q_{2 k+2}(\mathbb{D})-Q_{2 k+1}(\mathbb{D})\right) \alpha_{0} \\
& =\left(Q_{2 k+3}-Q_{2 k+2}-Q_{2 k+1}\right)(\alpha \bar{\alpha})
\end{aligned}
$$

Therefore

$$
\begin{aligned}
\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right) & =\left(Q_{2 k+3}-Q_{2 k+2}-Q_{2 k+1}\right)(\mathbb{D})\left(\beta_{3}-\gamma_{3}\right) \\
& =\frac{1}{2}\left(Q_{2 k+3}-Q_{2 k+2}-Q_{2 k+1}\right)(\mathbb{D})(\xi-\eta) .
\end{aligned}
$$

Since $\mathbb{D} \xi=2 \xi$ and

$$
\begin{aligned}
Q_{m}(2)=R_{2 j}(\sqrt{2}) & =\frac{\sin (2 j+1) \pi / 4}{\sin \pi / 4} \\
& =\left\{\begin{array}{rl}
1 & j=0,1(\bmod 4) \\
-1 & j=2,3(\bmod 4)
\end{array}\right.
\end{aligned}
$$

we have

$$
Q_{j}(\mathbb{D}) \xi=\left\{\begin{aligned}
\xi & j=0,1(\bmod 4) \\
-\xi & j=2,3(\bmod 4)
\end{aligned}\right.
$$

Similarly, since $\mathbb{D} \eta=0$ and

$$
Q_{j}(0)=R_{2 j}(0)=\frac{\sin (2 j+1) \pi / 2}{\sin \pi / 2}=(-1)^{j}
$$

we have

$$
Q_{j}(\mathbb{D}) \eta=(-1)^{j} \eta, \quad j=0,1,2 \ldots
$$

Therefore,

$$
\begin{aligned}
& \left(Q_{2 k+3}(\mathbb{D})-Q_{2 k+2}(\mathbb{D})-Q_{2 k+1}(\mathbb{D})\right) \xi \\
& \quad= \begin{cases}\left(Q_{4 l+3}(\mathbb{D})-Q_{4 l+2}(\mathbb{D})-Q_{4 l+1}(\mathbb{D})\right) \xi=-\xi & \text { for } k=2 l, l \in \mathbb{N}_{0}, \\
\left(Q_{4 l+5}(\mathbb{D})-Q_{4 l+4}(\mathbb{D})-Q_{4 l+3}(\mathbb{D})\right) \xi=\xi & \text { for } k=2 l+1, l \in \mathbb{N}_{0},\end{cases}
\end{aligned}
$$

and in both cases

$$
\left(Q_{2 k+3}(\mathbb{D})-Q_{2 k+2}(\mathbb{D})-Q_{2 k+1}(\mathbb{D})\right) \eta=-\eta
$$

Hence

$$
\begin{aligned}
&\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right)=\frac{1}{2}\left(Q_{2 k+3}-Q_{2 k+2}-Q_{2 k+1}\right)(\mathbb{D})(\xi-\eta) \\
&= \begin{cases}\frac{1}{2}(-\xi+\eta)=\gamma_{3}-\beta_{3} & k \text { even } \\
\frac{1}{2}(\xi+\eta)=\beta_{1}-\gamma_{1} & k \text { odd }\end{cases}
\end{aligned}
$$

Using the contragredient map we get in Case 1 that

$$
\begin{aligned}
\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right) & =\overline{\left(\bar{\beta}_{3}-\bar{\gamma}_{3}\right)\left(\bar{\beta}_{3}+\bar{\gamma}_{3}\right)} \\
& =\overline{\left(\gamma_{3}-\beta_{3}\right)\left(\gamma_{3}+\beta_{3}\right)} \\
& =-\overline{\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right)} \\
& = \begin{cases}-\left(\bar{\gamma}_{3}-\bar{\beta}_{3}\right)=-\left(\beta_{3}-\gamma_{3}\right) & k \text { even, } \\
-\left(\bar{\beta}_{1}-\bar{\gamma}_{1}\right)=-\left(\beta_{1}-\gamma_{1}\right) & k \text { odd }\end{cases}
\end{aligned}
$$

and in Case 2 (to be eliminated) that

$$
\begin{aligned}
\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right) & =\overline{\left(\bar{\beta}_{3}-\bar{\gamma}_{3}\right)\left(\bar{\beta}_{3}+\bar{\gamma}_{3}\right)} \\
& =\overline{\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right)} \\
& = \begin{cases}\bar{\gamma}_{3}-\bar{\beta}_{3}=\gamma_{3}-\beta_{3} & k \text { even } \\
\bar{\beta}_{1}-\bar{\gamma}_{1}=\gamma_{1}-\beta_{1} & k \text { odd }\end{cases}
\end{aligned}
$$

Thus in both cases,

$$
\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right)= \begin{cases}\gamma_{3}-\beta_{3} & k \text { even } \\ \gamma_{1}-\beta_{1} & k \text { odd }\end{cases}
$$

So far, we have obtained the three formulae

$$
\left(\beta_{3}-\gamma_{3}\right)^{2}=\left\{\begin{align*}
-\frac{1}{2}\left(x_{1}-y_{1}\right) & \text { in Case } 1  \tag{A}\\
\frac{1}{2}\left(x_{1}-y_{1}\right) & \text { in Case } 2
\end{align*}\right.
$$

$$
\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right)= \begin{cases}\frac{1}{2}(-\xi+\eta)=\gamma_{3}-\beta_{3} & k \text { even }  \tag{B}\\ \frac{1}{2}(\xi+\eta)=\beta_{1}-\gamma_{1} & k \text { odd }\end{cases}
$$

(C)

$$
\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right)= \begin{cases}\gamma_{3}-\beta_{3} & k \text { even } \\ \gamma_{1}-\beta_{1} & k \text { odd }\end{cases}
$$

Next we compute $\left(\beta_{3}+\gamma_{3}\right)^{2}$, in order to find $\beta_{3}^{2}, \gamma_{3}^{2}, \beta_{3} \gamma_{3}$ and $\gamma_{3} \beta_{3}$.

## Claim 2.4. We have

(D) $\left(\beta_{3}+\gamma_{3}\right)^{2}=2\left(c_{0} \alpha_{0}+c_{1} \alpha_{2}+\cdots+c_{2 k+1} \alpha_{4 k+2}\right)+c_{2 k+2}\left(\beta_{1}+\gamma_{1}\right)+c_{2 k}\left(\beta_{3}+\gamma_{3}\right)$,
where the $c_{j}$ are defined by

$$
\begin{aligned}
& c_{0}=1 \\
& c_{1}=c_{2}=0 \\
& c_{j}=c_{j-1}+c_{j-2}+c_{j-3} \quad \text { for } j \geq 3
\end{aligned}
$$

Proof. Recall that

$$
\begin{aligned}
\left(\beta_{3}+\gamma_{3}\right) & =\left(Q_{2 k+3}-Q_{2 k+2}-Q_{2 k+1}\right)(\mathbb{D}) \alpha_{0} \\
& =\left(R_{4 k+6}(\Delta)-R_{4 k+4}(\Delta)-R_{4 k+2}(\Delta)\right) \alpha_{0}
\end{aligned}
$$

thus

$$
\left(\beta_{3}+\gamma_{3}\right)^{2}=\left(R_{4 k+6}(\Delta)-R_{4 k+4}(\Delta)-R_{4 k+2}(\Delta)\right)\left(\beta_{3}+\gamma_{3}\right)
$$

Our strategy of the proof is as follows: First we find a sequence of polynomials $\left(S_{j}\right)$ such that $S_{j}(\Delta)\left(\beta_{3}+\gamma_{3}\right)$ is given by a simple formula. Next we rewrite the righthand side of $(\sharp)$ using the $S_{j}$.

From the graph, we obtain

$$
\begin{aligned}
& R_{0}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=\left(\beta_{3}+\gamma_{3}\right) \\
& R_{1}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=\left(\beta_{2}+\gamma_{2}\right) \\
& R_{2}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=\Delta\left(\beta_{2}+\gamma_{2}\right)-\left(\beta_{3}+\gamma_{3}\right)=\beta_{1}+\gamma_{1} \\
& R_{3}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=\Delta\left(\beta_{1}+\gamma_{1}\right)-\left(\beta_{2}+\gamma_{2}\right)=2 \alpha_{n} \\
& R_{4}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=2 \Delta \alpha_{n}-\left(\beta_{1}+\gamma_{1}\right)=2 \alpha_{n-1}+\beta_{1}+\gamma_{1}
\end{aligned}
$$

Define the polynomials $\left(S_{j}(t)\right)_{j \geq 3}$ by the recursive formula

$$
\begin{aligned}
& S_{3}(t)=R_{3}(t) \\
& S_{4}(t)=R_{4}(t)-R_{2}(t) \\
& S_{j}(t)=t S_{j-1}(t)-S_{j-2}(t), \quad j \geq 5
\end{aligned}
$$

By definition $S_{3}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=2 \alpha_{n}$ and $S_{4}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=2 \alpha_{n-1}$. Since $\alpha_{l-1}=$ $\Delta \alpha_{l}-\alpha_{l+1}$ for $l=1,2, \ldots, n-1$, we easily obtain

$$
S_{j}(\Delta)\left(\beta_{3}+\gamma_{3}\right)=2 \alpha_{n-j+3}
$$

for $j=3,4, \ldots, n+3$. Next we express the $R_{j}$ in terms of the $S_{j}$.
Lemma 2.5. For $j \geq 2$,

$$
\begin{aligned}
R_{2 j-1} & =d_{0} S_{2 j-1}+d_{1} S_{2 j-3}+\cdots+d_{j-2} S_{3}+\left(d_{j-1}-d_{j-2}\right) R_{1} \\
R_{2 j} & =d_{0} S_{2 j}+d_{1} S_{2 j-2}+\cdots+d_{j-2} S_{4}+d_{j-1} R_{2}+d_{j-3} R_{0}
\end{aligned}
$$

where the $d_{j}$ satisfy

$$
d_{-1}=0, \quad d_{0}=d_{1}=1, \quad d_{j}=d_{j-1}+d_{j-2}+d_{j-3}
$$

Proof. For $j=2$ this is obvious by the definition of the $S_{j}$. We proceed with induction. Assume the statement is true for $j \geq 2$. Using the recursion formulae for the $R_{j}$ and $S_{j}$, we have

$$
\begin{aligned}
R_{2 j+1}(t)= & t R_{2 j}(t)-R_{2 j-1}(t) \\
= & t\left(d_{0} S_{2 j}+d_{1} S_{2 j-2}+\cdots+d_{j-2} S_{4}+d_{j-1} R_{2}+d_{j-3}\right) \\
& \quad-\left(d_{0} S_{2 j-1}+d_{1} S_{2 j-3}+\cdots+d_{j-2} S_{3}+\left(d_{j-1}-d_{j-2}\right) R_{1}\right) \\
= & d_{0} S_{2 j+1}+d_{1} S_{2 j-1}+\cdots+d_{j-2} S_{5}+t\left(d_{j-1} R_{2}+d_{j-3}\right)-\left(d_{j-1}-d_{j-2}\right) R_{1} \\
= & d_{0} S_{2 j+1}+d_{1} S_{2 j-1}+\cdots+d_{j-2} S_{5}+d_{j-1}\left(t R_{2}-R_{1}\right)+t d_{j-3}-d_{j-2} R_{1} \\
= & d_{0} S_{2 j+1}+d_{1} S_{2 j-1}+\cdots+d_{j-2} S_{5}+d_{j-1} S_{3}+\left(d_{j-3}-d_{j-2}\right) R_{1} .
\end{aligned}
$$

The last equality was obtained using $S_{3}=R_{3}, R_{1}=t$, and $d_{j-2}+d_{j-3}=d_{j}-d_{j-1}$. Likewise we have

$$
\begin{aligned}
& R_{2 j+2}(t)= t R_{2 j+1}(t)-R_{2 j}(t) \\
&= d_{0} S_{2 j+2}+d_{1} S_{2 j}+\cdots+d_{j-2} S_{6} \\
& \quad+t\left(d_{j-1} S_{3}+\left(d_{j}-d_{j-1}\right) R_{1}\right)-\left(d_{j-1} R_{2}+d_{j-3} R_{0}\right) \\
&= d_{0} S_{2 j+2}+d_{1} S_{2 j}+\cdots+d_{j-2} S_{6}+d_{j-1} R_{4} \\
& \quad+\left(d_{j}-d_{j-1}\right)\left(R_{2}+R_{0}\right)-d_{j-3} R_{0} \\
&= d_{0} S_{2 j+2}+d_{1} S_{2 j}+\cdots+d_{j-2} S_{6}+d_{j-1} S_{4} \\
& \quad+d_{j} R_{2}+\left(d_{j}-d_{j-1}-d_{j-3}\right) R_{0} \\
&= d_{0} S_{2 j+2}+d_{1} S_{2 j}+\cdots+d_{j-2} S_{6}+d_{j-1} S_{4}+d_{j} R_{2}+d_{j-2} R_{0}
\end{aligned}
$$

which completes the proof of Lemma 2.5.
We return to (\#). Using Lemma 2.5,

$$
\begin{aligned}
& R_{4 k+6}-R_{4 k+4}-R_{4 k+2} \\
& =d_{0} S_{4 k+6}+\left(d_{1}-d_{0}\right) S_{4 k+4}+d_{-1} S_{4 k+2}+d_{0} S_{4 k}+d_{1} S_{4 k-2} \\
& \\
& \quad+\cdots+d_{2 k-2} S_{4}+d_{2 k-1} R_{2}+d_{2 k-3} R_{0} \\
& =S_{4 k+6}+d_{0} S_{4 k}+d_{1} S_{4 k-2}+\cdots+d_{2 k-2} S_{4}+d_{2 k-1} R_{2}+d_{2 k-3} R_{0}
\end{aligned}
$$

Recall

$$
\begin{aligned}
S_{j}(\Delta)\left(\beta_{3}+\gamma_{3}\right) & =2 \alpha_{n-j+3} \\
R_{2}\left(\beta_{3}+\gamma_{3}\right) & =\beta_{1}+\gamma_{1}
\end{aligned}
$$

Letting $c_{0}:=1, c_{1}=c_{2}=0$ and $c_{j}:=d_{j-3}$ for $j \geq 3$, we obtain Equation (D), which concludes the proof of Claim 2.4.

Thus far we have obtained the formulae for $\left(\beta_{3}-\gamma_{3}\right)^{2},\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right)$, $\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right)$ and $\left(\beta_{3}+\gamma_{3}\right)^{2}$ in Equations (A), (B), (C) and (D). This enables us to understand the fusion rules among $\beta_{3}, \gamma_{3}$ and their conjugates.

Proposition 2.6. Case 2 does not occur. Namely, $\beta_{1}$ and $\gamma_{1}$ are self conjugate and $\bar{\beta}_{3}=\gamma_{3}$ if there is a fusion algebra compatible with the graphs $\Gamma_{k}$ and $\Gamma_{k}^{\prime}$.

Proof. First observe that, by the definition of $c_{j}, j \geq 0$, in Claim 2.4, it follows that $c_{j}(\bmod 4)$ is periodic in $j$ with period 8 . The values are:

| $j(\bmod 8)$ | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $c_{j}(\bmod 4)$ | 1 | 0 | 0 | 1 | 1 | 2 | 0 | 0 |

In particular,
(*)

$$
\begin{cases}c_{2 j}=1(\bmod 4) & \text { for } \mathrm{j} \text { even } \\ c_{2 j}=0(\bmod 4) & \text { for } \mathrm{j} \text { odd. }\end{cases}
$$

In the following we assume Case 2 and derive a contradiction.
First consider the case when $k$ is even. By (B) and (C), we have

$$
\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right)=\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right)
$$

hence

$$
\begin{aligned}
\beta_{3} \gamma_{3}=\gamma_{3} \beta_{3} & =\frac{1}{2}\left(\beta_{3} \gamma_{3}+\gamma_{3} \beta_{3}\right) \\
& =\frac{1}{4}\left(\left(\beta_{3}+\gamma_{3}\right)^{2}-\left(\beta_{3}-\gamma_{3}\right)^{2}\right)
\end{aligned}
$$

From (A) for Case 2, (D) and Remark 2.3, the coefficient of $\beta_{3}$ in the expansion of $\beta_{3} \gamma_{3}$ in irreducible objects is equal to

$$
\frac{c_{2 k}+1}{4}
$$

Since $k$ is even, $c_{2 k}=1 \bmod 4$ by $(\star)$, so $\left(c_{2 k}+1\right) / 4$ is not an integer. This implies that Case 2 does not occur if $k$ is even.

Next consider the case when $k$ is odd. From (B) and (C), we get

$$
\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right)=-\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right)
$$

Hence

$$
\begin{aligned}
\beta_{3}^{2}=\gamma_{3}^{2} & =\frac{1}{2}\left(\beta_{3}^{2}+\gamma_{3}^{2}\right) \\
& =\frac{1}{4}\left(\left(\beta_{3}+\gamma_{3}\right)^{2}+\left(\beta_{3}-\gamma_{3}\right)^{2}\right)
\end{aligned}
$$

From (A) for Case 2, (D) and Remark 2.3, it follows that the coefficient of $\beta_{1}$ in the expansion of $\beta_{3}^{2}$ in irreducible objects is equal to

$$
\frac{c_{2 k+2}+1}{4}
$$

Since $k$ is odd, $c_{2 k+2}=1 \bmod 4$ by $(\star)$, so $\left(c_{2 k}+1\right) / 4$ is not an integer. This excludes Case 2 for $k$ odd as well.

In the following we determine all the irreducible decompositions for the products of any two objects in $V$ and show that the coefficients are nonnegative integers. Since we excluded Case 2, we rewrite (A) as
$\left(\mathrm{A}^{\prime}\right)\left(\beta_{3}-\gamma_{3}\right)^{2}=\left\{\begin{array}{r}-2\left(\alpha_{0}-\alpha_{6}+\alpha_{8}-\alpha_{14}+\alpha_{16}-\cdots+\alpha_{8 l}\right)-\left(\beta_{3}+\gamma_{3}\right) \\ k=2 l, l=0,1,2, \ldots, \\ -2\left(\alpha_{0}-\alpha_{6}+\alpha_{8}-\alpha_{14}+\alpha_{16}-\cdots+\alpha_{8 l}-\alpha_{8 l+6}\right)+\left(\beta_{1}+\gamma_{1}\right) \\ k=2 l+1, l=0,1,2, \ldots\end{array}\right.$

Put

$$
\begin{array}{ll}
A:=\left(\beta_{3}-\gamma_{3}\right)^{2}, & B:=\left(\beta_{3}-\gamma_{3}\right)\left(\beta_{3}+\gamma_{3}\right), \\
C:=\left(\beta_{3}+\gamma_{3}\right)\left(\beta_{3}-\gamma_{3}\right), & D:=\left(\beta_{3}+\gamma_{3}\right)^{2} .
\end{array}
$$

Then

$$
\begin{array}{ll}
\beta_{3} \gamma_{3}=\frac{(D-A)+(B-C)}{4}, & \beta_{3}^{2}=\frac{(D+A)+(B+C)}{4}, \\
\gamma_{3} \beta_{3}=\frac{(D-A)-(B-C)}{4}, & \gamma_{3}^{2}=\frac{(D+A)-(B+C)}{4} .
\end{array}
$$

We introduce new constants $\left(f_{j}\right)_{j \geq 0},\left(g_{j}\right)_{j \geq 0}$ by

$$
\begin{cases}f_{j}=\frac{1}{2}\left(c_{j}+1\right), g_{j}=\frac{1}{2}\left(c_{j}-1\right) & \text { for } j=0(\bmod 4) \\ f_{j}=\frac{1}{2}\left(c_{j}-1\right), g_{j}=\frac{1}{2}\left(c_{j}+1\right) & \text { for } j=3(\bmod 4), \\ f_{j}=g_{j}=\frac{1}{2} c_{j} & \text { for } j=1,2(\bmod 4) .\end{cases}
$$

Note that $f_{j}+g_{j}=c_{j}$ for all $j$. Further, from the table on page 268, observe that $f_{j}, g_{j}$ is an nonnegative integer for all $j \geq 0$. Here are some values of $f_{j}$ and $g_{j}$ :

| $j$ | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $f_{j}$ | 1 | 0 | 0 | 0 | 1 | 1 | 2 | 3 | 7 | 12 | 22 | 40 | 75 |
| $g_{j}$ | 0 | 0 | 0 | 1 | 0 | 1 | 2 | 4 | 6 | 12 | 22 | 41 | 74 |

For $k$ even, using (A'), (B), (C), (D), we have

$$
\begin{aligned}
\frac{D-A}{4} & =f_{0} \alpha_{0}+f_{1} \alpha_{2}+\cdots+f_{2 k+1} \alpha_{4 k+2}+\frac{1}{4} c_{2 k+2}\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{4}\left(c_{2 k}-1\right)\left(\beta_{3}+\gamma_{3}\right), \\
\frac{D+A}{4} & =g_{0} \alpha_{0}+g_{1} \alpha_{2}+\cdots+g_{2 k+1} \alpha_{4 k+2}+\frac{1}{4} c_{2 k+2}\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{4}\left(c_{2 k}+1\right)\left(\beta_{3}+\gamma_{3}\right), \\
\frac{B-C}{4} & =0, \\
\frac{B+C}{4} & =\frac{1}{2}\left(\gamma_{3}-\beta_{3}\right) .
\end{aligned}
$$

Since $k$ is even, $c_{2 k+2}=2 f_{2 k+2}=2 g_{2 k+2}, c_{2 k}+1=2 f_{2 k}$ and $c_{2 k}-1=2 g_{2 k}$. Hence we obtain the following theorem:

Theorem 2.7. For $k$ even,

$$
\begin{aligned}
\beta_{3} \gamma_{3}= & \gamma_{3} \beta_{3}=f_{0} \alpha_{0}+f_{1} \alpha_{2}+\cdots+f_{2 k+1} \alpha_{4 k+2} \\
& +\frac{1}{2} f_{2 k+2}\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{2}\left(f_{2 k}-1\right)\left(\beta_{3}+\gamma_{3}\right), \\
\beta_{3}^{2}=g_{0} \alpha_{0}+g_{1} \alpha_{2}+\cdots+g_{2 k+1} \alpha_{4 k+2} & +\frac{1}{2} g_{2 k+2}\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{2} g_{2 k} \beta_{3}+\frac{1}{2}\left(g_{2 k}+2\right) \gamma_{3}, \\
\gamma_{3}^{2}=g_{0} \alpha_{0}+g_{1} \alpha_{2}+\cdots+g_{2 k+1} \alpha_{2 k+2} & +\frac{1}{2} g_{2 k+2}\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{2}\left(g_{2 k}+2\right) \beta_{3}+\frac{1}{2} g_{2 k} \gamma_{3} .
\end{aligned}
$$

All the coefficients of irreducible elements are nonnegative integers.

Proof. The only remaining thing to prove is that $f_{2 k+2}$ is even, $f_{2 k}$ is odd and $g_{2 j}$ is even for any $j$. Since $k$ is even, $c_{2 k+2}=0(\bmod 4)$. Thus $f_{2 k+2}=\frac{1}{2} c_{2 k+2}$ is even. Likewise $c_{2 k}=1(\bmod 4)$, thus $f_{2 k}=\frac{1}{2}\left(c_{2 k}+1\right)$ is odd. Now,

$$
g_{2 j}= \begin{cases}\frac{1}{2}\left(c_{2 j}-1\right) & \text { for } j \text { even } \\ \frac{1}{2} c_{2 j} & \text { for } j \text { odd }\end{cases}
$$

Since $c_{2 j}-1=0(\bmod 4)$ for $j$ even and $c_{2 j}=0(\bmod 4)$ for $j$ odd, we have that $g_{2 j}$ is even for any $j$.

In the same way, we get for $k$ odd,

$$
\begin{aligned}
\frac{D-A}{4} & =f_{0} \alpha_{0}+f_{1} \alpha_{2}+\cdots+f_{2 k+1} \alpha_{4 k+2}+\frac{1}{4}\left(c_{2 k+2}+1\right)\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{4} c_{2 k}\left(\beta_{3}+\gamma_{3}\right), \\
\frac{D+A}{4} & =g_{0} \alpha_{0}+g_{1} \alpha_{2}+\cdots+g_{2 k+1} \alpha_{2 k+2}+\frac{1}{4}\left(c_{2 k+2}-1\right)\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{4} c_{2 k}\left(\beta_{3}+\gamma_{3}\right), \\
\frac{B-C}{4} & =\frac{1}{2}\left(\beta_{1}-\gamma_{1}\right), \\
\frac{B+C}{4} & =0 .
\end{aligned}
$$

Since $k$ is odd, $c_{2 k+2}+1=2 f_{2 k+2}, c_{2 k+2}-1=2 g_{2 k+2}$ and $c_{2 k}=2 f_{2 k}=2 g_{2 k}$. Hence we get:

Theorem 2.8. For $k$ odd,

$$
\begin{aligned}
& \beta_{3} \gamma_{3}=f_{0} \alpha_{0}+f_{1} \alpha_{2}+\cdots+ f_{2 k+1} \alpha_{4 k+2} \\
&+\frac{1}{2}\left(f_{2 k+2}+1\right) \beta_{1}+\frac{1}{2}\left(f_{2 k+2}-1\right) \gamma_{1}+\frac{1}{2} f_{2 k}\left(\beta_{3}+\gamma_{3}\right) \\
& \gamma_{3} \beta_{3}=f_{0} \alpha_{0}+f_{1} \alpha_{2}+\cdots+ f_{2 k+1} \alpha_{4 k+2} \\
&+\frac{1}{2}\left(f_{2 k+2}-1\right) \beta_{1}+\frac{1}{2}\left(f_{2 k+2}+1\right) \gamma_{1}+\frac{1}{2} f_{2 k}\left(\beta_{3}+\gamma_{3}\right), \\
& \beta_{3}^{2}=\gamma_{3}^{2}=g_{0} \alpha_{0}+g_{1} \alpha_{2}+\cdots+g_{2 k+1} \alpha_{4 k+2}+\frac{1}{2} g_{2 k+2}\left(\beta_{1}+\gamma_{1}\right)+\frac{1}{2} g_{2 k}\left(\beta_{3}+\gamma_{3}\right) .
\end{aligned}
$$

All the coefficients of irreducible elements are nonnegative integers.
Proof. It remains to show that $f_{2 k+2}$ is odd and $f_{2 k}$ is even. In the proof of Theorem 2.7, it has been already proved that $g_{2 j}$ is even for any $j$.

Since $k$ is odd, $c_{2 k+2}=1(\bmod 4)$. Thus $f_{2 k+2}-1=\frac{1}{2}\left(c_{2 k+2}-1\right)$ is even, that is, $f_{2 k+2}$ is odd. Likewise $c_{2 k}=0(\bmod 4)$, thus $f_{2 k}=\frac{1}{2} c_{2 k}$ is even.

Thus far we determined that $\beta_{1}$ and $\gamma_{1}$ are self-conjugate and computed the full irreducible decompositions of $\beta_{3}$ and $\gamma_{3}$, in particular, $\overline{\beta_{3}}=\gamma_{3}$. This determines the rest of the fusion rule. Note that the conjugate map $\pi$ on $\mathbb{Z} V_{11}$ is now determined.

First, for $\alpha_{2 j}, j=0,1, \ldots, 2 k+1$, the right and left multiplication of $\alpha_{2 j}$ on any other object from $V_{11}$ is represented by the matrices $Q_{j}(\mathbb{D})$ and $Q_{j}(\pi \mathbb{D} \pi)$ respectively.

Claim 2.9. The entries of the matrices $R_{i}(\Delta)$ for $i=0,1, \ldots, 4 k+3$ are nonnegative integers. In particular, the entries of the matrices $Q_{j}(\mathbb{D})$ for $j=0,1, \ldots$, $2 k+1$ are nonnegative integers.

Proof. This immediate from the result in [de la Harpe and Wenzl 1987], which states that when $\Delta$ is an adjacency matrix of a graph with norm greater than 2 , the matrix $R_{i}(\Delta)$ has nonnegative integer entries for any $i$.

It remains to determine the decomposition of tensor product of $\beta_{1}$ and $\gamma_{1}$ with themselves and $\beta_{3}$ and $\gamma_{3}$.

Since by the graph $\beta_{1}=\beta_{3} \alpha_{2}$ and $\gamma_{1}=\gamma_{3} \alpha_{2}$, the fusion among $\beta_{3}$ and $\gamma_{3}$ together with the fusion of $\alpha_{2}$ with all the objects determine $\beta_{3} \beta_{1}, \gamma_{3} \gamma_{1}, \beta_{3} \gamma_{1}$, $\gamma_{3} \beta_{1}$ by imposing associativity. Taking the conjugate, we obtain $\beta_{1} \beta_{3}, \gamma_{1} \gamma_{3}, \beta_{1} \gamma_{3}$, $\gamma_{1} \beta_{3}$ as well. Thus $\beta_{1}^{2}=\beta_{1} \gamma_{3} \alpha_{2}, \gamma_{1}^{2}=\gamma_{1} \gamma_{3} \alpha_{2}, \beta_{1} \gamma_{1}=\beta_{1} \gamma_{3} \alpha_{2}, \gamma_{1} \beta_{1}=\gamma_{1} \beta_{3} \alpha_{2}$ are all determined. Since there is no division, subtraction of objects are involved in the process of determining each desired fusion rule, the coefficients are all nonnegative integers.

2B. Fusion rules on ${ }_{N} \mathscr{X}_{\boldsymbol{N}} \times_{N} \mathscr{X}_{M}$. We identify ${ }_{N} \mathscr{X}_{N}$ with $V_{11}$ and ${ }_{N} \mathscr{X}_{M}$ with $V_{12}$. Claim 2.9 implies that $\alpha_{i} Y$ for $i$ even and any $Y \in V_{12}$ are determined, and so are $X \alpha_{i}$ for $X \in V_{11}$ and $i$ odd. Thus it remains to obtain $\beta_{i} Y$ and $\gamma_{i} Y$, where $i=1,3$, $Y=\beta_{2}$ or $\gamma_{2}$. They are easily determined, since $\beta_{2}=\beta_{3} \alpha_{1}, \gamma_{2}=\gamma_{3} \alpha_{1}$, and the fusion among $\beta_{i}, \gamma_{j}, i, j=1,3$ are already determined. (Here we used associativity again.) Since the fusion coefficients among the $\beta_{i}$ and the $\gamma_{j}$ are nonnegative integers and the product of $\alpha_{1}$ from the right gives fusion with nonnegative integers, the fusion coefficients of $\beta_{i} Y$ and $\gamma_{i} Y$ are nonnegative integers as well.

2C. Fusion rules on ${ }_{N} \mathscr{X}_{M} \mathbf{x}_{M} \mathscr{X}_{N}$. Let $X \in{ }_{N} \mathscr{X}_{M}$. Then for $j$ odd,

$$
X \bar{\alpha}_{j}=R_{j}(\Delta) X
$$

Claim 2.9 implies that $R_{j}(\Delta) X$ is a linear combination of the objects in ${ }_{N} \mathscr{X}_{N}$ with nonnegative integer coefficients. It remains to show that $\beta_{2} \bar{\beta}_{2}, \beta_{2} \bar{\gamma}_{2}, \gamma_{2} \bar{\beta}_{2}$ and $\gamma_{2} \bar{\gamma}_{2}$ also have this property. It is immediate, since $\bar{\beta}_{2}=\bar{\alpha}_{1} \bar{\beta}_{3}, \bar{\gamma}_{2}=\bar{\alpha}_{1} \bar{\gamma}_{3}$, $\beta_{2} \bar{\alpha}=\beta_{1}+\beta_{3}, \gamma_{2} \bar{\alpha}=\gamma_{1}+\gamma_{3}$, and all the fusion rules involved have decompositions into simple objects with $\mathbb{Z}_{\geq 0}$-coefficients.

2D. Fusion rules on $M_{M} \mathscr{X}_{M} \times_{M} \mathscr{X}_{M}$ and $\mathscr{X}_{M} \times_{M} \mathscr{X}_{N}$. Recall that we have identification ${ }_{M} \mathscr{X}_{M}=V_{22}$ and ${ }_{M} \mathscr{X}_{N}=V_{21}$. Let $\Delta^{\prime}$ be the adjacency matrix for $\Gamma^{\prime}$. Then the fusion rules of the tensor products of the $\alpha_{j}^{\prime}$ for $j=0,2, \ldots, n-1$, as well as the $\bar{\alpha}_{k}$ for $k=1,3, \ldots, n-1$ with any objects in $V_{21} \sqcup V_{22}$ are given by the matrices $R_{l}\left(\Delta^{\prime}\right)$, where $l=0,1, \ldots, n$. Similarly to Claim 2.9, the entries of $R_{l}\left(\Delta^{\prime}\right)$ are all nonnegative integers. Furthermore, using Frobenius reciprocity, this
also takes care of the coefficients of the $\alpha_{j}^{\prime}$ and $\bar{\alpha}_{k}$ in the tensor product of two bimodules.

2E. Fusion rules on $\boldsymbol{M}_{\boldsymbol{M}} \mathscr{X}_{\boldsymbol{M}} \mathscr{\mathscr { X }}_{\boldsymbol{M}}$. The remaining issue is to determine the fusion rule among $f$ and $g$. Observing the Perron-Frobenius weights shows that $\bar{f}=f$, $\bar{g}=g$. Since for $j$ even, each $\alpha_{j}^{\prime}$ is self-conjugate as well, $f g=g f$.

Theorem 2.10. We have

$$
\begin{aligned}
& \left\langle f^{2}, f\right\rangle=d_{2 k-1}, \quad\langle f g, f\rangle=d_{2 k} \\
& \langle f g, g\rangle=d_{2 k+1}, \quad\left\langle g^{2}, g\right\rangle=d_{2 k+2}
\end{aligned}
$$

where the $d_{k}$ are defined as in the proof of Claim 2.4 by

$$
d_{j}=d_{j-1}+d_{j-2}+d_{j-3}, \quad d_{-1}=0, \quad d_{0}=d_{1}=1
$$

Lemma 2.11. We have

$$
\begin{aligned}
\left\langle f^{2}, f\right\rangle-\langle f g, g\rangle & =d_{2 k-1}-d_{2 k+1} \\
\langle f g, f\rangle-\left\langle g^{2}, g\right\rangle & =d_{2 k}-d_{2 k+2} \\
\langle f g, g\rangle-\left\langle g^{2}, g\right\rangle & =d_{2 k+1}-d_{2 k+2}
\end{aligned}
$$

Proof of Lemma 2.11. We use a similar strategy to the proof of Claim 2.4. Let $G^{\prime}$ be the adjacency matrix for $\left(V_{22}, V_{21}\right)$ corresponding to the graph $\Gamma_{k}^{\prime}$ (see Figure 1), and let

$$
\Delta^{\prime}:=\left(\begin{array}{cc}
0 & G^{\prime} \\
G^{\prime t} & 0
\end{array}\right)
$$

Observe that

$$
\begin{aligned}
& R_{0}\left(\Delta^{\prime}\right)(g-f)=(g-f) \\
& R_{1}\left(\Delta^{\prime}\right)(g-f)=\bar{\gamma}_{2}+\bar{\beta}_{2} \\
& R_{2}\left(\Delta^{\prime}\right)(g-f)=g+f \\
& R_{3}\left(\Delta^{\prime}\right)(g-f)=2 \alpha_{n}^{\prime} \\
& R_{4}\left(\Delta^{\prime}\right)(g-f)=2 \alpha_{n-1}^{\prime}+f+g
\end{aligned}
$$

where $\alpha_{j}^{\prime}=\bar{\alpha}_{j}$ for $j$ odd. Then we have

$$
S_{j}\left(\Delta^{\prime}\right)(g-f)=2 \alpha_{n-j+3}^{\prime}
$$

for $j=3,4, \ldots, n+3$, where the polynomial $S_{j}$ is defined in the proof of Claim 2.4. On the other hand,

$$
g+f=R_{n+1}\left(\mathbb{D}^{\prime}\right) \alpha_{0}^{\prime}=R_{4 k+4}\left(\mathbb{D}^{\prime}\right) \alpha_{0}^{\prime}=Q_{2 k+2}\left(\bar{\alpha}_{1} \alpha_{1}\right)
$$

Using Lemma 2.5,

$$
\begin{aligned}
(g & +f)(g-f) \\
& =\left(d_{0} S_{2(2 k+2)}+d_{1} S_{2(2 k+1)}+\cdots+d_{2 k} S_{4}+d_{2 k+1} R_{2}+d_{2 k-1} R_{0}\right)\left(\Delta^{\prime}\right)(g-f) \\
& =\left(\text { linear combination of the } \alpha_{*}^{\prime}\right)+d_{2 k+1}(g+f)+d_{2 k-1}(g-f) \\
& =\left(\text { linear combination of the } \alpha_{*}^{\prime}\right)+\left(d_{2 k+1}+d_{2 k-1}\right) g+\left(d_{2 k+1}-d_{2 k-1}\right) f .
\end{aligned}
$$

Therefore we have

$$
\begin{align*}
& \langle(g-f)(g+f), g\rangle=\left\langle g^{2}, g\right\rangle-\left\langle f^{2}, g\right\rangle=d_{2 k+1}+d_{2 k-1}=d_{2 k+2}-d_{2 k}  \tag{b1}\\
& \langle(g-f)(g+f), f\rangle=\left\langle g^{2}, f\right\rangle-\left\langle f^{2}, f\right\rangle=d_{2 k+1}-d_{2 k-1}
\end{align*}
$$

We obtain further information by investigating $R_{2}\left(\Delta^{\prime}\right)(g+f)(g-f)$. Note that $R_{2}\left(\Delta^{\prime}\right)(g+f)=2 \alpha_{n-1}^{\prime}+f+3 g$. Therefore

$$
\begin{align*}
& R_{2}\left(\Delta^{\prime}\right)(g+f)(g-f) \\
& \quad=\left(2 \alpha_{n-1}^{\prime}+f+3 g\right)(g-f) \\
& \quad=2 \alpha_{n-1}^{\prime}(g-f)+3 g^{2}-f^{2}-2 f g \\
& \quad=\left(\alpha_{*}^{\prime} \mathrm{s}\right)+2\left(d_{2 k}(g+f)+d_{2 k-2}(g-f)\right)+3 g^{2}-f^{2}-2 f g \\
& \quad=\left(\alpha_{*}^{\prime} \mathrm{s}\right)+2\left(d_{2 k}+d_{2 k-2}\right) g+2\left(d_{2 k}-d_{2 k-2}\right) f+3 g^{2}-f^{2}-2 f g .
\end{align*}
$$

On the other hand,

$$
\begin{align*}
& R_{2}\left(\Delta^{\prime}\right)(g+f)(g-f) \\
&= R_{2}\left(\Delta^{\prime}\right)\left(2\left(d_{0} \alpha_{2}^{\prime}+d_{1} \alpha_{4}^{\prime}+\cdots+d_{2 k} \alpha_{4 k+2}^{\prime}\right)\right) \\
&+\left(d_{2 k+1}+d_{2 k-1}\right) R_{2}\left(\Delta^{\prime}\right) g \\
&+\left(d_{2 k+1}-d_{2 k-1}\right) R_{2}\left(\Delta^{\prime}\right) f \\
&=\left(\alpha_{*}^{\prime} \prime s\right)+2 d_{2 k}(f+g)+\left(d_{2 k+1}+d_{2 k-1}\right)\left(\alpha_{n-1}^{\prime}+f+2 g\right) \\
&+\left(d_{2 k+1}-d_{2 k-1}\right)\left(\alpha_{n-1}^{\prime}+g\right) \\
&=\left(\alpha_{*}^{\prime} s\right)+\left(2 d_{2 k}+d_{2 k+1}+d_{2 k-1}\right) f+\left(2 d_{2 k}\right.\left.+3 d_{2 k+1}+d_{2 k-1}\right) g
\end{align*}
$$

Comparing ( $\sharp 1$ ) and ( $\sharp 2$ ) we obtain

$$
\begin{align*}
3\left\langle g^{2}, g\right\rangle-\left\langle f^{2}, g\right\rangle-2\langle f g, g\rangle & =3 d_{2 k+1}+d_{2 k-1}-2 d_{2 k-2}  \tag{b2}\\
3\left\langle g^{2}, f\right\rangle-\left\langle f^{2}, f\right\rangle-2\langle f g, f\rangle & =d_{2 k+1}+d_{2 k-1}+2 d_{2 k-2}
\end{align*}
$$

Combining Equations (b1) and (b2), we obtain the statement of the lemma. Note that we use Frobenius reciprocity such as $\langle f g, f\rangle=\left\langle f^{2}, g\right\rangle$, etc.

The next lemma, together with Lemma 2.11, implies Theorem 2.10.
Lemma 2.12. $\left\langle g^{2}, g\right\rangle=d_{2 k+2}$.

Proof. Since $g=\bar{\beta}_{2} \alpha_{1}=\bar{\gamma}_{2} \alpha_{1}$,

$$
2 g=\left(\bar{\beta}_{2}+\bar{\gamma}_{2}\right) \alpha_{1}=\overline{\left(\beta_{3}+\gamma_{3}\right) \alpha_{1}} \alpha_{1}=\bar{\alpha}_{1}\left(\beta_{3}+\gamma_{3}\right) \alpha_{1}
$$

Also, $\bar{\gamma}_{2}=\bar{\gamma}_{3} \alpha_{1}=\bar{\alpha}_{1} \beta_{3}$. Therefore

$$
\begin{aligned}
4\left\langle g^{2}, g\right\rangle & =\left\langle\bar{\alpha}_{1}\left(\beta_{3}+\gamma_{3}\right) \alpha_{1} \bar{\alpha}_{1}\left(\beta_{3}+\gamma_{3}\right) \alpha_{1}, \bar{\alpha}_{1} \beta_{3} \alpha_{1}\right\rangle \\
& =\left\langle\alpha_{1} \bar{\alpha}_{1}\left(\beta_{3}+\gamma_{3}\right) \alpha_{1} \bar{\alpha}_{1}\left(\beta_{3}+\gamma_{3}\right) \alpha_{1} \bar{\alpha}_{1}, \beta_{3}\right\rangle \\
& =\left\langle\left(\beta_{3}+\gamma_{3}\right)^{2}\left(\alpha_{1} \bar{\alpha}_{1}\right)^{3}, \beta_{3}\right\rangle=\left\langle\left(\beta_{3}+\gamma_{3}\right)^{2}, \beta_{3}\left(\alpha_{1} \bar{\alpha}_{1}\right)^{3}\right\rangle
\end{aligned}
$$

where we used

$$
\begin{aligned}
\alpha_{1} \bar{\alpha}_{1}\left(\beta_{3}+\gamma_{3}\right) & =\beta_{1}+\beta_{3}+\gamma_{1}+\gamma_{3} \\
& =\overline{\beta_{1}+\beta_{3}+\gamma_{1}+\gamma_{3}}=\overline{\left(\beta_{3}+\gamma_{3}\right)} \alpha_{1} \bar{\alpha}_{1}=\left(\beta_{3}+\gamma_{3}\right) \alpha_{1} \bar{\alpha}_{1}
\end{aligned}
$$

A computation using the graph $\Gamma_{k}$ gives

$$
\beta_{3}\left(\alpha_{1} \bar{\alpha}_{1}\right)^{3}=5 \beta_{3}+10 \beta_{1}+6 \alpha_{n-1}+6 \gamma_{1}+\alpha_{n-3}+\gamma_{3}
$$

Using the formula for $\left(\beta_{3}+\gamma_{3}\right)^{2}$ given in Claim 2.4, we obtain

$$
\begin{aligned}
\left\langle\left(\beta_{3}+\gamma_{3}\right)^{2}, \beta_{3}\left(\alpha_{1} \bar{\alpha}_{1}\right)^{3}\right\rangle & =8 c_{2 k}+12 c_{2 k+1}+16 c_{2 k+2}=4 c_{2 k+1}+8 c_{2 k+2}+8 c_{2 k+3} \\
& =4 c_{2 k+2}+4 c_{2 k+3}+4 c_{2 k+4}=4 c_{2 k+5}=4 d_{2 k+2}
\end{aligned}
$$

Therefore $\left\langle g^{2}, g\right\rangle=d_{2 k+2}$.
2F. Fusion rules on $M_{M} \mathscr{X}_{M} \mathbf{x}_{M} \mathscr{X}_{\boldsymbol{N}}$. The remaining problem is to determine the fusion rule on $\{f, g\} \times\left\{\bar{\beta}_{2}, \bar{\gamma}_{2}\right\}$ :

$$
\begin{aligned}
\left\langle f \bar{\beta}_{2}, \bar{\beta}_{2}\right\rangle=\left\langle f, \bar{\beta}_{2} \beta_{2}\right\rangle=\left\langle f, \bar{\alpha}_{1} \beta_{3}^{2} \alpha_{1}\right\rangle & =\left\langle\alpha_{1} f \bar{\alpha}_{1}, \beta_{3}^{2}\right\rangle=\left\langle\alpha_{n} \bar{\alpha}_{1}, \beta_{3}^{2}\right\rangle \\
& =\left\langle\beta_{3}^{2}, \beta_{1}\right\rangle+\left\langle\beta_{3}^{2}, \gamma_{1}\right\rangle+\left\langle\beta_{3}^{2}, \alpha_{n-1}\right\rangle
\end{aligned}
$$

Theorems 2.7 and 2.8 imply that

$$
\left\langle f \bar{\beta}_{2}, \bar{\beta}_{2}\right\rangle=g_{2 k+2}+g_{2 k+1}
$$

Both values are nonnegative integers. Similarly we obtain

$$
\begin{aligned}
\left\langle f \bar{\beta}_{2}, \bar{\gamma}_{2}\right\rangle & =\left\langle f \bar{\gamma}_{2}, \bar{\beta}_{2}\right\rangle=f_{2 k+2}+f_{2 k+1} \\
\left\langle f \bar{\gamma}_{2}, \bar{\gamma}_{2}\right\rangle & =g_{2 k+2}+g_{2 k+1} \\
\left\langle g \bar{\beta}_{2}, \bar{\beta}_{2}\right\rangle & =\left\langle\bar{\beta}_{2} \alpha_{1} \bar{\beta}_{2}, \bar{\beta}_{2}\right\rangle=\left\langle\bar{\alpha}_{1} \bar{\beta}_{3} \alpha_{1} \bar{\alpha}_{1} \bar{\beta}_{3}, \bar{\alpha}_{1} \bar{\beta}_{3}\right\rangle=\left\langle\alpha_{1} \bar{\alpha}_{1} \gamma_{3} \alpha_{1} \bar{\alpha}_{1}, \gamma_{3} \beta_{3}\right\rangle \\
& =\left\langle\overline{\overline{\left(\gamma_{1}+\gamma_{3}\right)} \alpha_{1} \bar{\alpha}_{1}}, \gamma_{3} \beta_{3}\right\rangle \\
\overline{\left(\gamma_{1}+\gamma_{3}\right)} \alpha_{1} \bar{\alpha}_{1} & =\left(\gamma_{1}+\beta_{3}\right) \alpha_{1} \bar{\alpha}_{1}=\left(\alpha_{n-1}+\beta_{1}+2 \gamma_{1}+\gamma_{3}\right)+\beta_{1}+\beta_{3} \\
& =\alpha_{n-1}+2\left(\beta_{1}+\gamma_{1}\right)+\gamma_{3}+\beta_{3}=\overline{\alpha_{n-1}+2\left(\beta_{1}+\gamma_{1}\right)+\gamma_{3}+\beta_{3}}
\end{aligned}
$$

Thus, using Theorems 2.7 and 2.8 we obtain

$$
\left\langle g \bar{\beta}_{2}, \bar{\beta}_{2}\right\rangle= \begin{cases}f_{2 k+1}+2 f_{2 k+2}+f_{2 k}-1 & \text { for } k \text { even } \\ f_{2 k+1}+2 f_{2 k+2}+f_{2 k} & \text { for } k \text { odd }\end{cases}
$$

Similarly,

$$
\begin{aligned}
\left\langle g \bar{\beta}_{2}, \bar{\gamma}_{2}\right\rangle & =\left\langle g \bar{\gamma}_{2}, \bar{\beta}_{2}\right\rangle \\
& =\left\{\begin{array}{ll}
g_{2 k+1}+2 g_{2 k+2}+g_{2 k}+2 & \text { for } k \text { even, } \\
g_{2 k+1}+2 g_{2 k+2}+g_{2 k} & \text { for } k \text { odd, }
\end{array}\left\langle g \bar{\gamma}_{2}, \bar{\gamma}_{2}\right\rangle=\left\langle g \bar{\beta}_{2}, \bar{\beta}_{2}\right\rangle .\right.
\end{aligned}
$$

## 3. Existence of the fusion algebra

Let $k \in \mathbb{N}_{0}$, and put $n=4 k+3$ as before. In this section we will reserve the symbols

$$
\left(\alpha_{j}\right)_{0 \leq k \leq n}, \quad\left(\beta_{j}\right)_{1 \leq j \leq 3}, \quad\left(\gamma_{j}\right)_{1 \leq j \leq 3}
$$

for elements in a certain bigraded $\mathbb{Z}$-algebra $\mathscr{A}$ which we define later. Therefore we relabel the vertices of the graph $\Gamma_{k}$ as in Figure 2.

As in Section 2A, let $G$ be the adjacency matrix for $\left(\Gamma_{k}^{\text {even }}, \Gamma_{k}^{\text {odd }}\right.$ ), where

$$
\begin{aligned}
\Gamma_{k}^{\text {even }} & =\left\{a_{0}, a_{2}, \ldots, a_{n-1}, b_{1}, c_{1}, b_{3}, c_{3}\right\}, \\
\Gamma_{k}^{\text {odd }} & =\left\{a_{1}, a_{3}, \ldots, a_{n}, b_{2}, c_{2}\right\} .
\end{aligned}
$$

Set $\mathbb{D}=G G^{t}$ and

$$
\Delta:=\left(\begin{array}{cc}
0 & G \\
G^{t} & 0
\end{array}\right)
$$

Let $\left(q_{k}\right)_{k=0}^{\infty}$ be the sequence of polynomials defined by

$$
\begin{aligned}
& q_{0}(t)=t^{2}-5 t+3 \\
& q_{1}(t)=(t-1)\left(t^{3}-8 t^{2}+17 t-5\right) \\
& q_{k}(t)=\left(t^{2}-4 t+2\right) q_{k-1}(t)-q_{k-2}(t), \quad k \geq 2
\end{aligned}
$$



Figure 2
as in Section 2A. Then the characteristic polynomial for $\mathbb{D}$ is

$$
\chi_{k}(t)=t^{2}(t-2)^{2} q_{k}(t)
$$

(see Section 2A). Moreover $q_{k}(t)$ is a polynomial of degree $2 k+2$ with $2 k+2$ distinct roots, because by [Asaeda and Yasuda 2009], either $q_{k}(t)$ or $q_{k}(t) /(t-1)$ is an irreducible polynomial. The recursion formula for the $q_{k}$-polynomials implies

$$
\begin{aligned}
& q_{k}(0)=2 k+3 \\
& q_{k}(2)=(-1)^{k+1}(2 k+3)
\end{aligned}
$$

In particular, 0 and 2 are not roots of $q_{k}$. Let $k \in \mathbb{N}_{0}$ be fixed. Then $\chi_{k}(t)$ has exactly $2 k+4$ distinct roots $\left(t_{j}\right)_{k=1}^{2 k+4}$, where $t_{1}=0, t_{2}=2$ and $t_{3}, \ldots, t_{2 k+4}$ are the roots of $q_{k}(t)$. Since $\mathbb{D}=G G^{t}$ is a positive operator, $t_{j} \geq=0$ for $1 \leq j \leq 2 k+4$.
Lemma 3.1. Let $E_{j}$ be the orthogonal projection on the eigenspace of $\mathbb{D}$ corresponding to the eigenvalue $t_{j}, 1 \leq j \leq 2 k+4$, and put

$$
\mu_{j}=\left\langle E_{j} a_{0}, a_{0}\right\rangle
$$

where $\langle\cdot, \cdot\rangle$ is the inner product in $l^{2}\left(\Gamma_{k}^{\mathrm{even}}\right)$. Then
(a) $\sum_{j=1}^{2 k+4} \mu_{j}=1$,
(b) $\mu_{j}>0$ for $1 \leq j \leq 2 k+4$,
(c) $\mu_{1}=\mu_{2}=1 /(2 k+3)$.

Proof. (a) Since $\mathbb{D}$ is a symmetric matrix, $\sum_{j=1}^{2 k+4} E_{j}=I$, thus $\sum_{j=1}^{2 k+4} \mu_{j}=1$.
(b) From Section 2A, we have

$$
\begin{aligned}
Q_{j}(\mathbb{D}) a_{0} & =R_{2 j}(\Delta) a_{0}=a_{2 j}, \quad 0 \leq j \leq 2 k+1, \\
Q_{2 k+2}(\mathbb{D}) a_{0} & =R_{4 k+4}(\Delta) a_{0}=b_{1}+c_{1}, \\
Q_{2 k+3}(\mathbb{D}) a_{0} & =R_{4 k+6}(\Delta) a_{0}=b_{1}+c_{1}+b_{3}+c_{3} .
\end{aligned}
$$

Since $\left\{a_{0}, a_{2}, \ldots, a_{4 k+2}, b_{1}+c_{1}, b_{1}+c_{1}+b_{3}+c_{3}\right\}$ is a set of $2 k+4$ linearly independent vectors in $l^{2}\left(\Gamma_{k}^{\text {even }}\right)$, and since $\left(Q_{j}\right)_{0 \leq j \leq 2 k+3}$ spans the set of polynomials of degree less or equal to $2 k+3$, we have

$$
P(\mathbb{D}) a_{0} \neq 0
$$

for every nonzero polynomial $P \in \mathbb{R}[x]$ with $\operatorname{deg}(P) \leq 2 k+3$. On the other hand, $\mathbb{D}$ is diagonalizable with eigenvalues $\left(t_{j}\right)_{j=1}^{2 k+4}$, so

$$
E_{j}=P_{j}(\mathbb{D})
$$

where

$$
P_{j}(t)=\prod_{i \neq j} \frac{t-t_{i}}{t_{j}-t_{i}}, \quad t \in \mathbb{R},
$$

is a polynomial of degree $2 k+3$. Hence

$$
\mu_{j}=\left\langle E_{k} a_{0}, a_{0}\right\rangle=\left\|E_{j} a_{0}\right\|^{2}>0, \quad 1 \leq j \leq 2 k+4
$$

(c) From Section 2A, we have

$$
\begin{aligned}
& \operatorname{rg}\left(E_{1}\right)=E(\mathbb{D}, 0)=\operatorname{span}\left\{y_{1}, y_{2}\right\}, \\
& \operatorname{rg}\left(E_{2}\right)=E(\mathbb{D}, 2)=\operatorname{span}\left\{x_{1}, x_{2}\right\},
\end{aligned}
$$

where

$$
\begin{aligned}
& x_{1}:=2\left(a_{0}+a_{2}\right)-2\left(a_{4}+a_{6}\right)+\cdots+(-1)^{k} 2\left(a_{4 k}+a_{4 k+2}\right), \\
&+(-1)^{k+1}\left(b_{1}+c_{1}+b_{3}+c_{3}\right), \\
& x_{2}:=\left(b_{1}-c_{1}\right)+\left(b_{3}-c_{3}\right), \\
& y_{1}:=2 a_{0}-2 a_{2}+\cdots+2 a_{4 k}-2 a_{4 k+2}+\left(b_{1}+c_{1}\right)-\left(b_{3}+c_{3}\right), \\
& y_{2}:=\left(b_{1}-c_{1}\right)-\left(b_{3}-c_{3}\right) .
\end{aligned}
$$

Since $y_{1} \perp y_{2}$ and $y_{2} \perp a_{0}$, we get

$$
\mu_{1}=\left\langle E_{1} a_{0}, a_{0}\right\rangle=\frac{\left|\left\langle y_{1}, a_{0}\right\rangle\right|^{2}}{\left\|y_{1}\right\|^{2}}=\frac{1}{2 k+3}
$$

and similarly,

$$
\mu_{2}=\left\langle E_{2} a_{0}, a_{0}\right\rangle=\frac{\left|\left\langle x_{1}, a_{0}\right\rangle\right|^{2}}{\left\|x_{1}\right\|^{2}}=\frac{1}{2 k+3}
$$

Corollary 3.2. Let $\left(e_{i j}\right)_{i, j=1}^{2 k+4}$ be the matrix units of $M_{2 k+4}(\mathbb{R})$. Put

$$
\begin{aligned}
\mathscr{B} & =\operatorname{span}_{\mathbb{R}}\left\{e_{11}, e_{12}, e_{21}, e_{22}, e_{33}, e_{44}, \ldots, e_{2 k+4,2 k+4}\right\} \\
& \cong M_{2}(\mathbb{R}) \oplus l^{\infty}(\{3,4, \ldots, 2 k+4\}, \mathbb{R})
\end{aligned}
$$

Then $\mathscr{B}$ is a finite dimensional real $C^{*}$-algebra and the map $\mu: \mathscr{B} \rightarrow \mathbb{R}$ given by

$$
\mu(b):=\sum_{j=1}^{2 k+4} \mu_{j} b_{j j}, \quad b=\left(b_{i j}\right)_{i, j=1}^{2 k+4} \in \mathscr{B},
$$

is a faithful trace state on $\mathscr{B}$.
Proof. It is clear from Lemma 3.1(a), (b) that $\mu$ is a faithful state on $\mathscr{B}$. The trace property

$$
\mu(b c)=\mu(c b), \quad b, c \in \mathscr{B},
$$

follows from Lemma 3.1(c).
Lemma 3.3. Fix $k \in \mathbb{N}_{0}$, let $\mu: \mathscr{B} \rightarrow \mathbb{R}$ be the trace in Corollary 3.2, and put

$$
\left.A:=\operatorname{diag}\left(0, \sqrt{2}, \sqrt{t_{3}}, \ldots \sqrt{t_{2 k+4}}\right)\right)
$$

where $t_{3}, \ldots, t_{2 k+4}$ are the roots of $q_{k}$.
(a) For every even polynomial $P \in \mathbb{R}[x]$,

$$
\mu(P(A))=\left\langle P(\Delta) a_{0}, a_{0}\right\rangle
$$

(b) Let $P, Q \in \mathbb{R}[x]$ be two polynomials, which are either both even or both odd. Then

$$
\mu(P(A) Q(A))=\left\langle P(\Delta) a_{0}, Q(\Delta) a_{0}\right\rangle
$$

(c) Let $n=4 k+3$ (as usual). Then

$$
R_{n+4}(A)-R_{n+2}(A)-R_{n}(A)-R_{n-2}(A)=0
$$

Proof. (a) Choose $Q \in \mathbb{R}[x]$ so that $P(t)=Q\left(t^{2}\right)$. Then

$$
\left\langle P(\Delta) a_{0}, a_{0}\right\rangle=\left\langle Q(\mathbb{D}) a_{0}, a_{0}\right\rangle
$$

Let $E_{j}$ denote the spectral projection of $\mathbb{D}$ corresponding to the eigenvalue $t_{j}$, $1 \leq j \leq 2 k+4$, as before, where $t_{1}=0$ and $t_{2}=2$. Then

$$
Q(\mathbb{D})=\sum_{j=1}^{2 k+4} Q\left(t_{j}\right) E_{j} .
$$

Hence

$$
\left\langle Q(\mathbb{D}) a_{0}, a_{0}\right\rangle=\sum_{j=1}^{2 k+4} Q\left(t_{j}\right)\left\langle E_{j} a_{0}, a_{0}\right\rangle=\sum_{j=1}^{2 k+4} \mu_{j} Q\left(t_{j}\right)=\mu\left(Q\left(A^{2}\right)\right)=\mu(P(A))
$$

(b) Under the assumption on $P$ and $Q$, the product $P Q$ is an even polynomial. Hence by (a) we have

$$
\begin{aligned}
\mu(P(A) Q(A)) & =\left\langle P(\Delta) Q(\Delta) a_{0}, a_{0}\right\rangle \\
& =\left\langle P(\Delta) a_{0}, Q(\Delta) a_{0}\right\rangle
\end{aligned}
$$

(c) Put $P=Q=R_{n+4}-R_{n+2}-R_{n}-R_{n-2}$, which is an odd polynomial. By (b),

$$
\mu\left(P(A)^{2}\right)=\left\|P(\Delta) a_{0}\right\|_{2}^{2}
$$

From the recursive formula for the polynomials $R_{j}$,

$$
\begin{aligned}
R_{n-2}(\Delta) a_{0} & =a_{n-2} \\
R_{n}(\Delta) a_{0} & =a_{n} \\
R_{n+2}(\Delta) a_{0} & =a_{n}+b_{2}+c_{2} \\
R_{n+4}(\Delta) a_{0} & =a_{n-2}+2 a_{n}+b_{2}+c_{2} \\
& =\left(R_{n+2}(A)+R_{n}(A)+R_{n-2}(A)\right) a_{0} .
\end{aligned}
$$

Hence $\mu\left(P(A)^{2}\right)=\left\|P(\Delta) a_{0}\right\|_{2}^{2}=0$, and since $\mu$ is a faithful trace on $\mathscr{B}$, we have $P(A)=0$.

Remark 3.4. Since $P=R_{n+4}-R_{n+2}-R_{n}-R_{n-2}$ is an odd polynomial and $P(A)=0$, we know that $P(t)$ has at least $n+4=4 k+7$ roots

$$
0, \pm \sqrt{2}, \pm \sqrt{t_{3}}, \ldots, \sqrt{t_{2 k+4}}
$$

which are exactly the distinct roots of $t\left(t^{2}-2\right) q_{k}\left(t^{2}\right)$. Since $P$ and $t\left(t^{2}-2\right) q_{k}\left(t^{2}\right)$ are both monic polynomial of degree $4 k+7$, it follows that

$$
\left(R_{n+4}-R_{n+2}-R_{n}-R_{n-2}\right)(t)=t\left(t^{2}-2\right) q_{k}\left(t^{2}\right)
$$

It is not hard to prove this identity directly by using the recursion formulas for the polynomials $\left\{q_{k}\right\}$ and $\left\{R_{j}\right\}$.

Definition 3.5. Let $k \in \mathbb{N}_{0}, n=4 k+3$, and let $\mathscr{B}$ and $\mu$ be as in Corollary 3.2 and $A=\operatorname{diag}\left(\sqrt{t_{1}}, \sqrt{t_{2}}, \ldots, \sqrt{t_{2 k+4}}\right) \in \mathscr{B}$ be as in Lemma 3.3. Let $\left(f_{i j}\right)_{i, j=1}^{2}$ be the matrix units in $M_{2}(\mathbb{R})$, and put

$$
V:=V_{11} \sqcup V_{12} \sqcup V_{21} \sqcup V_{22},
$$

where $V_{i j} \subset \mathscr{B} \otimes f_{i j}, i, j=1,2$, are as follows:
(a) $V_{11}=\left\{\alpha_{0}, \alpha_{2}, \alpha_{4}, \ldots, \alpha_{4 k+2}, \beta_{1}, \gamma_{1}, \beta_{3}, \gamma_{3}\right\}$, where

$$
\begin{aligned}
\alpha_{2 j} & =R_{2 j}(A) \otimes f_{11}, \quad 0 \leq j \leq 2 k+1 \\
\beta_{1} & =\frac{1}{2}\left(R_{n+1}(A)+\sqrt{2 k+3}\left(e_{12}+e_{21}\right)\right) \otimes f_{11}, \\
\gamma_{1} & =\frac{1}{2}\left(R_{n+1}(A)-\sqrt{2 k+3}\left(e_{12}+e_{21}\right)\right) \otimes f_{11}, \\
\beta_{3} & =\frac{1}{2}\left(\left(R_{n+3}-R_{n+1}-R_{n-1}\right)(A)+\sqrt{2 k+3}\left(e_{12}-e_{21}\right)\right) \otimes f_{11}, \\
\gamma_{3} & =\frac{1}{2}\left(\left(R_{n+3}-R_{n+1}-R_{n-1}\right)(A)-\sqrt{2 k+3}\left(e_{12}-e_{21}\right)\right) \otimes f_{11} .
\end{aligned}
$$

(b) $V_{12}=\left\{\alpha_{1}, \alpha_{3}, \alpha_{5}, \ldots, \alpha_{4 k+3}, \beta_{2}, \gamma_{2}\right\}$, where

$$
\begin{aligned}
\alpha_{2 j+1} & =R_{2 j+1}(A) \otimes f_{12}, \quad 0 \leq j \leq 2 k+1 \\
\beta_{2} & =\frac{1}{2}\left(\left(R_{n+2}-R_{n}\right)(A)+\sqrt{2(2 k+3)} e_{12}\right) \otimes f_{12} \\
\gamma_{2} & =\frac{1}{2}\left(\left(R_{n+2}-R_{n}\right)(A)-\sqrt{2(2 k+3)} e_{12}\right) \otimes f_{12}
\end{aligned}
$$

(c) $V_{21}=\left\{\bar{\alpha}_{1}, \bar{\alpha}_{3}, \bar{\alpha}_{5}, \ldots, \bar{\alpha}_{4 k+3}, \bar{\beta}_{2}, \bar{\gamma}_{2}\right\}$, where

$$
\begin{aligned}
\bar{\alpha}_{2 j+1} & =R_{2 j+1}(A) \otimes f_{21}, \quad 0 \leq j \leq 2 k+1, \\
\bar{\beta}_{2} & =\frac{1}{2}\left(\left(R_{n+2}-R_{n}\right)(A)+\sqrt{2(2 k+3)} e_{21}\right) \otimes f_{21}, \\
\bar{\gamma}_{2} & =\frac{1}{2}\left(\left(R_{n+2}-R_{n}\right)(A)-\sqrt{2(2 k+3)} e_{21}\right) \otimes f_{21} .
\end{aligned}
$$

(d) $V_{22}=\left\{\alpha_{0}^{\prime}, \alpha_{2}^{\prime}, \ldots, \alpha_{4 k+2}^{\prime}, f, g\right\}$, where

$$
\begin{aligned}
\alpha_{j}^{\prime} & =R_{2 j}(A) \otimes f_{22}, \quad 0 \leq j \leq 2 k+1, \\
f & =\frac{1}{2}\left(R_{n-1}+2 R_{n+1}-R_{n+3}\right)(A) \otimes f_{22}, \\
g & =\frac{1}{2}\left(R_{n+3}-R_{n-1}\right)(A) \otimes f_{22} .
\end{aligned}
$$

(e) The conjugation map $V_{12} \rightarrow V_{21}$ and $V_{21} \rightarrow V_{12}$ is already defined earlier. For $V_{11}$ and $V_{22}$, all the elements are defined to be self-conjugate except $\beta_{3}$ and $\gamma_{3}$ which are defined to be conjugate of each other. Note that for every $X \in V_{i j}$, the conjugate $\bar{X}$ is equal to $X^{*}$ (or $X^{t}$, since all the matrices here are real).
(f) Equip $\mathbb{R} V_{i j} \subset \mathscr{B} \otimes f_{i j}$ with inner products given by

$$
\left\langle b \otimes f_{i j}, c \otimes f_{i j}\right\rangle_{\mu}:=\mu\left(c^{t} b\right)=\mu\left(b c^{t}\right)
$$

for every $b, c \in \mathbb{R} V_{i j}, i, j=1,2$.
Lemma 3.6. Let $i, j \in\{1,2\}$. For $X, Y \in V_{i j}$,

$$
\langle X, Y\rangle_{\mu}= \begin{cases}1 & \text { if } X=Y \\ 0 & \text { if } X \neq Y\end{cases}
$$

Proof. Let $(b, c)_{\mu}:=\mu\left(c^{t} b\right)=\mu\left(b c^{t}\right), b, c \in \mathscr{B}$, be the inner product on $\mathscr{B}$ given by $\mu$, and put $\|b\|_{\mu}(b, b)_{\mu}^{1 / 2}, b \in \mathscr{B}$.
(a) Case $(i, j)=(1,1)$. It suffices to show that
$S_{1}:=\left\{R_{0}(A), R_{2}(A), \ldots, R_{n+1}(A),\left(R_{n+3}-R_{n+1}-R_{n-1}\right)(A), e_{12}+e_{21}, e_{12}-e_{21}\right\}$
is an orthogonal set in $\mathscr{B}$ and that

$$
\begin{aligned}
\left\|R_{2 j}(A)\right\|_{\mu}^{2} & =1, \quad 0 \leq j \leq \frac{n-1}{2}, \\
\left\|R_{n+1}(A)\right\|_{\mu}^{2} & =2, \\
\left\|\left(R_{n+3}-R_{n+1}-R_{n-1}\right)(A)\right\|_{\mu}^{2} & =2, \\
\left\|e_{12}+e_{21}\right\|_{\mu}^{2} & =\left\|e_{12}-e_{21}\right\|_{\mu}^{2}=\frac{2}{2 k+3} .
\end{aligned}
$$

By the definition of $\mu$ in Corollary 3.2, it is clear that $e_{12}+e_{21}$ and $e_{12}-e_{21}$ are $\mu$-orthogonal to the remaining matrices in $S_{1}$, because $R_{j}(A)$ is a diagonal matrix for all $j \in \mathbb{N}_{0}$. Moreover, by Lemma 3.1,

$$
\begin{aligned}
\left\langle e_{12}+e_{21}, e_{12}-e_{21}\right\rangle_{\mu} & =\mu\left(e_{11}-e_{22}\right)
\end{aligned}=\mu_{1}-\mu_{2}=0, ~=e_{12}=e_{\mu}=\frac{2}{2 k+3} .
$$

By Lemma 3.3(b), the remaining part of the proof in the $V_{11}$ case reduces to showing that

$$
T_{1}:=\left\{R_{0}(\Delta) a_{0}, R_{2}(\Delta) a_{0}, \ldots, R_{n+1}(\Delta) a_{0},\left(R_{n+3}(\Delta)-R_{n+1}(\Delta)-R_{n-1}(\Delta)\right) a_{0}\right\}
$$

is an orthogonal set in $l^{2}\left(\Gamma_{k}\right)$ with

$$
\begin{aligned}
\left\|R_{2 j}(\Delta) a_{0}\right\|^{2} & =1, \quad 0 \leq j \leq n-1, \\
\left\|R_{n+1}(\Delta) a_{0}\right\|^{2} & =2 \\
\left\|\left(R_{n+3}-R_{n+1}-R_{n-1}\right)(\Delta) a_{0}\right\|^{2} & =2 .
\end{aligned}
$$

This follows from the fact that

$$
T_{1}=\left\{a_{0}, a_{2}, \ldots, a_{n-1}, b_{1}+c_{1}, b_{3}+c_{3}\right\}
$$

(b) Cases $(i, j)=(1,2)$ and $(i, j)=(2,1)$. It suffices to show that

$$
S_{2}:=\left\{R_{1}(A), R_{3}(A), \ldots R_{n}(A),\left(R_{n+2}-R_{n}\right)(A), e_{12}\right\}
$$

is an orthonormal set in $\mathscr{P}$ and that

$$
\begin{aligned}
\left\|R_{2 j+1}(A)\right\|_{\mu}^{2} & =1, \quad 0 \leq j \leq \frac{n-1}{2} \\
\left\|\left(R_{n+2}-R_{n}\right)(A)\right\|_{\mu}^{2} & =2 \\
\left\|e_{12}\right\|_{\mu}^{2} & =\frac{1}{2 k+3}
\end{aligned}
$$

It is easy to check that $e_{12}$ is orthogonal to the remaining elements of $S_{2}$ and that $\left\|e_{12}\right\|_{\mu}^{2}=(2 k+3)^{-1}$ by Lemma 3.3(b). The remaining statement about the set $S_{2}$ follow from the fact that

$$
\begin{aligned}
T_{2} & =\left\{R_{1}(\Delta) a_{0}, R_{3}(\Delta) a_{0}, \ldots, R_{n}(\Delta) a_{0},\left(R_{n+2}-R_{n}\right)(\Delta) a_{0}\right\} \\
& =\left\{a_{1}, a_{3}, \ldots, a_{n}, b_{2}+c_{2}\right\}
\end{aligned}
$$

is an orthonormal set in $l^{2}\left(\Gamma_{k}\right)$, and from the equalities

$$
\left\|b_{2}+c_{2}\right\|^{2}=2, \quad\left\|a_{2 j+1}\right\|^{2}=1 \quad \text { for } 0 \leq j \leq \frac{n-1}{2}
$$

(c) Case $(i, j)=(2,2)$. The statement follows in this case if we can show that
$S_{3}:=\left\{R_{0}(A), R_{2}(A), \ldots, R_{n-1}(A)\right.$,

$$
\left.\frac{1}{2}\left(R_{n-1}+2 R_{n+1}-R_{n+3}\right)(A), \frac{1}{2}\left(R_{n+3}-R_{n-1}\right)(A)\right\}
$$

is a $\mu$-orthogonal set in $\mathscr{B}$. By Lemma 3.3(b) this reduces to showing that

$$
T_{3}:=\left\{a_{0}, a_{2}, \ldots, a_{n-1}, \frac{1}{2}\left(b_{1}+c_{1}+b_{3}+c_{3}\right), \frac{1}{2}\left(b_{1}+c_{1}-b_{3}-c_{3}\right)\right\}
$$

is an orthogonal set in $l^{2}\left(\Gamma_{k}\right)$, which is obvious.

Theorem 3.7. Let $V=V_{11} \sqcup V_{12} \sqcup V_{21} \sqcup V_{22}$ as in Definition 3.5. Then $\mathbb{Z} V \subset M_{2}(\mathscr{B})$ forms a fusion ring, with coefficients given by

$$
N_{X, Y}^{Z}=\langle X Y, Z\rangle_{\mu}
$$

where $X \in V_{i j}, Y \in V_{j k}, Z \in V_{i k},(i, j, k) \in\{1,2\}^{3}$, and with units $\alpha_{0} \in V_{11}$ and $\alpha_{0}^{\prime} \in V_{22}$. Moreover the graph with vertices $V_{11} \sqcup V_{12}$ obtained by right multiplication by $\alpha=\alpha_{1}$ is $\Gamma_{k}$ and the graph with vertices $V_{21} \sqcup V_{22}$ obtained by right multiplication by $\bar{\alpha}$ is $\Gamma_{k}^{\prime}$.
Proof. By Lemma 3.6, for all $i, j \in\{1,2\}$, the set $V_{i j}$ is linearly independent in $\mathscr{B} \otimes f_{i j}$. Hence

$$
\begin{aligned}
& \operatorname{dim}\left(\mathbb{R} V_{11}\right)=\left|V_{11}\right|=2 k+6 \\
& \operatorname{dim}\left(\mathbb{R} V_{12}\right)=\operatorname{dim}\left(\mathbb{R} V_{21}\right)=\operatorname{dim}\left(\mathbb{R} V_{22}\right)=2 k+4
\end{aligned}
$$

This implies that

$$
\begin{aligned}
& \mathbb{R} V_{11}=\mathscr{B} \otimes f_{11}, \\
& \mathbb{R} V_{12}=\operatorname{span}\left\{e_{12}, e_{22}, e_{33}, \ldots, e_{2 k+4,2 k+4}\right\} \otimes f_{12}, \\
& \mathbb{R} V_{21}=\operatorname{span}\left\{e_{21}, e_{22}, e_{33}, \ldots, e_{2 k+4,2 k+4}\right\} \otimes f_{21}, \\
& \mathbb{R} V_{22}=\operatorname{span}\left\{e_{11}, e_{22}, e_{33}, \ldots, e_{2 k+4,2 k+4}\right\} \otimes f_{22},
\end{aligned}
$$

because the four inclusions $\subset$ are obvious, and the right-hand sides have dimensions $2 k+6$ (respectively, $2 k+4,2 k+4,2 k+4$ ). Therefore

$$
\mathbb{R} V=\mathbb{R} V_{11} \oplus \mathbb{R} V_{12} \oplus \mathbb{R} V_{21} \oplus \mathbb{R} V_{22}
$$

forms a bigraded $\mathbb{R}$-algebra, and the conjugation $X \rightarrow \bar{X}$ extends by linearity to all of $\mathbb{R} V$ and it is given by transposition of matrices. Moreover, for $X \in V_{i j}, Y \in V_{j k}$, $i, j, k \in\{1,2\}$, we have a unique decomposition

$$
X Y=\sum_{Z \in V_{i k}} N_{X, Y}^{Z} Z
$$

where by Lemma 3.6,

$$
N_{X, Y}^{Z}=\langle X Y, Z\rangle_{\mu} \in \mathbb{R}
$$

The identities

$$
N_{X, Y}^{Z}=N_{Z, \bar{Y}}^{X}=N_{\bar{X}, Z}^{Y}=N_{\bar{Z}, X}^{\bar{Y}}=N_{Y, \bar{Z}}^{\bar{X}}
$$

are now a simple consequence of the fact that $\mu$ is a trace state on the real $C^{*}$ algebra $\mathscr{B}$, so in particular

$$
\begin{aligned}
& \mu(b)=\mu\left(b^{t}\right), \quad b \in \mathscr{B}, \\
& \mu(b c)=\mu(c b), \quad b, c \in \mathscr{B} .
\end{aligned}
$$

It remains to prove that $N_{X, Y}^{Z} \in \mathbb{N}_{0}$ and that multiplication from the right by $\alpha=\alpha_{1}$ (respectively, $\bar{\alpha}$ ) on $V_{11}$ (respectively, $V_{22}$ ) generates the graph $\Gamma_{k}$ (respectively, $\Gamma_{k}^{\prime}$ ).

Lemma 3.8. Let $\alpha=\alpha_{1}$.
(a) For $X \in V_{11}, Y \in V_{12}$,

$$
\langle X \alpha, Y\rangle_{\mu}=\langle X, Y \bar{\alpha}\rangle_{\mu} \in \mathbb{N}_{0}
$$

and $\left(\langle X \alpha, Y\rangle_{\mu}\right)_{X \in V_{11}, Y \in V_{12}}$ is the adjacency matrix $G_{k}$ for $\Gamma_{k}$.
(b) For $X \in V_{22}, Y \in V_{21}$,

$$
\langle X \bar{\alpha}, Y\rangle_{\mu}=\langle X, Y \alpha\rangle_{\mu} \in \mathbb{N}_{0}
$$

and $\left(\langle X \bar{\alpha}, Y\rangle_{\mu}\right)_{X \in V_{22}, Y \in V_{21}}$ is the adjacency matrix $G_{k}^{\prime}$ for $\Gamma_{k}^{\prime}$.
Proof. This follows from simple computations using Definition 3.5, Lemma 3.6, the recursion formula

$$
t R_{n}(t)=R_{n+1}(t)+R_{n-1}(t), \quad n \geq 1
$$

and the identity from Lemma 3.3(c)

$$
R_{n+4}(A)-R_{n+2}(A)-R_{n}(A)-R_{n-2}(A)=0
$$

(a) It follows immediately from ( $\star$ ) that for $1 \leq j \leq 2 k+1$,

$$
\alpha_{2 j} \alpha=\alpha_{2 j+1}+\alpha_{2 j-1}
$$

which shows that $\alpha_{2 j} \in V_{11}$ is connected to $\alpha_{2 j+1}$ and $\alpha_{2 j-1}$ in $V_{12}$ (with simple edges) and not connected to any other $Y \in V_{12}$. To prove that we recover the graph $\Gamma_{k}$ this way we just have to check that $\alpha_{0} \alpha=\alpha_{1}$, which is obvious, and that $\beta_{1} \alpha=\alpha_{n}+\beta_{2}$ and $\beta_{3} \alpha=\beta_{2}$. The last equality follows from

$$
\begin{aligned}
\beta_{3} \alpha & \left.=\frac{1}{2}\left(\left(R_{n+3}-R_{n+1}-R_{n-1}\right)(A)+\sqrt{2 k+3}\left(e_{12}+e_{21}\right)\right) A\right) \otimes f_{12} \\
& \left.=\frac{1}{2}\left(R_{n+4}-2 R_{n}-R_{n-2}\right)(A)+\sqrt{2(2 k+3)} e_{12}\right) \otimes f_{12} \\
& =\frac{1}{2}\left(\left(R_{n+2}-R_{n}\right)(A)+\sqrt{2(2 k+3)} e_{12}\right) \otimes f_{12} \\
& =\beta_{2}
\end{aligned}
$$

where we used ( $\star$ ) and ( $\star \star$ ) and the fact that $e_{12} A=\sqrt{2} e_{12}, e_{21} A=0$. The proof of $\beta_{1} \alpha=\alpha_{n}+\beta_{2}$ is similar.
(b) To recover the graph $\Gamma_{k}$ from $V_{22} \sqcup V_{21}$, it suffices to prove that

$$
\begin{aligned}
\alpha_{0}^{\prime} \bar{\alpha} & =\bar{\alpha}_{1}, \\
\alpha_{2 j}^{\prime} \bar{\alpha} & =\bar{\alpha}_{2 j+1}+\bar{\alpha}_{2 j-1}, \quad 1 \leq j \leq 2 k+1, \\
f \bar{\alpha} & =\bar{\alpha}_{n}, \\
g \bar{\alpha} & =\bar{\alpha}_{n}+\bar{\beta}_{2}+\bar{\gamma}_{2} .
\end{aligned}
$$

The first two are obvious. A computation proves $f \bar{\alpha}=\bar{\alpha}_{n}$ :

$$
\begin{aligned}
f \bar{\alpha} & =\frac{1}{2}\left(\left(R_{n-1}(A)+2 R_{n+1}(A)-R_{n+3}(A)\right) A \otimes f_{21}\right. \\
& =\frac{1}{2}\left(R_{n-2}+3 R_{n}+R_{n+2}-R_{n+4}\right)(A) \otimes f_{21} \\
& =\frac{1}{2} \cdot 2 R_{n}(A) \otimes f_{21} \\
& =\bar{\alpha}_{n}
\end{aligned}
$$

where we again used $(\star)$ and $(\star \star)$. The formula for $g \bar{\alpha}$ is obtained similarly.
Lemma 3.9. Put

$$
\xi:=\left(\beta_{1}-\gamma_{1}\right)+\left(\beta_{3}-\gamma_{3}\right) .
$$

Then

$$
\bar{\xi}:=\left(\beta_{1}-\gamma_{1}\right)-\left(\beta_{3}-\gamma_{3}\right)
$$

and

$$
\begin{array}{rl}
\frac{1}{2} \xi \bar{\xi}=2 \alpha_{0}-2 \alpha_{2}+\cdots+2 \alpha_{4 k}-2 \alpha_{4 k+2}+\left(\beta_{1}+\gamma_{1}\right)-\left(\beta_{3}+\gamma_{3}\right) \\
\frac{1}{2} \bar{\xi} \xi=2\left(\alpha_{0}+\alpha_{2}\right)-2\left(\alpha_{4}+\alpha_{6}\right)+\cdots+(-1)^{k} & 2\left(\alpha_{4 k}+\alpha_{4 k+2}\right) \\
& +(-1)^{k+1}\left(\beta_{1}+\gamma_{1}+\beta_{3}+\gamma_{3}\right)
\end{array}
$$

Proof. Clearly $\bar{\xi}=\left(\beta_{1}-\gamma_{1}\right)-\left(\beta_{3}-\gamma_{3}\right)$. By Lemma 3.8, the linear maps

$$
\begin{aligned}
& R_{\alpha}: \mathbb{R} V_{11} \rightarrow \mathbb{R} V_{12}, \\
& R \bar{\alpha}: \mathbb{R} V_{12} \rightarrow \mathbb{R} V_{11}
\end{aligned}
$$

obtained by right multiplication by $\alpha$ (respectively, by $\bar{\alpha}$ ) have the matrices $G^{t}$ (respectively, $G$ ) expressed with respect to bases $V_{11}$ for $\mathbb{R} V_{11}$ and $V_{11}$ for $\mathbb{R} V_{12}$. Hence

$$
R_{\alpha \bar{\alpha}}:=R \bar{\alpha} R_{\alpha}: \mathbb{R} V_{11} \rightarrow \mathbb{R} V_{12}
$$

has the matrix $\mathbb{D}=G G^{t}$ with respect to the basis $V_{11}$ for $\mathbb{R} V_{11}$. We can now argue exactly as in Case 1 of Section 2A to get

$$
\begin{aligned}
& \xi \bar{\xi} \in E(\mathbb{D}, 0)_{s c}=\mathbb{R} y_{1}, \\
& \bar{\xi} \xi \in E(\mathbb{D}, 2)_{s c}=\mathbb{R} x_{1},
\end{aligned}
$$

where

$$
\begin{aligned}
& y_{1}=2 \alpha_{0}-2 \alpha_{2}+\cdots+2 \alpha_{4 k}-2 \alpha_{4 k+2}+\left(\beta_{1}+\gamma_{1}\right)-\left(\beta_{3}+\gamma_{3}\right) \\
& x_{1}=2\left(\alpha_{0}+\alpha_{2}\right)-2\left(\alpha_{4}+\alpha_{6}\right)+\cdots+(-1)^{k} 2\left(\alpha_{4 k}+\alpha_{4 k+2}\right) \\
& \quad+(-1)^{k+1}\left(\beta_{1}+\gamma_{1}+\beta_{3}+\gamma_{3}\right) .
\end{aligned}
$$

Since $\left\langle\xi \bar{\xi}, \alpha_{0}\right\rangle_{\mu}=\left\langle\bar{\xi} \xi, \alpha_{0}\right\rangle_{\mu}=\langle\xi, \xi\rangle_{\mu}=4$ and $\left\langle y_{1}, \alpha_{0}\right\rangle_{\mu}=\left\langle x_{1}, \alpha_{0}\right\rangle_{\mu}=2$, it follows that $\bar{\xi}=2 y_{1}$ and $\bar{\xi} \xi=2 x_{1}$.
End of proof of Theorem 3.7. It remains to prove that $N_{X, Y}^{Z} \in \mathbb{N}_{0}$ for all $X \in V_{i j}$, $Y \in V_{j k}$ and $Z \in V_{i k},(i, j \in\{1,2,3\})$.Having established the formulas for $\bar{\xi} \bar{\xi}$ and $\bar{\xi} \xi$ in Lemma 3.8, the proof that $N_{X, Y}^{Z} \in \mathbb{N}_{0}$ can be obtained from Section 2: Using

$$
N_{X, Y}^{Z}=N_{Z, \bar{Y}}^{X}=N_{\bar{X}, Z}^{Y}
$$

if $X, Y$ or $Z$ is one of the elements $\left(\alpha_{j}\right)_{0 \leq j \leq n},\left(\alpha_{j}^{\prime}\right)_{0 \leq j \leq n}$ (where $\alpha_{2 k+1}^{\prime}=\bar{\alpha}_{2 k+1}$ ), then $N_{X, Y}^{Z}$ is an entry of the matrix $R_{j}(\Delta)$ or $R_{j}\left(\Delta^{\prime}\right)$, which is a nonnegative integer by [de la Harpe and Wenzl 1987]. In the remaining cases, $X, Y$ and $Z$ are compatible and come from the list

$$
\beta_{1}, \gamma_{1}, \beta_{3}, \gamma_{3}, \beta_{2}, \gamma_{2}, \bar{\beta}_{2}, \bar{\gamma}_{2}, f, g
$$

For $X, Y, Z \in\left\{\beta_{1}, \gamma_{1}, \beta_{3}, \gamma_{3}\right\}$, we have $N_{X, Y}^{Z} \in \mathbb{N}_{0}$ by Theorems 2.7 and 2.8, and the remark at the end of Section 2A. The case $X, Y, Z \in\{f, g\}$ is treated in Theorem 2.10 and the remaining cases can easily be reduced to these two cases by using $\beta_{2}=\beta_{3} \alpha$ and $\gamma_{2}=\gamma_{3} \alpha$ (see Sections 2B and 2F).
Remark 3.10. From Definition 3.5, we have

$$
\begin{aligned}
& \xi=\left(\beta_{1}-\gamma_{1}\right)+\left(\beta_{3}-\gamma_{3}\right)=2 \sqrt{2 k+3} e_{12} \otimes f_{11} \\
& \bar{\xi}=\left(\beta_{1}-\gamma_{1}\right)-\left(\beta_{3}-\gamma_{3}\right)=2 \sqrt{2 k+3} e_{21} \otimes f_{11}
\end{aligned}
$$

Thus

$$
\begin{aligned}
& \xi \bar{\xi}=4(2 k+3) e_{11} \otimes f_{11} \\
& \bar{\xi} \xi=4(2 k+3) e_{22} \otimes f_{11}
\end{aligned}
$$

Since $A=\operatorname{diag}\left(0, \sqrt{2}, \sqrt{t_{3}}, \ldots, \sqrt{t_{2 k+4}}\right)$, where $t_{3}, \ldots, t_{2 k+4}$ are the distinct roots of $q_{k}(t)$, and since $0,2 \notin\left\{t_{3}, \ldots, t_{2 k+4}\right\}$, the maps $e_{11}$ and $e_{22}$ are the projections on the eigenspaces for $A$ with eigenvalues 0 and 2 , respectively. Using $q_{k}(0)=2 k+3$ and $q_{k}(2)=(-1)^{k+1}(2 k+3)$ gives

$$
\begin{aligned}
\left(2-A^{2}\right) q_{k}\left(A^{2}\right) & =2(2 k+3) e_{11} \\
A^{2} q_{k}\left(A^{2}\right) & =(-1)^{k+1}(2 k+3) e_{22}
\end{aligned}
$$

because the polynomial $(2-t) q_{k}(t)$ vanishes at $t=2$ and $t=t_{j}, 3 \leq j \leq 2 k+4$, and has the value $2(2 k+3)$ at $t=0$. Similarly $t q_{k}(t)$ vanishes at $t=0$ and
$t=t_{j}, 3 \leq j \leq 2 k+4$, and has the value $(-1)^{k+1} 2(2 k+3)$ at $t=2$. Hence the two identities

$$
\begin{aligned}
& \xi \bar{\xi}=2\left(2-A^{2}\right) q_{k}\left(A^{2}\right) \otimes f_{11}=2\left(1_{N}-\alpha \bar{\alpha}\right) q_{k}(\alpha \bar{\alpha}) \\
& \bar{\xi} \xi=(-1)^{k+2} 2 A^{2} q_{k}\left(A^{2}\right) \otimes f_{11}=(-1)^{k+2} 2 \alpha \bar{\alpha} q_{k}(\alpha \bar{\alpha})
\end{aligned}
$$

hold, where $1_{N}=\alpha_{0}$ and $\alpha=\alpha_{1}$. Let $Q_{j}$ denote as usual the polynomial for which $R_{2 j}(t)=Q_{j}\left(t^{2}\right), t \in \mathbb{R}$. Then by Definition 3.5,

$$
\begin{aligned}
\alpha_{2 j} & =Q_{j}(\alpha \bar{\alpha}) \\
\beta_{1}+\gamma_{1} & =Q_{2 k+2}(\alpha \bar{\alpha}) \\
\beta_{3}+\gamma_{3} & =\left(Q_{2 k+3}-Q_{2 k+2}-Q_{2 k+1}\right)(\alpha \bar{\alpha})
\end{aligned}
$$

Hence a more direct proof of Lemma 3.8 can be obtained if the two polynomial identities hold:

$$
\begin{aligned}
& r_{k}=\left(2 Q_{0}-2 Q_{1}+\cdots+2 Q_{2 k}-2 Q_{2 k+1}\right)+\left(Q_{2 k+1}+2 Q_{2 k+2}-Q_{2 k+3}\right) \\
& s_{k}=2\left(Q_{0}+Q_{2}\right)-2\left(Q_{2}+Q_{4}\right)+\cdots+(-1)^{k} 2\left(Q_{2 k}+Q_{2 k+1}\right) \\
& \quad+(-1)^{k+1}\left(Q_{2 k+3}-Q_{2 k+1}\right),
\end{aligned}
$$

where

$$
r_{k}(t)=(2-t) q_{k}(t), \quad s_{k}(t)=(-1)^{k+1} t q_{k}(t)
$$

These two polynomials identities are actually true, and they can be proved using the recursion formulas for $\left(q_{k}\right)_{k=0}^{\infty}$ and $\left(R_{j}\right)_{j=0}^{\infty}$.

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